

Start @ 12¹⁰

1. An $n \times n$ matrix is called nilpotent if $A^k = 0$, for some $k \in \mathbb{N}^+$.

Show that a nilpotent matrix A , $\det A = 0$. try it

Suppose A is nilpotent
ie, $A^k = 0$, for $k \in \mathbb{N}^+$

$\det(A^k) = \det(0) = 0$, since A is nilpotent
(consider $\det(A^k)$)

$$0 = \det(A \cdot A \cdot \dots \cdot A) \quad k \text{ times}$$

$$0 = \det(A) \cdot \dots \cdot \det(A)$$

$$\sqrt[k]{0} = \sqrt[k]{\det(A)}^k$$

$$0 = \det(A), \text{ as wanted.}$$

2. Prove if A, B are similar, then $\det(A) = \det(B)$

Suppose A, B are similar

$$\text{ie, } B = P^{-1}AP, \text{ for some } P, P^{-1} \in M_{n \times n}(F)$$

Consider $\det(B)$,

$$\begin{aligned}\det(B) &= \det(P^{-1}AP), \text{ since } A, B \text{ are similar} \\ &= \det(P^{-1}) \det(A) \det(P), \text{ by det prop.} \\ &= \frac{1}{\det(P)} \det(A) \det(P), \text{ by det prop.} \\ &= \det(A), \text{ as wanted}\end{aligned}$$

3. A real non matrix Q is called orthogonal if $Q^T Q = I$.

Prove that if Q is orthogonal, $\det(Q) = \pm 1$.

Suppose Q is orthogonal

$$\text{i.e., } Q^T Q = I$$

Consider $\det(Q^T Q)$,

$$\det(Q^T Q) = \det(Q^T) \det(Q), \text{ by det prop}$$

$$\det(I) = \det(Q) \cdot \det(Q), \text{ as proved before}$$

$$\sqrt{1} = \sqrt{\det(Q)^2}$$

$$1 = |\det(Q)|$$

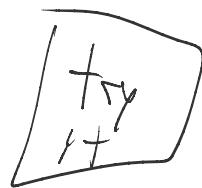
$$\Rightarrow \det(Q) = \pm 1, \text{ as wanted.}$$

4. Show if A, C are square matrices,

then $\det \begin{pmatrix} A & B \\ 0 & C \end{pmatrix} = \det A \cdot \det C$

hint: using Q 3.10 on HW 5

hint: $\begin{pmatrix} A & B \\ 0 & C \end{pmatrix} = \begin{pmatrix} I & B \\ 0 & C \end{pmatrix} \begin{pmatrix} A & 0 \\ 0 & I \end{pmatrix}$



Suppose A, C are square matrices.

Consider $\begin{pmatrix} A & B \\ 0 & C \end{pmatrix}$,

$$\begin{pmatrix} A & B \\ 0 & C \end{pmatrix} = \begin{pmatrix} I & B \\ 0 & C \end{pmatrix} \begin{pmatrix} A & 0 \\ 0 & I \end{pmatrix}$$

$$\det \begin{pmatrix} A & B \\ 0 & C \end{pmatrix} = \det \left(\begin{pmatrix} I & B \\ 0 & C \end{pmatrix} \begin{pmatrix} A & 0 \\ 0 & I \end{pmatrix} \right)$$

$$= \det \begin{pmatrix} I & B \\ 0 & C \end{pmatrix} \det \begin{pmatrix} A & 0 \\ 0 & I \end{pmatrix}, \text{ by det prop.}$$

(Q 3.10)

$$\det \begin{pmatrix} I & * \\ 0 & C \end{pmatrix} = \det C$$

$$\det \begin{pmatrix} A & 0 \\ * & I \end{pmatrix} = \det A$$

(CONT

$$= \det \begin{pmatrix} I & * \\ 0 & C \end{pmatrix} \cdot \det \begin{pmatrix} A & 0 \\ * & I \end{pmatrix} \quad (\text{has form})$$

$$= \det C \cdot \det A, \text{ by 3.10}$$

r.s wanted.

as wanted.

5. Let $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear map s.t.

$$T\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 3x + 2y \\ \frac{1}{2}x - y \end{pmatrix}$$

Find the matrix of T w.r.t the standard basis, $S = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$, and $B = \left\{ \begin{pmatrix} 2 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 3 \end{pmatrix} \right\}$.

Standard.

$$\begin{aligned} T(\vec{e}_1) &= T\begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 3 \\ \frac{1}{2} \end{pmatrix} \\ &= 3\vec{e}_1 + \frac{1}{2}\vec{e}_2 \end{aligned}$$

$$\begin{aligned} T(\vec{e}_2) &= T\begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix} \\ &= 2\vec{e}_1 + (-1)\vec{e}_2 \end{aligned}$$

$$[T]_{SS} = \begin{bmatrix} \overset{\uparrow}{[T(\vec{e}_1)]_S} & \overset{\uparrow}{[T(\vec{e}_2)]_S} \\ \downarrow & \downarrow \end{bmatrix}$$

$$= \begin{bmatrix} 3 & 2 \\ \frac{1}{2} & -1 \end{bmatrix} \quad \checkmark$$

Basis B,

$$T(\vec{b}_1) = T\begin{pmatrix} 2 \\ 1 \end{pmatrix} = \begin{pmatrix} 8 \\ 0 \end{pmatrix}$$
$$= 4\vec{b}_1 + \left(-\frac{4}{3}\right)\vec{b}_2$$

$$T(\vec{b}_2) = T\begin{pmatrix} 0 \\ 3 \end{pmatrix} = \begin{pmatrix} 6 \\ -3 \end{pmatrix}$$
$$= 3\vec{b}_1 + (-2)\vec{b}_2$$

$$[T]_{BB} = \begin{bmatrix} [T(\vec{b}_1)]_B & [T(\vec{b}_2)]_B \\ \downarrow & \downarrow \end{bmatrix}$$
$$= \begin{bmatrix} 4 & 3 \\ -\frac{4}{3} & -2 \end{bmatrix}, \quad \checkmark$$