

Final_project

February 19, 2021

1 Final task:

2 Dimensionality reduction via principal component analysis

```
[2]: %matplotlib inline
import matplotlib.pyplot as plt
from matplotlib import animation, rc
from mpl_toolkits.mplot3d import Axes3D
from matplotlib import cm
from matplotlib.ticker import LinearLocator, FormatStrFormatter

from IPython.display import HTML
import random
import copy
import numpy as np
import scipy as scy

from tqdm.notebook import trange, tqdm
import time
from scipy.stats import maxwell

#used for the video
import subprocess
import glob
import os
```

2.1 Introduction:

2.2 Task I: Implementation

Monte Carlo (MC) method with Metropolis algorithm that samples a 2D energy surface with:

$$U(x, y) = k_b T (0.28(0.25(a \cdot x + b \cdot y)^4 + 0.1(a \cdot x + b \cdot y)^3 - 3.24(a \cdot x + b \cdot y)^2 + 6.856(a \cdot y - b \cdot x)^2) + 3.5)$$

with $a = 0.809$ and $b = 0.588$.

```
[3]: a = 0.809
      b = 0.588
```

```
[4]: def Potential_energy (x,y):
      ax_plus_by = a*x + b*y
      ay_minus_bx =a*y - b*x

      U = k_b * Temp * (0.28*( 0.25*ax_plus_by**4 + 0.1*ax_plus_by**3 - 3.
      ↪24*ax_plus_by**2 + 6.856*ay_minus_bx**2)+3.5)
      return U
```

```
[5]: def Move(x,y):
      #Calculate U1
      U_1 = Potential_energy(x,y)

      #Move by dR = 0.01 nm in a random direction
      angle = np.random.uniform(0,2*np.pi)
      dx = np.sin(angle)*dR
      dy = np.cos(angle)*dR

      #Calculate U2
      U_2 = Potential_energy(x+dx, y+dy)

      if U_1 > U_2:
          #accept move
          return True, x+dx , y+dy, U_2

      else :
          P = np.exp(-(U_2 - U_1)/(k_b*Temp))
          q = np.random.uniform(0,1)
          if q < P:
              #accept move
              return True, x+dx , y+dy, U_2
          else :
              #Discard move
              return False, x, y, U_1
```

- Could do the Pand q in ln to simplify

2.3 Task II: Simulation

```
[6]: Temp = 300 #K

      #step size
      dR = 0.01 #nm

      #Initial position #nm
```

```

x_0 = 2
y_0 = 2

# Number of MC samples = 1000000
Nbr_MC = 2000000

#k_b_mol = 8.314462 #JK-1.mol-1
k_b = 1.380649e-23 #J.K-1
Na = 6.02214086e23 #mol-1

```

```

[7]: x_list = [x_0] + [0]*Nbr_MC
     y_list = [y_0] + [0]*Nbr_MC
     U_list = [Potential_energy(x_0,y_0)] + [0]*Nbr_MC

     #Number of accepted moves
     move_Nbr = 0

     while move_Nbr < Nbr_MC :
         if (100*move_Nbr/Nbr_MC)%5 == 0 :
             print(str(100 * move_Nbr/Nbr_MC)[:3])
             check_value, x, y, U = Move( x_list[move_Nbr], y_list[move_Nbr])
             if check_value == True :
                 move_Nbr += 1
                 x_list[move_Nbr] = x
                 y_list[move_Nbr] = y
                 U_list[move_Nbr] = U

     print('Done')

```

```

0.0
5.0
10.
15.
20.
25.
30.
35.
40.
45.
50.
55.
60.
65.
70.
75.
80.
85.

```

90.
95.
Done

Calculating the minimum

```
[26]: U_list_min1 = [10]*len(x_list)
      U_list_min2 = [10]*len(x_list)
      for ind in trange(len(x_list)):
          if x_list[ind] < 0 :
              U_list_min1[ind] = U_list[ind]
          else :
              U_list_min2[ind] = U_list[ind]

      U_min_1 = min(U_list_min1)
      min_ind_1 = U_list_min1.index(U_min_1)
      U_min_2 = min(U_list_min2)
      min_ind_2 = U_list_min2.index(U_min_2)
```

Plot of the data

```
[27]: plt.scatter(x_list, y_list, c = U_list, s=3)
      plt.scatter([x_list[min_ind_1],x_list[min_ind_2]],
          ↪[y_list[min_ind_1],y_list[min_ind_2]], c = 'red', marker='x',label='Minima')

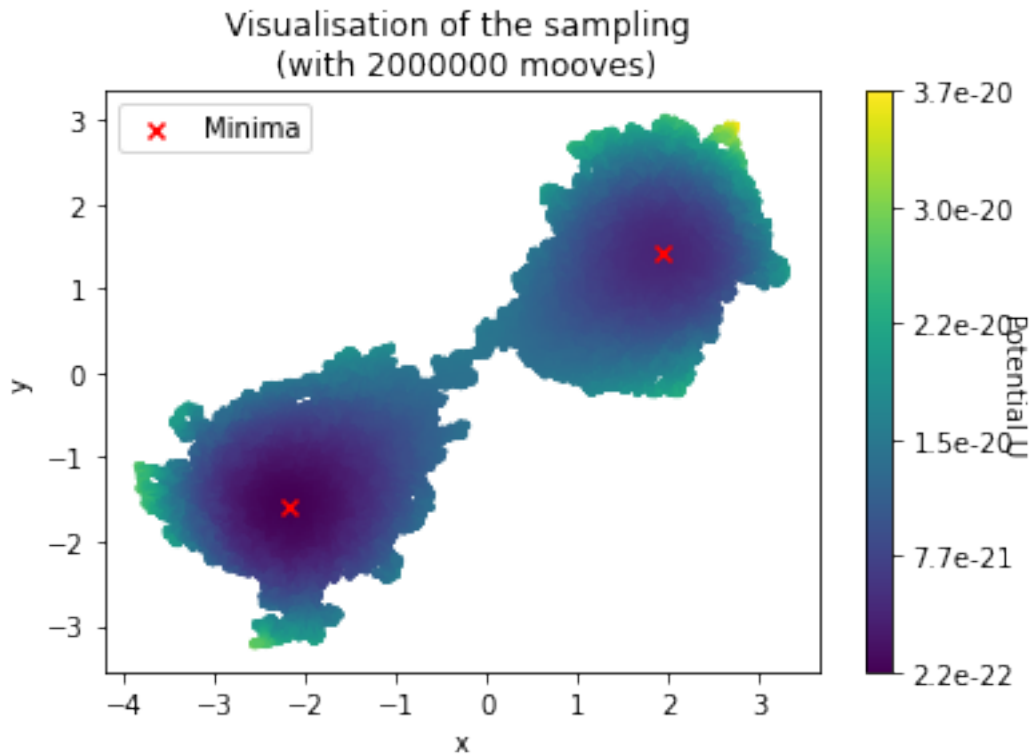
      plt.xlabel('x')
      plt.ylabel('y')
      t = 'Visualisation of the sampling \n (with ' + str(Nbr_MC) + ' mooves)'
      plt.title(t)
      plt.legend()

      cbar = plt.colorbar()

      U_ticks = np.linspace(min(U_list), max(U_list), 6)
      U_ticks = [str(U_ticks[i])[0:3] + str(U_ticks[i])[-4:] for i in
          ↪range(len(U_ticks))]
      cbar.ax.set_yticklabels(U_ticks)

      cbar.set_label('Potential U', rotation=270)

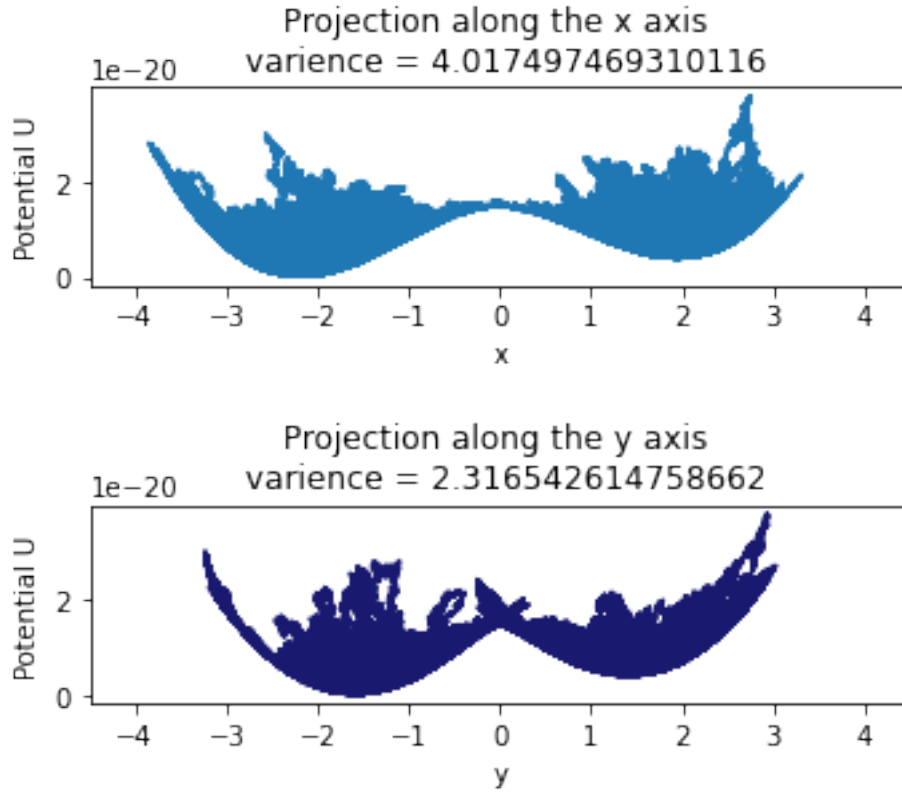
      print('Minimum 1 at: (', x_list[min_ind_1],y_list[min_ind_1], ') with U = ',
          ↪U_min_1)
      print()
      print('Minimum 2 at: (', x_list[min_ind_2],y_list[min_ind_2], ') with U = ',
          ↪U_min_2)
```



```
[29]: plt.subplot(211)
plt.plot(x_list, U_list)
t = 'Projection along the x axis \n variance = ' + str(sigma[0,0])
plt.title(t)
plt.xlim(-4.5, 4.5)
plt.xlabel('x')
plt.ylabel('Potential U')

plt.subplot(212)
plt.plot(y_list, U_list, c = 'midnightblue')
t = 'Projection along the y axis \n variance = ' + str(sigma[1,1])
plt.title(t)
plt.xlim(-4.5, 4.5)
plt.xlabel('y')
plt.ylabel('Potential U')

plt.tight_layout()
plt.subplots_adjust(bottom=0.1, right=0.8, top=0.9)
plt.show()
```



```
[9]: np.savez('save.npz', x_list, y_list, U_list)
```

2.4 Task III: Sampling

Free energy :

$$\begin{aligned}\Delta G(x, y) &= -k_b T \ln(P(x, y)) \\ &= (U_2 - U_1) = \Delta U\end{aligned}$$

With :

$$\ln(P) = -\frac{(U_2 - U_1)}{k_b T}$$

```
[10]: lnP_list = [0]* Nbr_MC
for i in range (1, Nbr_MC):
    U_1 = Potential_energy( x_list[i-1], y_list[i-1])
    U_2 = Potential_energy( x_list[i], y_list[i])
    lnP = abs((U_2 - U_1))
    lnP_list[i-1] = lnP
```

```
HBox(children=(FloatProgress(value=0.0, max=1999999.0), HTML(value='')))
```

```
[28]: plt.scatter(x_list[1:], y_list[1:], c = lnP_list[:,cmap=plt.
    ↳get_cmap('twilight'), s=3)
plt.scatter([2,-2], [1.5,-1.5], c = 'red', marker='x',label='Minima')

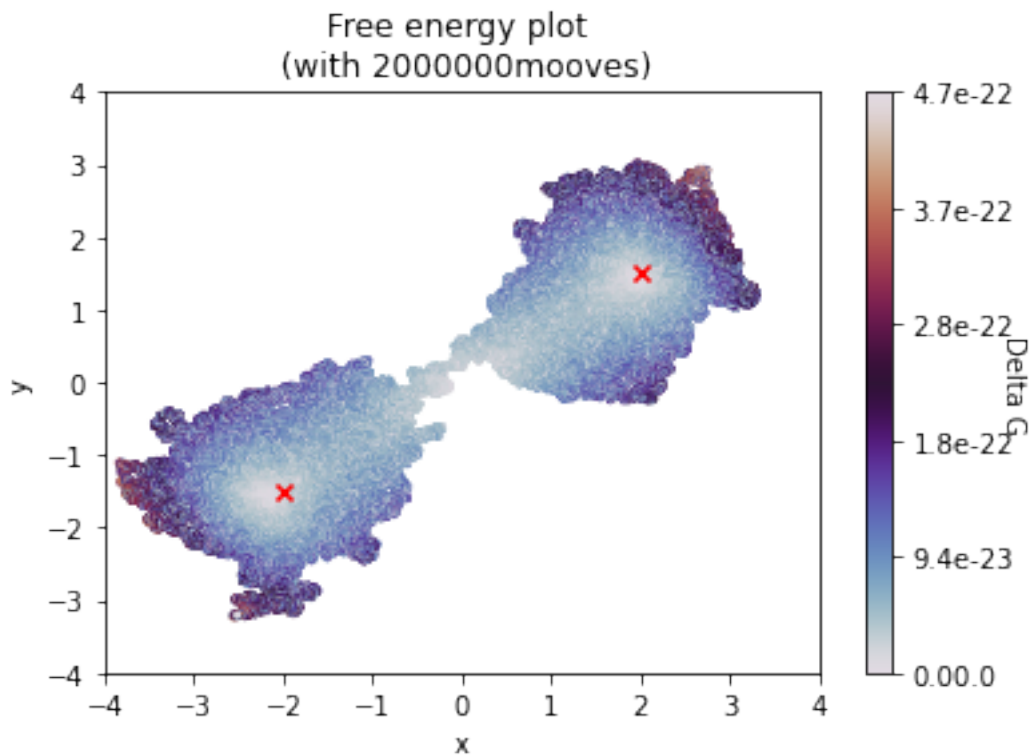
plt.xlabel('x')
plt.ylabel('y')
plt.xlim(-4,4)
plt.ylim(-4,4)

t = 'Free energy plot \n (with ' + str(Nbr_MC) + 'mooves)'
plt.title(t)

cbar = plt.colorbar(cm.ScalarMappable( cmap='twilight'))

lnP_ticks = np.linspace(min(lnP_list), max(lnP_list), 6)
lnP_ticks = [str(lnP_ticks[i])[0:3] + str(lnP_ticks[i])[-4:] for i in_
    ↳range(len(lnP_ticks))]
cbar.ax.set_yticklabels(lnP_ticks)

cbar.set_label('Delta G', rotation=270)
```



The lighter areas are ones with the lowest free energy and correspondingly with the smallest potential gradient. We can see that the free energy is minimised around the area of minimum potential but also along the connecting pathway between them.

2.5 Task IV: PCA

Means

```
[12]: mean_x = np.mean(x_list)
      mean_y = np.mean(y_list)
```

Variances

```
[13]: var_x = np.var(x_list)
      var_y = np.var(y_list)
```

Covariances and matrix σ_{ij}

$$\sigma_{ij} = \begin{pmatrix} \text{var}(x) & \text{cov}(x, y) \\ \text{cov}(y, x) & \text{var}(y) \end{pmatrix}$$

```
[14]: sigma = np.cov(x_list, y_list)
      print('_ij = \n', sigma)
```

```
_ij =
[[4.01749747 2.81880472]
 [2.81880472 2.31654261]]
```

Eigenvalues λ_k and eigenvectors $\vec{e}_{\lambda k}$

```
[15]: eig_values, eig_vectors = np.linalg.eig(sigma)

eig_vec_1 = eig_vectors[:,0]
eig_val_1 = eig_values[0]
eig_vec_2 = eig_vectors[:,1]
eig_val_2 = eig_values[1]

print('Lambda1 = ', eig_val_1, 'with eigenvector e1: ', eig_vec_1)
print('Lambda2 = ', eig_val_2, 'with eigenvector e2: ', eig_vec_2)
```

```
Lambda1 = 6.1113318329016835 with eigenvector e1: [0.80276223 0.59629925]
Lambda2 = 0.22270825116709414 with eigenvector e2: [-0.59629925 0.80276223]
```

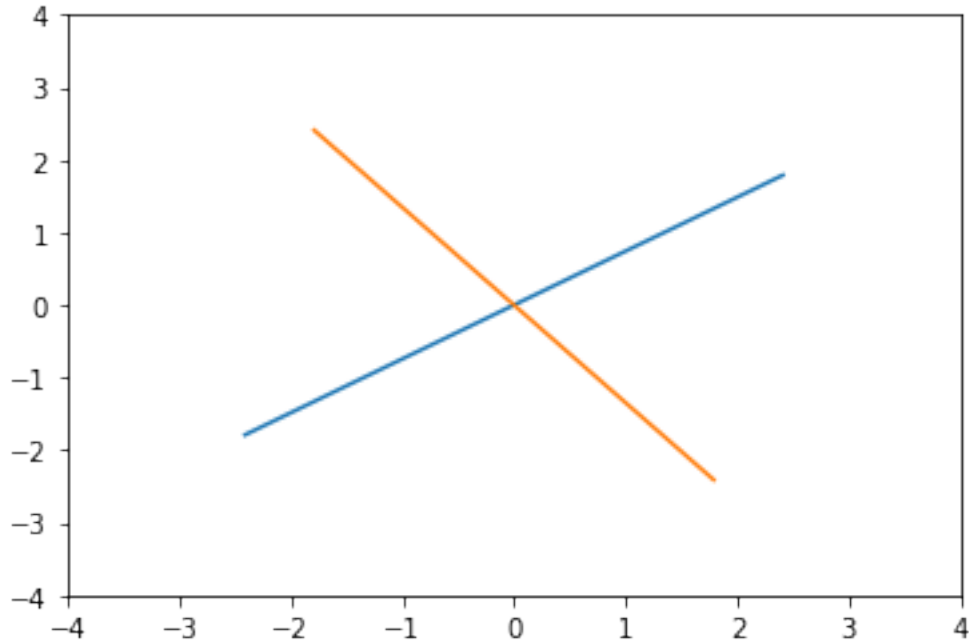
The eigenvectors match the data as expected, as we can see that our first vector has the same direction as the connecting axis between the two minimas and that our second vector is perpendicular to the first one as expected.

```
[16]: plt.plot([eig_vec_1[0]*(-3), eig_vec_1[0]*(3)],
               ↳ [eig_vec_1[1]*(-3), eig_vec_1[1]*(3)], label='Eigenvector 1')
      plt.plot([eig_vec_2[0]*(-3), eig_vec_2[0]*(3)],
               ↳ [eig_vec_2[1]*(-3), eig_vec_2[1]*(3)], label='Eigenvector 2')
```



```
plt.xlim(-4,4)
plt.ylim(-4,4)
```

[16]: (-4.0, 4.0)



2.6 Task V: Interpretation

Angle θ between the eigenvector \vec{e}_1

```
[17]: Theta = np.arctan(eig_vec_1[0]/eig_vec_1[1])
print('Theta ~', str(round(Theta/np.pi, 3)), '')
```

Theta ~ 0.297

The angle θ found is close to $\frac{\pi}{3}$, which seems correct compared to the plot of the potential displayed in Task II.

Clockwise rotation matrix R

$$R(\theta) = \begin{pmatrix} \cos(\theta) & \sin(\theta) \\ -\sin(\theta) & \cos(\theta) \end{pmatrix}$$

$$R \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x' \\ y' \end{pmatrix}$$

For x' and y' being the data in the rotated frame.

```
[18]: R = np.array([[np.cos(Theta), np.sin(Theta)], [- np.sin(Theta), np.cos(Theta)]])
```

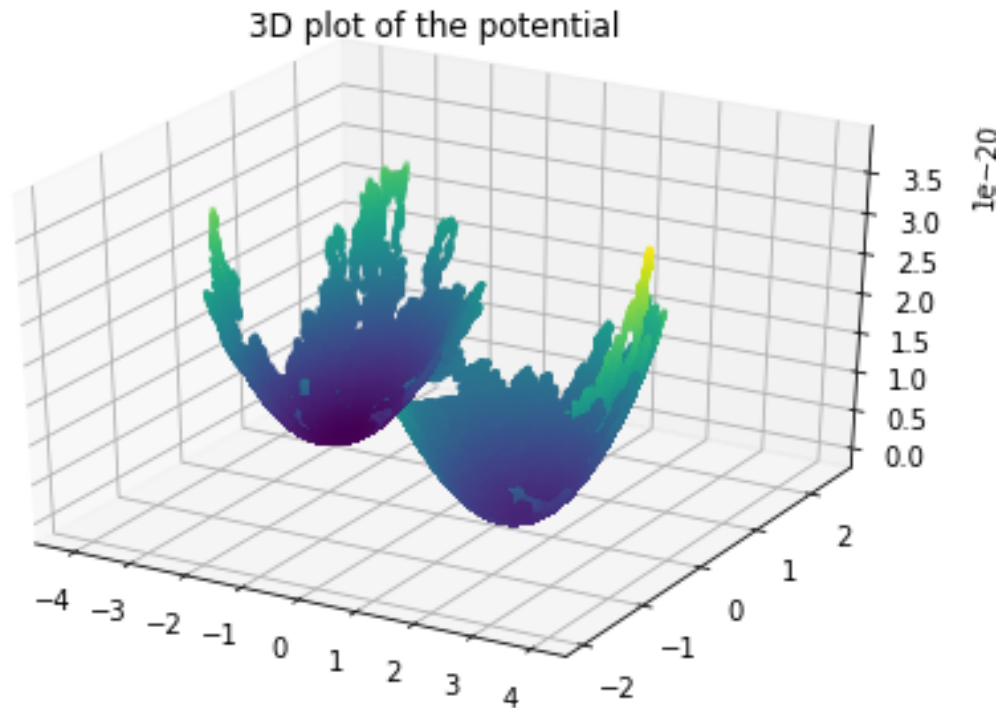
Calculate the data in the new frame

```
[19]: x_rot_list = [R[0,0]*x_list[i] + R[0,1]*y_list[i] for i in trange(len(x_list))]  
      y_rot_list = [R[1,0]*x_list[i] + R[1,1]*y_list[i] for i in trange(len(x_list))]
```

```
HBox(children=(FloatProgress(value=0.0, max=2000001.0), HTML(value='')))
```

```
HBox(children=(FloatProgress(value=0.0, max=2000001.0), HTML(value='')))
```

```
[37]: fig = plt.figure()  
      ax = fig.gca(projection='3d')  
  
      surf = ax.scatter(x_rot_list, y_rot_list, U_list, c=U_list, marker='o', s=2)  
  
      plt.title('3D plot of the potential')  
      #U_ticks = np.linspace(min(U_list), max(U_list), 6)  
      #U_ticks = [str(U_ticks[i])[0:3] + str(U_ticks[i])[-4:] for i in  
      ↪range(len(U_ticks))]  
  
      #ax.zaxis.set_major_locator(LinearLocator(10))  
      #ax.zaxis.set_major_formatter(U_ticks)  
  
      #cbar.ax.set_yticklabels(U_ticks)  
  
      #fig.colorbar(surf, shrink=0.5, aspect=5)  
      plt.tight_layout()  
      plt.show()
```



```
[35]: sigma_new = np.cov(x_rot_list, y_rot_list)
print('Previous covariance matrix : \n _ij = \n',sigma)
v1 = sigma[0,0]+ sigma[1,1]
print(str(sigma[0,0]/v1*100)[0:2], '%')
print()
print('New covariance matrix : \n _ij = \n',sigma_new)
v2 = sigma_new[0,0]+ sigma_new[1,1]
print(str(sigma_new[0,0]/v2*100)[0:2], '%')
```

Previous covariance matrix :

```
_ij =
[[4.01749747 2.81880472]
 [2.81880472 2.31654261]]
63 %
```

New covariance matrix :

```
_ij =
[[ 5.62000353 -1.62844832]
 [-1.62844832  0.71403655]]
88 %
```

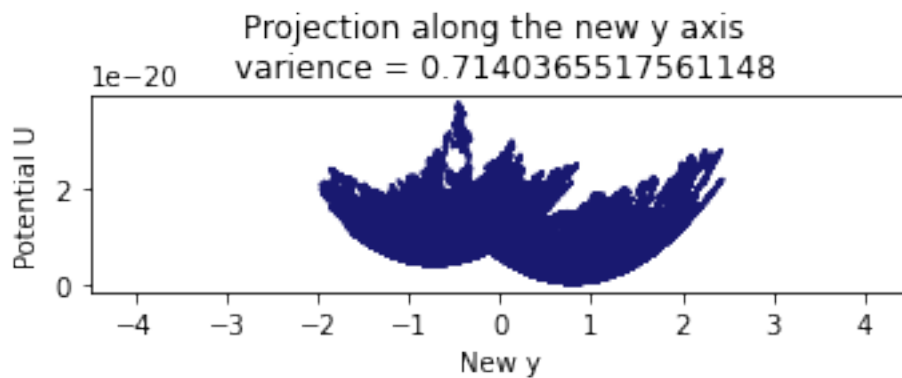
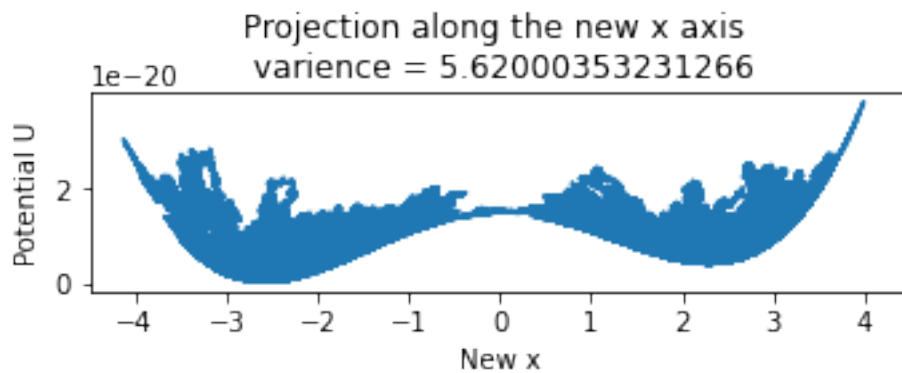
```
[34]: v1 = sigma[0,0]+ sigma[1,1]
v2 = sigma_new[0,0]+ sigma_new[1,1]
print(str(sigma[0,0]/v1*100)[0:2], '%', str(sigma_new[0,0]/v2*100)[0:2], '%')
```

63. % 88. %

```
[36]: plt.subplot(211)
plt.plot(x_rot_list, U_list)
t = 'Projection along the new x axis \n variance = ' + str(sigma_new[0,0])
plt.title(t)
plt.xlim(-4.5, 4.5)
plt.xlabel('New x')
plt.ylabel('Potential U')

plt.subplot(212)
plt.plot(y_rot_list, U_list, c = 'midnightblue')
t = 'Projection along the new y axis \n variance = ' + str(sigma_new[1,1])
plt.title(t)
plt.xlim(-4.5, 4.5)
plt.xlabel('New y')
plt.ylabel('Potential U')

plt.tight_layout()
plt.subplots_adjust(bottom=0.1, right=0.8, top=0.9)
plt.show()
```



From the covariance matrix and from the above plot of the data along our new x and y axis we can clearly see that most of the variance is not contained in the first component x (88% of the variance in contrast to 63% previously).

- “the histogram of Task III” is it not a plot that we are expecting?
- ΔG equivalent to U ???
- add comments on the percentages

[]: