

PRML Homework 1

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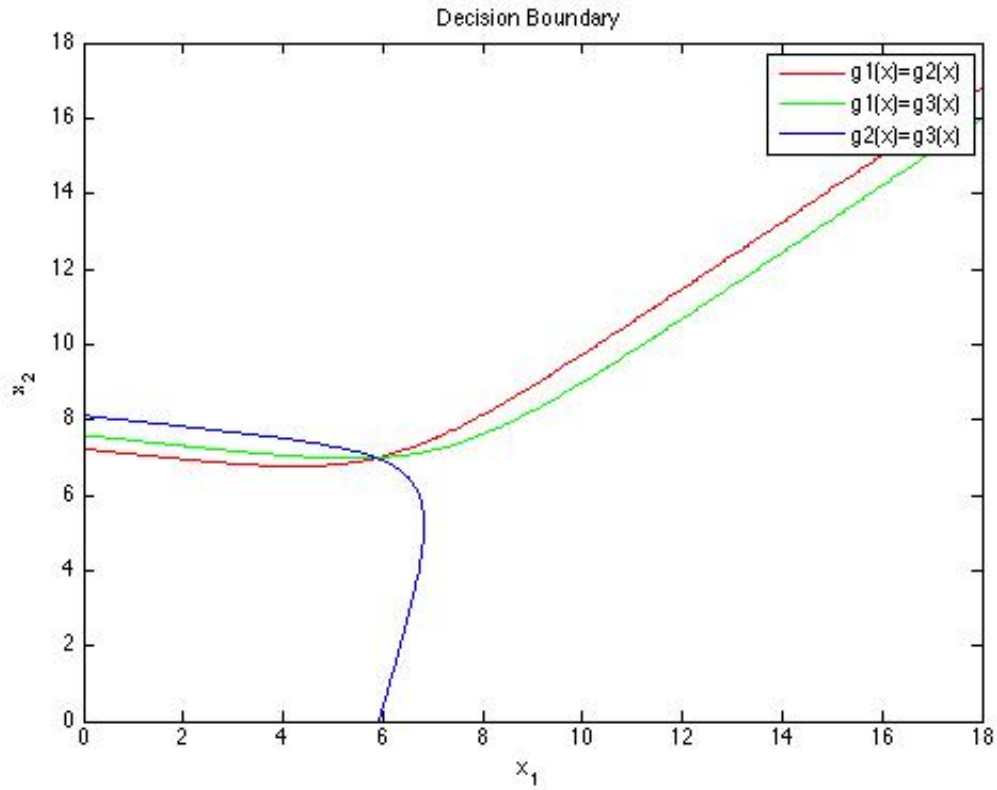
1 Problem 1

1. Solution: $g_i(x) = \sum_{y=j} \lambda(\alpha(x) = i|y = j)p(x|y = j)p(y = j)$.

As three class models $p(x|y = 1), p(x|y = 2), p(x|y = 3)$ are supposed to be 2D Gaussian distributions with the same covariance matrix $\Sigma = 9I$.

$$\text{Thus, } \begin{cases} p(x|y = 1) = \frac{1}{18\pi} \exp\left\{-\frac{(x_1-4)^2+(x_2-12)^2}{18}\right\} \\ p(x|y = 2) = \frac{1}{18\pi} \exp\left\{-\frac{(x_1-12)^2+(x_2-3)^2}{18}\right\} \\ p(x|y = 3) = \frac{1}{18\pi} \exp\left\{-\frac{(x_1-3)^2+(x_2-5)^2}{18}\right\} \end{cases}$$
$$\text{Then, } \begin{cases} g_1(x) = \frac{1}{15\pi} \exp\left\{-\frac{(x_1-12)^2+(x_2-3)^2}{18}\right\} + \frac{1}{45\pi} \exp\left\{-\frac{(x_1-3)^2+(x_2-5)^2}{18}\right\} \\ g_2(x) = \frac{2}{45\pi} \exp\left\{-\frac{(x_1-4)^2+(x_2-12)^2}{18}\right\} + \frac{1}{90\pi} \exp\left\{-\frac{(x_1-3)^2+(x_2-5)^2}{18}\right\} \\ g_3(x) = \frac{1}{15\pi} \exp\left\{-\frac{(x_1-4)^2+(x_2-12)^2}{18}\right\} + \frac{1}{45\pi} \exp\left\{-\frac{(x_1-12)^2+(x_2-3)^2}{18}\right\} \end{cases}$$

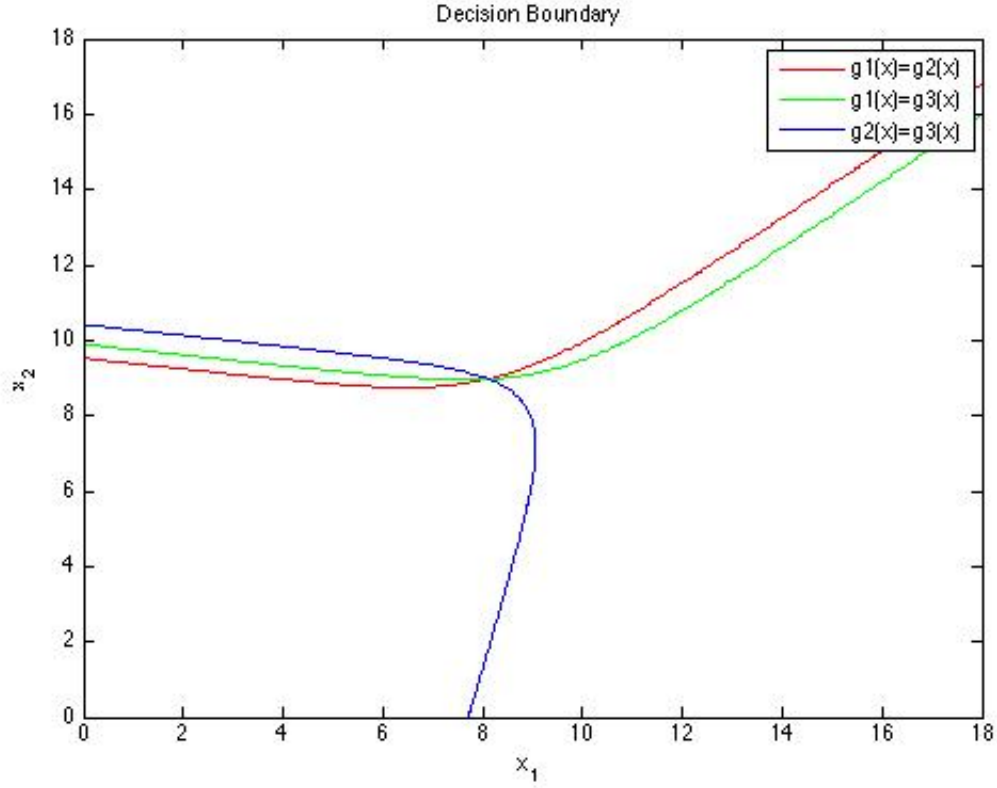
2. Solve the $g_i(x) = g_j(x)$ by MATLAB and draw the boundary as following figure.



3. When the prior distributions change, the discriminant functions change to:

$$\begin{cases} g_1(x) = \frac{1}{30\pi} \exp\left\{-\frac{(x_1-12)^2+(x_2-3)^2}{18}\right\} + \frac{1}{15\pi} \exp\left\{-\frac{(x_1-3)^2+(x_2-5)^2}{18}\right\} \\ g_2(x) = \frac{1}{45\pi} \exp\left\{-\frac{(x_1-4)^2+(x_2-12)^2}{18}\right\} + \frac{1}{30\pi} \exp\left\{-\frac{(x_1-3)^2+(x_2-5)^2}{18}\right\} \\ g_3(x) = \frac{1}{30\pi} \exp\left\{-\frac{(x_1-4)^2+(x_2-12)^2}{18}\right\} + \frac{1}{90\pi} \exp\left\{-\frac{(x_1-12)^2+(x_2-3)^2}{18}\right\} \end{cases}$$

We re-draw the decision boundary:



2 Problem 2

1. Solution

$$\begin{aligned} R_{ran} &= \int_{\Omega^d} R(\alpha|x)p(x)dx. \\ &= \int_{\Omega^d} \sum_{j \in \Sigma^c} \lambda(\alpha|y=j)p(y=j|x)p(x)dx. \end{aligned}$$

Due to it is 0-1 loss function, and the decision is made by a randomized decision rule, which decides x to class i following $\alpha(x) = y \sim p(y|x)$, so

$$\begin{aligned} \lambda(\alpha|y=j) &= \sum_{k \in \Omega^c, k \neq j} p(\alpha = k) \\ &= \sum_{k \in \Omega^c, k \neq j} p(y = k|x) \\ &= 1 - p(y = j|x) \end{aligned}$$

which leads to

$$\begin{aligned} R_{ran} &= \int_{\Omega^d} \sum_{j \in \Omega^c} (1 - p(y = j|x)) p(y = j|x) p(x) dx. \\ &= \int_{\Omega^d} (1 - \sum_{j \in \Omega^c} p^2(y = j|x)) p(x) dx. \end{aligned}$$

2. Proof.

$$\begin{aligned} R_{bayes} &= \int_{\Omega^d} R(\alpha|x) p(x) dx. \\ &= \int_{\Omega^d} (1 - p(y = t|x)) p(x) dx. \\ \text{where } t &= \operatorname{argmax}_{t \in \Omega^c} p(y|x). \end{aligned}$$

Compare integral parts of R_{ran}, R_{hayes} . Now, we consider each possible $x \in \Omega^d$, we want to prove $(1 - p(y = t|x)) p(x) \leq (1 - \sum_{j \in \Omega^c} p^2(y = j|x)) p(x)$ ($t = \operatorname{argmax}_{t \in \Omega^c} p(y|x)$), which can lead to R_{ran} is always larger than or equal to R_{bayes} .

$$\begin{aligned} &(1 - \sum_{j \in \Omega^c} p^2(y = j|x)) - (1 - p(y = t|x)) \\ &= p(y = t|x) - \sum_{j \in \Omega^c} p^2(y = j|x) \\ &= p(y = t|x)(1 - p(y = t|x)) - \sum_{j \in \Omega^c, j \neq t} p^2(y = j|x) \\ &= p(y = t|x) \sum_{j \in \Omega^c, j \neq t} p(y = j|x) - \sum_{j \in \Omega^c, j \neq t} p^2(y = j|x) \\ &= \sum_{j \in \Omega^c, j \neq t} p(y = j|x) \sum_{j \in \Omega^c, j \neq t} (p(y = t|x) - p(y = j|x)) \end{aligned}$$

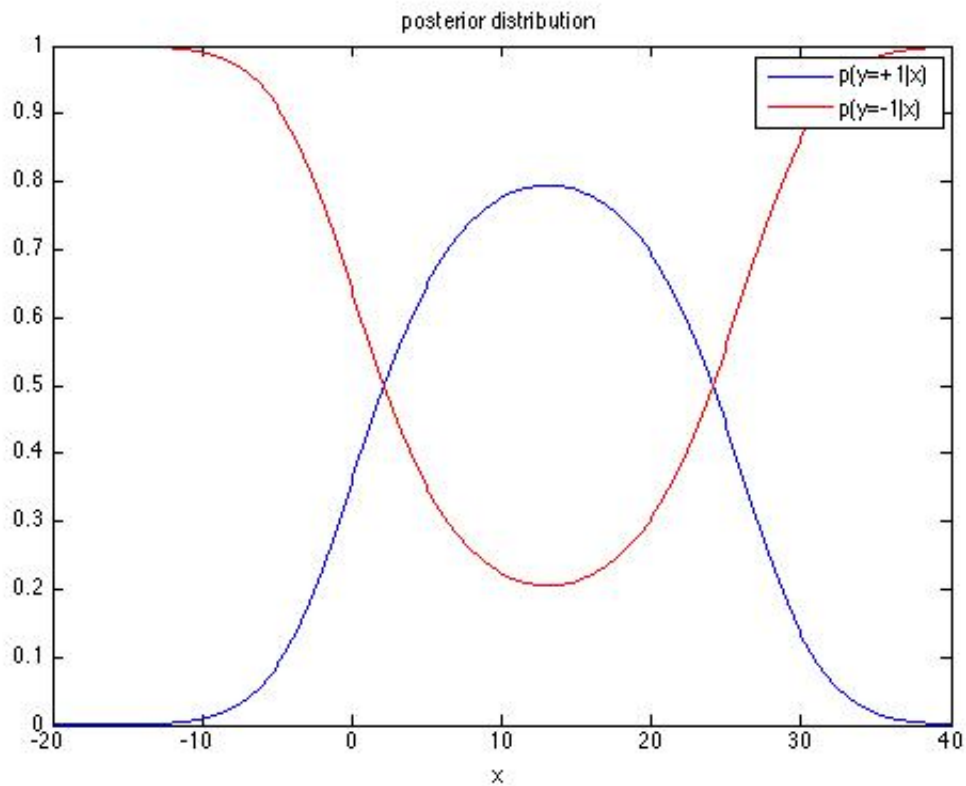
Due to $t = \operatorname{argmax}_{t \in \Omega^c} p(y|x)$, $(p(y = t|x) - p(y = j|x)) > 0$, which leads to $\sum_{j \in \Omega^c, j \neq t} p(y = j|x) \sum_{j \in \Omega^c, j \neq t} (p(y = t|x) - p(y = j|x)) \geq 0$. Therefore R_{ran} is always larger than or equal to R_{bayes} .

3. As we can see the equation in (2), when $p(y = t|x) = p(y = j|x), \forall j \in \Omega^c$, the $R_{ran} = R_{bayes}$, which means that all $p(y = j|x)$ are the same value $= \frac{1}{|\Omega^c|}$.

3 Problem 3

$$\begin{aligned} p(y = +1|x) &= \frac{p(x|y = +1)p(y = +1)}{f(x)} \\ &= \frac{p(x|y = +1)p(y = +1)}{p(x|y = +1)p(y = +1) + p(x|y = -1)p(y = -1)} \\ p(y = -1|x) &= \frac{p(x|y = -1)p(y = -1)}{p(x|y = +1)p(y = +1) + p(x|y = -1)p(y = -1)} \end{aligned}$$

plot in MATLAB:



The ROC and PR curves are showing as:

