Taylor Series: $\sum_{n=0}^{\infty} \frac{f^{(n)}(a)}{n!} (x-a)^n$ With Remainder: $f(x) = \sum_{n=0}^{m-1} \frac{f^{(n)}(a)}{n!} (x-a)^n + \frac{f^{(m)}(c)}{m!} (x-a)^n$ for some $c \in [x,a]$ $e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \frac{x^4}{4!} + \dots$ $\sin(x) = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots$ $\cos(x) = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots$ $\ln(1-x) = -x - \frac{x^2}{2} - \frac{x^3}{3} - \frac{x^4}{4} - \dots$ $\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \frac{x^4}{4} + \dots$ $\arctan(x) = x - \frac{x^2}{3} + \frac{x^5}{5} - \frac{x^7}{7} + \dots$ Memory Adds And Multiplies $P(x) = x^7(a_7 + x^5(a_{12} + x^5(a_{17} + x^5(a_{22} + x^5 \cdot a_{27})))$ Binary Exponentiation Repeating Representation: $\frac{a}{b}$ in base c need $\frac{a}{b} = \sum d_i c^i + c^j \cdot \frac{d_h}{c^k - 1}$ with $b|c^{h'}(c^k - 1)$ so relevant $\phi(p) = p - 1$ from prime factorisations lead to k and then fractional representation conversion.

 $\epsilon_{\rm machine}=2^{-52}$ Chopping, Rounding [Towards 0, Towards Even], Nearest: if the 53rd bit is 0 then round down truncate, if $1.\dots100\dots0\dots=1\dots1\overline{0}$ then round down truncate, else

IEEE Double Precision Representation For Floating Point Number: 1 Sign Bit 11 Exponent Bits 52 Mantissa Bits,

1.... $100....0\cdots = 1....10$ then round down truncate, else round up add 1 to 52nd bit and reoperate. Can express 9.4 as $+1.0010110011...101 \times 2^3$.

```
Round Down

1.00...000 +
. 110100 =

1.00...011

Round Down

1.11...111 +
. 001000 =

1.11...111

Round Up [?] In Register

1.11...111 +
. 001100 =

1.00...000 x 2^1
```

Relative Error $\frac{|\operatorname{float}(x)-x|}{|x|} \leq \frac{1}{2}\epsilon_{\operatorname{machine}}$ For $x \neq 0$ Bisection Method i.e. Binary Searching: if one has an interval [a,b] which contains a root e.g. f(a)f(b) < 0 then iteratedly replace the proper endpoint with $\frac{a+b}{2}$ thereby converging linearly upon the root r with factor $S = \frac{1}{2}$. Fixed Point: f(x) = x

Root Multiplicity: Intuitive $(x-r)^{\text{multiplicity}}$ term in finite polynomial functional representation, degree of derivative where $f^{(\text{multiplicity})}(r) \neq 0$, lowest degree term in Taylor Series around r.

Fixed Point Iteration:

Want Fixed Point Or Root Of f(x) e.g. Fixed Point Of Naive g(x) = f(x) + x Choose Rearrangement Carefully $x_0 = \text{initial guess}$

```
x_{i+1} = g(x_i)
```

Linear Convergence

Meaning Errors Satisfy $\lim_{i\to\infty}\frac{e_{i+1}}{e_i}=S=|g'(r)|<1$ Root Finding Problem

Forward Error: $|r - x_a|$

```
Backward Error: |f(x_a)|
Sensitive, Small Errors In Input Lead To Large Errors In
Output, Error Magnification Factor, Condition Number
Sensitivity Formula For Roots: if \epsilon \ll f'(r), r is a root of
f(x) and r + \Delta r is a root of f(x) + \epsilon g(x) then \Delta r \approx -\frac{\epsilon g(r)}{f'(r)}
error magnification factor = \frac{\text{relative forward error}}{\text{relative backward error}}
Newton's Method:
x_0 = initial guess
x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}
Quadratically Convergent If Root Has Multiplicity 1 i.e.
Meaning Errors Satisfy \lim_{i\to\infty} \frac{e_{i+1}}{e_i^2} = M, M = \frac{f''(r)}{2f'(r)}
Otherwise Linear
Multiplicity m Root r:
\lim_{i \to \infty} \frac{e_{i+1}}{e_i} = S = \frac{m-1}{m} Modified
x_{i+1} = x_i - m \cdot \frac{f(x_i)}{f'(x_i)}
Quadratically Convergent
Can blowup diverge to infinity f(x) = x^{\frac{1}{3}} or fail due to
divide by 0 if f'(x_i) = 0.
Secant Method:
x_0, x_1 = initial guesses
x_{i+1} = x_i - \frac{f(x_i)(x_i - x_{i-1})}{f(x_i) - f(x_{i-1})}
Method Of False Position:
for i=1,2,3,...
      c=(bf(a)-af(b))/(f(a)-f(b))
      if f(c)=0, stop, end
```

```
c=(bf(a)-af(b))/(f(a)-f(b))
if f(c)=0,stop,end
if f(a)f(c)<0
    b=c
else
    a=c
end
end</pre>
```

Muller's Method: use 3 previous points, parabola, nearest root to previous point is next point. Complex arithmetic software complex roots. Faster convergence than Secant Method.

Inverse Quadratic Interpolation: use 3 previous points, parabola function in y, Lagrange Interpolation. Faster convergence than Second Method.

Brent's Method: hybrid method, Matlab fzero command. Gaussian Elimination: $O(n^3)$

Reduced Row Echelon Form: can augment with b_i to resolve $Ax = b_i$.

Lower Upper Factorisation: add copies of row 1 to rows $2, 3, \ldots$ to zero column 1 below the diagonal in U and store those coefficients in column 1 of L, iterate. For the back substitution, solve $Lx' = b_i$ and then Ux = x'.

Compute Estimate: $\approx \frac{2}{3} \cdot n^3$ and $2n^2$ operations for Lower Upper Factorisation and each instance of computing x such that $Ax = b_i$ for a total of $\frac{2}{3} \cdot n^2 + 2n^2k$.