【代码解析】W3自定义WPS按钮事件

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一、如何自定义按钮事件

问题:

如题

解答:

- 1、通过设备BSP相关的资源文件定义Button,通过可能是一个GPIO口,具体参考<u>W2C</u>的GPIO定义与W3的GPIO定义。
- **2**、在./gpio-button-hotplug. c文件中找到button_map[],为button取一个名字。如下代码定义了wps_smartcfg。

```
1 Hatic struct bh map button map[] = {
2
                               "BTN 0"),
      BH MAP (BTN 0,
3
      BH MAP (BTN 1,
                               ^{\prime\prime}BTN_{1}^{\prime\prime}),
4
                               "BTN 2"),
      BH_MAP (BTN_2,
5
      BH MAP (BTN 3,
                               "BTN 3"),
6
      BH_MAP (BTN_4,
                               "BTN 4"),
7
      BH MAP (BTN 5,
                               "BTN 5"),
8
      BH MAP (BTN 6,
                               "BTN 6"),
9
      BH MAP (BTN 7,
                               "BTN 7"),
10
       BH MAP (BTN 8,
                                "BTN 8"),
11
        BH MAP (BTN 9,
                                 "BTN 9"),
12
        BH MAP (KEY POWER,
                                "power"),
13
        BH MAP (KEY RESTART,
                                   "reset"),
                                  "rfkill"),
14
        BH MAP (KEY RFKILL,
15
        //BH_MAP(KEY_WPS_BUTTON,
                                         "wps"),
                                      "wps smartcfg"),
16
        BH MAP (KEY WPS BUTTON,
17
        BH MAP (KEY WIMAX,
                                 "wwan"),
18 };
```

3、点击按钮,触发按钮发送uevent事件,触发过程可参考参考<u>W2C的GPIO定义</u>与<u>W3的GPIO定义</u>,事件内容如下:

```
{{"HOME":"\/", "PATH":"\/sbin:\/bin:\/usr\/sbin:\/usr\/bin", "SUBSYSTEM":"button", "ACTION":"pressed", "BUTTON":"wps_smartcfg", "SEEN":"2", "SEQNUM":"1065"}}
{{"HOME":"\/", "PATH":"\/sbin:\/bin:\/usr\/sbin:\/usr\/bin", "SUBSYSTEM":"button", "ACTION":"released", "BUTTON":"wps_smartcfg", "SEEN":"0", "SEQNUM":"1066"}}
其中BUTTON的值会写上wps smartcfg。
```

4、procd会通过hotplug函数,打开netlink接口,监听uevent事件,代码如下:

```
6
      rule_file = strdup(rules);
7
      memset(&nls, 0, sizeof(struct sockaddr_nl));
8
      nls.nl family = AF NETLINK;
9
      nls.nl_pid = getpid();
10
       nls.nl groups = -1;
11
12
       if ((hotplug fd. fd = socket (PF NETLINK, SOCK DGRAM | SOCK CLOEXEC,
NETLINK KOBJECT UEVENT)) == -1) {
           ERROR ("Failed to open hotplug socket: %s\n", strerror(errno));
13
14
           exit(1);
      }
15
16
      if (bind(hotplug fd. fd, (void *)&nls, sizeof(struct sockaddr nl))) {
           ERROR("Failed to bind hotplug socket: %s\n", strerror(errno));
17
18
           exit(1);
19
       }
20
21
       if (setsockopt (hotplug fd. fd, SOL SOCKET, SO RCVBUFFORCE,
&nlbufsize, sizeof(nlbufsize)))
22
           ERROR ("Failed to resize receive buffer: %s\n", strerror(errno));
23
24
       json script init(&jctx);
25
       queue_proc. cb = queue_proc_cb;
26
       uloop_fd_add(&hotplug_fd, ULOOP_READ);
27 }
第3~22行,创建netlink接口。
第24~26行,将neklink接口加入uloop框架进行监听,
5、收到uevent消息以后,通过hotplug handle函数进行处理。
1 Edatic void hotplug handler(struct uloop fd *u, unsigned int ev)
2 {
      int i = 0;
3
4
      static char buf[4096];
      int len = recv(u->fd, buf, sizeof(buf), MSG DONTWAIT);
5
      void *index;
6
7
      if (len < 1)
8
          return;
9
10
       blob buf init(&b, 0);
11
       index = blobmsg_open_table(&b, NULL);
12
       while (i < len) {
           int 1 = strlen(buf + i) + 1;
13
           char *e = strstr(&buf[i], "=");
14
15
           if (e) {
16
               *e = ' \setminus 0' :
17
               blobmsg_add_string(&b, &buf[i], &e[1]);
18
19
20
           i += 1;
21
      }
```

```
blobmsg_close_table(&b, index);
hotplug_handler_debug(b.head);
json_script_run(&jctx, rule_file, blob_data(b.head));
}
```

6、hotplug handle函数通过配置脚本hotplug.json进行处理,脚本关键点如下:

```
1 □ [ "if",
          [ "and",
2
             [ "has", "BUTTON" ],
3
              [ "eq", "SUBSYSTEM", "button" ],
4
5
          [ "exec", "/etc/rc.button/%BUTTON%" ]
6
7
     [ "if",
8
          [ "eq", "SUBSYSTEM",
9
              ["net", "input", "usb", "usbmisc", "ieee1394", "block",
10
"atm", "zaptel", "tty", "button" ]
           [ "exec", "/sbin/hotplug-call", "%SUBSYSTEM%" ]
12
13
```

第1~7行,如果有BUTTON项并且SUBSYSTEM等于button,执行脚本/etc/rc.button/*,这里会执行/etc/rc.button/wps_smartcfg应用。

第8~13行,如果SUBSYSTEM有button,则通过/sbin/hotplug-call botton,去执行/etc/hotplug.d/button目录下wps_smartcfg的脚本

Tips:

不论是/etc/rc.button/或/etc/hotplug. d/下脚本,脚本中都必须带#!/bin/sh,否则无法指定脚本内容。