Assignment 2: Policy Gradient

Andrew ID: Write your Andrew ID here.

Collaborators: Write the Andrew IDs of your collaborators here (if any).

NOTE: Please do **NOT** change the sizes of the answer blocks or plots.

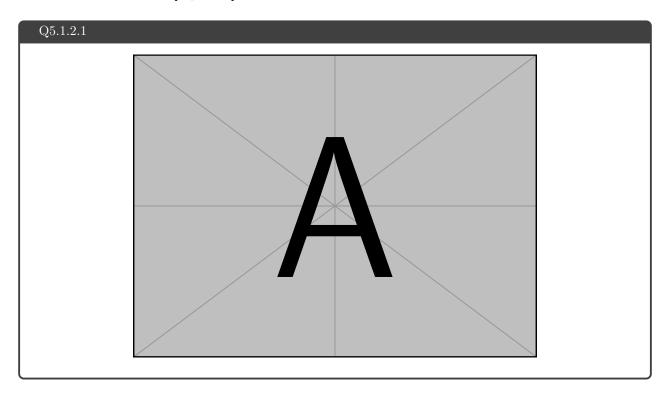
5 Small-Scale Experiments

- 5.1 Experiment 1 (Cartpole) [25 points total]
- 5.1.1 Configurations

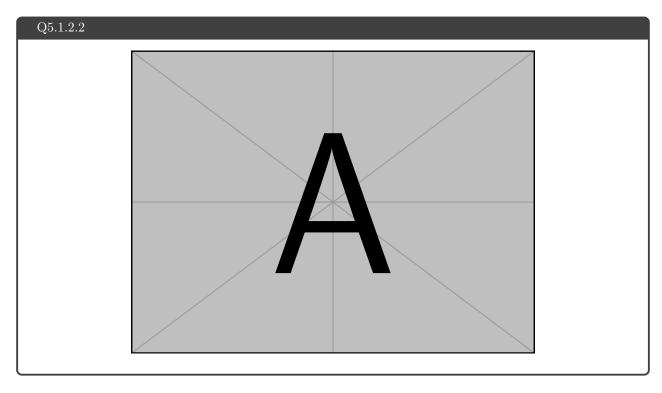


5.1.2 Plots

5.1.2.1 Small batch – [5 points]



5.1.2.2 Large batch – [5 points]



5.1.3 Analysis

5.1.3.1 Value estimator – [5 points]

Q5.1.3.1			

${\bf 5.1.3.2}\quad {\bf Advantage\ standardization}-[{\bf 5\ points}]$

Q5.1.3.2			

5.1.3.3	Batch	size –	[5	points

Q5.1.3.3	

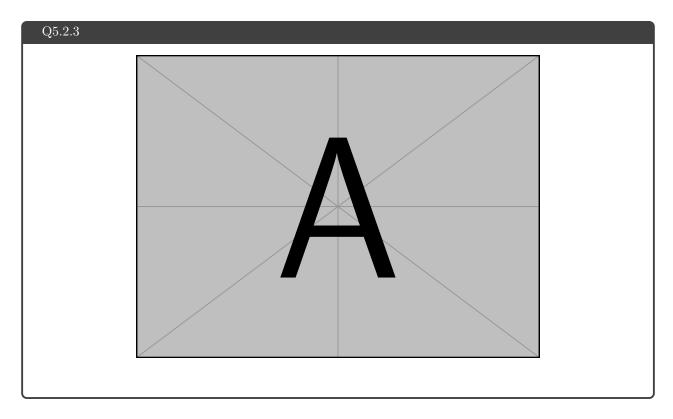
- $5.2 \quad Experiment \ 2 \ (InvertedPendulum) [15 \ points \ total]$
- 5.2.1 Configurations [5 points]



5.2.2 smallest b* and largest r* (same run) – [5 points]

Q5.2.2			

5.2.3 Plot – [5 points]

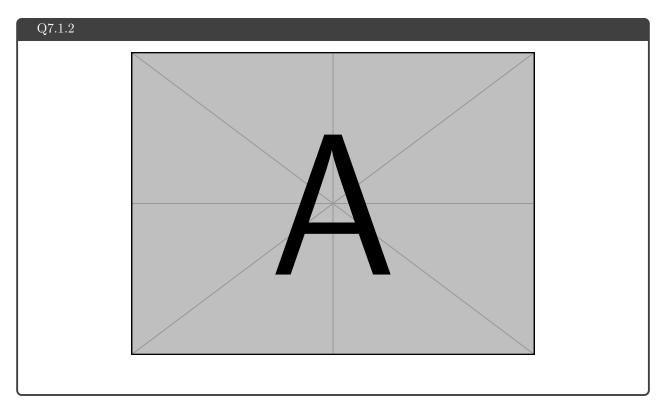


7 More Complex Experiments

- $7.1 \quad Experiment \ 3 \ (Lunar Lander) [10 \ points \ total]$
- 7.1.1 Configurations

Q7.1.1		

7.1.2 Plot – [10 points]

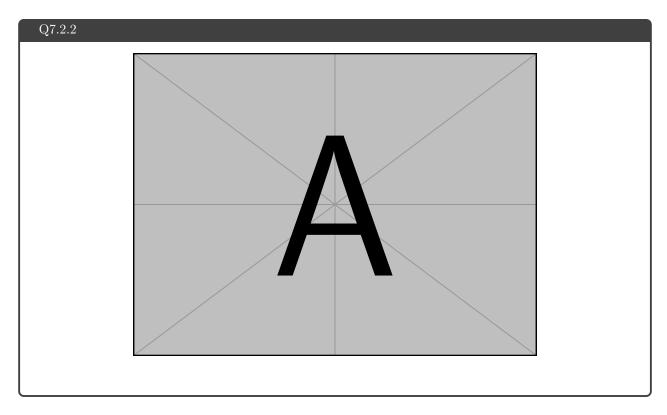


Experiment 4 (HalfCheetah) – [30 points] 7.2

7.2.1 Configurations



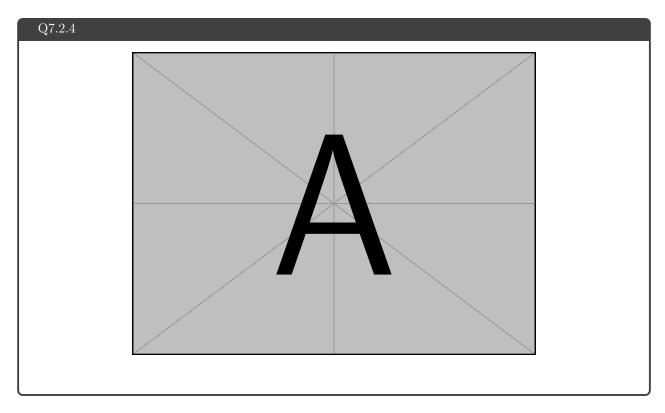
7.2.2 Plot – [10 points]



7.2.3 (Optional) Optimal b^* and $r^* - [3 points]$



7.2.4 (Optional) Plot – [10 points]

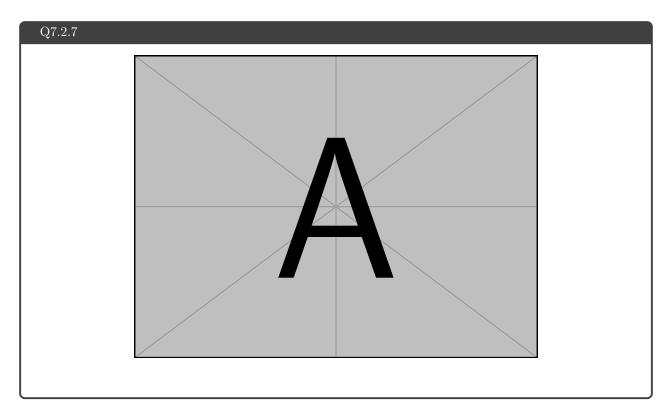


7.2.5 (Optional) Describe how b^* and r^* affect task performance – [7 points]

7.2.6 (Optional) Configurations with optimal b* and r* - [3 points]



7.2.7 (Optional) Plot for four runs with optimal b^* and $r^* - [7 points]$



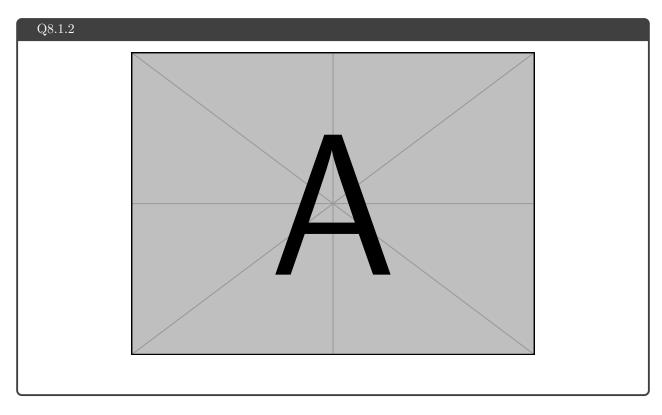
8 Implementing Generalized Advantage Estimation

8.1 Experiment 5 (Hopper) - [20 points]

8.1.1 Configurations



8.1.2 Plot – [13 points]



8.1.3 Describe how λ affects task performance – [7 points]

Q8.1.3		

9 Bonus! (optional)

9.1 Parallelization – [15 points]

Q9.1	
Difference in training time:	

9.2 Multiple gradient steps – [5 points]

