

EE2211 Introduction to Machine Learning

Lecture 5 Semester 2 2024/2025

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Course Contents

- Introduction and Preliminaries (Xinchao)
 - Introduction
 - Data Engineering
 - Introduction to Probability and Statistics
- Fundamental Machine Learning Algorithms I (Yueming)
 - Systems of linear equations
 - Least squares, Linear regression
 - Ridge regression, Polynomial regression
- Fundamental Machine Learning Algorithms II (Yueming)
 - Over-fitting, bias/variance trade-off
 - Optimization, Gradient descent
 - Decision Trees, Random Forest
- Performance and More Algorithms (Xinchao)
 - Performance Issues
 - K-means Clustering
 - Neural Networks



Least Squares and Linear Regression

Module II Contents

- Notations, Vectors, Matrices (introduced in L3)
- Operations on Vectors and Matrices
- Systems of Linear Equations
- Set and Functions
- Derivative and Gradient
- Least Squares, Linear Regression
- Linear Regression with Multiple Outputs
- Linear Regression for Classification
- Ridge Regression
- Polynomial Regression



Recap: Linear and Affine Functions

Linear Functions

A function $f: \mathcal{R}^d \to \mathcal{R}$ is **linear** if it satisfies the following two properties:

- Homogeneity $f(\alpha x) = \alpha f(x)$ Scaling
- Additivity f(x + y) = f(x) + f(y) Adding

Inner product function

$$f(\mathbf{x}) = \mathbf{a}^T \mathbf{x} = a_1 x_1 + a_2 x_2 + \cdots + a_d x_d$$

Affine function (linear function + offset)

$$f(\mathbf{x}) = \mathbf{a}^T \mathbf{x} + \mathbf{b}$$
 scalar \mathbf{b} is called the offset (or bias)

Ref: [Book4] Stephen Boyd and Lieven Vandenberghe, "Introduction to Applied Linear Algebra", Cambridge University Press, 2018 (p31)

optimization C finding max/min)

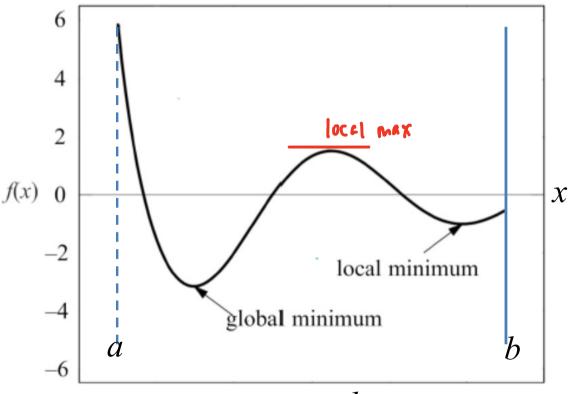
Functions: Maximum and Minimum



• f(x) has a **local minimum** at x = c if $f(x) \ge f(c)$ for every x in some open interval around x = c

f(x) has a global
 minimum at x = c if f(x) ≥
 f(c) for all x in the domain of f

A local and a global minima of a function



$$a < x \le b$$

Note: An **interval** is a set of real numbers with the property that any number that lies between two numbers in the set is also included in the set.

An **open interval** does not include its endpoints and is denoted using parentheses. E.g. (0, 1) means "all numbers greater than 0 and less than 1".

Ref: [Book1] Andriy Burkov, "The Hundred-Page Machine Learning Book", 2019 (p6-7 of chp2).

Functions: Maximum and Minimum



Max and Arg Max

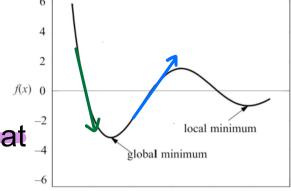
- Given a set of values $\mathcal{A} = \{a_1, a_2, ..., a_m\},\$
- The operator $\max_{a \in \mathcal{A}} f(a)$ returns the highest value f(a) for all elements in the set \mathcal{A}
- The operator $\underset{a \in \mathcal{A}}{\arg \max} f(a)$ returns the element of the set \mathcal{A} that maximizes f(a)
- When the set is **implicit** or **infinite**, we can write

$$\max_{a} f(a) \quad \text{or} \quad \arg\max_{a} f(a)$$
 E.g. $f(a) = 3a$, $a \in [0,1] \rightarrow \max_{a} f(a) = 3$ and $\arg\max_{a} f(a) = 1$
$$\max_{a} f(a) = 3a$$
 and $\max_{a} f(a) = 1$ the "max" element

Min and Arg Min operate in a similar manner

Note: **arg max** returns a value from the **domain** of the function and **max** returns from the **range** (**codomain**) of the function.

Ref: [Book1] Andriy Burkov, "The Hundred-Page Machine Learning Book", 2019 (p6-7 of chp2).



- The derivative f' of a function f is a function that describes how fast f grows (or decreases)
 - If the derivative is a constant value, e.g. 5 or −3
 - The function *f* grows (or decreases) constantly at any point *x* of its domain
 - When the derivative f' is a function
 - If f' is positive at some x, then the function f grows at this point
 - If f' is negative at some x, then the function f decreases at this point
 - The derivative of zero at x means that the function's slope at x is horizontal (e.g. maximum or minimum points) \rightarrow find 2^{nd} derivative
- The process of finding a derivative is called differentiation.
- Gradient is the generalization of derivative for functions that take several inputs (or one input in the form of a vector or some other complex structure).

Ref: [Book1] Andriy Burkov, "The Hundred-Page Machine Learning Book", 2019 (p8 of chp2).



The gradient of a function is a vector of partial derivatives

Differentiation of a scalar function w.r.t. a vector

If f(x) is a scalar function of d variables, x is a d x1 vector. Then differentiation of f(x) w.r.t. x results in a d x1 vector

$$\frac{df(\mathbf{x})}{d\mathbf{x}} = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_d} \end{bmatrix} \qquad \frac{1}{(\chi, \chi, \chi)}$$

$$\frac{1}{(\chi, \chi, \chi)}$$

This is referred to as the **gradient** of $f(\mathbf{x})$ and often written as $\nabla_{\mathbf{x}} f$.

E.g.
$$f(\mathbf{x}) = ax_1 + bx_2$$
 $\nabla_{\mathbf{x}} f = \begin{bmatrix} a \\ b \end{bmatrix}$ Ref: Duda, Hart, and Stork, "Pattern Classification", 2001 (Appendix)



Partial Derivatives

Differentiation of a vector function w.r.t. a vector

If f(x) is a vector function of size h x1 and x is a d x1 vector. Then differentiation of f(x) results in a $h \times d$ matrix

$$\frac{d\mathbf{f}(\mathbf{x})}{d\mathbf{x}} = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_d} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_h}{\partial x_1} & \dots & \frac{\partial f_h}{\partial x_d} \end{bmatrix}$$

The matrix is referred to as the **Jacobian** of f(x)

$$X = \begin{bmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{bmatrix}$$

$$A = \begin{bmatrix} \alpha_{11} & \alpha_{12} & \alpha_{13} \\ \alpha_{21} & \alpha_{22} & \alpha_{23} \end{bmatrix}$$



Some Vector-Matrix Differentiation Formulae

$$\frac{d(\mathbf{A}\mathbf{x})}{d\mathbf{x}_{3\times 1}} = \mathbf{A}_{2\times 3}$$

$$\frac{d(\mathbf{b}^T\mathbf{x})}{d\mathbf{x}_{3\times 1}} = \mathbf{b}_{1\times 3}$$

$$\frac{d(\mathbf{y}^T\mathbf{A}\mathbf{x})}{d\mathbf{x}} = \mathbf{A}^T\mathbf{y}$$

$$\mathbf{a}^T = [\mathbf{a}_1 \ \mathbf{a}_2 \ \mathbf{a}_3]$$

$$f(\mathbf{x}) = \mathbf{a}^T\mathbf{x} = a_1x_1 + a_2x_2 + \cdots + a_dx_d$$

$$\frac{d(\mathbf{a}^T\mathbf{a}_2)}{d\mathbf{a}^T\mathbf{a}_2} = \mathbf{b}_{1\times 3}$$

$$\mathbf{a}^T = [\mathbf{a}_1 \ \mathbf{a}_2 \ \mathbf{a}_3]$$

Derivations: https://www.math.uwaterloo.ca/~hwolkowi/matrixcookbook.pdf

Ref: Duda, Hart, and Stork, "Pattern Classification", 2001 (Appendix)



Poll on PollEv.com/ymjin Just "skip" if you are required to do registration

When poll is active respond at PollEv.com/ymjin

Suppose y = 3x+5, this is a linear function.

Office function -> Linear + offsef)

Office function -> Linear + offsef)



When poll is active respond at **PollEv.com/ymjin**



len?

Suppose g(x) is a scalar function of d variables where x is a $d \times 1$ vector, the outcome of differentiation of g(x) w.r.t. x is a $d \times 1$ vector.



True

0%

False

0%



 Linear regression is a popular regression learning algorithm that learns a model which is a linear combination of features of the input example.

$$Xw = y, \quad X \in \mathcal{R}^{m \times d}, \quad w \in \mathcal{R}^{d \times 1}, \quad y \in \mathcal{R}^{m \times 1}$$

$$X = \begin{bmatrix} x_{1,1} & x_{1,2} & \dots & x_{1,d} \\ \vdots & \vdots & \ddots & \vdots \\ x_{m,1} & x_{m,2} & \dots & x_{m,d} \end{bmatrix} \quad w = \begin{bmatrix} w_1 \\ \vdots \\ w_d \end{bmatrix}, \quad y = \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix}$$
[Cather] Gentine 2 Gentine 3

Ref: [Book1] Andriy Burkov, "The Hundred-Page Machine Learning Book", 2019 (p3 of chp3).





Problem Statement: To predict the unknown y for a given x (testing)

- We have a collection of labeled examples (training) $\{(\mathbf{x}_i, \mathbf{y}_i)\}_{i=1}^m$
 - m is the size of the collection
 - $-\mathbf{x}_i$ is the *d*-dimensional feature vector of example $i=1,\ldots,m$ (input)
 - $-y_i$ is a real-valued target (1-D) $-v_i$
 - Note:
 - when y_i is continuous valued, it is a regression problem (ie, like age)
 - when y_i is discrete valued, it is a classification problem (10, like gender)
- We want to build a model $f_{\mathbf{w},b}(\mathbf{x})$ as a linear combination of features of example \mathbf{x} : $f_{\mathbf{w},b}(\mathbf{x}) = \mathbf{x}^T\mathbf{w} + b$
 - where w is a d-dimensional vector of parameters and b is a real number.
- The notation $f_{\mathbf{w},b}$ means that the model f is parametrized by two values: \mathbf{w} and b

Ref: [Book4] Stephen Boyd and Lieven Vandenberghe, "Introduction to Applied Linear Algebra", Cambridge University Press, 2018 (chp.14)

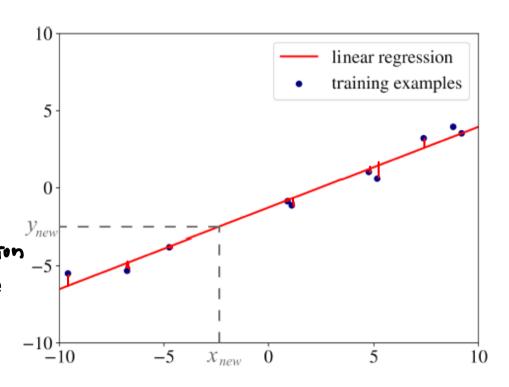


Learning objective function

• To find the optimal values for w* and b* which **minimizes** the following expression:

$$\frac{1}{m} \sum_{i=1}^{m} (f_{\mathbf{w},b}(\mathbf{x}_i) - \mathbf{y}_i)^2 \longrightarrow \text{predict}$$

 In mathematics, the expression we minimize or maximize is called an objective function, or, simply, an objective



 $(f_{\mathbf{w}}(\mathbf{x}_i) - \mathbf{y}_i)^2$ is called the **loss function**: a measure of the difference between $f_{\mathbf{w}}(\mathbf{x}_i)$ and \mathbf{y}_i or a penalty for misclassification of example *i*.

Ref: [Book1] Andriy Burkov, "The Hundred-Page Machine Learning Book", 2019 (chp3.1.2)



Learning objective function (using simplified notation hereon)

 To find the optimal values for w* which minimizes the following expression:

$$\sum_{i=1}^{m} (f_{\mathbf{w}}(\mathbf{x}_i) - \mathbf{y}_i)^2$$

with
$$f_{\mathbf{w}}(\mathbf{x}_i) = \mathbf{x}^T \mathbf{w}$$
, (\mathbf{p}_{1}) where we define $\mathbf{w} = [b, w_1, ... w_d]^T = [w_0, w_1, ... w_d]^T$, and $\mathbf{x}_i = [1, x_{i,1}, ... x_{i,d}]^T = [x_{i,0}, x_{i,1}, ... x_{i,d}]^T$, $i = 1, ..., m$

This particular choice of the loss function is called squared error loss

Note: The normalization factor $\frac{1}{m}$ can be omitted as it does not affect the optimization.

$$\sum_{i=1}^{m} (f_{\mathbf{w},b}(\mathbf{x}_i) - \mathbf{y}_i)^2$$



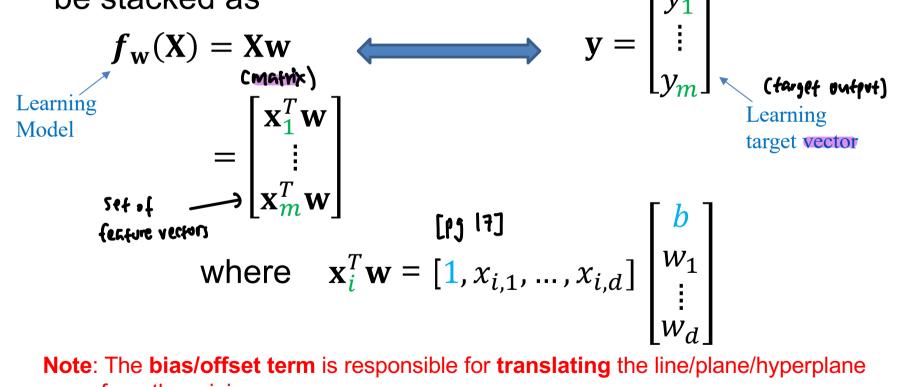
- All model-based learning algorithms have a loss function
- What we do to find the best model is to minimize the objective known as the cost function
- Cost function is a sum of loss functions over training set plus possibly some model complexity penalty (regularization)
- In linear regression, the cost function is given by the average loss, also called the empirical risk because we do not have all the data (e.g. testing data)
 - The average of all penalties is obtained by applying the model to the training data

Ref: [Book1] Andriy Burkov, "The Hundred-Page Machine Learning Book", 2019 (chp3.1.2)



Learning (Training)

 Consider the set of feature vector x_i and target output y_i indexed by i = 1, ..., m, a linear model $f_{\mathbf{w}}(\mathbf{x}) = \mathbf{x}^T \mathbf{w}$ can be stacked as



Note: The **bias/offset term** is responsible for **translating** the line/plane/hyperplane away from the origin.



Least Squares Regression

In vector-matrix notation, the minimization of the objective function can be written compactly using $\mathbf{e} = \mathbf{X}\mathbf{w} - \mathbf{y}$:

$$J(\mathbf{w}) = \mathbf{e}^{T} \mathbf{e}$$

$$= (\mathbf{X}\mathbf{w} - \mathbf{y})^{T} (\mathbf{X}\mathbf{w} - \mathbf{y})$$

$$= (\mathbf{w}^{T} \mathbf{X}^{T} - \mathbf{y}^{T}) (\mathbf{X}\mathbf{w} - \mathbf{y})$$

$$= \mathbf{w}^{T} \mathbf{X}^{T} \mathbf{X} \mathbf{w} - \mathbf{w}^{T} \mathbf{X}^{T} \mathbf{y} - \mathbf{y}^{T} \mathbf{X} \mathbf{w} + \mathbf{y}^{T} \mathbf{y}$$

$$= \mathbf{w}^{T} \mathbf{X}^{T} \mathbf{X} \mathbf{w} - 2 \mathbf{v}^{T} \mathbf{X} \mathbf{w} + \mathbf{v}^{T} \mathbf{v}.$$

1. Both
$$\mathbf{w}^T \mathbf{X}^T \mathbf{y}$$
 and $\mathbf{y}^T \mathbf{X} \mathbf{w}$ are scalars

2. Equal when transposed

$$\Rightarrow \mathbf{w}^{\mathsf{T}}\mathbf{X}^{\mathsf{T}}\mathbf{y} = (\mathbf{w}^{\mathsf{T}}\mathbf{X}^{\mathsf{T}}\mathbf{y})^{\mathsf{T}} = = y^{\mathsf{T}}\mathbf{X}\mathbf{w}$$

Note: when $f_{\mathbf{w}}(\mathbf{X}) = \mathbf{X}\mathbf{w}$, then

$$\sum_{i=1}^{m} (f_{\mathbf{w}}(\mathbf{x}_i) - \mathbf{y}_i)^2 = (\mathbf{X}\mathbf{w} - \mathbf{y})^T (\mathbf{X}\mathbf{w} - \mathbf{y}).$$



Differentiating J(w) with respect to w and setting the

result to **0**:

$$\frac{\partial}{\partial \mathbf{w}} J(\mathbf{w}) = \mathbf{0}$$

$$\frac{\partial}{\partial \mathbf{w}} (\mathbf{w}^T \mathbf{X}^T \mathbf{X} \mathbf{w} - 2\mathbf{y}^T \mathbf{X} \mathbf{w} + \mathbf{y}^T \mathbf{y}) = \mathbf{0}$$

$$\Rightarrow 2\mathbf{X}^T \mathbf{X} \mathbf{w} - 2\mathbf{X}^T \mathbf{y} = \mathbf{0}$$

$$\Rightarrow \mathbf{X}^T \mathbf{X} \mathbf{w} = \mathbf{X}^T \mathbf{y}$$

 \Rightarrow Any minimizer $\hat{\mathbf{w}}$ of $J(\mathbf{w})$ must satisfy $\mathbf{X}^T(\mathbf{X}\mathbf{w} - \mathbf{y}) = \mathbf{0}$. If $\mathbf{X}^T\mathbf{X}$ is invertible, then

Learning/training: $\hat{\mathbf{w}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$

Prediction/testing: $\hat{f}_{\mathbf{w}}(\mathbf{X}_{new}) = \mathbf{X}_{new}\hat{\mathbf{w}}$

Linear Regression ****



Example 1 Training set [
$$(x_i, y_i)$$
]_{i=1}^{m} {x = -9} $\rightarrow \{y = -6\}$ { $x = -7$ } $\rightarrow \{y = -6\}$ { $x = -7$ } $\rightarrow \{y = -6\}$ { $x = -7$ } $\rightarrow \{y = -6\}$ { $x = -5$ } $\rightarrow \{y = -4\}$ { $x = -5$ } $\rightarrow \{y = -4\}$ { $x = -5$ } $\rightarrow \{y = -1\}$ { $x = 5$ } $\rightarrow \{y = -1\}$ { $x = 5$ } $\rightarrow \{y = 1\}$ { $x = 9$ } $\rightarrow \{y = 4\}$

This set of linear equations has no exact solution

However, $\mathbf{X}^T\mathbf{X}$ is invertible

Cleff-inverse)

$$\widehat{\mathbf{w}} = \mathbf{X}^{\dagger} \mathbf{y} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

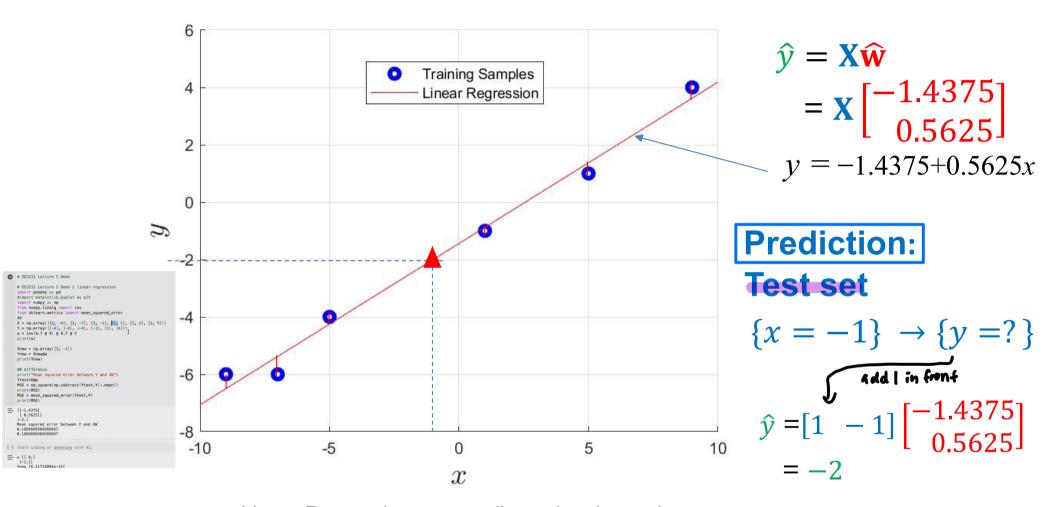
$$= \begin{bmatrix} 6 & -6 \\ -6 & 262 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 1 & 1 \\ -9 & -7 & -5 \end{bmatrix}$$

Least square approximation

$$= \mathbf{X}^{T} \mathbf{y} = (\mathbf{X}^{T} \mathbf{X})^{T} \mathbf{y}$$

$$= \begin{bmatrix} 6 & -6 \\ -6 & 262 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ -9 & -7 & -5 & 1 & 5 & 9 \end{bmatrix} \begin{bmatrix} -6 \\ -6 \\ -4 \\ -1 \\ 1 \\ 4 \end{bmatrix} = \begin{bmatrix} -1.4375 \\ 0.5625 \end{bmatrix}$$





Linear Regression on one-dimensional samples

Python demo 1



training data

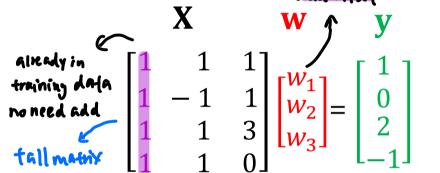
Example 2

$$\{(\mathbf{x}_i, \mathbf{y}_i)\}_{i=1}^m$$

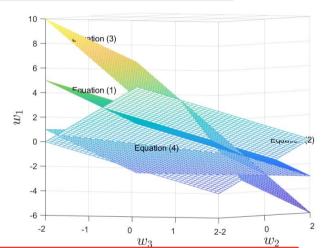
$\{x_1 = 1, x_2 = 1, x_3 = 1\} \rightarrow \{y = 1\}$

$$\{x_1 = 1, x_2 = -1, x_3 = 1\} \rightarrow \{y = 0\}$$

 $\{x_1 = 1, x_2 = 1, x_3 = 3\} \rightarrow \{y = 2\}$
 $\{x_1 = 1, x_2 = 1, x_3 = 0\} \rightarrow \{y = -1\}$



given training data first element already T, no need to add IN 3 THIS CASE



This set of linear equations has no exact solution

 \leftarrow However, $\mathbf{X}^T\mathbf{X}$ is invertible (left inverse)

a determine

$$\widehat{\mathbf{w}} = \mathbf{X}^{\dagger} \mathbf{y} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

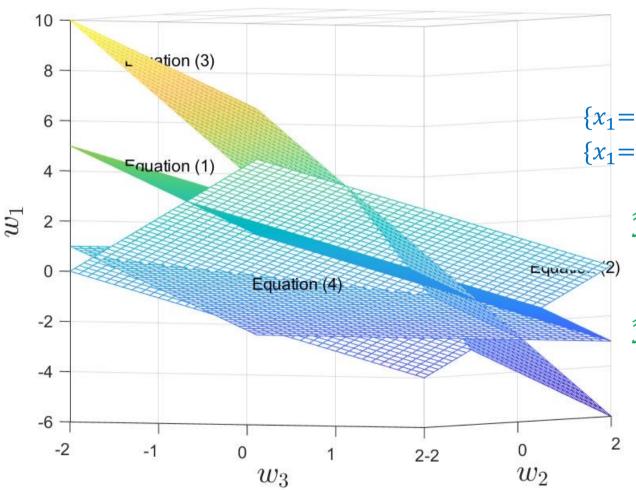
Least square approximation

$$= \begin{bmatrix} 4 & 2 & 5 \\ 2 & 4 & 3 \\ 5 & 3 & 11 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 1 \\ 1 & 1 & 3 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 2 \\ -1 \end{bmatrix} = \begin{bmatrix} -0.7500 \\ 0.1786 \\ 0.9286 \end{bmatrix}$$

4) over-determined



The four linear equations



Prediction:

Test set

$$\{x_1 = 1, x_2 = 6, x_3 = 8\} \rightarrow \{y = ?\}$$

 $\{x_1 = 1, x_2 = 0, x_3 = -1\} \rightarrow \{y = ?\}$

$$\widehat{\mathbf{y}} = \widehat{\mathbf{f}}_{\mathbf{w}}(\mathbf{X}_{new}) = \mathbf{X}_{new}\widehat{\mathbf{w}}$$

$$\widehat{\mathbf{y}} = \begin{bmatrix} 1 & 6 & 8 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} -0.7500 \\ 0.1786 \\ 0.9286 \end{bmatrix}$$
$$= \begin{bmatrix} 7.7500 \\ -1.6786 \end{bmatrix}$$



Learning of Vectored Function (Multiple Outputs)

For one sample: a linear model $\mathbf{f}_{\mathbf{w}}(\mathbf{x}) = \mathbf{x}^T \mathbf{W}$ Vector function

For m samples: $F_w(X) = XW = Y \rightarrow W$ and Y become matrix instead of vector

Sample 1
$$\cdots$$
 $=$ $\begin{bmatrix} \mathbf{X}_1^T \\ \vdots \\ \mathbf{X}_m^T \end{bmatrix} \mathbf{W} = \begin{bmatrix} 1 & \chi_{1,1} & \dots & \chi_{1,d} \\ \vdots & \ddots & \vdots \\ 1 & \chi_{m,1} & \dots & \chi_{m,d} \end{bmatrix} \begin{bmatrix} w_{0,1} & \dots & w_{0,h} \\ w_{1,1} & \dots & w_{1,h} \\ \vdots & \ddots & \vdots \\ w_{d,1} & \dots & w_{d,h} \end{bmatrix}$

Sample 1's output
$$y_{1,1}$$
 ... $y_{1,h}$ $y_{1,h}$ $y_{2,h}$ $y_$



Objective:
$$\sum_{i=1}^{m} (\mathbf{f_w}(\mathbf{x}_i) - \mathbf{y}_i)^2 = \mathbf{E}^T \mathbf{E}$$

Least Squares Regression of Multiple Outputs

In matrix notation, the sum of squared errors cost function can be written compactly using $\mathbf{E} = \mathbf{XW} - \mathbf{Y}$:

$$J(\mathbf{W}) = \operatorname{trace}(\mathbf{E}^T \mathbf{E})$$

$$= \operatorname{trace}[(\mathbf{X}\mathbf{W} - \mathbf{Y})^T (\mathbf{X}\mathbf{W} - \mathbf{Y})]$$

If $\mathbf{X}^T\mathbf{X}$ is invertible, then

Learning/training: $\widehat{\mathbf{W}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$

Prediction/testing: $\hat{\mathbf{F}}_{\mathbf{w}}(\mathbf{X}_{new}) = \mathbf{X}_{new}\hat{\mathbf{W}}$

Ref: Hastie, Tibshirani, Friedman, "The Elements of Statistical Learning", (2nd ed., 12th printing) 2017 (chp.3.2.4)



Least Squares Regression of Multiple Outputs

$$J(\mathbf{W}) = \operatorname{trace}(\mathbf{E}^T \mathbf{E})$$

$$= \operatorname{trace}(\begin{bmatrix} \mathbf{e}_1^T \\ \vdots \\ \mathbf{e}_h^T \end{bmatrix} [\mathbf{e}_1 \quad \mathbf{e}_2 \quad \dots \quad \mathbf{e}_h])$$

$$= \operatorname{trace}(\begin{bmatrix} \mathbf{e}_{1}^{T} \mathbf{e}_{1} & \mathbf{e}_{1}^{T} \mathbf{e}_{2} & \dots & \mathbf{e}_{1}^{T} \mathbf{e}_{h} \\ \mathbf{e}_{2}^{T} \mathbf{e}_{1} & \mathbf{e}_{2}^{T} \mathbf{e}_{2} & \dots & \mathbf{e}_{2}^{T} \mathbf{e}_{h} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{e}_{h}^{T} \mathbf{e}_{1} & \mathbf{e}_{h}^{T} \mathbf{e}_{2} & \dots & \mathbf{e}_{h}^{T} \mathbf{e}_{h} \end{bmatrix}) = \begin{bmatrix} \sum_{k=1}^{h} \mathbf{e}_{k}^{T} \mathbf{e}_{k} \\ \sum_{k=1}^{h} \mathbf{e}_{k}^{T} \mathbf{e}_{k} \end{bmatrix}$$

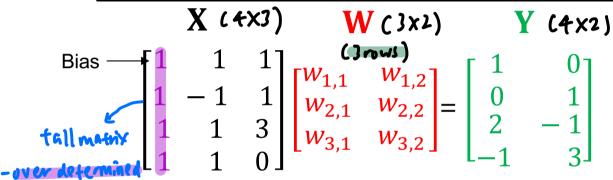
Linear Regression of multiple outputs



Example 3 (3 features)

Training set
$$\{x_1 = 1, x_2 = 1, x_3 = 1\} \rightarrow \{y_1 = 1, y_2 = 0\}$$

 $\{\mathbf{x}_i, \mathbf{y}_i\}_{i=1}^m \begin{cases} \{x_1 = 1, x_2 = -1, x_3 = 1\} \rightarrow \{y_1 = 0, y_2 = 1\} \\ \{x_1 = 1, x_2 = 1, x_3 = 3\} \rightarrow \{y_1 = 2, y_2 = -1\} \\ \{x_1 = 1, x_2 = 1, x_3 = 0\} \rightarrow \{y_1 = -1, y_2 = 3\} \end{cases}$



This set of linear equations has NO exact solution (left invers)

Least square approximation

$$\widehat{\mathbf{W}} = \mathbf{X}^{\dagger} \mathbf{Y} = (\mathbf{X}^{T} \mathbf{X})^{-1} \mathbf{X}^{T} \mathbf{Y}$$
 $\mathbf{X}^{T} \mathbf{X}$ is invertible

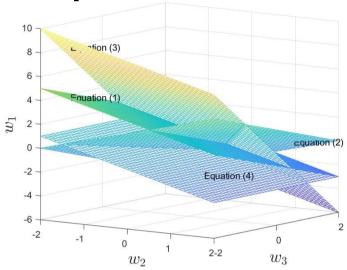
$$= \begin{bmatrix} 4 & 2 & 5 \\ 2 & 4 & 3 \\ 5 & 3 & 11 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & 1 \\ 1 & 1 & 3 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 2 & -1 \\ -1 & 3 \end{bmatrix} = \begin{bmatrix} -0.75 & 2.25 \\ 0.1786 & 0.0357 \\ 0.9286 & -1.2143 \end{bmatrix}$$

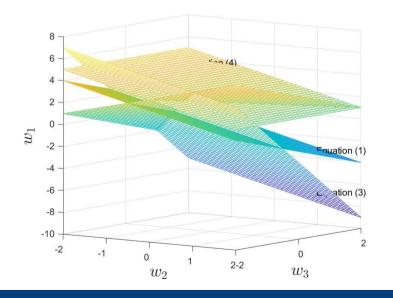
4) over-determined

Linear Regression of multiple outputs



Example 3



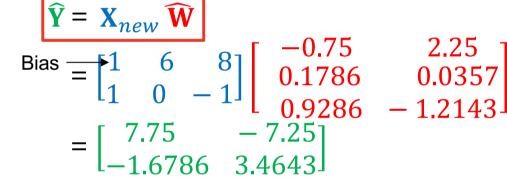


Prediction:

Test set: two new samples

$$\{x_1 = 1, x_2 = 6, x_3 = 8\} \rightarrow \{y_1 = ?, y_2 = ?\}$$

 $\{x_1 = 1, x_2 = 0, x_3 = -1\} \rightarrow \{y_1 = ?, y_2 = ?\}$





Python demo 2

Linear Regression of multiple outputs



Example 4

The values of feature x and their corresponding values of multiple outputs target **y** are shown in the table below.

Based on the least square regression, what are the values of \mathbf{w} ? Based on the current mapping, when $\mathbf{x} = 2$, what is the value of \mathbf{y} ?

X	[3]	[4]	[10]	[6]	[7]
У	[0, 5]	[1.5, 4]	[-3, 8]	[-4, 10]	[1, 6]

mport pandas as pd mport matplotlib.pyplot as plt

$$\widehat{\mathbf{W}} = \mathbf{X}^{\dagger} \mathbf{Y} = (\mathbf{X}^{T} \mathbf{X})^{-1} \mathbf{X}^{T} \mathbf{Y} = \begin{bmatrix} 1.9 & 3.6 \\ -0.4667 & 0.5 \end{bmatrix}$$

$$\widehat{\mathbf{Y}_{new}} = \mathbf{X}_{new} \ \widehat{\mathbf{W}} = \begin{bmatrix} \mathbf{1} & 2 \end{bmatrix} \ \widehat{\mathbf{W}} = \begin{bmatrix} 0.9667 & 4.6 \end{bmatrix}$$

Prediction

Summary



- Notations, Vectors, Matrices
- Operations on Vectors and Matrices
 - Dot-product, matrix inverse
- Systems of Linear Equations $f_{\mathbf{w}}(\mathbf{X}) = \mathbf{X}\mathbf{w} = \mathbf{y}$
 - Matrix-vector notation, linear dependency, invertible
 - Even-, over-, under-determined linear systems
- Functions, Derivative and Gradient
 - Inner product, linear/affine functions
 - Maximum and minimum, partial derivatives, gradient
- Least Squares, Linear Regression
 - Objective function, loss function
 - Least square solution, training/learning and testing/prediction
 - Linear regression with multiple outputs

Prediction/testing

Learning/training
$$\widehat{\mathbf{w}} = (\mathbf{X}_{train}^T \mathbf{X}_{train}^T)^{-1} \mathbf{X}_{train}^T \mathbf{y}_{train}$$

Prediction/testing $\mathbf{y}_{test} = \mathbf{X}_{test} \widehat{\mathbf{w}}$

- Classification
- Ridge Regression
- Polynomial Regression

Python packages: numpy, pandas, matplotlib.pyplot, numpy.linalg, and sklearn.metrics (for mean_squared_error), numpy.linalg.pinv