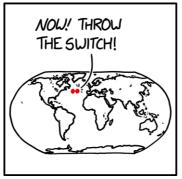
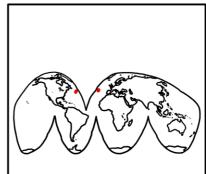
Projection cartographique de la Pseudosphère sur le plan

Gaspar Daguet, n=° 21528



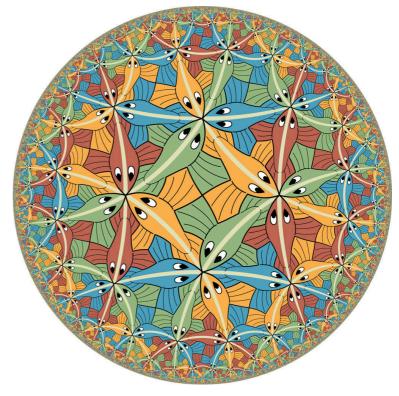






Sea Chase - Xkcd

- 1) Introduction & Problématique
- 2) La pseudosphère
- 3) La projection
- 4) Projeté des droites
- 5) Non conservation des longueurs
- 6) Conservation des angles



Cercle Limite III - M. C. Escher

1) Introduction & Problématique

1) Introduction & Problématique



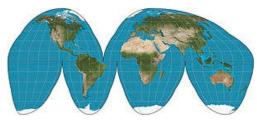
Cahill-Keyes



Rétro-azimutale de Craig



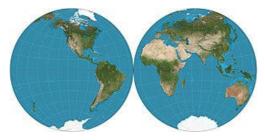
Équirectangulaire



Goode



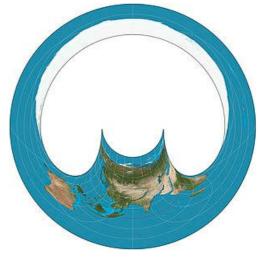
Transverse Universelle de Mercator



Globulaire de Nicolosi



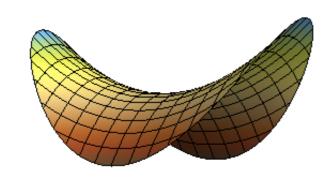
Stéréographique



Rétro-azimutale de Hammer

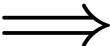
Problématique:

Comment projeter une surface hyperbolique sur le plan



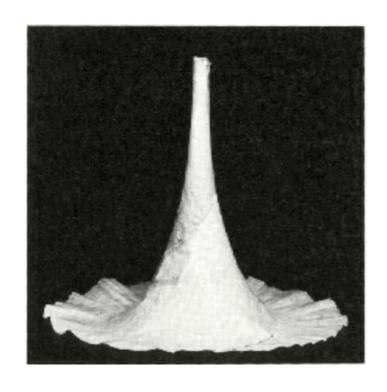
$$z = \frac{x^2}{a^2} - \frac{y^2}{b^2}, \quad \frac{x^2}{a^2} + \frac{y^2}{b^2} < 1$$

un pringle



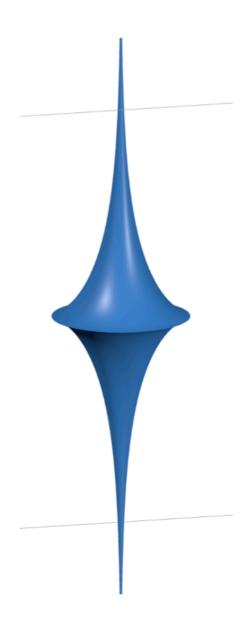


une carte



2) La Pseudosphère

$$P: \left\{ egin{array}{ll} [0;2\pi] imes \mathbb{R}_+ & \longrightarrow & \mathbb{R}^3 \ (u,v) & \longmapsto & \left(rac{\cos(u)}{\ch(v)} \ rac{\sin(u)}{\ch(v)} \ v- \th(v) \end{array}
ight) \end{array}
ight.$$



On note
$$\frac{\partial P}{\partial u} = P_u$$

L'application Normale :

$$N: [0; 2\pi] \times \mathbb{R}_+ \longrightarrow \mathbb{R}^3$$

$$p \longmapsto \frac{P_u(p) \wedge P_v(p)}{\|P_u(p) \wedge P_v(p)\|}$$

$$E(p) = \|P_u\|^2$$

$$F(p) = < P_u \mid P_v >$$

$$G(p) = \|P_v\|^2$$

$$L(p) = - < N_u \mid P_u >$$

$$M(p) = - < N_v \mid P_u >$$

$$N(p) = - < N_v \mid P_u >$$

La courbure en $p \in [0; 2\pi] \times \mathbb{R}_+$

$$K(p) = \frac{\mathrm{L}\;(p)\mathrm{N}\;(p) - \mathrm{M}\;(p)^2}{E(p)G(p) - F^2}$$

Pour la pseudosphère :

$$F = M = 0$$
 $L = -N = \frac{\operatorname{sh}(v)}{\operatorname{ch}(v)}$

$$E = \frac{1}{\operatorname{ch}(v)} \qquad G = \frac{\operatorname{sh}^{2}(v)}{\operatorname{ch}^{2}(v)}$$

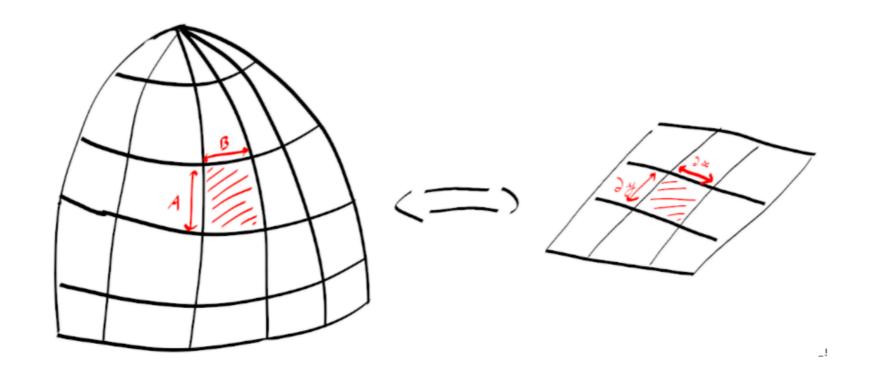
$$\forall p \in [0;2\pi] \times \mathbb{R}_+, K(p) = -1$$

Donc surface hyperbolique

3) La projection

3) La projection

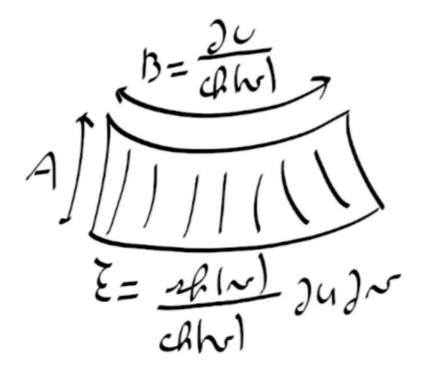
Idée de la projection de Mercator :



$$\frac{\partial y}{\partial x} = \frac{A}{B}$$

Surface élémentaire :

$$\mathbf{E} = \|P_u \wedge P_v\| \partial u \partial v$$



Pour la pseudosphère :

$$E = \frac{\sinh(v)}{\cosh^2(v)} \partial u \partial v$$

Or:

$$B = \frac{\partial u}{\operatorname{ch}(v)}$$

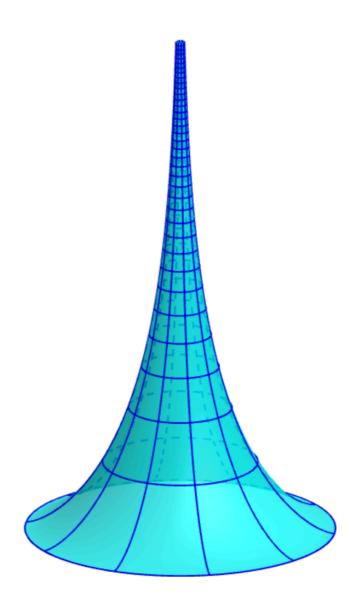
Donc

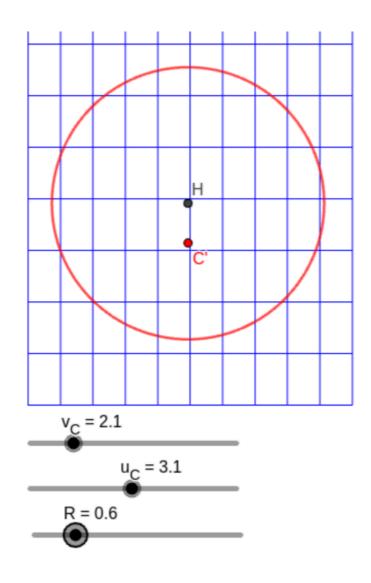
$$B = \frac{\partial u}{\operatorname{ch}(v)}$$
 $A = \frac{E}{B} = \operatorname{th}(v)\partial v$

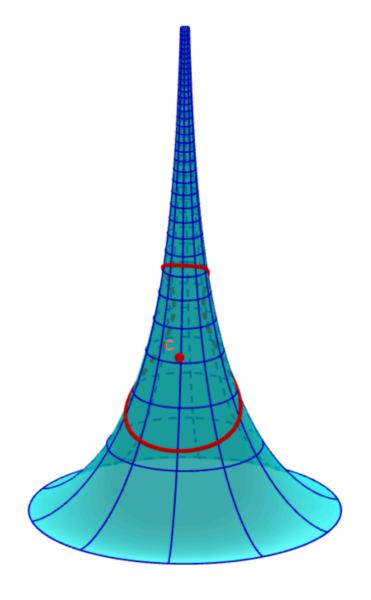
La projection:

$$C: \begin{cases} [0; 2\pi] \times \mathbb{R}_+ \longrightarrow \mathbb{R}^2 \\ p = (u, v) \longmapsto \begin{pmatrix} u \\ \operatorname{ch}(v) \end{pmatrix} \end{cases}$$









Trouver un moyen pour projter une image

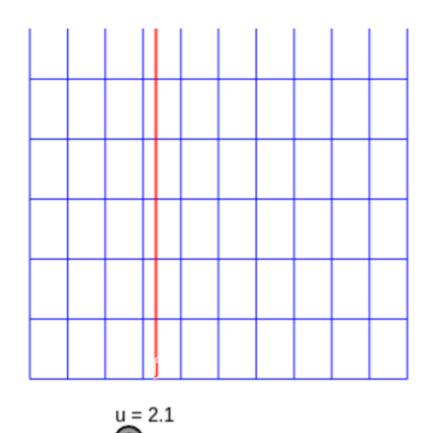
4) Projeté des droites

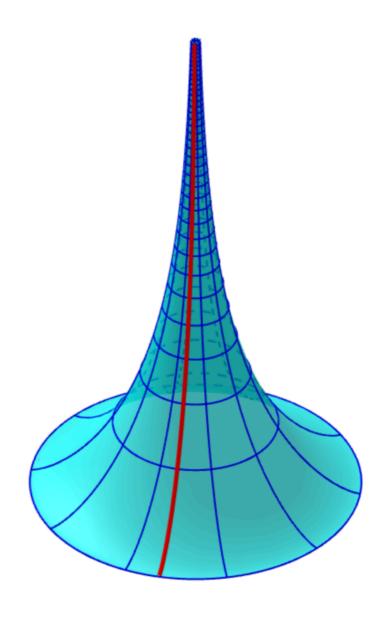
Équation des droites:

- Méridiens: $g: t \mapsto P(u, t)$
- Autres droites:

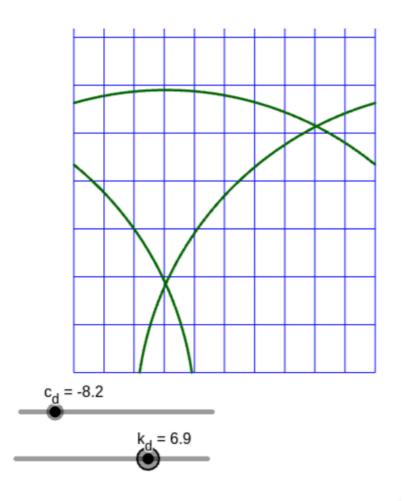
$$g:t\mapsto P\!\left(t,\operatorname{ch}\!\left(\sqrt{k^2-(t+c)^2}\right)\right)$$

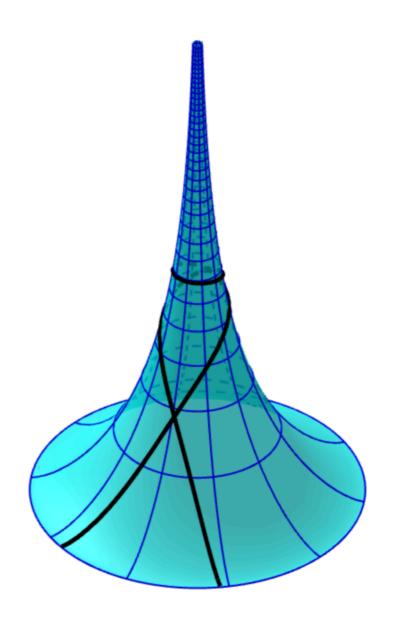
Méridiens:





Droites Quelconques:





Sur les méridiens $(v_A = v_B)$:

Sur la pseudosphère:

$$d(A,B) = \ln\left(\frac{\operatorname{ch}(u_B)}{\operatorname{ch}(u_A)}\right)$$

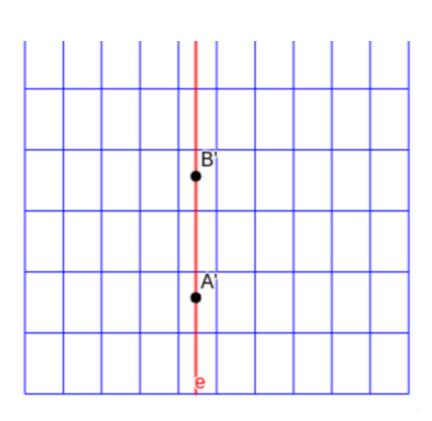
Sur la carte:

$$d(A,B) = \operatorname{ch}(u_B) - \operatorname{ch}(u_A)$$

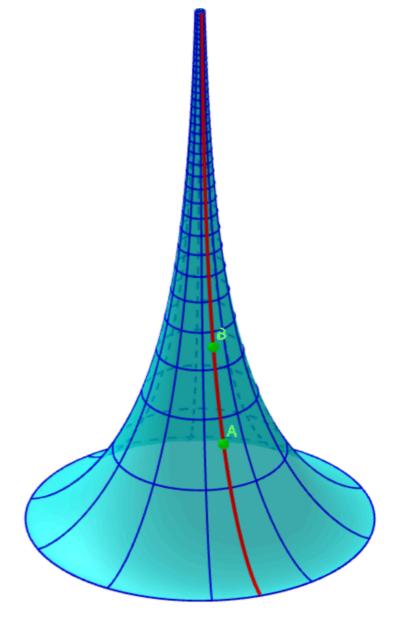
Donc la projection n'est pas équivalente



$$d(A,B) = \int_{t_A}^{t_B} \|g'(t)\| \, \mathrm{d}t$$



$$d(A,B) = 1,99$$

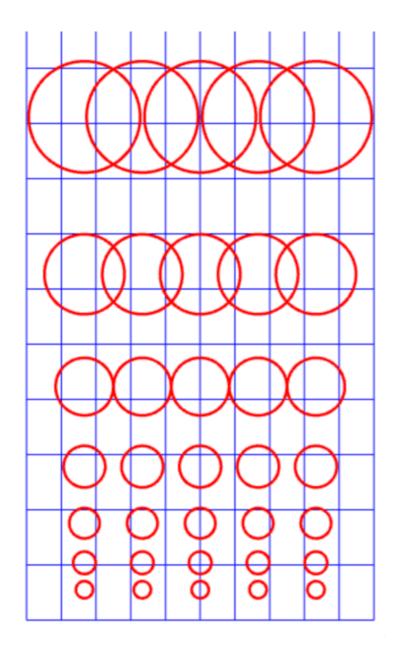


$$d(A,B) = 0,57$$

5) Conservation des angles

5) conservation des angles

faut que je travaille



Merci De votre attention

