Final_project

February 19, 2021

1 Final task:

2 Dimensionality reduction via principal component analysis

```
[2]: %matplotlib inline
     import matplotlib.pyplot as plt
     from matplotlib import animation, rc
     from mpl_toolkits.mplot3d import Axes3D
     from matplotlib import cm
     from matplotlib.ticker import LinearLocator, FormatStrFormatter
     from IPython.display import HTML
     import random
     import copy
     import numpy as np
     import scipy as scy
     from tqdm.notebook import trange, tqdm
     import time
     from scipy.stats import maxwell
     #used for the video
     import subprocess
     import glob
     import os
```

2.1 Introduction:

2.2 Task I: Implementation

Monte Carlo (MC) method with Metropolis algorithm that samples a 2D energy surface with:

$$U(x,y) = k_b T(0.28(0.25(a \cdot x + b \cdot y)^4 + 0.1(a \cdot x + b \cdot y)^3 - 3.24(a \cdot x + b \cdot y)^2 + 6.856(a \cdot y - b \cdot x)^2) + 3.5)$$
 with $a = 0.809$ and $b = 0.588$.

```
[3]: a = 0.809
     b = 0.588
[4]: def Potential_energy (x,y):
         ax_plus_by = a*x + b*y
         ay_minus_bx = a*y - b*x
         U = k_b * Temp * (0.28*(0.25*ax_plus_by**4 + 0.1*ax_plus_by**3 - 3.
      \rightarrow24*ax_plus_by**2 + 6.856*ay_minus_bx**2)+3.5)
         return U
[5]: def Move(x,y):
         #Calculate U1
         U_1 = Potential_energy(x,y)
         #Move by dR = 0.01 nm in a random direction
         angle = np.random.uniform(0,2*np.pi)
         dx = np.sin(angle)*dR
         dy = np.cos(angle)*dR
         #Calculate U2
         U_2 = Potential_energy(x+dx, y+dy)
         if U_1 > U_2:
             #accept move
             return True, x+dx , y+dy, U_2
         else :
             P = np.exp(-(U_2 - U_1)/(k_b*Temp))
             q = np.random.uniform(0,1)
             if q < P:
                 #accept move
                 return True, x+dx , y+dy, U_2
```

• Could do the Pand q in ln to simplify

#Discard move

return False, x, y, U_1

2.3 Task II: Simulation

else :

```
[6]: Temp = 300 #K

#step size
dR = 0.01 #nm

#Initial position #nm
```

```
x_0 = 2
y_0 = 2

# Number of MC samples = 1000000

Nbr_MC = 2000000

#k_b_mol = 8.314462 #JK^(-1).mol^(-1)
k_b = 1.380649e-23 #J.K-1
Na = 6.02214086e23 #mol-1
```

```
[7]: x_list = [x_0] + [0]*Nbr_MC
y_list = [y_0] + [0]*Nbr_MC
U_list = [Potential_energy(x_0,y_0)] + [0]*Nbr_MC

#Number of accepted moves
move_Nbr = 0

while move_Nbr < Nbr_MC :
    if (100*move_Nbr/Nbr_MC)%5 == 0 :
        print(str(100 * move_Nbr/Nbr_MC)[:3])
    check_value, x, y, U = Move(x_list[move_Nbr], y_list[move_Nbr])
    if check_value == True :
        move_Nbr += 1
        x_list[move_Nbr] = x
        y_list[move_Nbr] = y
        U_list[move_Nbr] = U</pre>
```

0.0

5.0

10.

15.

20.

25.

30.

35.

40.

45.

50.

55.

60. 65.

70.

75.

80.

85.

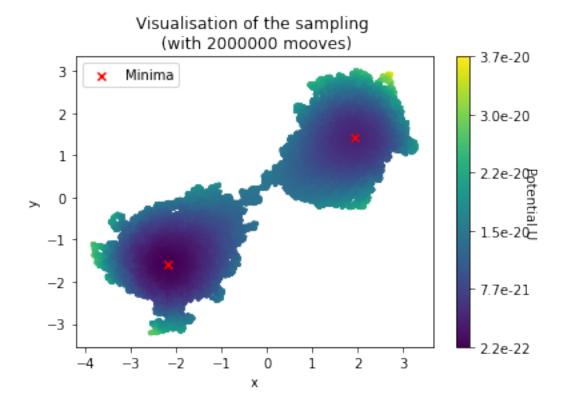
```
90.
95.
Done
```

Calculating the minimum

```
[26]: U_list_min1 = [10]*len(x_list)
U_list_min2 = [10]*len(x_list)
for ind in trange(len(x_list)):
    if x_list[ind] < 0:
        U_list_min1[ind] = U_list[ind]
    else:
        U_list_min2[ind] = U_list[ind]</pre>
U_min_1 = min(U_list_min1)
min_ind_1 = U_list_min1.index(U_min_1)
U_min_2 = min(U_list_min2)
min_ind_2 = U_list_min2.index(U_min_2)
```

Plot of the data

```
[27]: plt.scatter(x_list, y_list, c = U_list, s=3)
      plt.scatter([x list[min ind 1],x list[min ind 2]],
       →[y_list[min_ind_1],y_list[min_ind_2]], c = 'red', marker='x',label='Minima')
      plt.xlabel('x')
      plt.ylabel('y')
      t = 'Visualisation of the sampling \n (with ' + str(Nbr_MC) + ' mooves)'
      plt.title(t)
      plt.legend()
      cbar = plt.colorbar()
      U ticks = np.linspace(min(U list), max(U list), 6)
      U_{\text{ticks}} = [\text{str}(U_{\text{ticks}}[i])[0:3] + \text{str}(U_{\text{ticks}}[i])[-4:] \text{ for } i \text{ in}_{\text{LL}}
       →range(len(U_ticks))]
      cbar.ax.set_yticklabels(U_ticks)
      cbar.set_label('Potential U', rotation=270)
      print('Minimum 1 at: (', x_list[min_ind_1],y_list[min_ind_1], ') with U = ',__
       \hookrightarrow U_{\min}1)
      print()
      print('Minimum 2 at: (', x_list[min_ind_2],y_list[min_ind_2], ') with U = ',__
        \hookrightarrow U_min_2)
```



```
[54]: plt.subplot(211)
      plt.plot(x_list, U_list)
      MIN1_X = 'Min n^1 at y = ' + str(y_list[min_ind_1])[0:5]
      MIN2_X = 'Min n^2 at y = ' + str(y_list[min_ind_2])[0:5]
      plt.plot([x_list[min_ind_1]], [U_list[min_ind_1]],c = 'red', marker='x',__
      →linestyle='None',label= MIN1_X )
      plt.plot([x_list[min_ind_2]], [U_list[min_ind_2]],c = 'orange', marker='x',__
      →linestyle='None',label= MIN2_X )
      t = 'Projection along the x axis \n varience = ' + str(sigma[0,0])
      plt.title(t)
      plt.xlim(-4.5, 4.5)
      plt.xlabel('x')
      plt.ylabel('Potential U')
      plt.legend(title='Minimum ', bbox_to_anchor=(1.05, 1), loc='upper left')
      plt.subplot(212)
      plt.plot(y_list, U_list, c = 'midnightblue')
```

```
MIN1_Y = 'Min n°1 at x = ' + str(x_list[min_ind_1])[0:5]

MIN2_Y = 'Min n°2 at x = ' + str(x_list[min_ind_2])[0:5]

plt.plot([y_list[min_ind_1]], [U_list[min_ind_1]],c = 'red', marker='x',u

$\toplot([y_list[min_ind_2]], [U_list[min_ind_2]],c = 'orange', marker='x',u

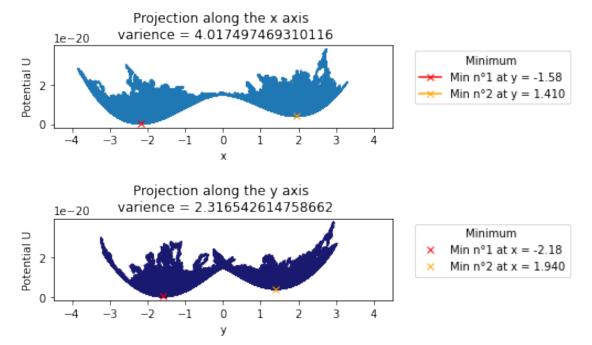
$\toplot([y_list[min_ind_2]],c = 'orange', marker='x',u

$\toplot([y_list[min_ind_2],c = 'orange', marker='x',u

$\toplot([y_list[min_ind_2],c = 'orange',u

$\toplot([y_list[min_ind_2],c = 'orange',u

$\toplot([y_list[min_ind_
```



```
[9]: np.savez('save.npz', x_list, y_list, U_list)
```

2.4 Task III: Sampling

Free energy:

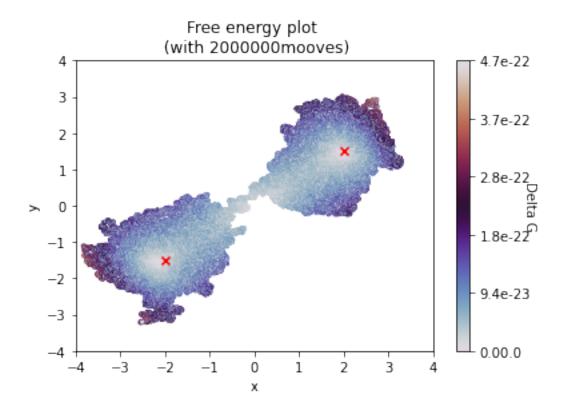
$$\Delta G(x,y) = -k_b T \ln(P(x,y))$$
$$= (U2 - U1) = \Delta U$$

With:

$$ln(P) = -\frac{(U2 - U1)}{k_b T}$$

```
[10]: lnP_list = [0]* Nbr_MC
for i in trange (1, Nbr_MC):
    U_1 = Potential_energy( x_list[i-1], y_list[i-1])
    U_2 = Potential_energy( x_list[i], y_list[i])
    lnP = abs((U_2 - U_1))
    lnP_list[i-1] = lnP
```

HBox(children=(FloatProgress(value=0.0, max=1999999.0), HTML(value='')))



The lighter areas are ones with the lowest free energy and correspondingly with the smallest potential gradient. We can see that the free energy is minimised around the area of minimum potential but also along the conecting pathay between them.

2.5 Task IV: PCA

Means

Variances

Covariances and matrix σ_{ij}

$$\sigma_{ij} = \begin{pmatrix} var(x) & cov(x,y) \\ cov(y,x) & var(y) \end{pmatrix}$$

```
_ij = [[4.01749747 2.81880472] [2.81880472 2.31654261]]
```

Eigenvalues λ_k and eigenvectors $\vec{e}_{\lambda k}$

```
[15]: eig_values, eig_vectors = np.linalg.eig(sigma)

eig_vec_1 = eig_vectors[:,0]
eig_val_1 = eig_values[0]
eig_vec_2 = eig_vectors[:,1]
eig_val_2 = eig_values[1]

print('Lambda1 = ', eig_val_1, 'with eigenvector e1: ', eig_vec_1)
print('Lambda2 = ', eig_val_2, 'with eigenvector e2: ',eig_vec_2)
```

```
Lambda1 = 6.1113318329016835 with eigenvector e1: [0.80276223 0.59629925]

Lambda2 = 0.22270825116709414 with eigenvector e2: [-0.59629925 0.80276223]
```

The eigenvectors match the data as expected, as we can see that our first vector has the same direction as the connecting axis between the two minimas and that our second vector is perpendicular to the first our as expected.

2.6 Task V: Interpretation

Angle θ between the eigenvector \vec{e}_1

```
[17]: Theta = np.arctan(eig_vec_1[0]/eig_vec_1[1])
print('Theta ~', str(round(Theta/np.pi, 3)),' ')
```

Theta ~ 0.297

The angle θ found is close to $\frac{\pi}{3}$, which seems correct compared to the plot of the potential displayed in Task II.

Clockwise rotation matrix R

$$R(\theta) = \begin{pmatrix} Cos(\theta) & Sin(\theta) \\ -Sin(\theta) & Cos(\theta) \end{pmatrix}$$

$$R\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x' \\ y' \end{pmatrix}$$

For x' and y' being the data in the rotated frame.

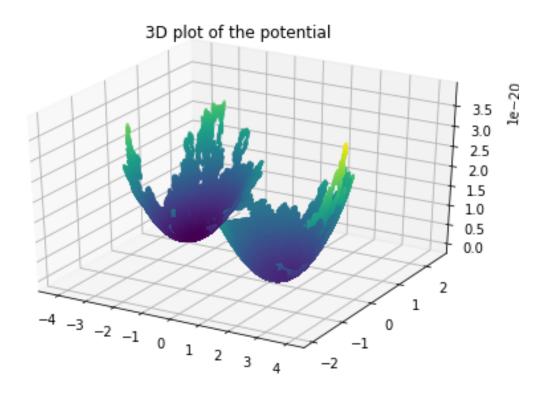
```
[18]: R = np.array([[np.cos(Theta), np.sin(Theta)],[- np.sin(Theta), np.cos(Theta)]])
```

Calculate the data in the new frame

```
[19]: x_rot_list = [R[0,0]*x_list[i] + R[0,1]*y_list[i] for i in trange(len(x_list))]
y_rot_list = [R[1,0]*x_list[i] + R[1,1]*y_list[i] for i in trange(len(x_list))]
```

```
HBox(children=(FloatProgress(value=0.0, max=2000001.0), HTML(value='')))
```

```
HBox(children=(FloatProgress(value=0.0, max=2000001.0), HTML(value='')))
```



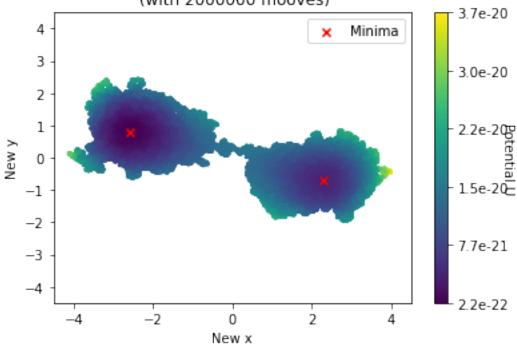
```
[43]: plt.scatter(x_rot_list, y_rot_list, c = U_list, s=3)
     plt.scatter([x_rot_list[min_ind_1],x_rot_list[min_ind_2]],__
      →marker='x',label='Minima')
     plt.xlabel('New x')
     plt.ylabel('New y')
     plt.xlim(-4.5,4.5)
     plt.ylim(-4.5, 4.5)
     t = 'Visualisation of the sampling after \n clockwise rotation of ' +_{\sqcup}

→str(round(Theta/np.pi, 3)) + 'pi\n (with ' + str(Nbr_MC) + ' mooves)'
     plt.title(t)
     plt.legend()
     cbar = plt.colorbar()
     U_ticks = np.linspace(min(U_list), max(U_list), 6)
     U_ticks = [str(U_ticks[i])[0:3] + str(U_ticks[i])[-4:] for i in_
      →range(len(U_ticks))]
     cbar.ax.set_yticklabels(U_ticks)
     cbar.set_label('Potential U', rotation=270)
     print('Minimum 1 at: (x,y) = (', str(x_rot_list[min_ind_1])[0:5],u

→str(y_rot_list[min_ind_1])[0:5], ') with U = ', U_min_1)
     print()
     print('Minimum 2 at: (x,y) = (', str(x_rot_list[min_ind_2])[0:5],__
      \rightarrowstr(y_rot_list[min_ind_2])[0:5], ') with U = ', U_min_2)
```

```
Minimum 1 at: (x,y) = (-2.57 \ 0.805) with U = 2.2978051441872487e-22
Minimum 2 at: (x,y) = (2.289 \ -0.71) with U = 4.075809248912603e-21
```

Visualisation of the sampling after clockwise rotation of 0.297pi (with 2000000 mooves)



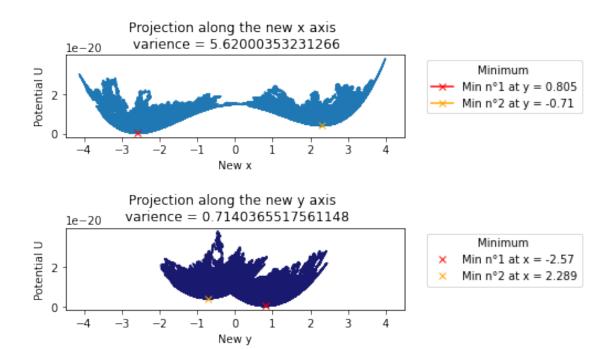
```
[35]: sigma_new = np.cov(x_rot_list, y_rot_list)
    print('Previous covarience matrix : \n _ij = \n', sigma)
    v1 = sigma[0,0] + sigma[1,1]
    print(str(sigma[0,0]/v1*100)[0:2],'%')
    print()
    print('New covarience matrix : \n _ij = \n', sigma_new)
    v2 = sigma_new[0,0] + sigma_new[1,1]
    print(str(sigma_new[0,0]/v2*100)[0:2],'%')

Previous covarience matrix :
    _ij =
```

```
[[4.01749747 2.81880472]
[2.81880472 2.31654261]]
63 %

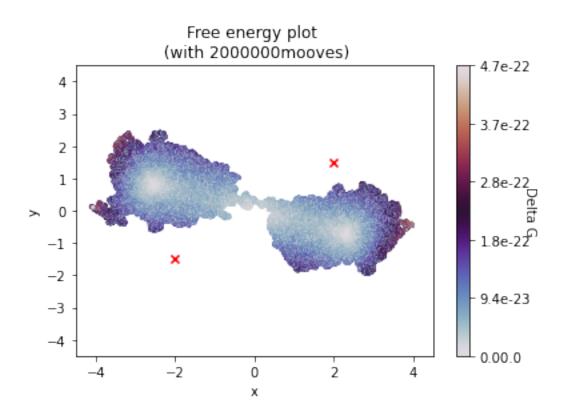
New covarience matrix :
    _ij =
    [[ 5.62000353 -1.62844832]
[-1.62844832 0.71403655]]
88 %
```

```
[55]: plt.subplot(211)
      plt.plot(x_rot_list, U_list)
      MIN1_X = 'Min n^1 at y = ' + str(y_rot_list[min_ind_1])[0:5]
      MIN2_X = 'Min n^2 at y = ' + str(y_rot_list[min_ind_2])[0:5]
      plt.plot([x_rot_list[min_ind_1]], [U_list[min_ind_1]],c = 'red', marker='x',__
      →linestyle='None',label= MIN1_X )
      plt.plot([x_rot_list[min_ind_2]], [U_list[min_ind_2]],c = 'orange', marker='x',__
      →linestyle='None',label= MIN2_X )
      t = 'Projection along the new x axis \n varience = ' + str(sigma_new[0,0])
      plt.title(t)
      plt.xlim(-4.5, 4.5)
      plt.xlabel('New x')
      plt.ylabel('Potential U')
     plt.legend(title='Minimum ', bbox_to_anchor=(1.05, 1), loc='upper left')
      plt.subplot(212)
     plt.plot(y_rot_list, U_list, c = 'midnightblue')
      MIN1_Y = 'Min n^{\circ}1 at x = ' + str(x_rot_list[min_ind_1])[0:5]
      MIN2_Y = 'Min n^2 at x = ' + str(x_rot_list[min_ind_2])[0:5]
      plt.plot([y_rot_list[min_ind_1]], [U_list[min_ind_1]],c = 'red', marker='x',__
      →linestyle='None',label= MIN1_Y )
      plt.plot([y_rot_list[min_ind_2]], [U_list[min_ind_2]],c = 'orange', marker='x',u
      →linestyle='None',label= MIN2_Y )
      t = 'Projection along the new y axis \n varience = ' + str(sigma_new[1,1])
      plt.title(t)
      plt.xlim(-4.5, 4.5)
      plt.xlabel('New y')
      plt.ylabel('Potential U')
      plt.legend(title='Minimum ', bbox_to_anchor=(1.05, 1), loc='upper left')
      plt.tight_layout()
      plt.subplots_adjust(bottom=0.1, right=0.8, top=0.9)
      plt.show()
```



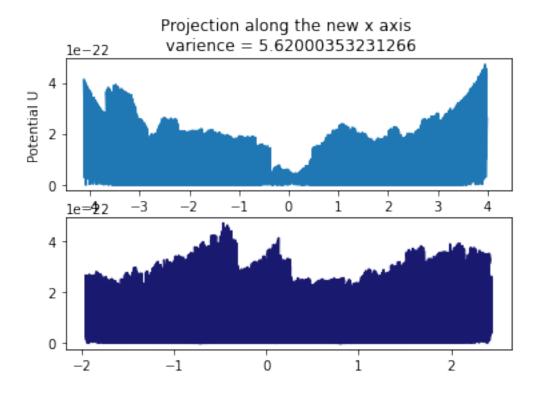
```
[48]: plt.scatter(x_rot_list[1:], y_rot_list[1:], c = lnP_list[:],cmap=plt.

→get_cmap('twilight'), s=3)
     plt.scatter([x_rot_list[min_ind_1],x_rot_list[min_ind_2]],__
      →marker='x',label='Minima')
     plt.xlabel('x')
     plt.ylabel('y')
     plt.xlim(-4.5,4.5)
     plt.ylim(-4.5,4.5)
     t = 'Free energy plot \n (with ' + str(Nbr_MC) + 'mooves)'
     plt.title(t)
     cbar = plt.colorbar(cm.ScalarMappable( cmap='twilight'))
     lnP_ticks = np.linspace(min(lnP_list), max(lnP_list), 6)
     lnP_ticks = [str(lnP_ticks[i])[0:3] + str(lnP_ticks[i])[-4:] for i in_
      →range(len(lnP_ticks))]
     cbar.ax.set_yticklabels(lnP_ticks)
     cbar.set_label('Delta G', rotation=270)
```



```
[52]: plt.subplot(211)
                          plt.plot(x_rot_list[0:-1], lnP_list)
                          MIN1_X = 'Min \ n^{\circ}1 \ at \ y = ' + str(y_rot_list[min_ind_1])[0:5]
                          MIN2_X = 'Min \ n^2 \ at \ y = ' + str(y_rot_list[min_ind_2])[0:5]
                          plt.plot([x\_rot\_list[min\_ind\_1]], \ [U\_list[min\_ind\_1]], c = 'red', \sqcup list[min\_ind\_1]], c = 'red', \sqcup list[min\_ind\_1], c = 'red', u = 'red'
                            \hookrightarrow marker='x', label= MIN1_X )
                          plt.plot([x\_rot\_list[min\_ind\_2]], \ [U\_list[min\_ind\_2]], c = 'orange', \ \Box
                             \hookrightarrow marker='x', label= MIN2_X )
                            111
                          t = 'Projection along the new x axis \n varience = ' + str(sigma_new[0,0])
                          plt.title(t)
                          plt.xlim(-4.5, 4.5)
                          plt.xlabel('New x')
                          plt.ylabel('Potential U')
                          #plt.leqend(title='Minimum ', bbox to_anchor=(1.05, 1), loc='upper left')
                          plt.subplot(212)
                          plt.plot(y_rot_list[0:-1], lnP_list, c = 'midnightblue')
```

[52]: [<matplotlib.lines.Line2D at 0x7f23818017c0>]



From the covarience matrix and from the above plot of the data along our new x and y axis we can clearly see that most of the varience is not contained in the first componant x (88% of the varience in contrast to 63% previously).

- "the histogram of Task III" is it not a plot that we are expecting?
- ΔG equivalent to U ???
- add comments on the percentages

[]: