

SOLUTIONS: COMPLEX CALCULUS EE2L

1. Exercise

- a) (similar to examples done in class) The curve $\partial^+ B$ can be parameterized as γ given below:

$$\gamma(t) = e^{it}, \quad t \in [0, 2\pi].$$

By definition of integral of complex variable we have:

$$\int_{\partial^+ B} \frac{e^{iz}}{z} dz = \int_0^{2\pi} \frac{e^{i\gamma(t)}}{\gamma(t)} \dot{\gamma}(t) dt.$$

[2]

Since $\dot{\gamma}(t) = ie^{it}$ we see that:

$$\begin{aligned} \int_{\partial^+ B} \frac{e^{iz}}{z} dz &= \int_0^{2\pi} ie^{i(\cos(t) + i\sin(t))} dt = \\ &= \int_0^{2\pi} ie^{-\sin(t)} e^{i\cos(t)} dt = \\ &= \int_0^{2\pi} ie^{-\sin(t)} [\cos(\cos(t)) + i\sin(\cos(t))] dt. \end{aligned}$$

This proves that:

$$I = \operatorname{Im} \left[\int_{\partial^+ B} \frac{e^{iz}}{z} dz \right].$$

[2]

- b) (similar to results derived in class) The function e^{iz} is a composition of holomorphic functions (multiplication times complex scalar and complex exponential). It is therefore holomorphic in \mathbb{C} . The function z is also holomorphic in \mathbb{C} , therefore their ratio is holomorphic whenever the denominator is different from 0. This is also the domain of definition of the function. The point $z = 0$ is the only singularity, and it is a pole of multiplicity 1, as it is easily verified by noticing that $e^{i0} = 1 \neq 0$ and realizing that $z \cdot \frac{e^{iz}}{z} = e^{iz}$ for all $z \neq 0$, which, as previously claimed is holomorphic.

[3]

- c) (similar to examples done in class) The residue of the function at 0 is given by:

$$\lim_{z \rightarrow 0} z \frac{e^{iz}}{z} = e^{i0} = 1.$$

Hence, by the Residue's theorem:

$$\int_{\partial^+ B} \frac{e^{iz}}{z} dz = 2\pi i \cdot 1 = 2\pi i.$$

It follows that $I = 2\pi$.

[3]

- d) (similar to problems solved in class) Differentiating u with respect to x and y yields:

$$\frac{\partial u}{\partial x} = e^x \cos(y) + e^{-y} \cos(x),$$

$$\frac{\partial u}{\partial y} = -e^x \sin(y) - e^{-y} \sin(x).$$

[1]

Differentiating again, yields:

$$\frac{\partial^2 u}{\partial x^2} = e^x \cos(y) - e^{-y} \sin(x),$$

$$\frac{\partial^2 u}{\partial y^2} = e^{-y} \sin(x) - e^x \cos(y).$$

[2]

It is easy to see that:

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0,$$

which proves that u is a solution of the Laplace's equation in \mathbb{R}^2 and hence harmonic.

[1]

- e) (similar to problems solved in class) To find the conjugate v we exploit the Cauchy-Riemann's equations. In particular:

$$\frac{\partial v}{\partial y} = \frac{\partial u}{\partial x} = e^x \cos(y) + e^{-y} \cos(x).$$

This implies:

$$\begin{aligned} v(x, y) &= \int e^x \cos(y) + e^{-y} \cos(x) dy = \\ &= e^x \sin(y) - e^{-y} \cos(x) + c_1(x), \end{aligned}$$

where $c_1(x)$ is an arbitrary function of x .

[1]

Similarly:

$$\frac{\partial v}{\partial x} = -\frac{\partial u}{\partial y} = e^x \sin(y) + e^{-y} \sin(x).$$

This implies:

$$\begin{aligned} v(x, y) &= \int e^x \sin(y) + e^{-y} \sin(x) dx = \\ &= e^x \sin(y) - e^{-y} \cos(x) + c_2(y), \end{aligned}$$

where c_2 is an arbitrary function of y .

[1]

Equating the previous expressions for v yields:

$$c_1(x) = c_2(y) = c$$

for some scalar $c \in \mathbb{R}$. Hence:

$$v(x, y) = e^x \sin(y) - e^{-y} \cos(x) + c.$$

[2]

- f) (similar to examples done in class) To find the function g as requested we evaluate $u + iv$ on the real axis ($y = 0$). This gives:

$$u(x, 0) + iv(x, 0) = e^x + \sin(x) + i[-\cos(x) + c].$$

Hence we may let:

$$g(z) = e^z + \sin(z) - i\cos(z) + ic = e^z - ie^{iz} + ic.$$

The function $g(z)$ equals $u(x, y) + iv(x, y)$ on the real axis, and is clearly holomorphic. Hence it coincides with $u(x, y) + iv(x, y)$ for all $(x, y) \in \mathbb{R}^2$. [3]

- g) (unseen) A holomorphic function g is conformal at every point where $g'(z) \neq 0$. Hence, provided z is such that:

$$g'(z) = e^z + e^{-iz} \neq 0$$

[1]

Notice that, to have

$$e^z = -e^{-iz} = e^{-i(z+\pi)}$$

we need:

$$\operatorname{Re}(z) = \operatorname{Re}(-i(z + \pi)) = \operatorname{Im}(z)$$

(which implies the two sides of the previous equation have the same modulus), and

$$\operatorname{Im}(z) + 2k\pi = \operatorname{Im}(-i(z + \pi))$$

(which implies the two sides of the previous equation have the same argument). [2]

We have a (linear) system of two equations in two real unknowns, $\operatorname{Re}(z)$, $\operatorname{Im}(z)$, whose solution is:

$$\operatorname{Re}(z) = \operatorname{Im}(z) = \frac{2k+1}{2}\pi,$$

with k an arbitrary integer. Hence there are infinitely many point in \mathbb{C} where g is not conformal, these are:

$$z = \frac{2k+1}{2}\pi + i\frac{2k+1}{2}\pi, \quad k \in \mathbb{Z}.$$

[1]

2. Exercise (Similar to equations solved in class)

- a) Let $X(s)$ denote $\mathcal{L}[x]$. Then $\mathcal{L}[dx/dt] = sX(s)$ and $\mathcal{L}[d^3x/dt^3] = s^3X(s)$. Applying Laplace's transforms to both sides of the differential equation yields:

$$(s^3 + 3s - 4)X(s) = \frac{1}{s}.$$

[6]

Solving with respect to $X(s)$ yields:

$$X(s) = \frac{1}{s(s^3 + 3s - 4)}.$$

[4]

Notice that: $(s^3 + 3s - 4) = (s - 1)(s^2 + s + 4)$, therefore:

$$X(s) = \frac{A}{s-1} + \frac{Bs+C}{s^2+s+4} + \frac{D}{s}$$

with:

$$A = \lim_{s \rightarrow 1} (s-1)X(s) = \frac{1}{6}$$

$$D = \lim_{s \rightarrow 0} sX(s) = -\frac{1}{4}$$

$$C = -\frac{1}{12}, \quad B = \frac{1}{12}.$$

[5]

Taking inverse Laplace's transforms yields:

$$x(t) = \frac{e^t}{6} + \frac{e^{-\frac{t}{2}} \left(\cos\left(\frac{\sqrt{15}t}{2}\right) - \frac{\sqrt{15} \sin\left(\frac{\sqrt{15}t}{2}\right)}{5} \right)}{12} - \frac{1}{4}.$$

[5]

- b) Since $x(t)$ needs to be constant we do have $\dot{x}(t) \equiv 0$, $\ddot{x}(t)$ and $x^{(3)}(t) \equiv 0$ for all $t > 0$. In particular, then, $-4x(t) = 1$ for all $t > 0$. Since \dot{x} , \ddot{x} and x are continuous in t we may pick:

$$x(0) = -\frac{1}{4}, \quad \dot{x}(0) = 0, \quad \ddot{x}(0) = 0.$$

[5]