电子电路与系统基础Ⅱ

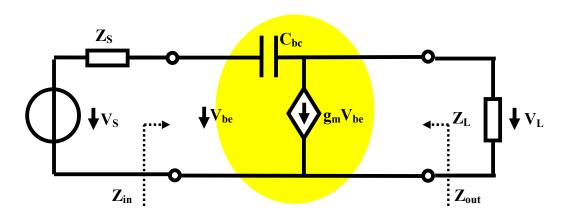
习题课第十三讲

晶体管电路回顾与拓展(下半) 负阻LC正弦波振荡器

李国林 清华大学电子工程系

作业6: 晶体管放大器不稳定的原因

• 练习10.4.10: 图E10.4.6是用来考察CE组态晶体管C_{bc}对输入阻抗和输出阻抗影响的原理性电路,其中只剩下晶体管原本设计的压控流源和跨接在压控流源输出和输入之间的寄生电容C_{bc},考察当Z_c=R_c,jωL₂两种负载情况下,输入阻抗Z_{in}的性质;考察当Z_s=R_s,jωL₁两种负载情况下,输出阻抗Z_{out}的性质。



只要是三点式连接关系,在**GS、DS、GD**端口都能看到等效负阻

方法1: 先求二端口网络的y参量,再由y参量求输入输出阻抗

方法2: 加压求流

输入

I_t † V_{be}

端

加加

流水

压

$$\dot{V_t} = \dot{I_t} \frac{1}{j\omega C_{bc}} + \left(\dot{I_t} - g_m \dot{V_t}\right) Z_L = \dot{I_t} \left(\frac{1}{j\omega C_{bc}} + Z_L\right) - g_m \dot{V_t} Z_L$$

 $I_{t\text{-}} \; g_m V_{be}$

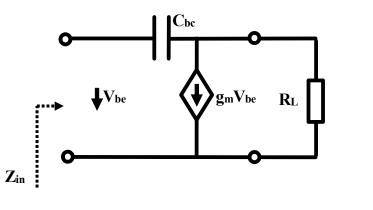
$$Z_{in} = \frac{\dot{V_t}}{\dot{I_t}} = \frac{\frac{1}{j\omega C_{bc}} + Z_L}{1 + g_m Z_L} = \frac{1}{j\omega (1 + g_m Z_L)C_{bc}} + \frac{Z_L}{1 + g_m Z_L}$$

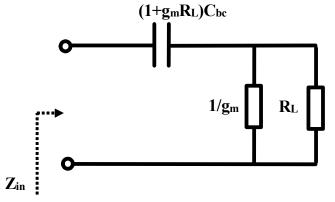
$$Z_{in}(Z_L = R_L) = \frac{1}{j\omega(1 + g_m R_L)C_{bc}} + R_L || \frac{1}{g_m}$$

$$Z_{in}(Z_L = j\omega L) = \frac{1}{j\omega C_{bc} - \omega^2 L C_{bc} g_m} + j\omega L||\frac{1}{g_m}$$

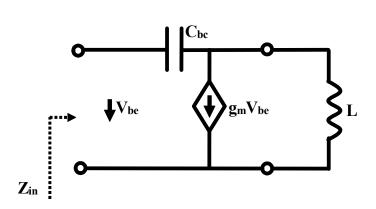
输入阻抗等效电路

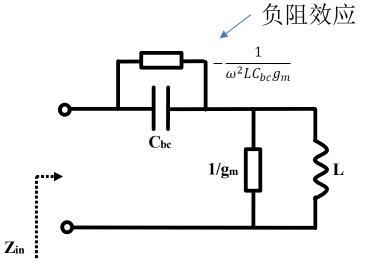
密勒效应





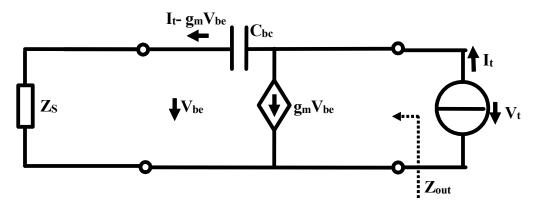
$$Z_{in}(Z_L = R_L) = \frac{1}{j\omega(1 + g_m R_L)C_{bc}} + R_L || \frac{1}{g_m}$$





$$Z_{in}(Z_L = j\omega L) = \frac{1}{j\omega C_{bc} - \omega^2 L C_{bc} g_m} + j\omega L || \frac{1}{g_m}$$





$$\dot{V_{be}} = (\dot{I_t} - g_m \dot{V_{be}}) Z_S$$

$$\dot{V_{be}} = \frac{Z_S}{1 + g_m Z_S} \dot{I_t}$$

 $Z_S \mid\mid \frac{1}{g_m}$

端

$$\dot{V_t} = \left(\dot{I_t} - g_m \dot{V_{be}}\right) \left(\frac{1}{j\omega C_{bc}} + Z_S\right) = \left(\dot{I_t} - g_m \frac{Z_S}{1 + g_m Z_S} \dot{I_t}\right) \left(\frac{1}{j\omega C_{bc}} + Z_S\right)$$

加

求

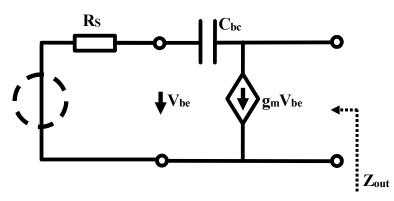
$$Z_{out} = \frac{\dot{V}_t}{\dot{I}_t} = \frac{\frac{1}{j\omega C_{bc}} + Z_S}{1 + g_m Z_S} = \frac{1}{j\omega (1 + g_m Z_S)C_{bc}} + \frac{Z_S}{1 + g_m Z_S}$$

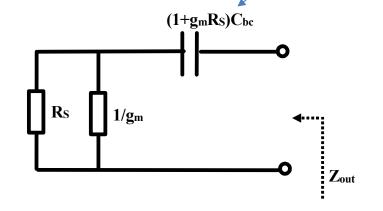
$$Z_{out}(Z_S = R_S) = \frac{1}{j\omega(1 + g_m R_S)C_{bc}} + R_S \mid \mid \frac{1}{g_m}$$

$$Z_{out}(Z_S=j\omega L)=\frac{1}{j\omega C_{bc}-\omega^2 L C_{bc}g_m}+j\omega L||\frac{1}{g_m}$$

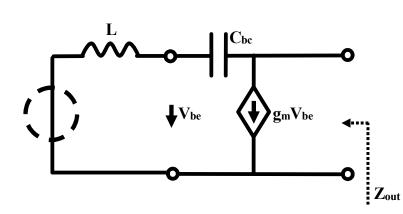
输出阻抗等效电路

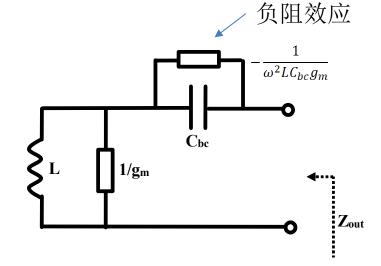
密勒效应





$$Z_{out}(Z_S = R_S) = \frac{1}{j\omega(1 + g_m R_S)C_{bc}} + R_S \mid \mid \frac{1}{g_m}$$





$$Z_{out}(Z_S = j\omega L) = \frac{1}{j\omega C_{bc} - \omega^2 L C_{bc} g_m} + j\omega L||\frac{1}{g_m}$$

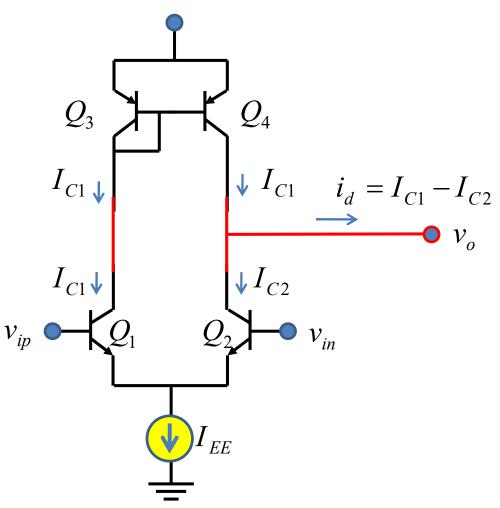
寄生电容效应

- C_{bc}是跨接在CE组态晶体管输入端和输出端的 跨接电容
 - 密勒效应: 当一个端口接电阻负载时,另一个端口看入阻抗中有一个等效大电容,从而**C**_{bc}很容易呈现高频短路效应,从而高频增益严重下降

$$C_{in} = (1 + g_m R_L)C_{bc} \qquad C_{out} = (1 + g_m R_S)C_{bc}$$

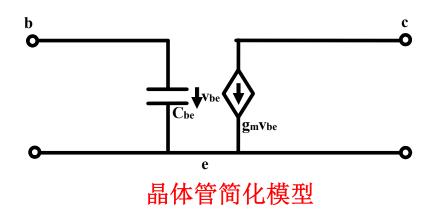
- 负阻效应: 当一个端口接电感负载时,另一个端口 看入阻抗中有一个等效负阻,当端口正阻无法抵偿 等效负阻时,放大器将自激振荡,C_{bc}是CE组态晶 体管放大器的不稳定来源
 - 哈特莱三点式结构,从任何一个端口看,都会看到等效 负阻,其中C_{bc}是寄生的,而两个电感则是用来做共轭匹 配的,从而放大器调试时出现自激振荡

作业7:寄生电容产生的零点

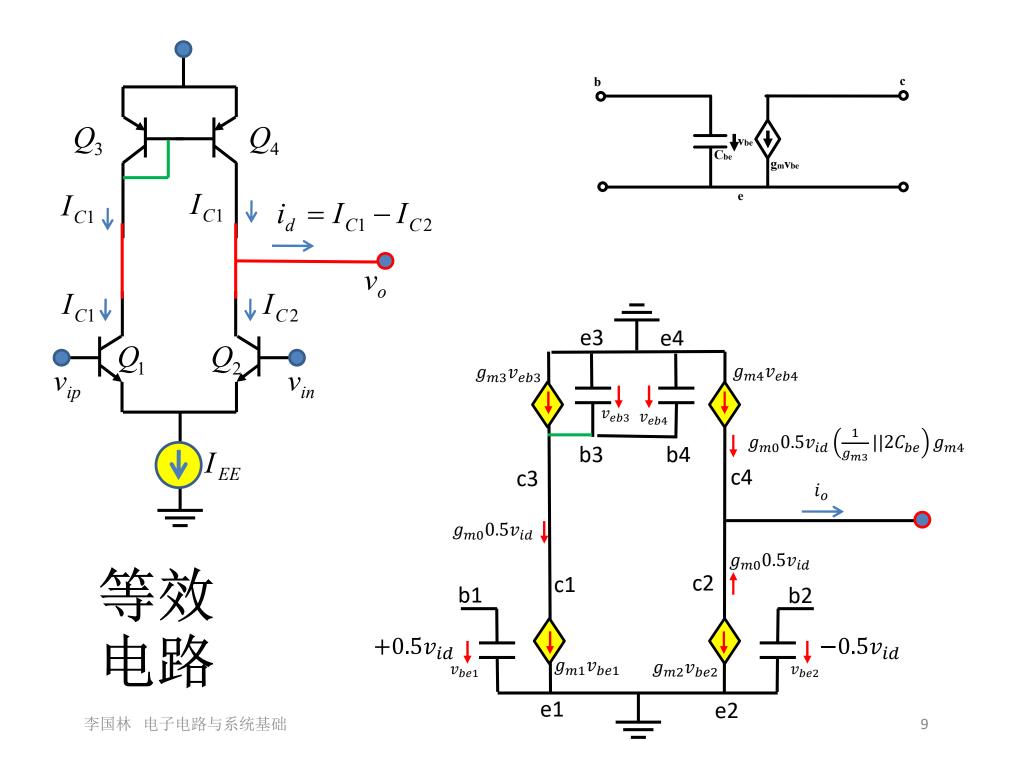


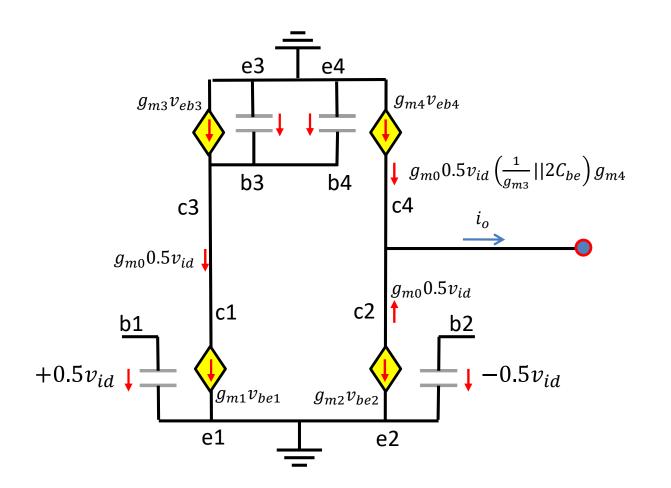
· 仅考虑寄生电容 C_{be}影响,求传 递函数表达式

$$H = \frac{i_d}{v_{id}}$$



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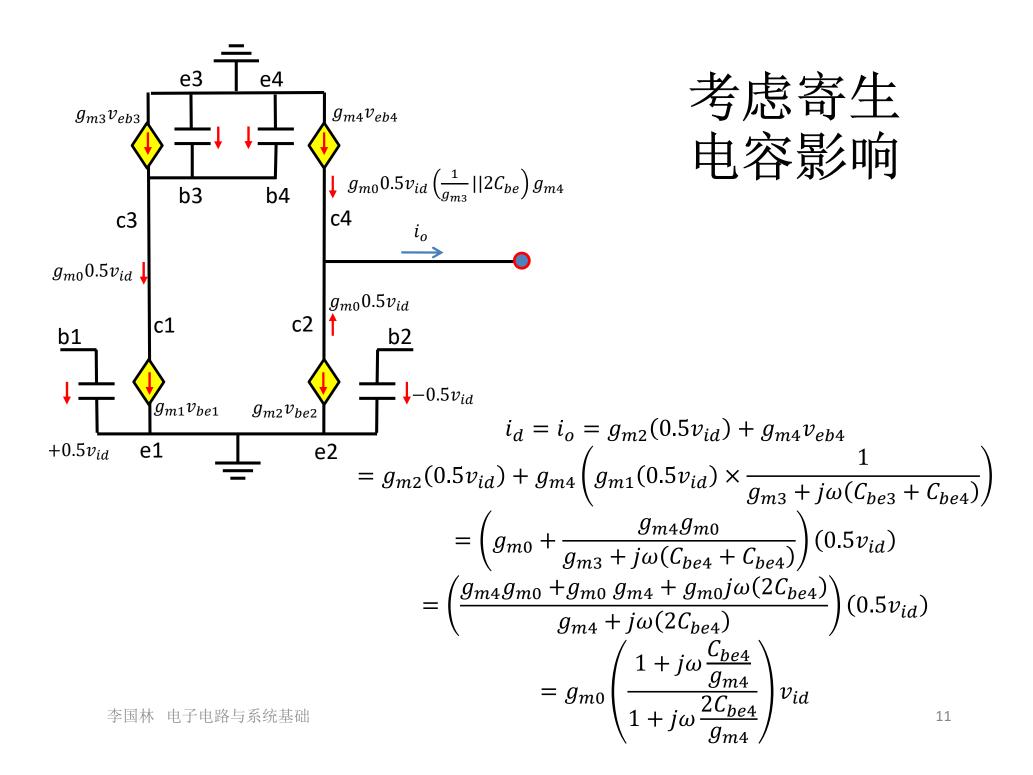
$$i_{d} = i_{o} = g_{m2}(0.5v_{id}) + g_{m4}v_{eb4}$$

$$= g_{m0}(0.5v_{id}) + g_{m4}\left(g_{m0}(0.5v_{id})\frac{1}{g_{m3}}\right)$$

$$= g_{m0}(0.5v_{id}) + g_{m0}(0.5v_{id})$$

$$= g_{m0}v_{id}$$

电阻电路分析结果 电流镜完成双端转单端功能 实现差分电流的合并



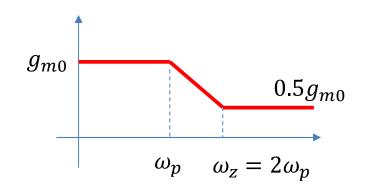
$$i_{d} = g_{m0} \left(\frac{1 + j\omega \frac{C_{be4}}{g_{m4}}}{1 + j\omega \frac{2C_{be}}{g_{m4}}} \right) v_{id} \qquad H = \frac{i_{d}}{v_{id}} = H_{0} \left(\frac{1 + \frac{j\omega}{\omega_{z}}}{1 + \frac{j\omega}{\omega_{p}}} \right)$$

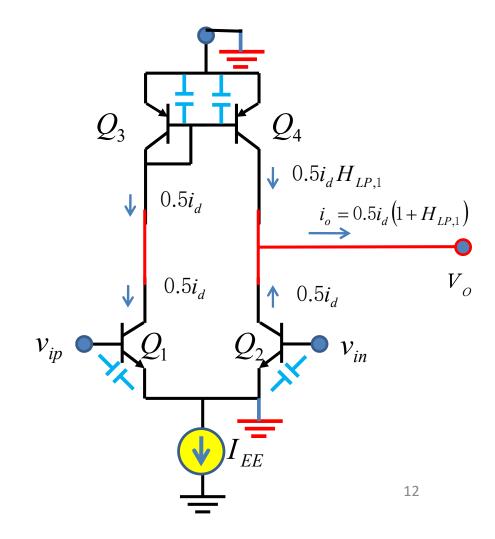
$$H = \frac{i_d}{v_{id}} = H_0 \left(\frac{1 + \frac{j\omega}{\omega_z}}{1 + \frac{j\omega}{\omega_p}} \right)$$

$$H_0 = g_{m0}$$

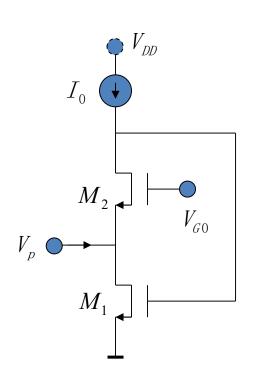
$$\omega_p = \frac{g_{m4}}{2C_{be4}}$$

$$\omega_z = \frac{g_{m4}}{C_{be4}} = 2\omega_p$$

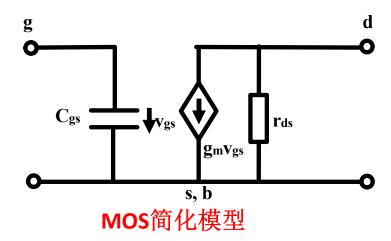




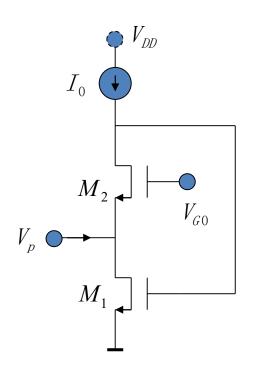
作业8:寄生电容的回旋对偶变换导致阻容电路出现谐振现象

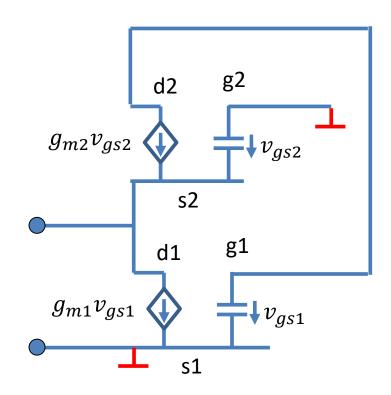


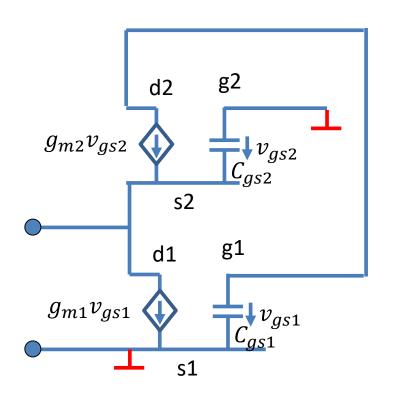
- 证明:考虑了晶体管的寄生电容效应后,从V。端口看入,其等效电路为RLC并联谐振回路
 - 给出等价RLC

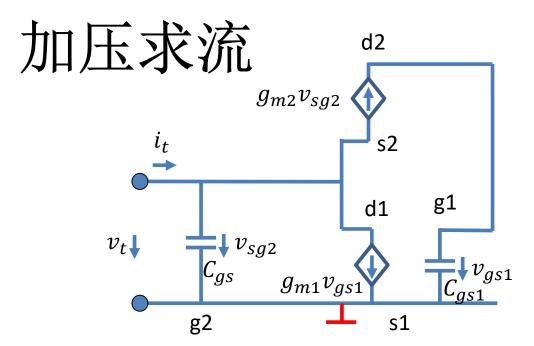


简化模型



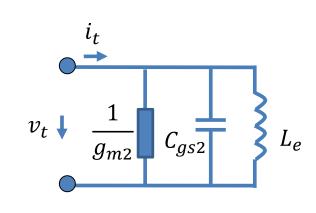




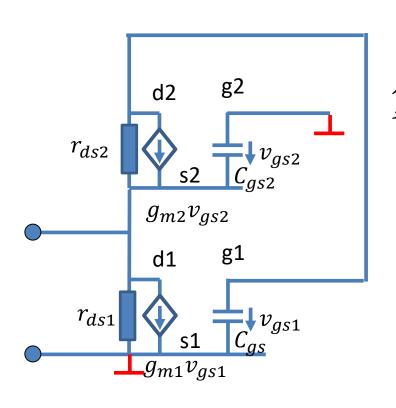


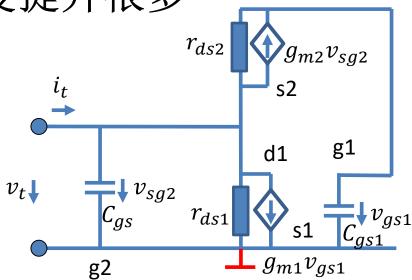
$$I_t = sC_{gs2}V_t + g_{m2}V_t + g_{m1}\left(\frac{g_{m2}V_t}{sC_{gs1}}\right)$$

$$Y_{in} = \frac{I_t}{V_t} = sC_{gs2} + g_{m2} + \frac{g_{m1}g_{m2}}{sC_{gs1}} = g_{m2} + sC_{gs2} + \frac{1}{sL_e}$$



$$L_e = \frac{C_{gs1}}{g_{m1}g_{m2}}$$
 15





d2

$$I_{t} = V_{t}(sC_{gs2} + g_{ds1}) + g_{m1}V_{gs1} + g_{m2}V_{t} + (V_{t} - V_{gs1})g_{ds2}$$

$$sC_{gs1}V_{gs1} = g_{m2}V_{t} + (V_{t} - V_{gs1})g_{ds2} \quad V_{gs1} = V_{t}\frac{g_{m2} + g_{ds2}}{sC_{gs1} + g_{ds2}}$$

$$Y_{in} = \frac{I_t}{V_t} = g_{m2} + g_{ds1} + g_{ds} + sC_{gs2} + \frac{(g_{m1} - g_{ds2})(g_{m2} + g_{ds2})}{sC_{gs1} + g_{ds2}} \qquad L_e = \frac{C_{gs1}}{(g_{m1} - g_{ds2})(g_{m2} + g_{ds2})} = g_{m2} + g_{ds1} + g_{ds2} + sC_{gs2} + \frac{1}{sL_e + r_{se}} \qquad r_{se} = \frac{g_{ds2}}{(g_{m1} - g_{ds2})(g_{m2} + g_{ds2})}$$

$$L_e = \frac{C_{gs1}}{(g_{m1} - g_{ds2})(g_{m2} + g_{ds2})}$$

$$r_{se} = \frac{g_{ds2}}{(g_{m1} - g_{ds2})(g_{m2} + g_{ds2})}$$

第12讲 负阻正弦振荡原理

作业1: 求振荡幅度和振荡频率

 $\overline{g}_n = \frac{0.01}{V_m}$ 电压单位: \mathbf{v} 跨导单位: \mathbf{s} $-\overline{g}_n$

• 已知电感为 $0.1\mu H$,电容为200pF,电感无载Q 值为 $Q_0=100$

$$Q_0 = \frac{Y_0}{G_{p0}} = \frac{1}{G_{p0}\omega_0 L}$$

• 负载电阻为 $1k\Omega$

$$G_{p0} = \frac{1}{Q_0 \omega_0 L}$$

• 求输出正弦振荡信号的频率和幅度

$$\sum B(\omega_{osc}) = 0$$
 虚部(频率)平衡条件
决定振荡频率

$$\omega_{osc}C - \frac{1}{\omega_{osc}L} = 0$$

$$f_{osc} = f_0 = \frac{1}{2\pi\sqrt{LC}}$$

$$= \frac{1}{2\times3.14\times\sqrt{0.1\times10^{-6}\times200\times10^{-12}}}$$

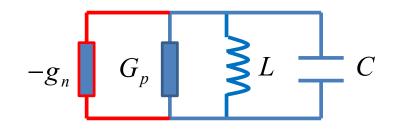
$$= 35.6MHz$$

$$G_p = G_L + G_{p,L} = \frac{1}{R_L} + \frac{1}{Q_0 \omega_0 L}$$

$$= \frac{1}{1000} + \frac{1}{100 \times 2 \times 3.14 \times 35.6 \times 10^6 \times 0.1 \times 10^{-6}}$$

$$= \frac{1}{1000} + \frac{1}{2236} = 1.45 mS$$

并联型负阻振荡器



$$\sum Y = 0$$

$$\sum G + j \sum B = 0$$
 实部条件 虚部条件

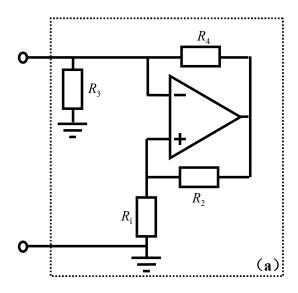
$$\overline{g_n} = G_p$$
 实部(幅度)平衡条件
决定振荡幅度

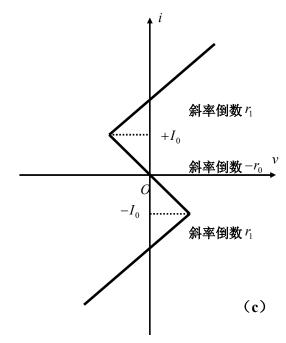
$$\overline{g_n}(V_{m\infty}) = \frac{0.01}{V_{m\infty}} = G_p = 1.45mS$$

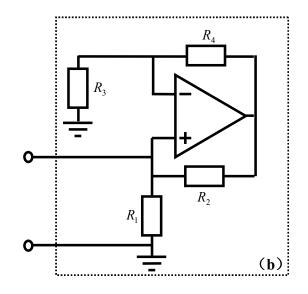
$$V_{m\infty} = \frac{0.01}{1.45 \times 10^{-3}} = 6.91V$$

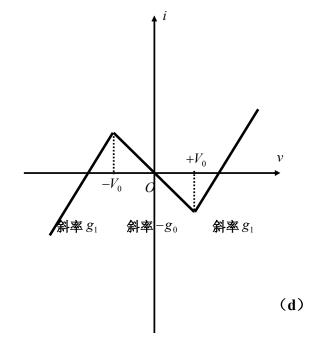
作业2 等效负阻

图**E10.4.1a**可用 来实现**S**型负阻, 图E10.4.1b可用 理想运放, 负饱和电压为 $\pm V_{sat}$ °



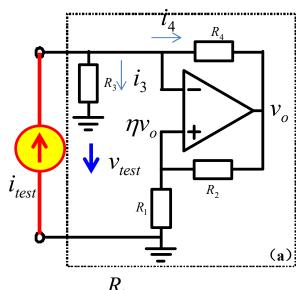


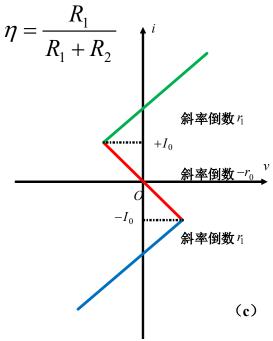




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$$i_{test} = i_3 + i_4 = \frac{v_{test}}{R_3} + \frac{v_{test} - v_o}{R_4}$$

$$j_{test} = G$$

$$v_{o}$$
 $v_{test} = \frac{i_{test}}{G_3 + G_4} + \frac{G_4}{G_3 + G_4} v_{o}$

情形1: 运放工作在正饱和区: $v_o = +V_{sat}$

$$v_{test} = \frac{i_{test}}{G_3 + G_4} + \frac{G_4}{G_3 + G_4} V_{sat} \qquad v_p > v_n \Rightarrow v_{test} < \eta V_{sat}$$

$$i_{test} < (\eta (G_3 + G_4) - G_4) V_{sat} = -I_0$$

$$v_o = +v_{sat}$$

$$<(n(G_2+G_4)-G_4)V_{xxx}=-I_0$$

情形3: 运放工作在负饱和区: $v_o = -V_{sat}$

$$v_{test} = \frac{i_{test}}{G_3 + G_4} - \frac{G_4}{G_3 + G_4} V_{sat} \qquad v_p < v_n \Rightarrow v_{test} > -\eta V_{sat}$$

$$i_{test} > (G_4 - \eta (G_3 + G_4)) V_{sat} = I_0$$

$$v_p < v_n \Rightarrow v_{test} > -\eta V_{sat}$$

$$i_{test} > (G_4 - \eta(G_3 + G_4))V_{sat} = I_0$$

情形2: 运放工作在线性区 $-V_{sat} < v_o < +V_{sat}$

$$v_{test} = \frac{i_{test}}{G_3 + G_4} + \frac{G_4}{G_3 + G_4} v_o \qquad v_p = v_n \Rightarrow v_{test} = \eta v_o$$

$$i_{test}$$

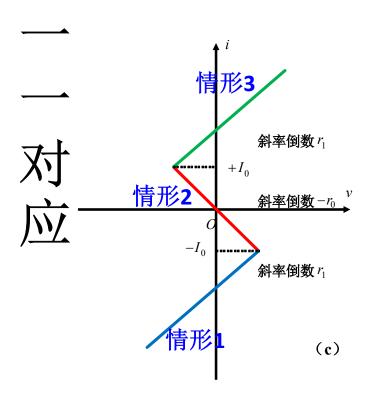
$$= \frac{i_{test}}{G_3 + G_4} + \frac{G_4}{G_3 + G_4} \frac{v_{test}}{\eta}$$

$$-V_{sat} < v_o < +V_{sat}$$

$$v_p = v_n \Rightarrow v_{test} = \eta v_o$$

$$= \frac{i_{test}}{G_3 + G_4} + \frac{G_4}{G_3 + G_4} \frac{v_{test}}{\eta} -I_0 < i_{test} < I_0$$

$$v_{test} = \frac{i_{test}}{G_3 + G_4 - \frac{G_4}{\eta}}$$



$$r_1 = \frac{1}{G_3 + G_4}$$

$$-r_0 = \frac{1}{G_3 + G_4 - \frac{G_4}{\eta}}$$

$$I_0 = (G_4 - \eta(G_3 + G_4))V_{sat}$$

情形1: 运放工作在正饱和区:

$$v_{test} = \frac{i_{test}}{G_3 + G_4} + \frac{G_4}{G_3 + G_4} V_{sat}$$

$$i_{test} < -I_0$$

$$I_0 = (G_4 - \eta(G_3 + G_4))V_{sat}$$

情形2: 运放工作在线性区

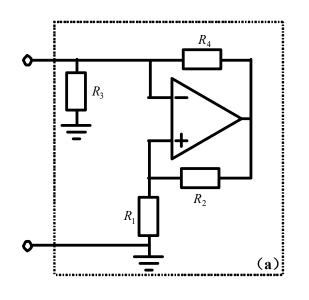
$$v_{test} = \frac{i_{test}}{G_3 + G_4 - \frac{G_4}{\eta}}$$

$$-I_0 < i_{test} < +I_0$$

情形3: 运放工作在负饱和区:

$$v_{test} = \frac{i_{test}}{G_3 + G_4} - \frac{G_4}{G_3 + G_4} V_{sat}$$

$$i_{test} > +I_0$$



$$r_1 = \frac{1}{G_3 + G_4}$$

$$-r_0 = \frac{1}{G_3 + G_4 - \frac{G_4}{\eta}}$$

$$I_0 = (G_4 - \eta(G_3 + G_4))V_{sat}$$

斜率倒数
$$r_1$$

+ I_0
斜率倒数 $-r_0$
斜率倒数 r_1

$$\eta = \frac{I_0 r_0}{V_{sat}} = \frac{R_1}{R_1 + R_2}$$

$$G_4 = \eta \left(\frac{1}{r_1} + \frac{1}{r_0}\right) = \frac{I_0}{V_{sat}} \left(\frac{r_0}{r_1} + 1\right)$$

$$G_3 = \frac{1}{r_1} - G_4 = \frac{1}{r_1} - \frac{I_0}{V_{sat}} \left(\frac{r_0}{r_1} + 1 \right) \qquad \qquad \mathbf{\overline{gx}}$$

$$G_3 > 0 \Rightarrow V_{sat} > I_0 \left(r_1 + r_0 \right)$$

电路设计

$$G_3 + G_4 = \frac{1}{r_1}$$

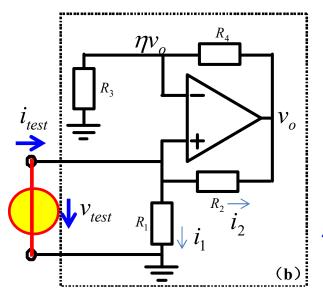
$$\frac{G_4}{\eta} = \frac{1}{r_1} + \frac{1}{r_0}$$

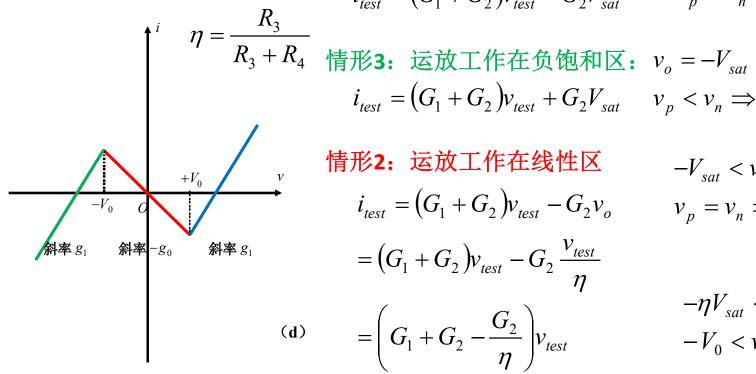
$$I_0 = \eta \frac{V_{sat}}{r_0}$$

$$\eta < 1 \Longrightarrow V_{sat} > r_0 I_0$$

出的

不是所有负阻均可实现,对运放有要求:饱和电压,输出电流 李国林 电子电路与系统基础





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$$i_{test} = i_1 + i_2 = \frac{v_{test}}{R_1} + \frac{v_{test} - v_o}{R_2}$$
 $i_{test} = (G_1 + G_2)v_{test} - G_2v_o$

$$i_{test} = (G_1 + G_2)v_{test} - G_2V_{sa}$$

$$v_o = +V_{sat}$$
 $i_{test} = (G_1 + G_2)v_{test} - G_2V_{sat}$ $v_p > v_n \Rightarrow v_{test} > \eta V_{sat} = V_0$

$$i_{test} = (G_1 + G_2)v_{test} + G_2V_{sat}$$

形3: 运风工作任页饱和区:
$$v_o = -V_{sat}$$

$$i_{test} = (G_1 + G_2)v_{test} + G_2V_{sat} \quad v_p < v_n \Rightarrow v_{test} < -\eta V_{sat} = -V_0$$

情形2: 运放工作在线性区

$$i_{test} = (G_1 + G_2)v_{test} - G_2v_o \qquad v_p = v_n \Rightarrow v_{test} = \eta v_o$$

$$= (G_1 + G_2)v_{test} - G_2\frac{v_{test}}{\eta}$$

$$= (G_1 + G_2 - \frac{G_2}{\eta})v_{test} \qquad -\eta V_{sat} < v_{test} < \eta V_{sat}$$

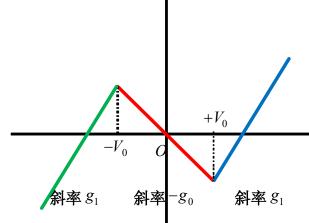
$$-V_0 < v_{test} < +V_0$$

$$-V_{sat} < v_o < +V_{sat}$$
$$v_p = v_n \Rightarrow v_{test} = \eta v_o$$

$$-\eta V_{sat} < v_{test} < \eta V_{sat}$$
$$-V_0 < v_{test} < +V_0$$

i

对



情形1: 运放工作在正饱和区:

$$i_{test} = (G_1 + G_2)v_{test} - G_2V_{sat}$$

$$v_{test} > \eta V_{sat}$$

情形2: 运放工作在线性区

$$i_{test} = \left(G_1 + G_2 - \frac{G_2}{\eta}\right) v_{test}$$

$$-\eta V_{sat} < v_{test} < \eta V_{sat}$$

$g_1 = G_1 + G_2$

$$-g_0 = G_1 + G_2 - \frac{G_2}{\eta}$$

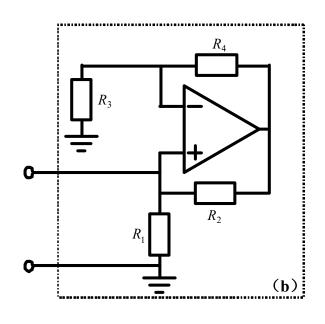
$$\eta V_{sat} = V_0$$

情形3: 运放工作在负饱和区:

$$i_{test} = (G_1 + G_2)v_{test} + G_2V_{sat}$$

$$v_{test} < -\eta V_{sat}$$

(d)



 $斜率g_1$

$$g_1 = G_1 + G_2$$

电路设计

$$-g_0 = G_1 + G_2 - \frac{G_2}{\eta}$$

$$\eta V_{sat} = V_0$$

❸确定R₃R₄电阻

$$\eta = \frac{V_0}{V_{sat}} = \frac{R_3}{R_3 + R_4}$$

$$G_2 = \eta (g_0 + g_1)$$

❹确定R₂R₁电阻

$$G_1 = g_1 - G_2$$

= $g_1 - \eta (g_0 + g_1)$

$$\eta = \frac{V_0}{V_{sat}} < 1 \Longrightarrow V_{sat} > V_0$$

❷确定分压系数 对运放提出的要求

$$G_1 > 0 \Rightarrow V_{sat} > \left(\frac{g_0}{g_1} + 1\right)V_0$$

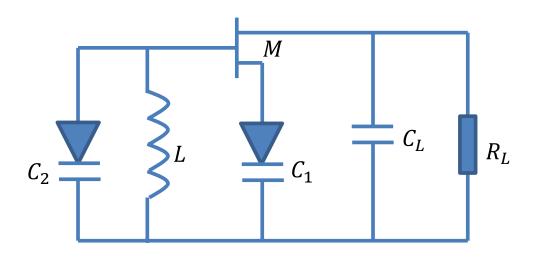
5验证运放输出电流在工作范围内满足要求(可提供如此大电流)

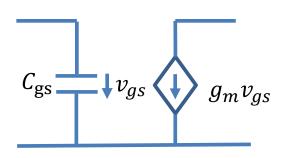
(d)

❶选运放

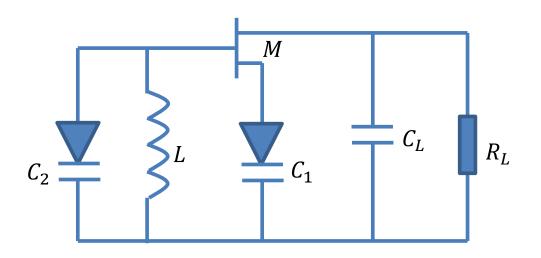
作业3等效负阻

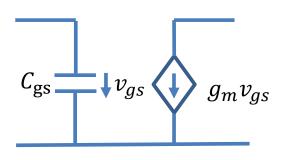
• 图示为微波频段的变容管调谐的正弦波振荡器,请用负阻振荡原理说明它是振荡器



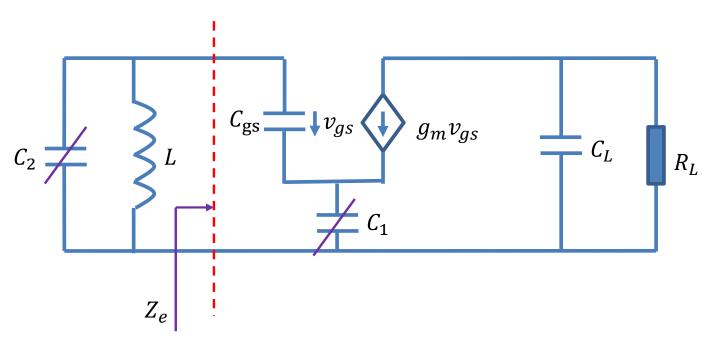


GaAs MESFET简化分析模型

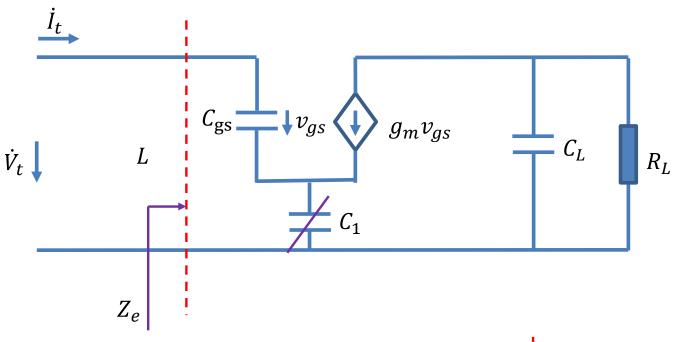




GaAs MESFET简化分析模型

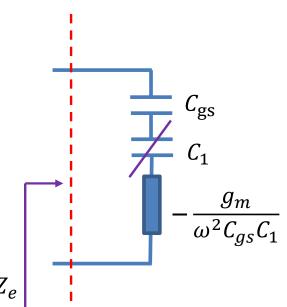


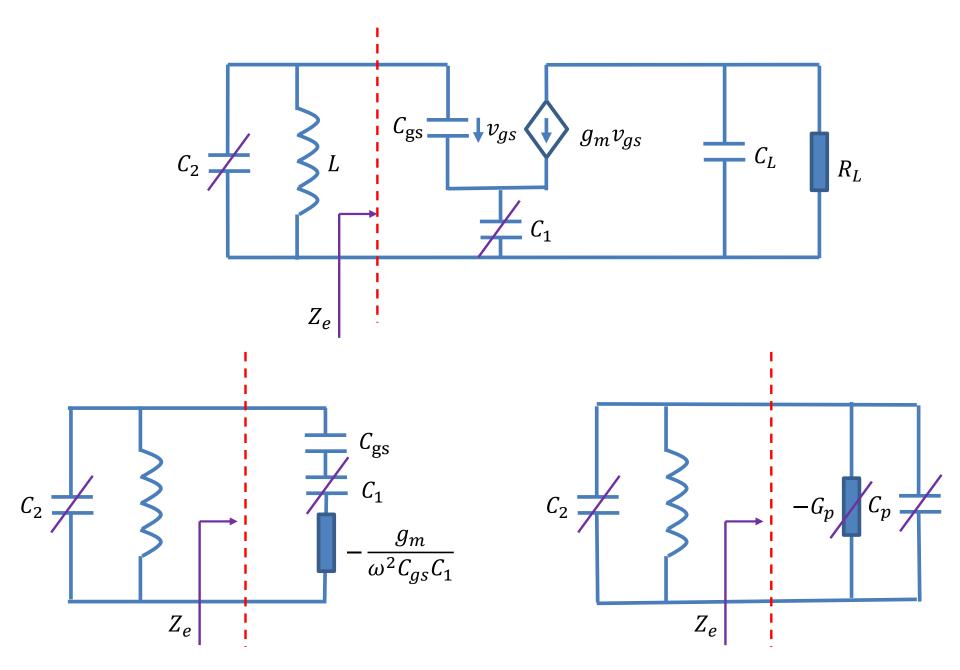
基本思路: 首先找到谐振腔,证明谐振腔外并联负导或谐振腔内串联负阻



$$\dot{V}_t = \dot{I}_t \frac{1}{j\omega C_{gs}} + \left(\dot{I}_t + g_m \dot{I}_t \frac{1}{j\omega C_{gs}}\right) \frac{1}{j\omega C_1}$$

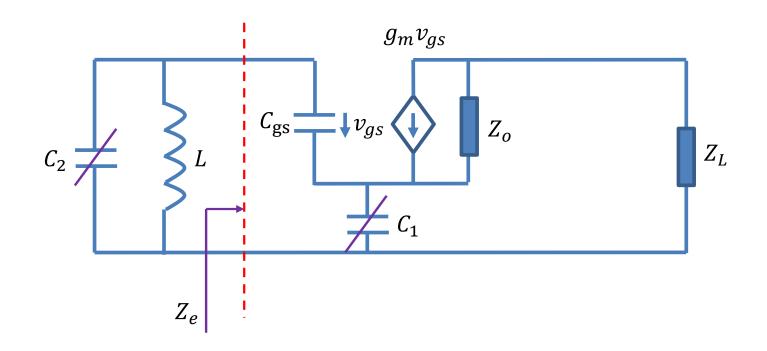
$$\begin{split} Z_e &= \frac{\dot{V}_t}{\dot{I}_t} = \frac{1}{j\omega C_{gs}} + \left(1 + g_m \frac{1}{j\omega C_{gs}}\right) \frac{1}{j\omega C_1} \\ &= \frac{1}{j\omega C_{gs}} + \frac{1}{j\omega C_1} + g_m \frac{1}{j\omega C_{gs}} \frac{1}{j\omega C_1} \\ &= \frac{1}{j\omega C_{gs}} + \frac{1}{j\omega C_1} - \frac{g_m}{\omega^2 C_{gs} C_1} \end{split}$$





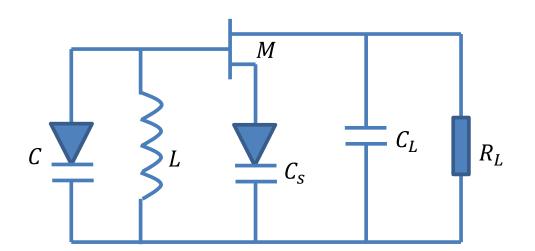
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三点式的变种



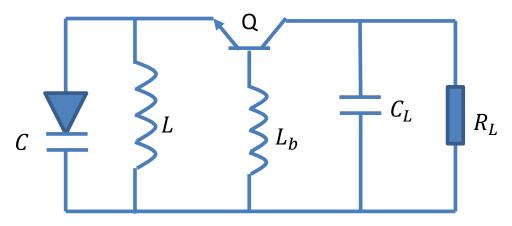
 $Z_o \rightarrow \infty$ 时, Z_L 和恒流源串联,可视为短路,构成三点式结构

微波频段常见三点式振荡器变种

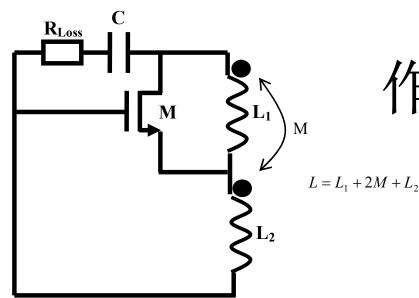


微波频段大多不用正反馈原理, 多用负阻原理进行分析;微波 频段大多采用由测量获得的二 端口网络参量电路模型进行振 荡器设计

微波频段考虑的寄生效应太多, 基于器件结构的电路模型过于 复杂,因而一般用二端口网络 参量这种二端口戴维南或诺顿 等效电路模型进行分析和设计



基本思路: 首先找到谐振腔,证明谐振腔外并联负导或谐振腔内串联负阻



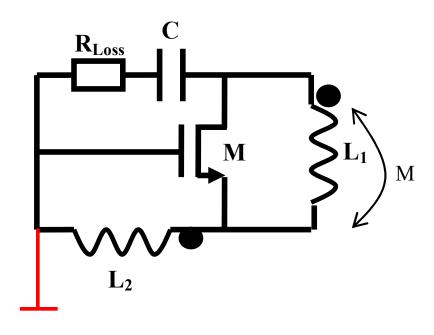
作业4起振条件分析

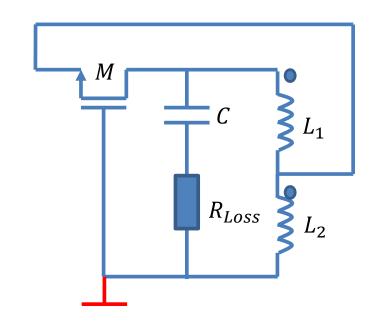
 $L = L_1 + 2M + L_2 = (N_1 + N_2)^2 \Xi$

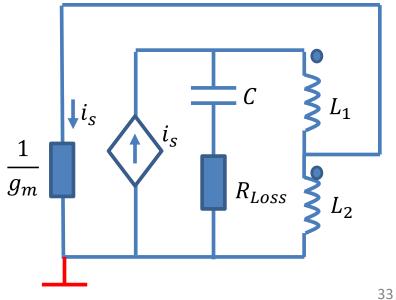
- 某同学在设计哈特莱正弦波振荡器时 -个在磁环上绕了N圈制成的电 两端则分别接在晶体管的 系,即*M* = $\sqrt{L_1L_2}$,其中 这里N,,N,和N为电感在磁环. 数,N=N1+N2。假设电路中的 为g_m。
- (1) 请分析该振荡器,用图示的 己知电路元件参量L、M、C、R_{Loss}、 gm表述该正弦波振荡器的振荡频率 和起振条件。
- (2) 在实际电路设计中,我们往 往期望低功耗设计,因而希望直流 偏置电流足够的小,换句话说,希 望和直流偏置电流成正比关系的跨 导gm应足够的小,该振荡器仍然可 以起振。请分析图示振荡电路的电 感中间抽头如何引出(即接入系数 p=N₂/N 如何取值),该电路可以 在较小的gm(对应较小的直流偏置 电流)条件下就可以起振。

正反馈原理

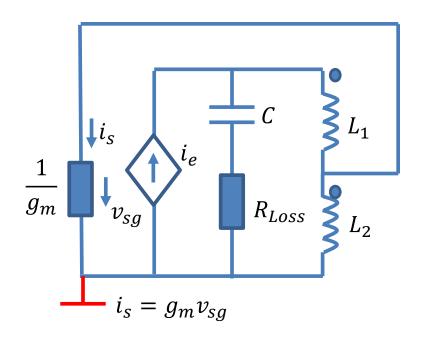
把晶体管建模为放大器 需要考虑晶体管组态 三点式振荡结构和地无关 人为添加地 (任意位置均可)

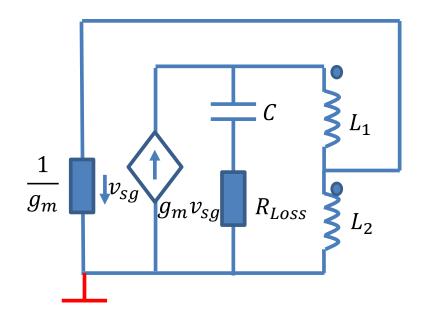


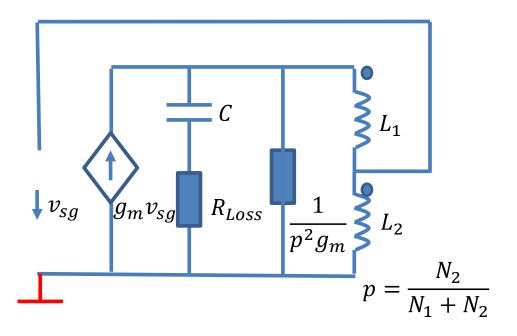


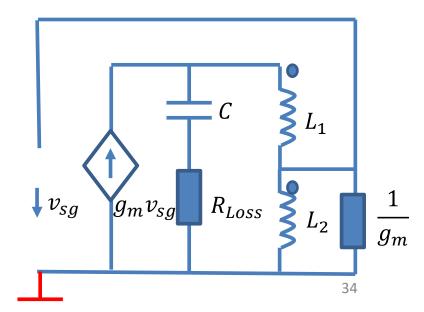


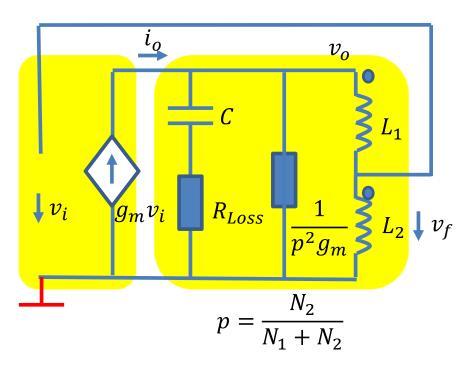
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$$pg_m\left(\frac{1}{p^2g_m + \frac{1}{j\omega L} + \frac{j\omega C}{1 + j\omega CR_{Loss}}}\right) > 1$$

$$A = \frac{\dot{I}_o}{\dot{V}_i} = g_m$$

$$F = \frac{\dot{V}_f}{\dot{l}_o} = \frac{\dot{V}_f}{\dot{V}_o} \frac{\dot{V}_o}{\dot{l}_o} = p \left(L || \frac{1}{p^2 g_m} || (R_{Loss} \oplus C) \right)$$

$$= p \left(\frac{1}{p^2 g_m + \frac{1}{j\omega L} + \frac{1}{R_{Loss} + \frac{1}{j\omega C}}} \right)$$

$$= p \left(\frac{1}{p^2 g_m + \frac{1}{j\omega L} + \frac{1}{m}} \right)$$

$$= p \left(\frac{1}{p^2 g_m + \frac{1}{j\omega L} + \frac{j\omega C}{1 + j\omega C R_{Loss}}} \right)$$

$$> 1$$

$$pg_{m}\left(\frac{1}{p^{2}g_{m} + \frac{(\omega C)^{2}R_{Loss}}{1 + (\omega CR_{Loss})^{2}} + \frac{1}{j\omega L} + \frac{j\omega C}{1 + (\omega CR_{Loss})^{2}}\right) > 1$$

$$pg_{m}\left(\frac{1}{p^{2}g_{m} + \frac{(\omega C)^{2}R_{Loss}}{1 + (\omega CR_{Loss})^{2} + \frac{1}{j\omega L} + \frac{j\omega C}{1 + (\omega CR_{Loss})^{2}}}\right) > 1$$

$$p = \frac{N_{2}}{N_{1} + N_{2}}$$

$$\frac{1}{j\omega L} + \frac{j\omega C}{1 + (\omega C R_{Loss})^2} = 0$$

$$\omega_0^2 = \frac{1}{LC - R_{Loss}^2 C^2}$$

$$\frac{1}{j\omega L} + \frac{j\omega C}{1 + (\omega C R_{Loss})^2} = 0 \qquad \omega_0^2 = \frac{1}{LC - R_{Loss}^2 C^2} \qquad \omega_0 = \frac{1}{\sqrt{LC - R_{Loss}^2 C^2}}$$

幅度条件(实部条件)决定振荡幅度(是否起振)

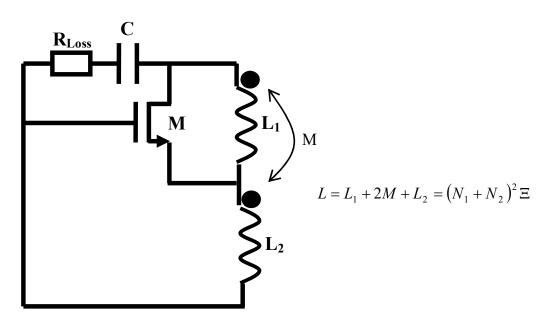
$$pg_{m}\left(\frac{1}{p^{2}g_{m} + \frac{(\omega_{0}C)^{2}R_{Loss}}{1 + (\omega_{0}CR_{Loss})^{2}}}\right) > 1$$

$$pg_{m} > p^{2}g_{m} + \frac{(\omega_{0}C)^{2}R_{Loss}}{1 + (\omega_{0}CR_{Loss})^{2}}$$

$$pg_m > p^2 g_m + \frac{(\omega_0 C)^2 R_{Loss}}{1 + (\omega_0 C R_{Loss})^2}$$

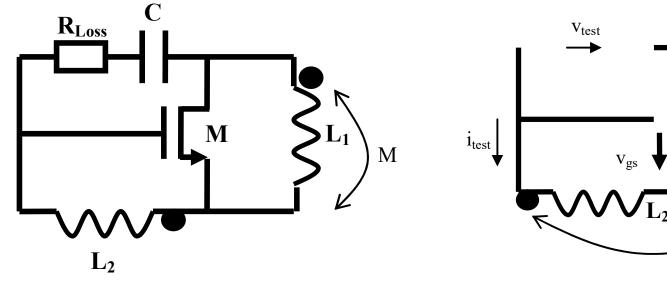
$$g_m > \frac{1}{p(1-p)} \frac{(\omega_0 C)^2 R_{Loss}}{1 + (\omega_0 C R_{Loss})^2} = \frac{1}{\frac{N_2}{N_1 + N_2} \frac{N_1}{N_1 + N_2}} \frac{\frac{C^2}{LC - R_{Loss}^2 C^2} R_{Loss}}{1 + \frac{R_{Loss}^2 C^2}{LC - R_{Loss}^2 C^2}}$$

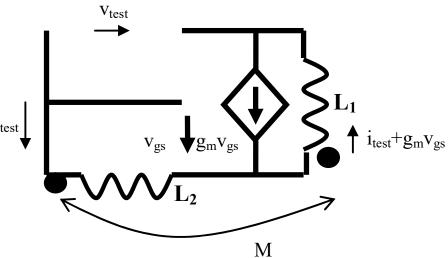
$$= \frac{1}{\frac{N_2}{N_1 + N_2} \frac{N_1}{N_1 + N_2}} \frac{R_{Loss}C^2}{LC} = \frac{1}{\frac{N_2}{N_1 + N_2} \frac{N_1}{N_1 + N_2}} \frac{R_{Loss}C}{L} = \frac{R_{Loss}C}{M}$$



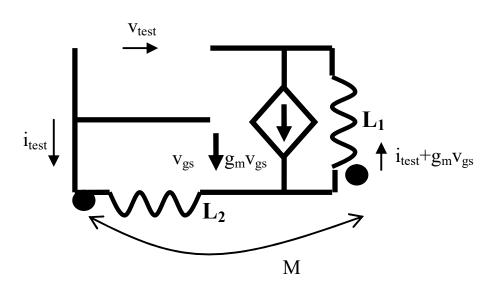
负阻原理

加流求压





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$$\dot{V}_{gs} = j\omega L_2 \dot{I}_{test} + j\omega M \left(\dot{I}_{test} + g_m \dot{V}_{gs} \right)$$

$$\dot{V}_{gs} = \frac{j\omega (L_2 + M)}{1 - j\omega M g_m} \dot{I}_{test}$$

$$\dot{V}_1 = j\omega L_1 \left(\dot{I}_{test} + g_m \dot{V}_{gs} \right) + j\omega M \dot{I}_{test}$$

$$\dot{V}_{1} = j\omega(L_{1} + M)\dot{I}_{test} + j\omega L_{1}g_{m} \frac{j\omega(L_{2} + M)}{1 - j\omega Mg_{m}}\dot{I}_{test}$$

$$\dot{V}_{test} = \dot{V}_{gs} + \dot{V}_{1} = \frac{j\omega(L_{2} + M)}{1 - j\omega Mg_{m}} \dot{I}_{test} + j\omega(L_{1} + M)\dot{I}_{test} + j\omega L_{1}g_{m} \frac{j\omega(L_{2} + M)}{1 - j\omega Mg_{m}} \dot{I}_{test}$$

$$Z_{in} = \frac{\dot{V}_{test}}{\dot{I}_{test}} = j\omega(L_1 + M) + (1 + j\omega L_1 g_m) \frac{j\omega(L_2 + M)}{1 - j\omega M g_m}$$
$$= j\omega(L_1 + 2M + L_2) - \frac{\omega^2(L_1 + M)(L_2 + M)g_m}{1 - j\omega M g_m}$$

$$Z_{im} = j\omega(L_{1} + 2M + L_{2}) - \frac{\omega^{2}(L_{1} + M)(L_{2} + M)g_{m}}{1 - j\omega Mg_{m}}$$

$$= j\omega(N_{1}^{2}\Xi + 2N_{1}N_{2}\Xi + N_{2}^{2}\Xi) - \frac{\omega^{2}(N_{1}^{2}\Xi + N_{1}N_{2}\Xi)(N_{2}^{2}\Xi + N_{1}N_{2}\Xi)g_{m}}{1 - j\omega Mg_{m}}$$

$$= j\omega(N_{1} + N_{2})^{2}\Xi - \frac{\omega^{2}N_{1}N_{2}\Xi(N_{1} + N_{2})^{2}\Xi g_{m}}{1 - j\omega Mg_{m}}$$

$$= j\omega L - \frac{\omega^{2}MLg_{m}}{1 - j\omega Mg_{m}}$$

$$= j\omega L - \frac{\omega^{2}MLg_{m}(1 + j\omega Mg_{m})}{1 + (\omega Mg_{m})^{2}}$$

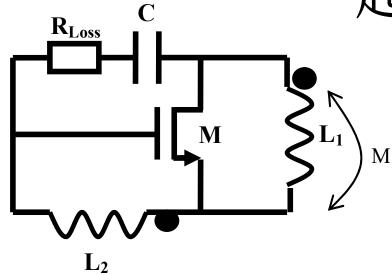
$$= j\omega L \frac{1}{1 + (\omega Mg_{m})^{2}} - \frac{\omega^{2}MLg_{m}}{1 + (\omega Mg_{m})^{2}}$$

$$i_{test}$$

$$i_{test}$$

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起振条件

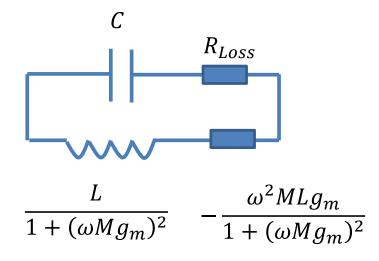


起振条件
$$\frac{\omega^2 M L g_m}{1 + (\omega M g_m)^2} > R_{Loss}$$

$$\frac{1}{\frac{LC - g_m^2 M^2}{LC - g_m^2 M^2}} > R_{Loss}$$

$$1 + \frac{g_m^2 M^2}{LC - g_m^2 M^2}$$

$$g_m > \frac{R_{Loss}C}{M}$$



振荡频率

$$\frac{1}{\omega_0^2} = \frac{LC}{1 + (\omega_0 Mg_m)^2}$$

$$\omega_0 = \frac{1}{\sqrt{LC - g_m^2 M^2}}$$

振荡频率和增益有关,增益代入满足平衡条件的准线性增益

$$\omega_0 \stackrel{g_m = \frac{R_{LOSS}C}{M}}{\stackrel{\frown}{=}} \frac{1}{\sqrt{LC - R_{LOSS}^2 C^2}}$$

在实际电路设计中,我们往往期望低功耗设计,因而希望直流偏置电流足够的小,换句话说,希望和直流偏置电流成正比关系的跨导 g_m 应足够的小,该振荡器仍然可以起振。请分析图示振荡电路的电感中间抽头如何引出(即接入系数 $p=N_2/N$ 如何取值),该电路可以在较小的 g_m (对应较小的直流偏置电流)条件下就可以起振。

$$g_m > \frac{R_{Loss}C}{M} = \frac{R_{Loss}C}{p(1-p)L} = \frac{R_{Loss}}{p(1-p)Z_0^2} = \frac{G_p}{p(1-p)}$$

恢复为三点式振荡器起振条件的一般形式

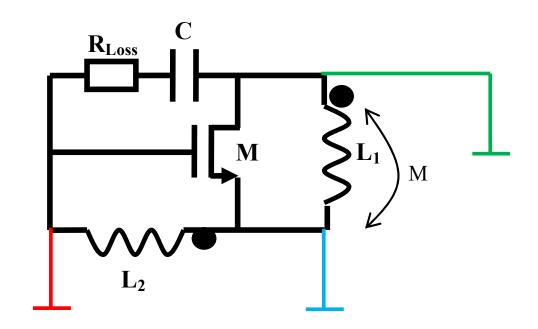
 $G_p = \frac{R_{Loss}}{Z_0^2}$ 是电路中的损耗折合到bc(gd)端口的等效导纳

$$p = \frac{N_2}{N_1 + N_2}$$
是三点式(电容或)电感接入系数

$$p(1-p) \le \frac{1}{4}$$
 $g_m > \frac{G_p}{p(1-p)} \ge 4G_p$

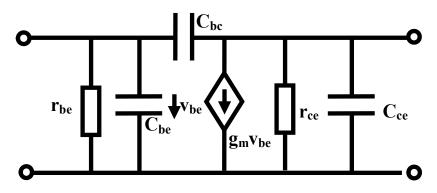
显然接入系数 $p = \frac{N_2}{N_1 + N_2} = 0.5$ 可使得跨导增益不必很大即可起振,属低功耗设计方案这是三点式振荡器设计的一般初始设计方案: 取部分介入系数为0.5

自行练习 地的选择不同,不影响最终结论

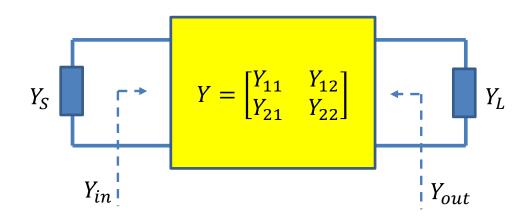


选作1:绝对稳定区

二端口网络所谓绝对稳定,指的是其两个端口端接无源负载时,另一个端口的看入阻抗也是无源的。绝对稳定的二端口网络,在端接任意无源负载时,不会出现振荡现象。求图示晶体管二端口网络的绝对稳定区(不会自激振荡的工作频率范围)。



绝对稳定

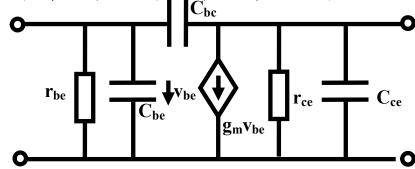


如果 $ReY_L \ge 0$,则必有 $ReY_{in} \ge 0$

如果 $ReY_S \ge 0$,则必有 $ReY_{out} \ge 0$

绝对稳定:无源负载情况下不会出现等效负阻(负导),于是在进行放大器共轭匹配调试时,绝对不会出现振荡不稳定现象,则称之为绝对稳定

根据绝对稳定性定义求绝对稳定区



$$\mathbf{Y} = \begin{bmatrix} g_{be} & 0 \\ g_m & g_{ce} \end{bmatrix} + \begin{bmatrix} j\omega C_{be} + j\omega C_{bc} & -j\omega C_{bc} \\ -j\omega C_{bc} & j\omega C_{ce} + j\omega C_{bc} \end{bmatrix}$$

$$\mathbf{Y} = \begin{bmatrix} g_{be} + j\omega C_{be} + j\omega C_{bc} & -j\omega C_{bc} \\ g_m - j\omega C_{bc} & g_{ce} + j\omega C_{ce} + j\omega C_{bc} \end{bmatrix}$$

$$Y_{in} = Y_{11} - \frac{Y_{12}Y_{21}}{Y_{22} + Y_L} = g_{be} + j\omega C_{be} + j\omega C_{bc} + \frac{j\omega C_{bc}(g_m - j\omega C_{bc})}{g_{ce} + j\omega C_{ce} + j\omega C_{bc} + G_L + jB_L}$$

$$= g_{be} + j\omega C_{be} + j\omega C_{bc} + \frac{(\omega C_{bc})^2 + j\omega C_{bc}g_m}{g_{ce} + G_L + j(\omega C_{ce} + \omega C_{bc} + B_L)}$$

$$\forall B_L \qquad G_L \ge 0 \qquad \Longrightarrow \quad \text{Re}Y_{in} \ge 0$$

$$Y_{in} = Y_{11} - \frac{Y_{12}Y_{21}}{Y_{22} + Y_L} = g_{be} + j\omega C_{be} + j\omega C_{bc} + \frac{(\omega C_{bc})^2 + j\omega C_{bc}g_m}{g_{ce} + G_L + j(\omega C_{ce} + \omega C_{bc} + B_L)}$$

$$ReY_{in} = g_{be} + \frac{(\omega C_{bc})^2 (g_{ce} + G_L) + \omega C_{bc} g_m (\omega C_{ce} + \omega C_{bc} + B_L)}{(g_{ce} + G_L)^2 + (\omega C_{ce} + \omega C_{bc} + B_L)^2}$$

$$= \frac{g_{be}(\omega C_{ce} + \omega C_{bc} + B_L)^2 + \omega C_{bc}g_m(\omega C_{ce} + \omega C_{bc} + B_L) + (\omega C_{bc})^2(g_{ce} + G_L) + g_{be}(g_{ce} + G_L)^2}{(g_{ce} + G_L)^2 + (\omega C_{ce} + \omega C_{bc} + B_L)^2}$$

$$\forall B_L \qquad G_L \geq 0 \qquad \implies \operatorname{Re} Y_{in} \geq 0$$

$$\Delta = (\omega C_{bc} g_m)^2 - 4g_{be} \big((\omega C_{bc})^2 (g_{ce} + G_L) + g_{be} (g_{ce} + G_L)^2 \big) \leq 0$$

$$\Delta = (\omega C_{bc})^2 (g_m^2 - 4g_{be}(g_{ce} + G_L)) - 4g_{be}^2 (g_{ce} + G_L)^2 \le 0$$

$$(\omega C_{bc})^2 (g_m^2 - 4g_{be}(g_{ce} + G_L)) \le 4g_{be}^2 (g_{ce} + G_L)^2$$

$$(\omega C_{bc})^2 \le \frac{4g_{be}^2 (g_{ce} + G_L)^2}{g_m^2 - 4g_{be}(g_{ce} + G_L)}$$

$$\forall B_L \qquad G_L \geq 0 \qquad \implies \operatorname{Re} Y_{in} \geq 0$$

绝对稳定区

$$(\omega C_{bc})^2 \le \frac{4g_{be}^2 (g_{ce} + G_L)^2}{g_m^2 - 4g_{be}(g_{ce} + G_L)}$$

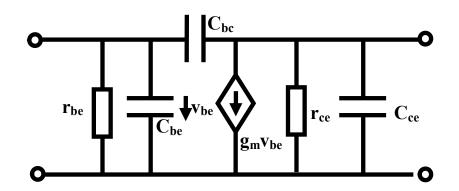
$$\omega \leq \frac{2g_{be}(g_{ce} + G_L)}{C_{bc}\sqrt{g_m^2 - 4g_{be}(g_{ce} + G_L)}}$$

$$\frac{2g_{be}(g_{ce} + G_L)}{C_{bc}\sqrt{g_m^2 - 4g_{be}(g_{ce} + G_L)}} \ge \frac{2g_{be}g_{ce}}{C_{bc}\sqrt{g_m^2 - 4g_{be}g_{ce}}} = \omega_{us}$$

只要
$$\omega \leq \omega_{us}$$
,则 $\omega \leq \frac{2g_{be}(g_{ce}+G_L)}{c_{bc}\sqrt{g_m^2-4g_{be}(g_{ce}+G_L)}}$ 恒成立

于是 $\omega \leq \omega_{us}$ 为绝对稳定区

BJT晶体管核心模型的绝对稳定区



$$\omega \le \omega_{us} = \frac{2g_{be}g_{ce}}{C_{bc}\sqrt{g_m^2 - 4g_{be}g_{ce}}}$$

CE组态不稳定的来源是Cbc

- 晶体管核心模型
 - 绝对稳定区范围和C_{bc}成反比关系,C_{bc}=0时,绝对稳定区为全频带:没有输出到输入的反馈,则没有产生负阻的可能性
 - 如果网络本身无源,则全频带绝对稳定
 - 不稳定是因为有源,但有源未必不稳定 $g_m^2 \leq 4g_{be}g_{ce}$

习题**10.9**给出的一般性结论 和前述推导相同的过程,非特定网络

• 满足如下条件的网络称为绝对稳定网络

网络参量矩阵P = Z, Y, h, g

$$ReP_{11} \ge 0$$

输出开路或短路时,输入阻抗或导纳必须无源

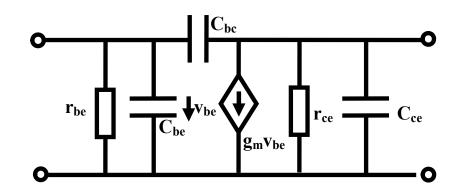
$$ReP_{22} \ge 0$$

输入开路或短路时,输出阻抗或导纳必须无源

$$k = \frac{2 \mathrm{Re} P_{11} \mathrm{Re} P_{22} - \mathrm{Re} (P_{12} P_{21})}{|P_{12} P_{21}|} \geq 1$$

罗莱特稳定性系数:确定二端口网络稳定性的一个参量

Y参量 稳定性系数 绝对稳定区



$$\mathbf{Y} = \begin{bmatrix} g_{be} + j\omega C_{be} + j\omega C_{bc} & -j\omega C_{bc} \\ g_m - j\omega C_{bc} & g_{ce} + j\omega C_{ce} + j\omega C_{bc} \end{bmatrix}$$

$$ReY_{11} = g_{be} > 0$$

$$ReY_{22} = g_{ce} > 0$$

$$k = \frac{2\text{Re}Y_{11}\text{Re}Y_{22} - \text{Re}(Y_{12}Y_{21})}{|Y_{12}Y_{21}|} = \frac{2g_{be}g_{ce} + \omega^2 C_{bc}^2}{\omega C_{bc}\sqrt{g_m^2 + \omega^2 C_{bc}^2}} \ge 1$$

$$\frac{2g_{be}g_{ce} + \omega^2 C_{bc}^2}{\omega C_{bc}} \ge \sqrt{g_m^2 + \omega^2 C_{bc}^2}$$

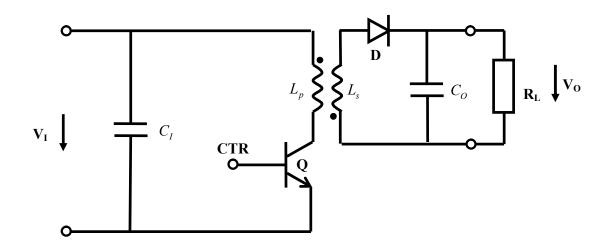
$$\omega \le \frac{2g_{be}g_{ce}}{C_{bc}\sqrt{g_m^2 - 4g_{be}g_{ce}}} = \omega_{us}$$

$$\left(\frac{2g_{be}g_{ce}}{\omega C_{bc}}\right)^2 + \frac{4g_{be}g_{ce}}{\omega C_{bc}}\omega C_{bc} + (\omega C_{bc})^2 \ge g_m^2 + \omega^2 C_{bc}^2$$

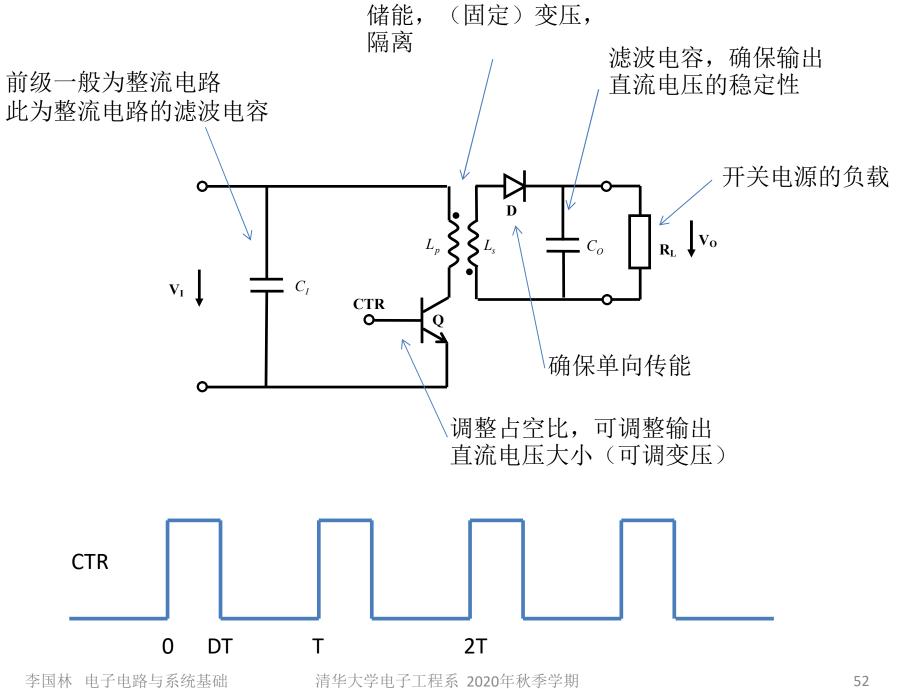
绝对稳定工作区

选作2:

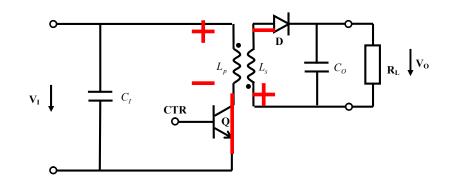
Flyback converter



• 反激DC-DC转换器: CTR=1,晶体管Q饱和导通, 流电压V₁为初级线圈L_p充磁,变压器同名端 反相从而二极管D反偏截」 储于变压器结构 对Ca电容充电补充(同时也为R₁提供直流电能。 波占空比为D,请分析输出直流电压Vo和输

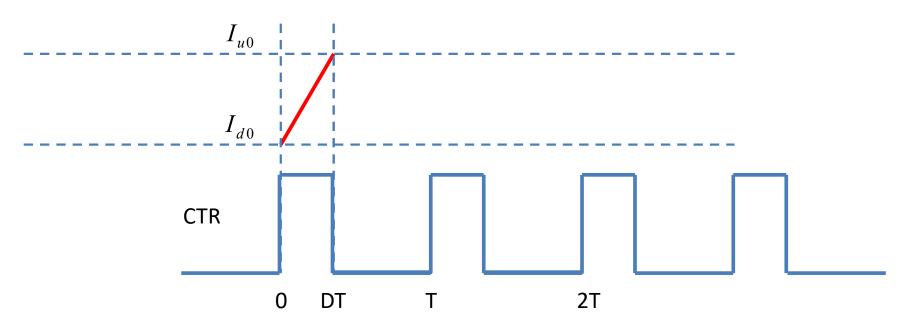


CTR=1 开关闭合



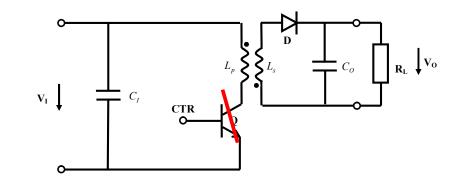
$$i_1(t) = I_{d0} + \frac{1}{L_1} \int_0^t V_I dt = I_{d0} + \frac{V_I}{L_1} t$$

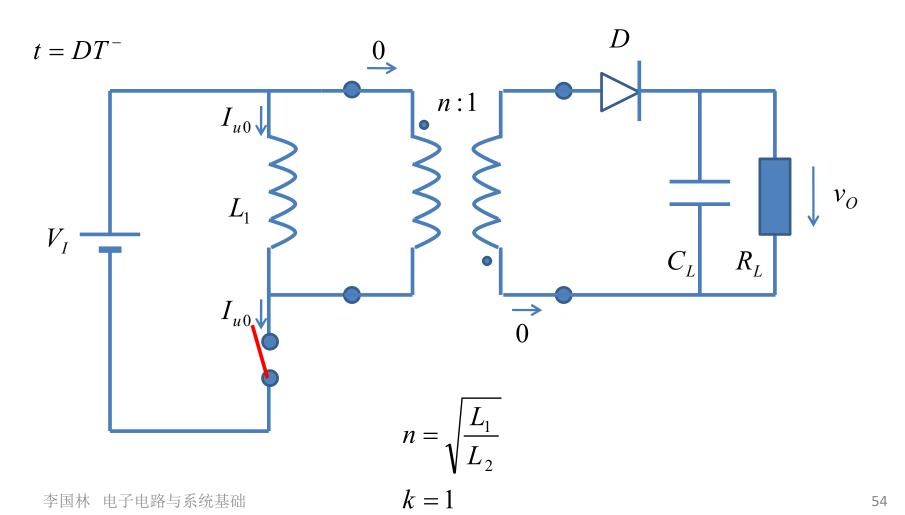
$$I_{u0} = i_1(DT) = I_{d0} + \frac{V_I}{L_1}DT$$



CTR=0

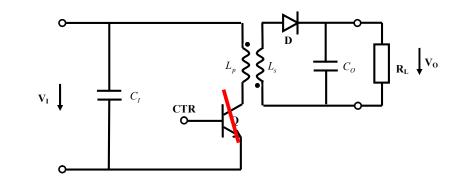
开关断开前瞬间

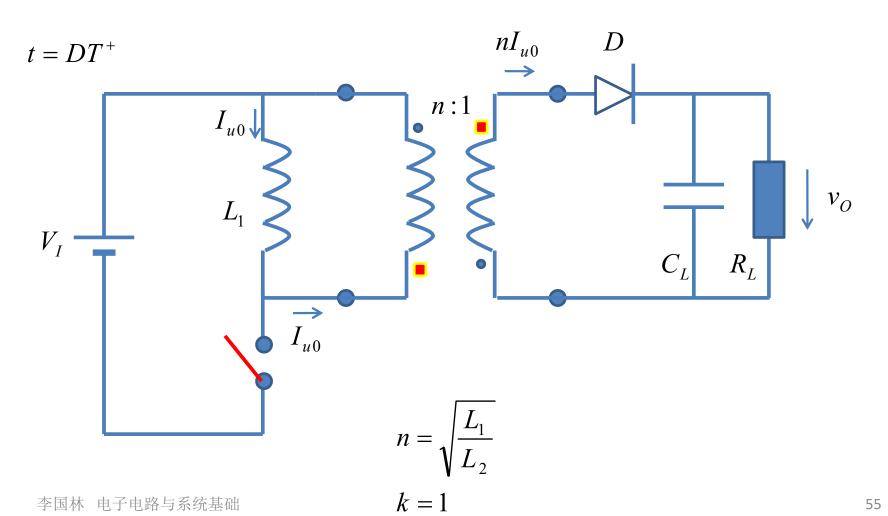


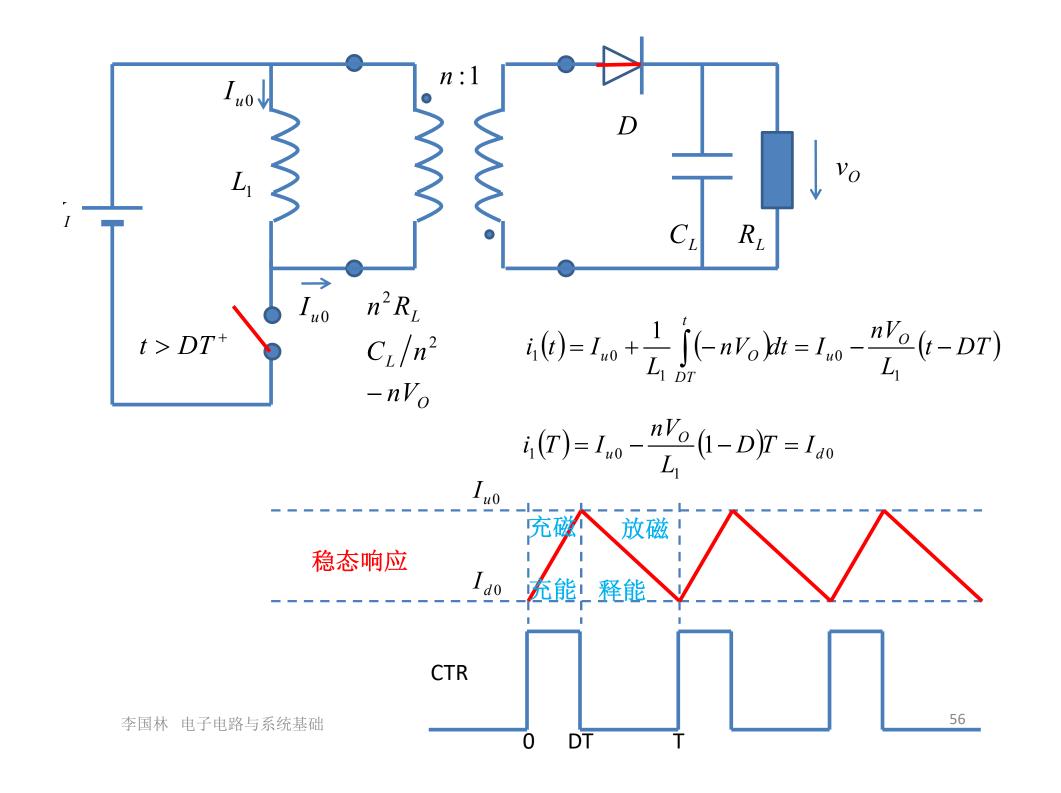


CTR=0

开关断开后瞬间







$$I_{u0} = i_1(DT) = I_{d0} + \frac{V_I}{L_1}DT$$

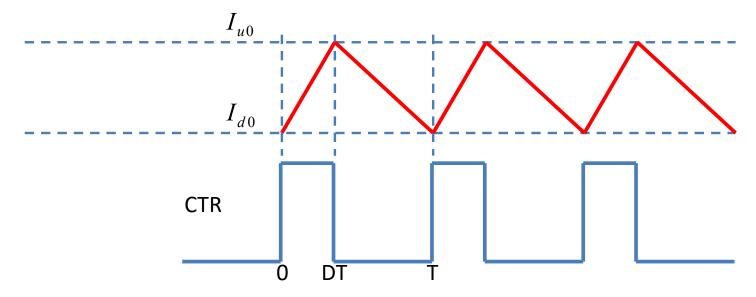
$$I_{d0} = i_1(T) = I_{u0} - \frac{nV_O}{L_1}(1-D)T$$

$$\frac{V_I}{L_1}DT = \frac{nV_O}{L_1}(1-D)T$$

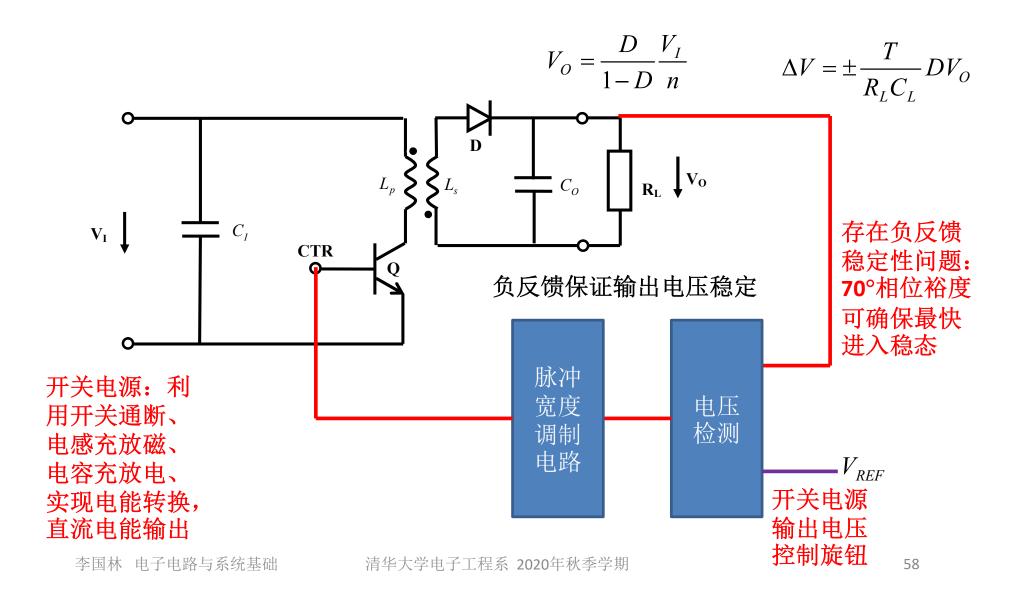
磁通守恒:变压器次级释放的磁通等于初级吸收的磁通

$$V_O = \frac{D}{1 - D} \frac{V_I}{n}$$

输出直流电压Vo可通过调节占空比D调整

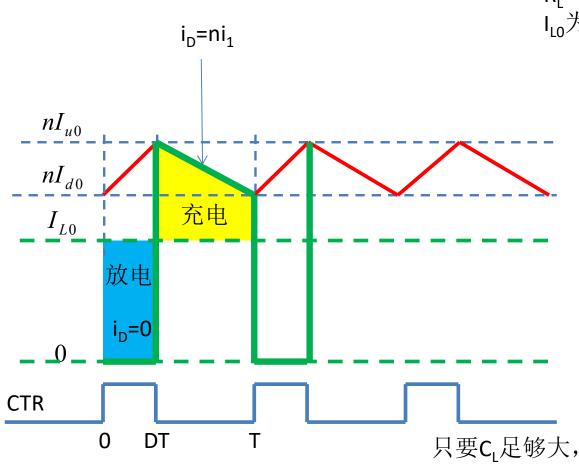


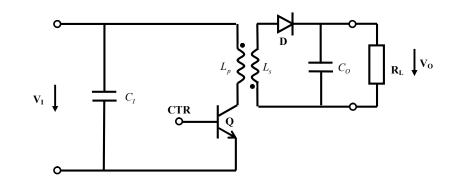
可用于实现开关电源



纹波电压

假设Vo不变,其实Vo在变 但可以使得其变化很小





对输出 $R_L C_L$ 而言 $I_{L0} = \frac{V_O}{R_r}$ 对输出R_LC_L而言 ILO为iD的直流分量

$$I_{L0} = \frac{V_O}{R_L}$$

CTR=1:电容放电

$$\Delta Q = I_{L0}DT$$

CTR=0:电容充电ΔQ补偿放电

$$\Delta V = \pm \frac{\Delta Q}{C_L}$$

$$= \pm \frac{V_0}{R_L C_L} DT$$

$$= \pm \frac{T}{R_L C_L} DV_0$$

只要C₁足够大,则可认为Vo几乎不变