# Pytorch micro tuto

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# Deep learning framework

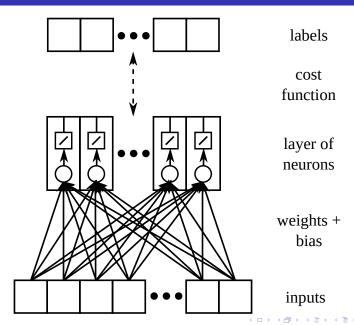
# Objectives

- automatic differentiation (on the dependence tree of variables)
- easy to develop
- code sharing

# Available

- Theano (Montreal university)
- Pytorch (Facebook)
- Tensorflow (Google)
- Keras

# Perceptron architecture



#### Hyperparameters

 $batch\_size = 5$ ,  $nb\_epochs = 10$ , eta = 0.00001,  $w\_min = -0.001$ ,  $w\_max = 0.001$ 

### Model .

```
w = torch.empty((data.shape[1],label.shape[1]))
b = torch.empty((1,label.shape[1]))
torch.nn.init.uniform_(w,w_min,w_max)
torch.nn.init.uniform_(b,w_min,w_max)
```

## Data

```
(data,label) = torch.load('mnist.pkl'))
indices = numpy.arange(data.shape[0],step=batch_size)
for n in range(nb_epochs):
    numpy.random.shuffle(indices)
    for i in indices:
        x = data[i:i+batch_size]
        t = label[i:i+batch size]
```

# Output

```
y = torch.mm(x,w)+b
```

#### Learning

```
grad = (t-y)
w += eta * torch.mm(x.T,grad)
b += eta * grad.sum(axis=0)
```



```
Hyperparameters _____
```

batch\_size = 5, nb\_epochs = 10, eta = 0.00001, w\_min = -0.001, w\_max = 0.001

## Model

```
w = torch.empty((data.shape[1],label.shape[1]))
b = torch.empty((1,label.shape[1]))
torch.nn.init.uniform_(w,w_min,w_max)
torch.nn.init.uniform_(b,w_min,w_max)
```

#### Data

```
(data,label) = torch.load('mnist.pkl'))
dataset = torch.utils.data.TensorDataset(data,label)
loader = torch.utils.data.DataLoader(dataset, batch_size, shuffle=True)
for n in range(nb_epochs):
    for x,t in train_loader:
```

## Output

```
y = torch.mm(x,w)+b
```

### Learning

```
grad = (t-y)
w += eta * torch.mm(x.T,grad)
b += eta * grad.sum(axis=0)
```

# Automatic differentiation

```
Hyperparameters
batch_size = 5, nb_epochs = 10, eta = 0.00001, w_min = -0.001, w_max = 0.001
                                  Model
w = torch.empty((data.shape[1],label.shape[1]),requires_grad=True)
b = torch.empty((1,label.shape[1]),requires_grad=True)
torch.nn.init.uniform (w.w min.w max)
torch.nn.init.uniform_(b,w_min,w_max)
                                  Data
(data.label) = torch.load('mnist.pkl'))
dataset = torch.utils.data.TensorDataset(data,label)
loader = torch.utils.data.DataLoader(dataset, batch size, shuffle=True)
for n in range(nb_epochs):
   for x,t in train_loader:
                                 Output
       y = torch.mm(x,w)+b
                                 Learning
       loss = ((t-y).pow(2)).sum()
       loss.backward()
       with torch.no_grad():
            w -= eta*w.grad
            b -= eta*b.grad
            w.grad.zero ()
```

b.grad.zero\_()

```
model = torch.nn.Linear(data_train.shape[1],label_train.shape[1])
torch.nn.init.uniform_(model.weight,w_min,w_max)
```

```
Output
```

```
y = model(x)
```

# Learning

```
loss = ((t-y).pow(2)).sum()
loss.backward()
with torch.no_grad():
    w -= eta*w.grad
    b -= eta*b.grad
    w.grad.zero_()
    b.grad.zero_()
```

```
Hyperparameters
batch_size = 5, nb_epochs = 10, eta = 0.00001, w_min = -0.001, w_max = 0.001
                                  Model
model = torch.nn.Linear(data train.shape[1].label train.shape[1])
torch.nn.init.uniform_(model.weight,w_min,w_max)
loss func = torch.nn.MSELoss(reduction='sum')
optim = torch.optim.SGD(model.parameters(), lr=eta)
                                  Data
(data,label) = torch.load('mnist.pkl'))
dataset = torch.utils.data.TensorDataset(data,label)
loader = torch.utils.data.DataLoader(dataset, batch size, shuffle=True)
for n in range(nb_epochs):
    for x.t in train loader:
                                 Output
        y = model(x)
                                 Learning
        loss = loss func(t.v)
        loss.backward()
        optim.step()
        optim.zero grad()
```

# For CNNs

## Convolution layer

torch.nn.Conv2d(in\_channels, out\_channels, kernel\_size, stride, padding, bias=True)

## Max pooling layer

torch.nn.MaxPool2d(kernel\_size, stride, padding)

# Or max pooling function

torch.nn.functional.max\_pool2d(input, kernel\_size, stride, padding)

# Modules

```
import torch
import torch.nn as nn
import torch.nn.functional as F

class MyModel(nn.Module):
```

```
def __init__(self):
    super(MyModel, self).__init__()
    self.conv1 = nn.Conv2d(1, 6, 5)
    self.conv2 = nn.Conv2d(6, 16, 5)
    self.fc1 = nn.Linear(16 * 5 * 5, 120)
    self.fc2 = nn.Linear(120, 84)
    self.fc3 = nn.Linear(84, 10)
```

```
def forward(self, x):
    x = F.max_pool2d(F.relu(self.conv1(x)), (2, 2))
    x = F.max_pool2d(F.relu(self.conv2(x)), 2)
    x = torch.flatten(x, 1)
    x = F.relu(self.fc1(x))
    x = F.relu(self.fc2(x))
    x = self.fc3(x)
    return x
```

model = MyModel()

