

	<p>EXAMINATION QUESTIONS/SOLUTIONS 2007-08</p> <p>EEZ - MATHS PAPER 3 -</p> <p>SOLUTIONS 2008</p>	<p>Course</p> <p>①</p> <p>CORE</p>
<p>Question</p> <p>8</p>		<p>Marks &amp; seen/unseen</p>
<p>Parts</p>	<p>a) Take the principal branch <math>-\pi &lt; \arg z \leq \pi</math>.  <i>which is well-defined everywhere except at <math>z=0</math>.</i></p> <p>b) Yes, since <math>\frac{dw}{dz} = 1/z</math> <i>mapping is conformal except at <math>z=0</math>.</i></p> <p>c) If <math>z = re^{i\theta}</math>  then <math>w = u + iv = \log r + i\theta \Rightarrow \begin{matrix} u = \log r \\ v = \theta \end{matrix} \Rightarrow</math></p> <p><del>if</del> If <math>\theta = 0</math>, the positive real axis is mapped into the <math>u</math>-axis.</p> <p>d) A straight line <math>\theta = \alpha</math>, <math>-\pi &lt; \theta \leq \pi</math>  in the <math>z</math>-plane is mapped into the straight line <math>v = \alpha</math> in the <math>w</math>-plane.</p> <p>e) A <del>circle</del> <sup>circle</sup> with radius <math>r = a &gt; 0</math> &amp; center at the origin is mapped onto the line segment <math>\log a + i\theta</math> <math>-\pi &lt; \theta \leq \pi</math> in the <math>w</math>-plane.</p>	<p>②</p> <p>④</p> <p>①</p> <p>②</p> <p>②</p> <p>④</p>
	<p>Setter's initials</p> <p>PB</p>	<p>Page number</p>

Checker's initials

RLJ

CORE

Question

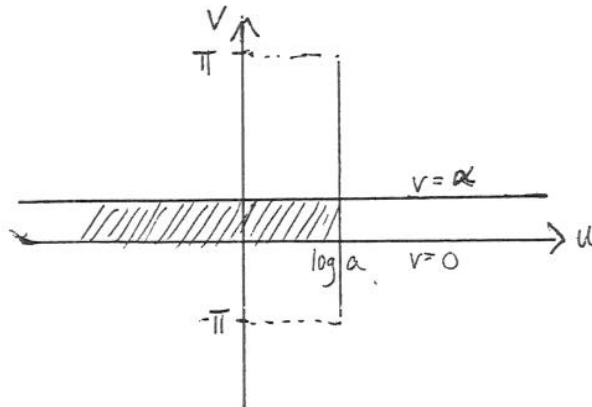
8

Marks &amp;

seen/unseen

## Parts

f)



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Page number

	EXAMINATION QUESTIONS/SOLUTIONS 2007-08	Course EE2 <b>(2)</b> Pap 3
Question 2		Marks & seen/unseen
Parts	$f(z) = \frac{z}{(z-1)^2(z-i)^2}$ <p>i) Res at the double pole at <math>z=1</math> is</p> $\lim_{z \rightarrow 1} \frac{d}{dz} \{ (z-1)^2 f(z) \} = \lim_{z \rightarrow 1} \frac{d}{dz} \left[ \frac{z}{(z-i)^2} \right]$ $= \lim_{z \rightarrow 1} \left\{ \frac{(z-i)^2 - 2z(z-i)}{(z-i)^4} \right\} = - \lim_{z \rightarrow 1} \frac{(z+i)}{(z-i)^3}$ $= - \frac{(1+i)}{(1-i)^3} = -(1+i)(1-3i-3+i)^{-1} = \frac{1}{2}$ <p>ii) Res at the double pole at <math>z=i</math> is</p> $\lim_{z \rightarrow i} \frac{d}{dz} \{ (z-i)^2 f(z) \} = \lim_{z \rightarrow i} \frac{d}{dz} \left[ \frac{z}{(z-1)^2} \right]$ $= \lim_{z \rightarrow i} \frac{(z-1)^2 - 2z(z-1)}{(z-1)^4} = - \lim_{z \rightarrow i} \frac{z+1}{(z-1)^3}$ $= - \frac{i+1}{(i-1)^3} = \frac{i+1}{(1-i)^3} = -1/2 \text{ from (i)}$ <p>iii)</p> $\oint_C f(z) dz = 2\pi i \left\{ \frac{1}{2} - \frac{1}{2} \right\} \text{ by R.T.}$ $= 0$ <p>as both poles at <math>z=1</math> &amp; <math>z=i</math> lie within <math>C</math>.</p>	<p>7</p> <p>7</p> <p>6</p>
	Setter's initials JDG <span style="margin-left: 100px;">Checker's initials Agw</span>	Page number 1

# EXAMINATION QUESTIONS/SOLUTIONS 2007-08

Course

3

EE2

pag 3

Question

3

Marks &

seen/unseen

Parts

i)

$$F(z) = \frac{e^{iz}}{z(z^2+4)}$$

Pole at  $z=0$

Poles at  $z = \pm 2i$

3

ii)

$$\text{Res at } z=0 \text{ is } \lim_{z \rightarrow 0} \left\{ \frac{ze^{iz}}{z(z^2+4)} \right\} = \frac{1}{4}$$

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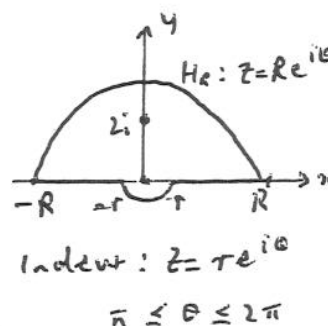
$$\text{" " } z=2i \text{ is } \lim_{z \rightarrow 2i} \left\{ \frac{(z-2i)e^{iz}}{z(z^2+4)} \right\} = -\frac{e^{-2}}{8}$$

3

iii)

$$\oint_C \frac{e^{iz}}{z(z^2+4)} = 2\pi i \left\{ \frac{1}{4} - \frac{e^{-2}}{8} \right\}$$

Now split up the contour into



2

$$\oint_C = \left( \int_{-R}^{-r} + \int_r^R \right) \frac{e^{ix} dx}{x(x^2+4)}$$

$$+ \int_{H_R} \frac{e^{iz} dz}{z(z^2+4)} + \int_{h_r} \frac{e^{iz} dz}{z(z^2+4)}$$

4

By Jordan's Lemma  $\lim_{R \rightarrow \infty} \int_{H_R} f(z) e^{iz} dz = 0$

because a) only singularities are poles

b)  $n=1 > 0$

c)  $|f(z)| \rightarrow 0$  fast enough as  $R \rightarrow \infty$ .

2

Thus we take the 2 limits  $R \rightarrow \infty, r \rightarrow 0$

$$\therefore 2\pi i \left\{ \frac{1}{4} - \frac{e^{-2}}{8} \right\} = \int_{-\infty}^{\infty} \frac{e^{ix} dx}{x(x^2+4)} + \lim_{r \rightarrow 0} \int_{h_r} \frac{e^{iz} dz}{z(z^2+4)}$$

$$\text{and } \lim_{r \rightarrow 0} \int_{h_r} \frac{e^{iz} dz}{z(z^2+4)} = \frac{i}{4} \int_{\pi}^{2\pi} d\theta = \frac{\pi i}{4}$$

2

$$\therefore \int_{-\infty}^{\infty} \frac{e^{ix} dx}{x(x^2+4)} = \pi i \left\{ \frac{1}{4} - \frac{e^{-2}}{4} \right\}$$

Now  $\int_{-\infty}^{\infty} f(x) e^{ix} dx = 0$  as  $f(x)$  is odd, thus

$$\int_{-\infty}^{\infty} \frac{\sin x dx}{x(x^2+4)} = \frac{\pi}{4} \{1 - e^{-2}\}$$

2

Setter's initials

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Checker's initials

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Page number

1

	EXAMINATION QUESTIONS/SOLUTIONS 2007-08	Course <b>4</b> EE2 Pap 3
Question <b>4</b>		Marks & seen/unseen
Parts	$\int_{-\infty}^{\infty} \frac{e^{iqt}}{t} dt = \int_{t=-\infty}^{t=\infty} \frac{e^{i\theta}}{\theta} d\theta \quad \theta = qt$ <p> <math>q &gt; 0 \quad t \in [-\infty, \infty] \rightarrow \theta \in [-\infty, \infty]</math>  <math>q &lt; 0 \quad \rightarrow \theta \in [\infty, -\infty]</math> </p> <p>Thus: <math>\int_{-\infty}^{\infty} \frac{e^{iqt}}{t} dt = \text{sgn}(q) \int_{-\infty}^{\infty} \frac{e^{i\theta}}{\theta} d\theta = i\pi \text{sgn}(q)</math></p> <hr/> <p>F.T. of <math>\frac{\sin \frac{1}{2}t}{\frac{1}{2}t}</math> is <math>2 \int_{-\infty}^{\infty} \frac{e^{-i\omega t}}{t} \sin(\frac{1}{2}t) dt</math></p> $= \frac{1}{i} \int_{-\infty}^{\infty} e^{-i\omega t} \frac{(e^{\frac{1}{2}it} - e^{-\frac{1}{2}it})}{t} dt$ $= \frac{1}{i} \left\{ \underbrace{\int_{-\infty}^{\infty} \frac{e^{i(\frac{1}{2}-\omega)t}}{t} dt}_{(1)} - \underbrace{\int_{-\infty}^{\infty} \frac{e^{-i(\frac{1}{2}+\omega)t}}{t} dt}_{(2)} \right\}$ <p>Now</p> $(1) = \begin{cases} i\pi & \omega < \frac{1}{2} \\ -i\pi & \omega > \frac{1}{2} \end{cases} \quad (2) = \begin{cases} i\pi & \omega < -\frac{1}{2} \\ -i\pi & \omega > -\frac{1}{2} \end{cases}$ <p> <math>\therefore \text{F.T.} = \begin{cases} 0 &amp; \omega &lt; -\frac{1}{2} &amp; \text{Cancellation} \\ 0 &amp; \omega &gt; \frac{1}{2} &amp; \text{Cancellation} \\ 2\pi &amp; -\frac{1}{2} &lt; \omega &lt; \frac{1}{2} &amp; \text{Addition.} \end{cases}</math> </p>	<p>6</p> <p>2</p> <p>4</p> <p>4</p> <p>4</p>
	Setter's initials JDC <span style="margin-left: 100px;">Checker's initials AJW</span>	Page number 1

	EXAMINATION QUESTIONS/SOLUTIONS 2007-08	Course <b>5</b> EE2 Pap 3
Question 5		Marks & seen/unseen
Parts	<p>i) <math>\int_{-\infty}^{\infty} f(t) g^*(t) dt</math></p> $= \left(\frac{1}{2\pi}\right)^2 \int_{-\infty}^{\infty} \left( \int_{-\infty}^{\infty} \bar{f}(\omega) e^{+i\omega t} d\omega \right) \left( \int_{-\infty}^{\infty} \bar{g}(\omega') e^{i\omega' t} d\omega' \right)^* dt$ $= \left(\frac{1}{2\pi}\right)^2 \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \bar{f}(\omega) \bar{g}^*(\omega') e^{i(\omega-\omega')t} dt d\omega' d\omega$ <p>Given that <math>\int_{-\infty}^{\infty} e^{i(\omega-\omega')t} dt = 2\pi \delta(\omega-\omega')</math> we have</p> $\int_{-\infty}^{\infty} f(t) g^*(t) dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \bar{f}(\omega) \bar{g}^*(\omega') \delta(\omega-\omega') d\omega' d\omega$ $= \frac{1}{2\pi} \int_{-\infty}^{\infty} \bar{f}(\omega) \bar{g}^*(\omega) d\omega \quad \square$ <p>ii) With <math>f(t) = e^{- t }</math> <math> t  = \begin{cases} t &amp; t &gt; 0 \\ -t &amp; t &lt; 0 \end{cases}</math></p> $\bar{f}(\omega) = \int_{-\infty}^0 e^{+(1-i\omega)t} dt + \int_0^{\infty} e^{-(1+i\omega)t} dt$ $= \frac{1}{1-i\omega} + \frac{1}{1+i\omega} = \frac{2}{1+\omega^2}$ $\bar{g}(\omega) = \frac{1}{t} \int_{-\infty}^{\infty} e^{-i\omega t} (e^{i\omega_0 t} + e^{-i\omega_0 t}) dt$ $= \pi \{ \delta(\omega - \omega_0) + \delta(\omega + \omega_0) \}$ $\therefore \int_{-\infty}^{\infty} e^{- t } \cos \omega_0 t dt = \frac{\pi}{2\pi} \int_{-\infty}^{\infty} \frac{2[\delta(\omega - \omega_0) + \delta(\omega + \omega_0)]}{1+\omega^2} d\omega$ $= \frac{2}{1+\omega_0^2}$	<p>Seen.</p> <p>4</p> <p>4</p> <p>Unseen.</p> <p>4</p> <p>4</p> <p>4</p>
	<p>Setter's initials JDE</p> <p>Checker's initials Agy</p>	Page number 1

	EXAMINATION QUESTIONS/SOLUTIONS 2007-08	Course <b>6</b> EE2 Pap3
Question 6		Marks & seen/unseen
Parts	<p> <math>\mathcal{L}(x) = s\bar{x}(s) - x(0)</math> Take <math>\mathcal{L}(\ddot{x}) = s^2\bar{x}(s) - sx(0) - \dot{x}(0)</math>  <math>\mathcal{L}(\ddot{x}) = \int_0^\infty e^{-st}\ddot{x} dt = \int_0^\infty e^{-st}d(\dot{x})</math>  <math>= [\dot{x} e^{-st}]_0^\infty + s\mathcal{L}(\dot{x})</math>  <math>= s^3\bar{x}(s) - s^2x(0) - s\dot{x}(0) - \ddot{x}(0)</math> </p> <p>Now <math>x(0) = \dot{x}(0) = \ddot{x}(0) = 0</math>; thus LT. the ODE</p> $(s^3 + 3s^2 + 3s + 1)\bar{x}(s) = \bar{f}(s)$ $\therefore \bar{x}(s) = \frac{\bar{f}(s)}{(s+1)^3}$ <p>Now we know i) <math>\mathcal{L}(t^n) = n!/s^{n+1}</math> (take)  ii) Shift Thm <math>\mathcal{L}(e^{at}f(t)) = \bar{f}(s-a)</math> (take)</p> <p><math>\therefore \mathcal{L}[\frac{1}{2}e^{-t}t^2] = \frac{1}{(s+1)^3}</math> choosing <math>n=2</math> in (i)  and <math>a=-1</math> in (ii)</p> <p>If <math>\bar{x}(s) = \bar{f}(s)\bar{g}(s)</math> where <math>f(t)</math> given  the Lap. conv. thm says <math>g(t) = \frac{1}{2}e^{-t}t^2</math></p> $x(t) = \int_0^t f(t-u)g(u)du = f * g$ <p>Thus <math>x(t) = \frac{1}{2} \int_0^t f(t-u)e^{-u}u^2 du.</math></p>	<p>5</p> <p>5</p> <p>2</p> <p>2</p> <p>2</p> <p>4</p>
	Setter's initials JDL	Checker's initials Agn
		Page number 1

# EXAMINATION QUESTIONS/SOLUTIONS 2007-08

Course **7**

EE2

Pap3

Question

7

Marks & seen/unseen

Parts

Choose  $\underline{v} = iP + jQ \Rightarrow \text{curl } \underline{v} = \underline{k}(Q_x - P_y)$

$\therefore \underline{v} \cdot d\underline{r} = Pdx + Qdy$   
 $\underline{k} \cdot \text{curl } \underline{v} = Q_x - P_y \} \therefore \text{G.T.} \rightarrow 2D, \text{ Stokes' Thm.}$

When  $\underline{v} = \frac{1}{2}(y^2 \underline{i} + x^2 \underline{j}) : \text{curl } \underline{v} = \underline{k}(x - y)$

$\therefore \iint_R (x - y) dx dy = \frac{1}{2} \oint_C (y^2 dx + x^2 dy)$

$C_1: y=0 \quad 0 \leq x \leq 2$

$\int_{C_1} = 0$

$C_2: x=2 \quad \int_{C_2} = 2 \int_0^{1/2} dy = 1$

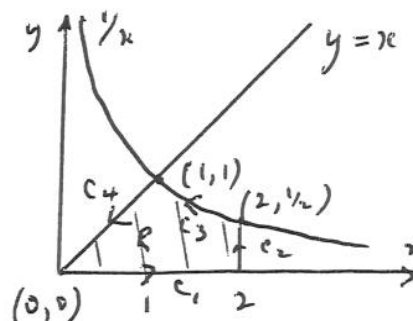
$C_3: y=1/x \quad dy = -dx/x^2$

$\int_{C_3} = \frac{1}{2} \int_2^1 \left( \frac{dx}{x^2} - dx \right) = -\frac{1}{2} \left[ x + \frac{1}{x} \right]_2^1 = \frac{1}{2} \left[ x + \frac{1}{x} \right]_1^2$   
 $= \frac{1}{2} \left( 2 + \frac{1}{2} \right) - \frac{1}{2} (1 + 1) = 1/4$

$C_4: y=x : dy = dx \quad \int_{C_4} = \frac{1}{2} \int_1^0 x^2 dx + x^2 dx$

$\therefore \int_{C_4} = -\int_0^1 x^2 dx = -1/3$

Total =  $0 + 1 + 1/4 - 1/3 = 5/4 - 1/3 = 11/12$ .



6

2

2 (pic)

4x2 (for each  $\int_{C_i}$ )

2

Via the double integral is also acceptable:

$\iint_R (x - y) dx dy = \int_0^1 \left\{ \int_0^x (x - y) dy \right\} dx + \int_1^2 \left\{ \int_0^{1/x} (x - y) dy \right\} dx$   
 $= \int_0^1 \left\{ x^2 - \frac{1}{2} x^2 \right\} dx + \int_1^2 \left\{ 1 - \frac{1}{2} \frac{1}{x} \right\} dx$   
 $= \frac{1}{6} + 1 + \frac{1}{2} \left( \frac{1}{2} - 1 \right) = \frac{1}{6} + \frac{3}{4} = \frac{22}{24} = 11/12$

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Page number

1



## EXAMINATION QUESTIONS/SOLUTIONS 2007-08

Course

EGE (3)

8

2nd Year.

solution

Question

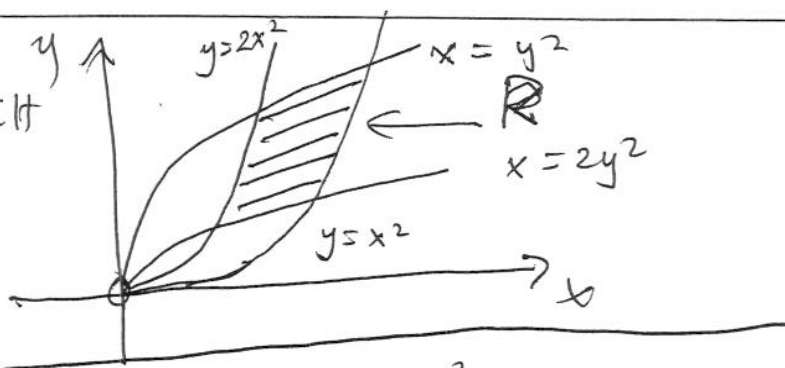
C3

Marks &  
seen/unseen

Parts

(1)

SKETCH



$$\text{When } y = x^2 \quad u = \frac{x^2}{y} = 1$$

$$\text{when } y = 2x^2 \quad u = \frac{x^2}{y} = \frac{1}{2}$$

$$\text{when } x = y^2 \quad v = \frac{y^2}{x} = 1$$

$$\text{when } x = 2y^2 \quad v = \frac{y^2}{x} = \frac{1}{2}$$

$$x^3 = \left(\frac{x^2}{y}\right)^2 \left(\frac{y^2}{x}\right) = u^2 v \Rightarrow x = (u^2 v)^{1/3}$$

$$y^3 = \left(\frac{y^2}{x}\right)^2 \left(\frac{x^2}{y}\right) = v^2 u \Rightarrow y = (u v^2)^{1/3}$$

$$J = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} \frac{2}{3} u^{-1/3} v^{1/3} & \frac{1}{3} u^{2/3} v^{-2/3} \\ \frac{1}{3} u^{-2/3} v^{2/3} & \frac{2}{3} u^{1/3} v^{-1/3} \end{vmatrix}$$

$$= \frac{4}{9} - \frac{1}{9} = \frac{1}{3}$$

Or else use  $\bar{J} = \frac{1}{J}$

$$\text{where } \bar{J}' = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix} = 3$$

R

Setter's initials

RW

Checker's initials

RB

Page number

## EXAMINATION QUESTIONS/SOLUTIONS 2007-08

 Course  
 EE 1(3)

8

Solution

Question

C3

 Marks &  
 seen/unseen

Parts

Further  $x, y = uv$

So Int =  $\int_{\frac{1}{2}}^1 \int_{\frac{1}{2}}^1 v e^{uv} J du dv$

$$= \frac{1}{3} \int_{\frac{1}{2}}^1 v \left[ \frac{1}{v} e^{uv} \right]_{u=\frac{1}{2}}^1 dv$$

$$= \frac{1}{3} \int_{\frac{1}{2}}^1 (e^v - e^{\frac{1}{2}v}) dv$$

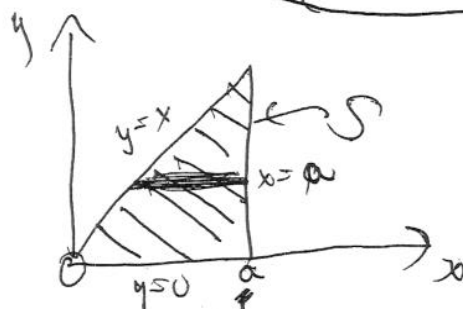
$$= \frac{1}{3} \left[ e^v - 2e^{\frac{1}{2}v} \right]_{\frac{1}{2}}^1 = \frac{(e - 2e^{\frac{1}{2}} - (-e^{\frac{1}{2}} + 2e^{\frac{1}{4}}))}{3}$$

$$= (e - 3e^{\frac{1}{2}} + 2e^{\frac{1}{4}})/3.$$

4

3

(ii)



omit

$$I_{02} = \int_{y=0}^{y=a} \int_{x=y}^{x=a} (x^2 + y^2) dx dy$$

$$= \int_{y=0}^a \left[ \frac{x^3}{3} + xy^2 \right]_{x=y}^{x=a} dy$$

$$= \int_0^a \left( \frac{a^3}{3} + ay^2 - \frac{y^3}{3} - y^3 \right) dy$$

$$= a^3 \left( \frac{1}{3} + \frac{1}{3} - \frac{1}{12} - \frac{1}{4} \right) = \frac{1}{3} a^4$$

20

Setter's initials

RLW

Checker's initials

PB

Page number

	EXAMINATION QUESTIONS/SOLUTIONS 2007-08	Course <b>EEII(3)</b> 9
Question C4	Solution	Marks & seen/unseen
Parts	$\text{grad } \varphi = \left( \frac{\partial \varphi}{\partial x}, \frac{\partial \varphi}{\partial y}, \frac{\partial \varphi}{\partial z} \right)$ $\text{curl grad } \varphi = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ \partial_x & \partial_y & \partial_z \\ \partial_x \varphi & \partial_y \varphi & \partial_z \varphi \end{vmatrix}$ $= \underline{i} (\partial_y \partial_z \varphi - \partial_z \partial_y \varphi) - \underline{j} (\partial_x \partial_z \varphi - \partial_z \partial_x \varphi) + \underline{k} (\partial_x \partial_y \varphi - \partial_y \partial_x \varphi) = 0.$ <hr/> $\text{curl } \underline{E} = \underline{i} (\partial_y E_3 - \partial_z E_2) - \underline{j} (\partial_x E_3 - \partial_z E_1) + \underline{k} (\partial_x E_2 - \partial_y E_1)$ $\text{div curl } \underline{E} = \cancel{\partial_x (\partial_y E_3 - \partial_z E_2)} + \cancel{\partial_y (\partial_x E_3 - \partial_z E_1)} + \partial_z (\partial_x E_2 - \partial_y E_1)$ <p>cancellation of terms in pairs gives result.</p> <hr/> <p>From <math>\underline{E} = \underline{A} + \text{grad } \varphi</math> it follows that <math>\text{curl } \underline{E} = \text{curl } \underline{A} + \text{curl grad } \varphi</math> Last term is zero so result <del>follows</del> follows.</p> <hr/> $\text{curl } \underline{E} = \underline{i}(0) - \underline{j}(0) + \underline{k}(ae^{ax} \sin y + e^{ax} \sin y)$ $\text{curl } \underline{A} = \underline{i}(1-1) - \underline{j}(0) + \underline{k}(+2e^{ax} \sin y)$ <p>These are equal if <math>a = 1</math>.</p>	<p>4</p> <p>4</p> <p>3</p> <p>4</p>
Setter's initials RLW	Checker's initials TB	Page number 1/2

Sol	EXAMINATION QUESTIONS/SOLUTIONS 2007-08	Course EEII(3) 9
Question C4		Marks & seen/unseen
Parts	<p>If <math>a = 1</math>      <math>\text{grad } \phi = \underline{\tilde{E}} - \underline{\tilde{A}}</math>      so</p> $\frac{\partial \phi}{\partial x} = -e^x \cos y - x$ $\frac{\partial \phi}{\partial y} = e^x \sin y - z$ $\frac{\partial \phi}{\partial z} = z^2 - y$ <p>Thus <math>\phi(x, y, z) = -e^x \cos y - \frac{x^2}{2} + f(y, z)</math></p> $\phi(x, y, z) = -e^x \cos y - zy + g(x, z)$ $\phi(x, y, z) = \frac{z^3}{3} - yz + h(x, y)$ <p>By comparison (or otherwise)</p> $\phi(x, y, z) = -e^x \cos y + \frac{z^3}{3} - yz - \frac{x^2}{2} + C.$	<p>5</p> <p>20</p>
Setter's initials RW	Checker's initials PB	Page number 2/2

	EXAMINATION QUESTIONS/SOLUTIONS 2007-08	Course EE II(3)
Solution	2nd Year	10
Question C5		Marks & seen/unseen
Parts	$\frac{\partial g}{\partial x} = -e^x(y \cos y + x \sin y + \sin y)$ $\frac{\partial f}{\partial y} = e^x(-x \sin y - \sin y - y \cos y)$ } Equal. Hence conservative.	3
	<hr/> $\frac{\partial \phi}{\partial x} = f = e^x(x \cos y - y \sin y) \quad \text{--- (1)}$ $\frac{\partial \phi}{\partial y} = g = -e^x(y \cos y + x \sin y) \quad \text{--- (2)}$ Integrate (1) wrt. $x$ to get $\phi(x,y) = e^x(x \cos y - y \sin y) - \int e^x \cos y dx$ $= e^x(x \cos y - y \sin y - \cos y) + h(y) \quad \text{--- (3)}$ Substitute (3) into (2) to get $e^x(-x \sin y - \sin y - y \cos y + \sin y) + \frac{dh}{dy}$ $= -e^x(y \cos y + x \sin y)$ $\Rightarrow \frac{dh}{dy} = 0 \Rightarrow h = C$ Thus $\phi(x,y) = e^x(x \cos y - y \sin y - \cos y) + C$ <hr/> Line integral is independent of path for a conservative field. Hence $I_{AB} = \phi(B) - \phi(A)$ $= \phi(1, \frac{\pi}{2}) - \phi(0,0) = \dots$	7
	Setter's initials RLJ	Checker's initials PB
		Page number

## EXAMINATION QUESTIONS/SOLUTIONS 2007-08

Course

EEII(3)

Sol

10

Question

C5

Marks &  
seen/unseen

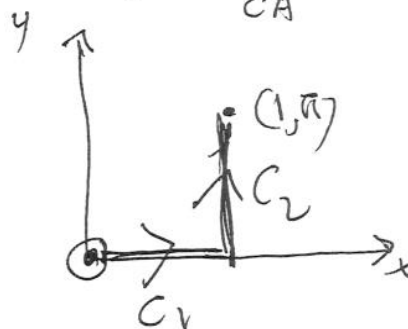
Parts

$$\text{Int} = e^{(1 \cdot 0 - 1 \cdot 0 - f(1))} - 1(0.1 - 0.0 - 1)$$

$$= 1$$

$$\text{Second integral} = \text{First integral} + \int_{CA}^B (x dx + \sin \frac{y}{2} dy)$$

CA path shown



$$\therefore \text{Second int} = 1 + \int_{C_1} + \int_{C_2}$$

On  $C_1$   $y=0$ ,  $dy=0$   $x$  ranges from 0 to 1

On  $C_2$   $x=1$ ,  $dx=0$   $y$  ranges from 0 to  $\pi$

$$\text{Thus Second int} = 1 + \int_0^1 x dx + \int_0^\pi \sin \frac{y}{2} dy$$

$$= 1 + \frac{1}{2} + \left[ -2 \cos \frac{y}{2} \right]_0^\pi$$

$$= 1 + \frac{1}{2} + 2 = 3\frac{1}{2}$$

7

20

Setter's initials

RL

Checker's initials

PB

Page number

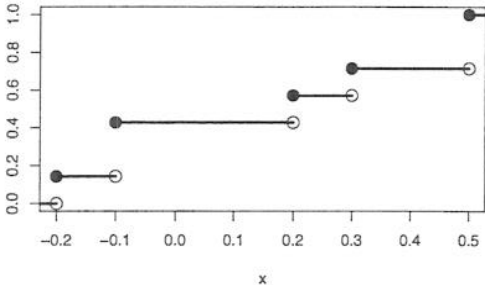
	EXAMINATION SOLUTIONS 2007-08	Course EE2(3) <span style="border: 1px solid black; border-radius: 50%; padding: 2px;">11</span>
Question 11		Marks & seen/unseen
Parts	<p>(i) <math>1 = \int_0^\pi k \sin(x) dx = -k \cos(x) _{x=0}^\pi = 2k</math>. Hence, <math>k = \frac{1}{2}</math>.</p> <p>(ii) <math>P(1 \leq X \leq 4) = \int_1^\pi \frac{\sin(x)}{2} dx = -\frac{1}{2} \cos(x) _{x=1}^\pi = \frac{1}{2}(\cos(1) + 1) \approx 0.770</math></p> <p>(iii) <math>P(X &gt; 2   X &gt; 1) = \frac{P(X &gt; 2)}{P(X &gt; 1)} = \frac{\int_2^\pi \frac{\sin(x)}{2} dx}{\frac{1}{2}(\cos(1)+1)} = \frac{\frac{1}{2}(\cos(2)+1)}{\frac{1}{2}(\cos(1)+1)} \approx 0.380</math></p> <p>(iv) <math>E(X) = \int_0^\pi x \sin(x)/2 dx = -x \cos(x)/2 _{x=0}^\pi - \int_0^\pi -\cos(x)/2 dx</math>  <math>= \frac{\pi}{2} + \sin(x)/2 _{x=0}^\pi = \frac{\pi}{2} \approx 1.57</math>  <math>E(X^2) = \int_0^\pi x^2 \sin(x)/2 dx = \frac{1}{2}[(2-x^2) \cos(x) + 2x \sin(x)] _{x=0}^\pi</math>  <math>= \frac{1}{2}[(2-\pi^2)(-1) - 2] = \pi^2/2 - 2 \approx 2.93</math>  <math>\text{Var}(X) = E(X^2) - (E(X))^2 = \pi^2/2 - 2 - \pi^2/4 = \frac{1}{4}\pi^2 - 2 \approx 0.467</math></p>	<p>3</p> <p>4</p> <p>4</p> <p>4</p> <p>3</p> <p>2</p> <p style="text-align: right;">Seen similar</p>
	Setter's initials <i>AG</i> Checker's initials <i>MJC</i>	Page number

	EXAMINATION SOLUTIONS 2007-08	Course EE2(3) <b>12</b>
Question 12		Marks & seen/unseen
Parts	<p>(i) A time series <math>\{e_t\}</math> is called white noise if  <math>E(e_t) = 0</math> for all <math>t</math>,  <math>\text{cov}(e_t, e_s) = 0</math> for all <math>t \neq s</math>  <math>\text{Var}(e_t)</math> does not depend on <math>t</math>.</p> <p>(ii) <math>\gamma(t, t) = \text{Var}(y_t) = 0.3^2 \text{Var}(e_t) + 0.5^2 \text{Var}(e_{t-1}) + 0.2^2 \text{Var}(e_{t-2})</math>  <math>= 0.3^2 + 0.5^2 + 0.2^2 = 0.38</math>  <math>\gamma(t, t+1) = \text{cov}(y_t, y_{t+1}) = 0.3 \cdot 0.5 \text{cov}(e_t, e_t) + 0.5 \cdot 0.2 \text{cov}(e_{t-1}, e_{t-1})</math>  <math>= 0.3 \cdot 0.5 + 0.5 \cdot 0.2 = 0.25</math>  <math>\gamma(t, t+2) = 0.3 \cdot 0.2 = 0.06</math>  <math>\gamma(t, t+k) = 0</math> for <math>k = 3, 4, \dots</math></p> <p>(iii) The covariance <math>\gamma(t, t+s)</math> is independent of <math>t</math> by (ii).  <math>\mu_t = E(y_t) = 0.3 E(e_t) + 0.5 E(e_{t-1}) + 0.2 E(e_{t-2}) = 0</math>  Since both <math>\mu_t</math> and <math>\gamma(t, t+s)</math> does not depend on <math>t</math>, the time series is stationary.</p> <p>(iv) <math>\gamma_1 = 0.25/0.38 \approx 0.658</math>  <math>\gamma_2 = 0.06/0.38 \approx 0.157</math>  <math>\gamma_k = 0</math> for <math>k = 3, 4, \dots</math></p> <p>(v) The spectrum is given by</p> $f(\omega) = \gamma_0 + 2 \sum_{k=1}^{\infty} \gamma_k \cos(k\omega) = 0.38 + 0.5 \cos(\omega) + 0.12 \cos(2\omega)$	<p>3</p> <p>8</p> <p>3</p> <p>3</p> <p>3</p> <p>Seen Similar</p>
	Setter's initials <i>AG</i> Checker's initials <i>MJC</i>	Page number



	<p>EXAMINATION QUESTIONS/SOLUTIONS 2007-08</p> <p>EE2 - MATHS PAPER 4 - SOLUTIONS 2008</p>	<p>Course ① EE2 Pap 4</p>
<p>Question 1</p>		<p>Marks &amp; seen/unseen</p>
<p>Parts</p>	<p>i) <math>A \underline{e}_i = \lambda_i \underline{e}_i</math> <sup>①</sup> Transpose &amp; c.c.  <math>\underline{e}_i^{*T} A^T = \lambda_i^* \underline{e}_i^{*T}</math> RH multiply by <math>\underline{e}_i</math>  <math>\therefore \underline{e}_i^{*T} A^T \underline{e}_i = \lambda_i^* \underline{e}_i^{*T} \underline{e}_i</math> — ②          Now take ① &amp; LH multiply by <math>\underline{e}_i^{*T}</math>  <math>\underline{e}_i^{*T} A \underline{e}_i = \lambda_i \underline{e}_i^{*T} \underline{e}_i</math> — ③          Compare ② &amp; ③ using <math>A^T = A : \Rightarrow \lambda_i = \lambda_i^*</math>          Hence <math>\lambda_i</math> are real.</p> <p>ii) Take ① &amp; LH multiply by <math>\underline{e}_j^T</math>  <math>\underline{e}_j^T A \underline{e}_i = \lambda_i \underline{e}_j^T \underline{e}_i</math> — ④          &amp; consider <math>A \underline{e}_j = \lambda_j \underline{e}_j \Rightarrow \underline{e}_j^T A = \lambda_j \underline{e}_j^T</math>          RH multiply this by <math>\underline{e}_i</math>  <math>\underline{e}_j^T A \underline{e}_i = \lambda_j \underline{e}_j^T \underline{e}_i</math> — ⑤          Subtract ⑤ from ④ : <math>\underline{e}_j^T \underline{e}_i (\lambda_j - \lambda_i) = 0</math>          We know <math>\lambda_i \neq \lambda_j \Rightarrow \underline{e}_j^T \underline{e}_i = 0</math> — ⑥</p> <p>iii) <math>P = \{ \underline{e}_1 \ \underline{e}_2 \ \dots \ \underline{e}_n \}</math> a row of col-vecs  <math>P^T = \begin{pmatrix} \underline{e}_1^T \\ \underline{e}_2^T \\ \vdots \\ \underline{e}_n^T \end{pmatrix}</math> col of row-vecs.  <math>\therefore P^T P = \{ \underline{e}_i^T \underline{e}_j \} = \begin{pmatrix} 1 &amp; &amp; 0 \\ &amp; \ddots &amp; \\ 0 &amp; &amp; 1 \end{pmatrix} = I</math> from ⑥</p>	<p>4  4  4</p>
	<p>Setter's initials JDC</p>	<p>Checker's initials Agw</p>
		<p>Page number 1</p>

	EXAMINATION QUESTIONS/SOLUTIONS 2007-08	Course <b>②</b> EE2 Pcp4
Question <b>2</b>		Marks & seen/unseen
Parts	<p> <math>A = \begin{pmatrix} 1 &amp; \sqrt{2} &amp; 0 \\ \sqrt{2} &amp; 1 &amp; \sqrt{2} \\ 0 &amp; \sqrt{2} &amp; 1 \end{pmatrix} \Rightarrow \begin{vmatrix} 1-\lambda &amp; \sqrt{2} &amp; 0 \\ \sqrt{2} &amp; 1-\lambda &amp; \sqrt{2} \\ 0 &amp; \sqrt{2} &amp; 1-\lambda \end{vmatrix} = 0</math> </p> <p> <math>\therefore (1-\lambda)[(1-\lambda)^2 - 2] = \sqrt{2}[\sqrt{2}(1-\lambda)]</math> </p> <p> <math>\therefore \lambda = 1 \text{ and } (1-\lambda)^2 = 4 \therefore \lambda^2 - 2\lambda - 3 = 0 \quad \lambda = -1</math>  <math>\lambda = 3</math> </p> <p> <math>\lambda_1 = 3 \quad \lambda_2 = 1 \quad \lambda_3 = -1</math> </p> <p> <math>\lambda_1 = 3 \quad \begin{pmatrix} -2 &amp; \sqrt{2} &amp; 0 \\ \sqrt{2} &amp; -2 &amp; \sqrt{2} \\ 0 &amp; \sqrt{2} &amp; -2 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0 \quad \begin{matrix} \sqrt{2}a = b \\ c + a = \sqrt{2}b \\ b = \sqrt{2}c \end{matrix} \quad \underline{e}_1 = \frac{1}{2} \begin{pmatrix} 1 \\ \sqrt{2} \\ 1 \end{pmatrix}</math> </p> <p> <math>\lambda_2 = 1 \quad \begin{pmatrix} 0 &amp; \sqrt{2} &amp; 0 \\ \sqrt{2} &amp; 0 &amp; \sqrt{2} \\ 0 &amp; \sqrt{2} &amp; 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0 \quad \begin{matrix} b = 0 \\ c = -a \\ b = 0 \end{matrix} \quad \underline{e}_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}</math> </p> <p> <math>\lambda_3 = -1 \quad \begin{pmatrix} 2 &amp; \sqrt{2} &amp; 0 \\ \sqrt{2} &amp; 2 &amp; \sqrt{2} \\ 0 &amp; \sqrt{2} &amp; 2 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = 0 \quad \begin{matrix} b = -\sqrt{2}a \\ a + c = -\sqrt{2}b \\ b = -\sqrt{2}c \end{matrix} \quad \underline{e}_3 = \frac{1}{2} \begin{pmatrix} 1 \\ -\sqrt{2} \\ 1 \end{pmatrix}</math> </p> <p> <math>Q = \underline{x}^T A \underline{x} \text{ with } A \text{ as above; write } \underline{x} = P \underline{y}</math> </p> <p> <math>\underline{x}^T = \underline{y}^T P^T \Rightarrow Q = \underline{y}^T (P^T A P) \underline{y}</math> </p> <p> <math>P^T A P = \Lambda \quad \left. \begin{matrix} \text{Reason } AP = P\Lambda \\ \Lambda = \begin{pmatrix} \lambda_1 &amp; 0 \\ 0 &amp; \lambda_2 &amp; 0 \\ 0 &amp; 0 &amp; \lambda_3 \end{pmatrix} \end{matrix} \right\} \text{ if } P = \{\underline{e}_1, \underline{e}_2, \underline{e}_3\} \left\{ \begin{matrix} P^T A P = \Lambda \\ P^T A P = \Lambda \end{matrix} \right.</math> </p> <p> <math>P = \begin{pmatrix} \frac{1}{2} &amp; \frac{1}{\sqrt{2}} &amp; \frac{1}{2} \\ \frac{1}{\sqrt{2}} &amp; 0 &amp; -\frac{1}{\sqrt{2}} \\ \frac{1}{2} &amp; -\frac{1}{\sqrt{2}} &amp; \frac{1}{2} \end{pmatrix} : Q = \underline{y}^T \Lambda \underline{y} = 3y_1^2 + y_2^2 - y_3^2</math> </p> <p> <math>\underline{y} = P^T \underline{x} = P^T \underline{x} \quad y_1 = \frac{1}{2}x_1 + \frac{1}{\sqrt{2}}x_2 + \frac{1}{2}x_3</math>  <math>y_2 = \frac{1}{\sqrt{2}}(x_1 - x_3)</math>  <math>y_3 = \frac{1}{2}x_1 - \frac{1}{\sqrt{2}}x_2 + \frac{1}{2}x_3</math> </p>	<p>3</p> <p>2</p> <p>2</p> <p>2</p> <p>2</p> <p>3</p> <p>2</p> <p>4</p>
Setter's initials JDE	Checker's initials Agyw	Page number 1

	EXAMINATION SOLUTIONS 2007-08	Course <b>EE2(4)</b> <b>3</b>
Question 3		Marks & seen/unseen
Parts (i)	<p>Empirical cdf <math>F_n(x)</math></p>  <p>(ii) <math>\bar{x} = \frac{1}{7}(-0.2 + 0.3 + \dots + 0.5) = 1.1/7 \approx 0.157</math> Median: 0.2</p> <p>(iii) Let <math>x_1, \dots, x_7</math> denote the observed values.</p> $s^2 = \frac{1}{7-1} \left( \sum_{k=1}^7 x_k^2 - \frac{1}{7} \left( \sum_{j=1}^7 x_j \right)^2 \right) = \frac{1}{6} \left( 0.69 - \frac{1}{7}(1.1)^2 \right)$ $\approx \frac{1}{6}(0.69 - 0.1729) = \frac{0.5171}{6} \approx 0.0862$ <p>so <math>s = \sqrt{s^2} \approx 0.2936</math>.</p> <p>(iv) From the Student t table we find <math>t_0 = t_{7-1,0.1} = 1.94</math>. The 90% confidence interval for <math>\mu</math> is thus</p> $\left( \bar{x} - t_0 \frac{s}{\sqrt{7}}, \bar{x} + t_0 \frac{s}{\sqrt{7}} \right) = \left( 0.157 - 1.94 \frac{0.2936}{\sqrt{7}}, 0.157 + 1.94 \frac{0.2936}{\sqrt{7}} \right)$ $\approx (-0.058, 0.372)$ <p>(v) The test statistic is <math>t = \frac{\bar{x}-0}{s/\sqrt{7}} = \frac{1.1/7}{0.2936/\sqrt{7}} \approx 1.42</math> Since we have one-sided hypotheses one should use a one-sided test. Taking into account that the formula sheet only gives two-sided values, the critical value is given by <math>t_0 = t_{6,0.1} = 1.94</math>. Since <math>t &lt; 1.94</math> the hypothesis <math>H_0</math> is not rejected.</p>	<p>3</p> <p>2</p> <p>1</p> <p>3</p> <p>1</p> <p>2</p> <p>2</p> <p>2</p> <p>2</p> <p>2</p>
	<p>Setter's initials <b>AG</b></p> <p>Checker's initials <b>MJC</b></p>	Page number

	EXAMINATION SOLUTIONS 2007-08	Course <b>EE2(4)</b> <span style="border: 1px solid black; border-radius: 50%; padding: 2px;">4</span>
Question 4		Marks & seen/unseen
Parts		
(i)	<p>We know that <math>\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) dy dx = 1</math>. Hence,</p> $  \begin{aligned}  1 &= k \int_0^1 \int_0^{1-y} xy^2 dx dy = k \int_0^1 \frac{1}{2} y^2 (1-y)^2 dy \\  &= k \frac{1}{2} \int_0^1 (y^4 - 2y^3 + y^2) dy = k \frac{1}{2} \left[ \frac{1}{5} y^5 - \frac{1}{2} y^4 + \frac{1}{3} y^3 \right]_{y=0}^1 \\  &= k \frac{1}{2} \left( \frac{1}{5} - \frac{2}{4} + \frac{1}{3} \right) = k \frac{1}{60}  \end{aligned}  $ <p>Hence, <math>k=60</math>.</p>	<div style="text-align: right; transform: rotate(90deg);">       Seen Similar     </div> <div style="text-align: right;">4</div>
(ii)	<p><math>f_X(x) = \int_{-\infty}^{\infty} f(x, y) dy</math>. Hence, <math>f_X(x) = 0</math> for <math>x &lt; 0</math> or <math>x &gt; 1</math>. For <math>0 \leq x \leq 1</math>,</p> $f_X(x) = \int_0^{1-x} kxy^2 dy = kx[y^3/3]_{y=0}^{1-x} = 20x(1-x)^3.$	<div style="text-align: right;">3</div>
(iii)	$  \begin{aligned}  E[X] &= \int_{-\infty}^{\infty} xf_X(x) dx = 20 \int_0^1 x^2(1-x)^3 dx \\  &= 20 \int_0^1 (-x^5 + 3x^4 - 3x^3 + x^2) dx \\  &= 20[-x^6/6 + 3x^5/5 - 3x^4/4 + x^3/3]_{x=0}^1 \\  &= 20(-1/6 + 3/5 - 3/4 + 1/3) = 1/3  \end{aligned}  $	<div style="text-align: right;">4</div>
(iv)	$  \begin{aligned}  E(XY) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xyf(x, y) dx dy = 60 \int_0^1 \int_0^{1-y} x^2 y^3 dx dy \\  &= 60 \int_0^1 y^3 (1-y)^3 / 3 dy = 20 \int_0^1 (-y^6 + 3y^5 - 3y^4 + y^3) dy \\  &= 20(-1/7 + 3/6 - 3/5 + 1/4) = 1/7 (\approx 0.143)  \end{aligned}  $ <p>Hence,</p> $\text{cov}(X, Y) = E(XY) - E(X)E(Y) = \frac{1}{7} - \frac{1}{3} \frac{1}{2} = -\frac{1}{42} \approx -0.024$	<div style="text-align: right;">3</div>
(v)	No, since $\text{cov}(X, Y) \neq 0$ .	<div style="text-align: right;">2</div>
(vi)	No, since they are correlated.	<div style="text-align: right;">2</div>
	Setter's initials <b>AG</b> Checker's initials <b>MJC</b>	Page number

	EXAMINATION SOLUTIONS 2007-08	Course EE2(4) <b>5</b>
Question 5		Marks & seen/unseen
Parts		
(i)	<p>For the <math>i</math>th student let <math>Y_i</math> denote the result of the spinner, let <math>Z_i = 1</math> if the student has cheated and <math>Z_i = 0</math> otherwise and let <math>X_i</math> denote the number the student reports.</p> <p>One can assume that <math>Y_i</math> and <math>Z_i</math> are independent. Hence,  <math>P(X_i = 1) = P(Y_i = 1, Z_i = 1) + P(Y_i = 0, Z_i = 0) = \theta p + (1 - \theta)(1 - p)</math>  <math>= \theta(2p - 1) + (1 - p).</math></p>	<p>3</p> <p>unseen</p>
(ii)	$P(X_i = 0) = 1 - P(X_i = 1) = 1 - (\theta(2p - 1) + (1 - p)) = \theta(1 - 2p) + p$	1
(iii)	<p>The likelihood function is given by</p> $L(\theta) = P(X_i = 1)^{\sum_{i=1}^n X_i} P(X_i = 0)^{n - \sum_{i=1}^n X_i}$ $= (\theta(2p - 1) + (1 - p))^{\sum_{i=1}^n X_i} (\theta(1 - 2p) + p)^{n - \sum_{i=1}^n X_i}$ <p>Differentiating the loglikelihood leads to the equation</p> $\sum_{i=1}^n X_i \frac{2p - 1}{\hat{\theta}(2p - 1) + (1 - p)} + (n - \sum_{i=1}^n X_i) \frac{1 - 2p}{\hat{\theta}(1 - 2p) + p} = 0$ <p>for the maximum likelihood estimator <math>\hat{\theta}</math>. Since <math>p \neq 1/2</math> this is equivalent to</p> $-\sum_{i=1}^n X_i (\hat{\theta}(1 - 2p) + p) + (n - \sum_{i=1}^n X_i) (\hat{\theta}(2p - 1) + (1 - p)) = 0$ <p>Hence,</p> $\hat{\theta} = \frac{p \sum_{i=1}^n X_i - (n - \sum_{i=1}^n X_i)(1 - p)}{-\sum_{i=1}^n X_i(1 - 2p) + (n - \sum_{i=1}^n X_i)(2p - 1)}$ $= \frac{\sum_{i=1}^n X_i - n(1 - p)}{n(2p - 1)} = \frac{\frac{1}{n} \sum_{i=1}^n X_i - (1 - p)}{2p - 1}$	<p>4</p> <p>4</p>
(iv)	$E_{\theta}(\hat{\theta}) = \frac{1}{2p-1} (\frac{1}{n} \sum_{i=1}^n E(X_i) + p - 1) = \frac{1}{2p-1} (\theta(2p - 1) + 1 - p + p - 1)$ $= \theta$ <p>Hence, <math>\hat{\theta}</math> is an unbiased estimator for <math>\theta</math>.</p>	<p>4</p>
	<p>Setter's initials AG</p> <p>Checker's initials MJC</p>	Page number

	EXAMINATION SOLUTIONS 2007-08	Course EE2(4) <b>6</b>
Question 6		Marks & seen/unseen
Parts	<p>(i) For <math>0 &lt; x &lt; 1</math>:  <math>F_{X^5}(x) = P(X^5 \leq x) = P(X \leq x^{1/5}) = F_X(x^{1/5}) = x^{1/5}</math>  Hence, <math>f_{X^5}(x) = \frac{d}{dx} x^{1/5} = x^{-4/5}/5</math>.  For <math>x \leq 0</math> or <math>x \geq 1</math> we have <math>f_{X^5}(x) = 0</math>.</p> <p>(ii) Since <math>X</math> and <math>Y</math> are independent, <math>\text{cov}(X, Y) = 0</math>.  Hence, from the formula sheet: <math>X + Y</math> is <math>N(0 + 5, 1 + 3)</math>, i.e. <math>N(5, 4)</math>.</p> <p>(iii) For <math>t &gt; 0</math>,  <math display="block">f_{X+Y}(t) = (f_X * f_Y)(t)</math> <math display="block">= \int_0^{\min(t,1)} \lambda e^{-\lambda(t-y)} dy</math> <math display="block">= e^{-\lambda t} \int_0^{\min(t,1)} \lambda e^{\lambda y} dy = e^{-\lambda t} (e^{\lambda \min(t,1)} - 1)</math> <math display="block">= \begin{cases} e^{-\lambda t} (e^\lambda - 1) &amp; \text{if } 1 \leq t \\ 1 - e^{-\lambda t} &amp; \text{if } 0 &lt; t &lt; 1 \end{cases}</math> <math>f_{X+Y}(t) = 0 \text{ for } t \leq 0.</math></p>	<p>4 3 1</p> <p>4</p> <p>8</p> <p>Seen Similar</p>
	<p>Setter's initials AG</p> <p>Checker's initials MJC</p>	Page number