

Claude Bernard University Lyon 1

Machine Learning And Application

Deep Learning

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1. Data

The MNIST (Modified National Institute of Standards and Technology) dataset is one of the most popular datasets in the fields of machine learning and computer vision. Data includes:

- The training set contains 63,000 images.
- The test set contains 7,000 images.

```
# read data and check size

((data_train, label_train), (data_test, label_test)) = torch.load(gzip.open("mnist.pkl.gz"))

print("Size of data_train", data_train.shape)
print("Size of lable_train", label_train.shape)
print("Size of data_test", data_test.shape)
print("Size of label_test", label_test.shape)

Size of data_train torch.Size([63000, 784])
Size of data_test torch.Size([63000, 10])
Size of data_test torch.Size([7000, 784])
Size of label_test torch.Size([7000, 10])
```

Displays some images in the data set

```
# plot first few images
for i in range(9):
    # define subplot
    plt.subplot(330 + 1 + i)
    # plot raw pixel data
    plt.imshow(np.array(data_train[i], dtype='float').reshape(28, 28), cmap=plt.get_cmap('gray'))
plt.show()
10
                       10
                                               10
                        0 -
 0
10
                       10
                                               10
20
 0
                        0
10
                       10
                                               10
20
```

Prepare data

```
batch_size = 5 # number of data read each time

# initialising the data loaders
train_dataset = torch.utils.data.TensorDataset(data_train, label_train)
test_dataset = torch.utils.data.TensorDataset(data_test, label_test)
train_loader = torch.utils.data.DataLoader(train_dataset, batch_size=batch_size, shuffle=True)
test_loader = torch.utils.data.DataLoader(test_dataset, batch_size=1, shuffle=False)
```

2. Part 1: Perceptron - Indicate the size of each tensor of the provided file perceptron_pytorch.py. Explain.

In file perceptron_pytorch.py, we have the tensors:

- "data_train" is the training data, which is a tensor containing training samples from the MNIST dataset. The size of "data_train" is (number of training samples, number of features).
 - The size of tensor data_train = torch.Size([63000, 784])
- "label_train" is the corresponding label for the training data. The size of "label train" is (number of training samples, number of classes).
 - The size of tensor label_train = torch.Size([63000, 10])
- "data_test" is the testing data, containing test samples from the MNIST dataset. The size of "data_test" is (number of testing samples, number of features)
 - The size of tensor data_test = torch.Size([7000, 784])
- "Label_test" is the corresponding label for the testing data. The size of "label_test" is (number of testing samples, number of classes)
 - The size of tensor label_test = torch.Size([7000, 10])
- "w" is a tensor that contains the model's weights. The size of "w" is (the number of features, the number of classes). It is initialized with random values in the range from -0.001 to 0.001.
 - The size of tensor w = torch.Size([784, 10])
- "b" is a tensor that contains bias values of the model. The size of "b" is (1, number of classes), and it is also initialized with random values in the range from -0.001 to 0.001.
- The size of tensor b = torch.Size([1, 10])

3. Part 2: Shallow network- In this part, you will implement a MLP with only one hidden layer and a linear output layer.

The model is built as a simple feedforward neural network with: an input layer, a hidden layer, and an output layer.

```
# Define simple MLP model
class SimpleMLP(nn.Module):
    def __init__(self, input_size, hidden_size, output_size):
        super(SimpleMLP, self).__init__()
        self.fc1 = nn.Linear(input_size, hidden_size)
        self.relu = nn.ReLU()
        self.fc2 = nn.Linear(hidden_size, output_size)

def forward(self, x):
    x = self.fc1(self.relu(x))
    x = self.fc2(x)
    return x
```

I use the ReLU activation function.

Create a function to train the model

```
def train_model_SimpleMLP(learning_rate, hidden_size):
      # Define
      input_size = data_train.shape[1] # Number of input features (corresponding to MNIST image size)
      output_size = label_train.shape[1] # Size of output (corresponding to digits 0 to 9)
      # Define model simpleMLP
      model = SimpleMLP(input_size, hidden_size, output_size)
      # Define loss function and optimizer
      criterion = nn.MSELoss(reduction='sum')
      optimizer = optim.SGD(model.parameters(), lr=learning_rate)
      for epoch in range(5): # number of iteration (epoch)
          for data, target in train_loader:
             optimizer.zero_grad()
              output = model(data)
              loss = criterion(output, target)
              loss.backward()
              optimizer.step()
          # Evaluate the model on the test set
          correct = 0
          total = 0
          with torch.no_grad():
              for data, target in test_loader:
                  output = model(data)
                  _, predicted = torch.max(output, 1)
                  _, labels = torch.max(target, 1)
                  total += labels.size(0)
                  correct += (predicted == labels).sum().item()
          accuracy = 100 * correct / total
          print(f"Epoch: {epoch} - Accurary: {accuracy}")
      return accuracy
```

• Hyperparameters explained

Hidden_size: Controls the model's capacity to capture complex patterns. A larger hidden_size can lead to better performance but may result in overfitting if not tuned properly.

Learning_rate: Determines the training speed and stability. The choice of learning rate affects the convergence and optimization process. Selecting an appropriate learning rate is necessary for successful training.

So, I try different values of *learning_rate* and *hidden_size* to find the best *hidden_size* and *learning_rate*.

```
# A few values of learning_rate and hidden_size
learning_rates = [0.001, 0.01, 0.1]
hidden_sizes = [64, 128, 256]
best accuracy = 0.0
best_hidden_size = 0
best_learning_rate = 0.0
# train model to find best hyperparameters
for lr in learning_rates:
    for hs in hidden_sizes:
       print(f"Training with learning rate {lr} and hidden size {hs}")
       acc = train_model_SimpleMLP(lr, hs)
       # Check if this combination is the best so far
       if acc > best_accuracy:
           best accuracy = acc
            best_hidden_size = hs
           best_learning_rate = lr
print(f"Best Hidden Size: {best_hidden_size}, Best Learning Rate: {best_learning_rate}, Best Accuracy: {best_accuracy:.2f}%")
```

The code for the results: Best Hidden Size: 128, Best Learning Rate: 0.001, Best Accuracy: 86.38%

4. Part 3 : Deep network - Model Deeper_MLP - It is a multi-layer perceptron (MLP) model with three fully connected layers.

Define a model with 2 hidden layers like below:

```
# Define deeper model MLP
class Deeper_MLP(nn.Module):
    def __init__(self):
        super(Deeper_MLP, self).__init__()
        self.fc1 = nn.Linear(data_train.shape[1], 512)
        self.relu = nn.ReLU()
        self.fc2 = nn.Linear(512, 256)
        self.fc3 = nn.Linear(256, label_train.shape[1])
    def forward(self, x):
        x = x.view(-1, 28 * 28)
        x = self.fc1(x)
        x = self.relu(x)
        x = self.fc2(x)
        x = self.relu(x)
        x = self_fc3(x)
        return x
```

- fc1: Input layer with data_train.shape[1] input features and 512 output features.
- relu: ReLU activation function.
- fc2: Hidden layer with 512 input features and 256 output features.
- fc3: Output layer with 256 input features and label_train.shape[1] output features.
- The forward method is responsible for the forward pass of the model. It takes an input x, reshapes it to a 2D tensor, and passes it through the layers in the defined sequence, applying ReLU activation after each fully connected layer. The final output of the model is returned.

Similar to part 2, I try several learning_rate values to find the best value.

```
# Training deeper model MLP
def train_deeper_mlp(learning_rate):
    model_deeper = Deeper_MLP()
    criterion = nn.MSELoss(reduction='sum')
   optimizer = optim.SGD(model_simpleMlP.parameters(), learning_rate)
    # iteration (epoch)
    for epoch in range(5):
        for data, target in train_loader:
           optimizer.zero_grad()
           output = model_deeper(data)
            loss = criterion(output, target)
           loss.backward()
           optimizer.step()
        # Evaluate the model on the test set
        correct = 0
       with torch.no_grad():
           for data, target in test loader:
               output = model_deeper(data)
               _, predicted = torch.max(output, 1)
                _, labels = torch.max(target, 1)
                total += labels.size(0)
               correct += (predicted == labels).sum().item()
        accuracy = 100 * correct / total
        print(f"Epoch: {epoch} - Accurary: {accuracy}")
    return accuracy
```

=> Best Learning Rate: **0.01**, Best Accuracy: **98.64%**

Improve the model by finding the best value of number of hidden layers and the number of neurons in the hidden layers

Build a model to try the values of the number of hidden layers and the number of neurons in the hidden layers.

```
# Define a model with at least two hidden layers

class DeepNetwork(nn.Module):

def __init__(self, input_size, hidden_sizes, output_size):
    super(DeepNetwork, self).__init__()
    self.input_layer = nn.Linear(input_size, hidden_sizes[0])
    self.hidden_layers = nn.ModuleList(inn.Linear(hidden_sizes[i], hidden_sizes[i + 1]) for i in range(len(hidden_sizes) - 1)])

self.output_layer = nn.Linear(hidden_sizes[-1], output_size)

def forward(self, x):
    x = torch.relu(self.input_layer(x))
    for layer in self.hidden_layers:
        x = torch.relu(layer(x))
    x = self.output_layer(x)
    return x
```

Designing a function to train and evaluate a deep neural network model with a specific set of hyperparameters, including learning rate and hidden layer sizes. It performs training using the Adam optimizer and means squared error loss for a specified number of epochs. After each epoch, it evaluates the model on the test set and prints the accuracy. The purpose is to observe the model's performance under different hyperparameter configurations and assess how changes in learning rate and hidden layer sizes affect accuracy.

```
# Function to train and test a model with a specific set of parameters
 def train_and_evaluate(learning_rate, hidden_sizes):
    # Model definition
    model_deeper = DeepNetwork(input_size, hidden_sizes, output_size)
    # Loss function definition and optimization
     criterion = nn.MSELoss(reduction='sum')
     optimizer = optim.SGD(model_deeper.parameters(), lr=learning_rate)
     # iteration (epoch)
     for epoch in range(5):
        for data, target in train_loader:
            optimizer.zero_grad()
             output = model_deeper(data)
             loss = criterion(output, target)
            loss.backward()
            optimizer.step()
         # Evaluate the model on the test set
         correct = 0
         total = 0
         with torch.no_grad():
             for data, target in test_loader:
                output = model_deeper(data)
                _, predicted = torch.max(output, 1)
                 _, labels = torch.max(target, 1)
                total += labels.size(0)
                correct += (predicted == labels).sum().item()
         accuracy = 100 * correct / total
         print(f"Epoch: {epoch} - Accurary: {accuracy}")
     return accuracy
```

Try with 2 layers:

Try with 2 layers

```
# The values to try
learning_rates = [0.001, 0.01]
hidden_sizes_list = [[64, 32], [128, 64], [256, 128]]

# Generate all parameter combinations
parameter_combinations = [(lr, hs) for lr in learning_rates for hs in hidden_sizes_list]

# Set up hyperparameters
input_size = 784
output_size = 10
num_epochs = 5

# Start searching for hyperparameters
best_accuracy = 0
best_params = None

for lr, hs in parameter_combinations:
    accuracy = train_and_evaluate(lr, hs)
    print(f'Learning Rate: {lr}, Hidden Sizes: {hs}, Accuracy: {accuracy}')

if accuracy > best_accuracy
    best_accuracy = accuracy
    best_accuracy = accuracy
    best_params = (lr, hs)

print(f'Best Parameters: Learning Rate = {best_params[0]}, Hidden Sizes = {best_params[1]}, Best Accuracy = {best_accuracy}')
```

Best Parameters:

- Learning Rate = 0.01: The learning rate is a hyperparameter that determines the step size at each iteration while moving toward a minimum of the loss function. In this case, a learning rate of 0.001 was found to be the most effective during the model training process.

- *Hidden Sizes* = [256, 128]: The hidden sizes refer to the number of neurons in each hidden layer of the neural network. In this context, the model has two hidden layers with 256 neurons in the first hidden layer and 128 neurons in the second hidden layer. These values were identified as optimal for achieving the highest accuracy during training.
- Best Accuracy = 98.48571428571428%: This represents the highest accuracy achieved by the model on the test set. It indicates the percentage of correctly predicted instances out of the total instances in the test set. The mentioned accuracy of approximately 97.94% is considered the best accuracy attained by the model under the specified learning rate and hidden layer sizes.

Try with 3 layers

```
# The values to try
learning_rates = [0.001, 0.01]
hidden_sizes_list_3_layer = [[64, 32, 16], [128, 64, 32], [256, 128, 64]]

# Generate all parameter combinations|
parameter_combinations_3 = [(lr, hs) for lr in learning_rates for hs in hidden_sizes_list_3_layer]

# Start searching for hyperparameters
best_accuracy_3 = 0
best_params_3 = None

for lr, hs in parameter_combinations_3:
    accuracy = train_and_evaluate(lr, hs)
    print(f'Learning Rate: {lr}, Hidden Sizes: {hs}, Accuracy: {accuracy}')

if accuracy > best_accuracy
    best_accuracy_3 = accuracy
    best_params_3 = (lr, hs)

print(f'Best Parameters: Learning Rate = {best_params_3[0]}, Hidden Sizes = {best_params_3[1]}, Best Accuracy = {best_accuracy_3}')
```

Best Parameters:

- Learning Rate = 0.001: The learning rate is a hyperparameter that controls the step size during the optimization process. In this case, a learning rate of 0.001 was found to be the most effective for updating the model parameters while training.
- *Hidden Sizes* = [256, 128, 64]: The hidden sizes correspond to the number of neurons in each hidden layer of the neural network. The model in question has three hidden layers, with 256 neurons in the first layer, 128 neurons in the second layer, and 64 neurons in the third layer. These specific hidden layer sizes were determined as optimal for achieving high accuracy during training.

- Best Accuracy = 97.98571428571428%: This indicates the highest accuracy achieved by the model on the test set. The accuracy represents the percentage of correctly predicted instances out of the total instances in the test set. In this scenario, the model achieved an accuracy of approximately 97.99%, which is considered the best accuracy under the specified learning rate and hidden layer sizes.

Let's discuss the hyperparameters and their influence:

- Learning Rate (learning_rate): This parameter controls the step size during optimization. Too high a learning rate may cause the model to converge too quickly and potentially overshoot the minimum. Too low a learning rate may result in slow convergence or the model getting stuck in a local minimum. Common values to try are 0.1, 0.01, 0.001, etc.
- *Number of Hidden Layers (hidden_sizes)*: This parameter determines the depth of your network. Adding more layers allows the model to capture more complex relationships in the data but also increases the risk of overfitting. Start with a small number of hidden layers and gradually increase if needed.
- Number of Neurons in Hidden Layers (hidden_sizes): The number of neurons in each hidden layer influences the capacity of the model to learn complex patterns. More neurons provide the model with more capacity but also increase the risk of overfitting. You can experiment with different numbers based on the size of your dataset.

5. Part4: CNN: Implement a CNN architecture (more adapted to images).

```
# Define SimpleCNN model
class SimpleCNN(nn.Module):
   def __init__(self):
        super(SimpleCNN, self).__init__()
        self.conv1 = nn.Conv2d(1, 32, kernel_size=3, stride=1, padding=1)
        self.conv2 = nn.Conv2d(32, 64, kernel_size=3, stride=1, padding=1)
        self.pool = nn.MaxPool2d(kernel_size=2, stride=2, padding=0)
        self.fc1 = nn.Linear(64 * 7 * 7, 128)
        self.fc2 = nn.Linear(128, 64)
        self.fc3 = nn.Linear(64, 32)
        self.fc4 = nn.Linear(32, 10)
    def forward(self, x):
       x = x.view(-1, 1, 28, 28)
        x = torch.relu(self.conv1(x))
        x = self.pool(x)
       x = torch.relu(self.conv2(x))
        x = self.pool(x)
        x = x.view(-1, 64 * 7 * 7)
        x = torch.relu(self.fc1(x))
        x = torch.relu(self.fc2(x))
        x = torch.relu(self.fc3(x))
        x = self.fc4(x)
        return x
```

- The layers in the model are defined as follows:
 - **conv1**: First convolutional layer with 1 input channel, 32 output channels, a kernel size of 3x3, and padding of 1
 - **conv2**: Second convolutional layer with 32 input channels, 64 output channels, a kernel size of 3x3, and padding of 1.
 - **relu**: ReLU activation function.
 - **pool**: Max pooling layer with a kernel size of 2x2 and stride of 2.
 - **fc1**: First fully connected (linear) layer with 64 * 7 * 7 input features and 128 output features.
 - **fc2**: Second fully connected layer with 128 input features and 64 output features.
 - **fc3**: Third fully connected layer with 64 input features and 32 output features.
 - **fc4**: Fourth fully connected layer with 32 input features and 10 output features (corresponding to the number of classes).
 - => The forward method is responsible for the forward pass of the model. It takes an input x, passes it through the convolutional layers with ReLU activation and max pooling, reshapes it to a 1D tensor, and passes it through the fully connected layers. The final output of the model is returned

```
: print(model)
  SimpleCNN(
    (conv1): Conv2d(1, 32, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
     (conv2): Conv2d(32, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
     (pool): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1, ceil_mode=False)
    (fc1): Linear(in_features=3136, out_features=128, bias=True)
    (fc2): Linear(in_features=128, out_features=64, bias=True)
     (fc3): Linear(in_features=64, out_features=32, bias=True)
    (fc4): Linear(in_features=32, out_features=10, bias=True)
 # Initialize model, criterion, and optimizer
 model = SimpleCNN()
 criterion = nn.MSELoss(reduction='sum')
 optimizer = optim.Adam(model.parameters(), lr=0.001)
 # Training the model
 num_epochs = 5
 start_time = time.time()
 for epoch in range(num_epochs):
     model.train()
     for i, (inputs, labels) in enumerate(train_loader):
        optimizer.zero_grad()
         outputs = model(inputs)
         loss = criterion(outputs, labels)
         loss.backward()
        optimizer.step()
         if i % 2000 == 0:
            print(f'Epoch: {epoch + 1}/{num_epochs}, Batch: {i}, Loss: {loss.item()}')
 print(f'Training completed in {time.time() - start_time} seconds')
```

This code initializes a SimpleCNN model, defines a mean squared error loss (nn.MSELoss), and uses the Adam optimizer (optim.Adam) for training. The training loop runs for a specified number of epochs (num_epochs), and within each epoch, it iterates over batches of training data (train_loader). The primary objective is to train the CNN model to minimize the mean squared error between its predictions (outputs) and the actual labels (labels).

```
# Evaluate the model
model.eval()
correct = 0
total = 0

with torch.no_grad():
    for inputs, labels in test_loader:
        outputs = model(inputs)
        _, predicted = torch.max(outputs.data, 1)
        total += labels.size(0)
        correct += (predicted == labels).sum().item()

accuracy = correct / total
print(f'Test Accuracy: {accuracy * 100:.2f}%')
```

Test Accuracy: 99.66%

6. Part **5** : To push forward (optional)

• Try another loss function (as cross entropy) with Simple MLP (1 layer)

```
# Instantiate the model
model = SimpleMLP(data_train.shape[1], 256, label_train.shape[1])
# Loss function and optimizer
criterion = nn.CrossEntropyLoss()
optimizer = optim.SGD(model.parameters(), lr=0.001)
# Training loop
num_epochs = 5
for epoch in range(num_epochs):
    model.train()
    for inputs, labels in train_loader:
        optimizer.zero_grad()
        outputs = model(inputs)
        loss = criterion(outputs, labels)
        loss.backward()
        optimizer.step()
# Evaluation
model.eval()
correct = 0
total = 0
with torch.no_grad():
    for inputs, labels in test_loader:
       outputs = model(inputs)
        _, predicted = torch.max(outputs.data, 1)
        # If labels are one-hot encoded, convert them to class indices
        _, true_labels = torch.max(labels, 1)
        total += true_labels.size(0)
        correct += (predicted == true_labels).sum().item()
accuracy = correct / total
print(f'Test Accuracy: {accuracy * 100:.2f}%')
```

With the same set of hyperparameters (hidden_size = 128, learning_rate = 0.001), when using Cross-Entropy, the model performs better than when using MSE. (91.33%)