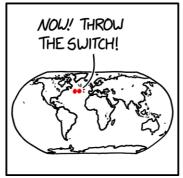
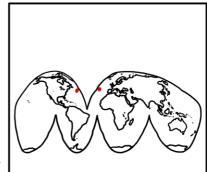
# Projection cartographique de la Pseudosphère sur le plan

Gaspar Daguet, n=° XXXXXXX



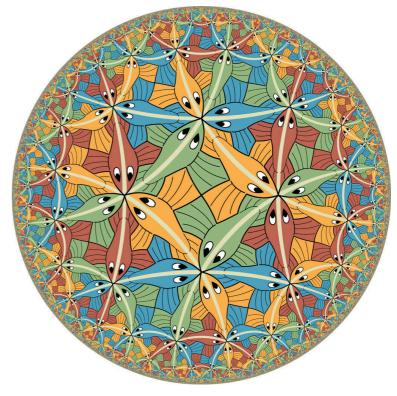






Sea Chase - Xkcd

- 1) Introduction & Problématique
- 2) La pseudosphère
- 3) La projection
- 4) projeté des droites et des cercles
- 5) non conservation des longueurs
- 6) conservation des angles



Cercle Limite III - M. C. Escher

### 1) Introduction & Problématique

#### 1) Introduction & Problématique



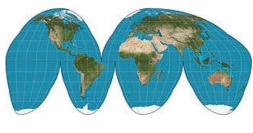
Cahill-Keyes



Rétro-azimutale de Craig



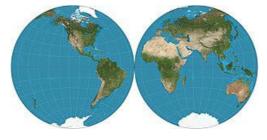
Équirectangulaire



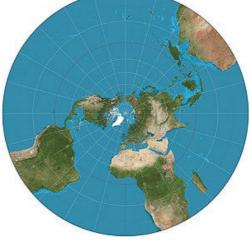
Goode



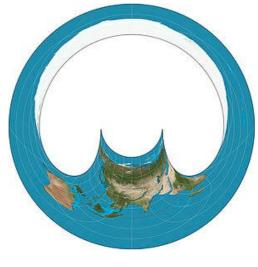
Transverse Universelle de Mercator



Globulaire de Nicolosi



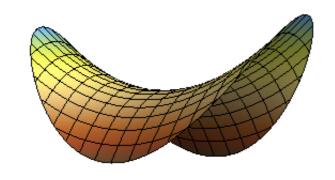
Stéréographique



Rétro-azimutale de Hammer

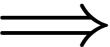
#### Problématique:

Comment projeter une surface hyperbolique sur le plan



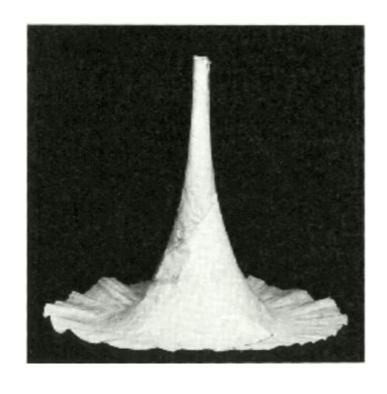
$$z = \frac{x^2}{a^2} - \frac{y^2}{b^2}, \quad \frac{x^2}{a^2} + \frac{y^2}{b^2} < 1$$

un pringle



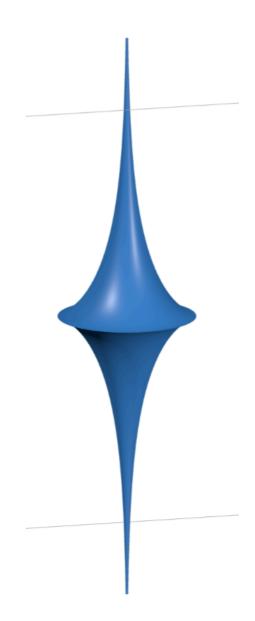


une carte



## 2) La Pseudosphère

$$P: \left\{ \begin{array}{ccc} [0;2\pi] \times \mathbb{R}_+ & \longrightarrow & \mathbb{R}^3 \\ (u,v) & \longmapsto \begin{pmatrix} \frac{\cos(u)}{\operatorname{ch}(v)} \\ \frac{\sin(u)}{\operatorname{ch}(v)} \\ v - \operatorname{th}(v) \end{pmatrix} \right.$$



#### L'application Normale :

$$N: [0; 2\pi] \times \mathbb{R}_+ \longrightarrow \mathbb{R}^3$$

$$p \longmapsto \frac{P_u(p) \wedge P_v(p)}{\|P_u(p) \wedge P_v(p)\|}$$

$$E(p) = \|P_u\|^2$$

$$F(p) =$$

$$G(p) = \|P_v\|^2$$

$$\mathcal{L}(p) = - < N_u \mid P_u >$$

$$\mathcal{M}(p) = - < N_v \mid P_u >$$

$$\mathcal{M}(p) = - < N_v \mid P_v >$$

La courbure en  $p \in [0; 2\pi] \times \mathbb{R}_+$ 

$$K(p) = \frac{\mathscr{L}(p)\mathscr{N}(p) - \mathscr{M}(p)^2}{E(p)G(p) - F^2}$$

Pour la pseudosphère :

$$F = \mathscr{M} = 0$$
  $\mathscr{L} = -\mathscr{N} = \frac{\operatorname{sh}(v)}{\operatorname{ch}(v)}$ 

$$E = \frac{1}{\operatorname{ch}(v)} \qquad G = \frac{\operatorname{sh}^{2}(v)}{\operatorname{ch}^{2}(v)}$$

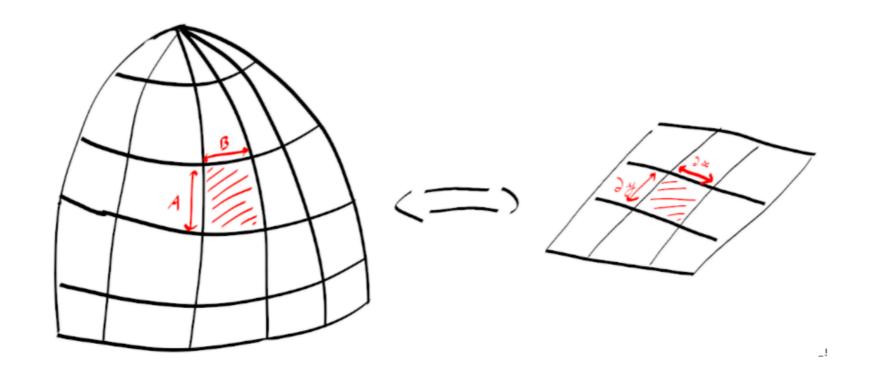
$$\forall p \in [0;2\pi] \times \mathbb{R}_+, K(p) = -1$$

Donc surface hyperbolique

## 2) La projection

### 2) La projection

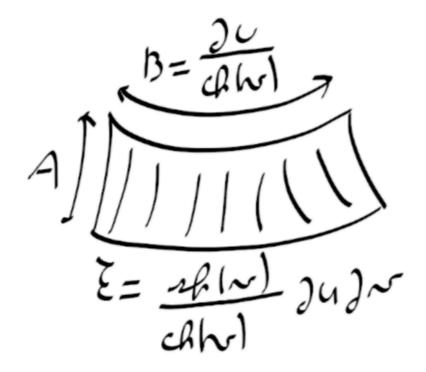
Idée de la projection de Mercator :



$$\frac{\partial y}{\partial x} = \frac{A}{B}$$

Surface élémentaire :

$$\mathcal{E} = \|f_u \wedge f_v\| \partial u \partial v$$



Pour la pseudosphère :

$$\mathcal{E} = \frac{\sinh(v)}{\cosh^2(v)} \partial u \partial v$$

Or:

$$B = \frac{\partial u}{\operatorname{ch}(v)}$$

Donc

$$B = \frac{\partial u}{\operatorname{ch}(v)} \qquad A = \frac{\mathscr{E}}{B} = \operatorname{th}(v)\partial v$$

On pose

$$\frac{\partial x}{\partial u} = 1$$

Et comme

$$\frac{\partial y}{\partial x} = \frac{\sinh(v)\partial v}{\partial u}$$

Ainsi:

$$y = \operatorname{ch}(v)$$

La projection:

$$C: \begin{cases} [0; 2\pi] \times \mathbb{R}_+ \longrightarrow \mathbb{R}^2 \\ p = (u, v) \longmapsto \begin{pmatrix} u \\ \operatorname{ch}(v) \end{pmatrix} \end{cases}$$

Plein d'image de projection!!

### 3) projeté des droites et des sphères

dèf droites et cercle
calcule par la projection
joli dessin

### 4) non conservation des longueurs

calcule de la distance sur S et sur P voir que diff

### 5) conservation des angles

faut que je travaille

