

Paper Number(s): **E4.10**  
**C2.1**  
**SC4**

IMPERIAL COLLEGE OF SCIENCE, TECHNOLOGY AND MEDICINE  
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DEPARTMENT OF ELECTRICAL AND ELECTRONIC ENGINEERING  
EXAMINATIONS 2001

MSc and EEE PART IV: M.Eng. and ACGI

**PROBABILITY AND STOCHASTIC PROCESSES**

Wednesday, 9 May 10:00 am

There are SIX questions on this paper.

Answer FOUR questions.

Time allowed: 3:00 hours

**Corrected Copy**

4, 3, 5, 6

Examiners: Vinter, R.B. and Clark, J.M.C.

**Special instructions for invigilators:**

None

**Information for candidates:**

None

- 1(a) A source signal  $X$  and a transmitted signal  $Z$  are modelled as binary random variables taking values 0 and 1.

A received signal  $Y$  is modelled as

$$Y = NZ$$

in which  $N$  is a binary random variable which takes values 0 or 1 and is independent of  $X$  and  $Z$ . ( $N = 0$  corresponds to receiver failure.)

Assume that

$$P[X = 0] = P[X = 1] = 1/2$$

$$P[Z = 0|X = 0] = P[Z = 1|X = 1] = \alpha$$

$$P[N = 1] = p.$$

A signal  $Y = 0$  is received. What is the probability that the source signal was  $X = 0$ ?

- 1(b) A section of a communication link is modelled as indicated in *Figure 1*. The possible states of each switch  $S_1, \dots, S_5$  are *open* and *closed*. The events

$$S_i \text{ is closed} \quad i = 1, \dots, 5$$

are independent and

$$P[S_i \text{ is closed}] = q \quad \text{for each } i.$$

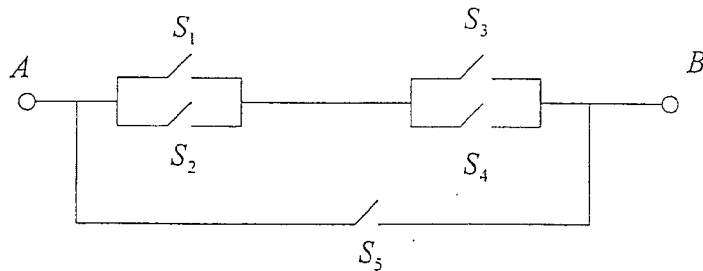
Calculate the probability that there is a closed path between points  $A$  and  $B$ .

Now suppose that a communication link is composed of identical sections, connected in series. Suppose that the states of all switches are independent,

$$q = (1 - 10^{-3})$$

and that the length of each section is 1 metre. What is the maximum length of the communication link such that

$$P[\text{there is a closed path through the entire link}] \geq 0.99?$$



*Figure 1*

2 A signal  $X(\omega)$ , corrupted by a bias  $n$ , is rectified by a device with characteristic

$$R(x) = \begin{cases} x^2 & \text{for } x \geq 0 \\ 0 & \text{for } x < 0. \end{cases}$$

$X(\omega)$  is modelled as a random variable with uniform probability density function

$$f_X(x) = \begin{cases} 1/2 & \text{for } -1 \leq x \leq +1 \\ 0 & \text{otherwise} \end{cases}.$$

The bias  $n$  is taken to be a constant ( $0 \leq n \leq 1$ ). See *Figure 2*.

Write  $Z(\omega)$  and  $Z^*(\omega)$  for the rectified noisy signal and the rectified noise-free signal respectively:

$$Z(\omega) = R(X(\omega) + n)$$

$$Z^*(\omega) = R(X(\omega)).$$

Calculate the average power of the rectifier output error, namely

$$E[(Z(\omega) - Z^*(\omega))^2].$$

(Assume  $n$  is small, so that terms involving  $n^3$ ,  $n^4$ , etc., can be ignored).

Hence determine the signal to noise ratios  $S_{in}$  and  $S_{out}$  at the input and output of the rectifier respectively

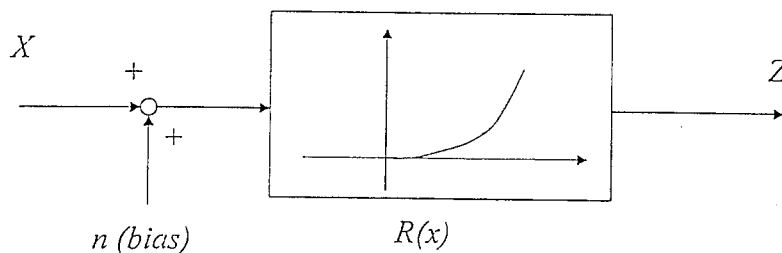
$$S_{in} = \frac{n^2}{E[X^2(\omega)]} \quad \text{and} \quad S_{out} = \frac{E[(Z(\omega) - Z^*(\omega))^2]}{E[Z^{*2}(\omega)]}.$$

Notice that  $S_{in} \neq S_{out}$ . Is this a nonlinear phenomenon, i.e., is it possible that  $S_{in} \neq S_{out}$  if the nonlinear characteristic  $R(x)$  were replaced by a pure gain  $Kx$  ( $K \neq 0$ )?

*Hint:* obtain formulae for  $R(x+n) - R(x)$  in the regions

$$(i) \ x < -n \quad (ii) \ -n \leq x \leq 0 \quad (iii) \ x \geq 0.$$

Do not attempt to calculate the distribution function of  $Z(\omega)$ .



*Figure 2*

- 3(a) Let  $X(\omega)$  and  $Y(\omega)$  be jointly distributed, zero mean, normal random variables, with variance  $\sigma^2$  and correlation coefficient  $r$ ,  $-1 < r < +1$ :

$$f_{XY}(x, y) = \frac{1}{\sqrt{\pi(1-r^2)}\frac{1}{2}\sigma^2} \exp \left\{ -\frac{1}{2\sigma^2(1-r^2)} (|x - ry|^2 + (1-r^2)y^2) \right\}.$$

Derive the conditional probability density  $f_{X|Y}(x; y)$  of  $X(\omega)$  given  $Y(\omega) = y$ . Show that the mean and variance of the conditional probability density are

$$\begin{aligned} m_{X|Y}(y) &= ry, \\ \text{var}_{X|Y}(y) &= \sigma^2(1-r^2). \end{aligned}$$

- 3(b) Now interpret  $X(\omega)$  as a signal and  $Y(\omega)$  as a measurement of the signal and

$$\hat{X}(y) = m_{X|Y}(y)$$

as an estimator of  $X(\omega)$  given  $Y(\omega) = y$ .

The higher the quality of the sensor, the larger is the absolute value of the correlation coefficient. Assume

$$\text{sensor cost} = \frac{10}{1-|r|^2} \quad (\text{\$/s})$$

What is the minimum cost of the sensor, if we require

$$\text{var}_{X|Y}(y) \leq 0.01 E[|X(\omega)|^2] \quad ?$$

(In part (a), you can use the fact that

$$f(x) = \frac{1}{(\sqrt{2\pi}\sigma)^{\frac{1}{2}}} \exp \left\{ -\frac{1}{2\sigma^2}(x-m)^2 \right\}$$

is the probability density function of a random variable with mean  $m$  and variance  $\sigma^2$ .)

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- 4 A transmitted signal  $X(\omega)$  is modelled as a continuous random variable with probability density function  $f_X(x)$ . The received signal  $Y(\omega)$  has a random offset  $N(\omega)$ :

$$Y(\omega) = X(\omega) + N(\omega).$$

The offset is modelled as a discrete random variable, independent of  $X(\omega)$ , with

$$P[N(\omega) = 0] = p \quad \text{and} \quad P[N(\omega) = \frac{1}{2}] = (1 - p).$$

Show that the conditional probability mass function of  $X(\omega)$  given  $Y(\omega) = y$  is

$$P[X(\omega) = y | Y(\omega) = y] = \frac{pf_X(y)}{pf_X(y) + (1-p)f_X(y - \frac{1}{2})} \quad ,$$

$$P[X(\omega) = y - \frac{1}{2} | Y(\omega) = y] = \frac{(1-p)f_X(y - \frac{1}{2})}{pf_X(y) + (1-p)f_X(y - \frac{1}{2})} \quad .$$

Hence derive a formula for the least squares estimate

$$\hat{X} = g(y)$$

of  $X(\omega)$  given  $Y(\omega) = y$ .

Evaluate  $g(y)$  in the case when

$$f_X(x) = \begin{cases} 1 & 0 \leq x \leq 1 \\ 0 & \text{otherwise.} \end{cases}$$

Comment on the results.

*Hint:* In the last part of the question, consider separately the cases

$$(i) \ 0 \leq y < \frac{1}{2}, \quad (ii) \ \frac{1}{2} \leq y \leq 1, \quad (iii) \ 1 < y \leq 1\frac{1}{2}$$

- 5(a) An  $r$ -vector stationary stochastic process  $\{y_k\}$  is modelled by the state space equations

$$x_{k+1} = Ax_k + be_k \quad y_k = Cx_k$$

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in which  $A$  is a 'stable'  $n \times n$  matrix,  $b$  is an  $n$ -vector,  $C$  is an  $r \times n$  matrix and  $\{e_k\}$  is a sequence of zero mean, independent scalar random variables with common variance

$$E[e_k^2] = \sigma^2.$$

Derive a set of equations, including the matrix Lyapunov equation, for the covariance function  $R_y(l)$ ,  $l = \dots, -1, 0, +1, \dots$

- 5(b) Consider the two stationary scalar processes  $\{u_k\}$  and  $\{v_k\}$  modelled by the difference equations:

$$\begin{aligned} u_{k+1} &= v_k + e_k \\ v_{k+1} &= -au_k + e_k. \end{aligned}$$

Here,  $a$  is a modelling parameter and  $\{e_k\}$  is a sequence of zero mean, independent scalar random variables with common variance

$$E[e_k^2] = \sigma^2.$$

It is known that the covariance functions  $R_u(l)$  and  $R_v(l)$  of  $\{u_k\}$  and  $\{v_k\}$  satisfy

$$R_v(0) = \frac{5}{8}R_u(0).$$

By using the results of Part (a), or otherwise, determine the value of  $a$ .

- 6(a) Define the spectral density  $\Phi_r(\omega)$  of a stationary, second order, zero mean, scalar stochastic process  $\{r_k\}$ .

Now suppose that

$$r_k = u_k + v_k, \quad k = \dots, -1, 0, +1, \dots$$

for stationary, second order, zero mean, scalar stochastic processes  $\{u_k\}$  and  $\{v_k\}$  such that

$u_k$  and  $v_j$  are independent for all  $k, j$ .

Show that

$$\Phi_r(\omega) = \Phi_u(\omega) + \Phi_v(\omega).$$

- 6(b) A transmitted signal  $\{s_k\}$  is modelled as a stationary, zero mean, scalar stochastic process satisfying

$$(2 - z^{-1})s_k = e_k,$$

in which  $\{e_k\}$  is a scalar, unit variance, white noise process.

Due to the presence of noise and channel distortion, the received signal  $\{r_k\}$  is the solution to the difference equation

$$(3 - z^{-1})r_k = s_k + d_k.$$

Here, the disturbance process  $\{d_k\}$  is generated by the equation

$$d_k = D(z)\tilde{e}_k,$$

in which  $D(z)$  is an unknown transfer function and  $\{\tilde{e}_k\}$  is a unit variance, white noise process, independent of  $\{e_k\}$ . See *Figure 3*.

The spectral density of the received signal  $\{r_k\}$  is known to be

$$\Phi_r(\omega) = \frac{1 + (17 - 4e^{j\omega} - 4e^{-j\omega})(5 - 2e^{j\omega} - 2e^{-j\omega})}{(5 - 2e^{j\omega} - 2e^{-j\omega})(10 - 3e^{j\omega} - 3e^{-j\omega})}.$$

Find the transfer functions  $G_1(z)$  and  $G_2(z)$  such that

$$r_k = u_k + v_k, \text{ where } u_k = G_1 e_k, v_k = G_2 \tilde{e}_k.$$

By using the results of Part (a), or otherwise, determine the transfer function  $D(z)$  which generates the disturbance process  $\{d_k\}$ .

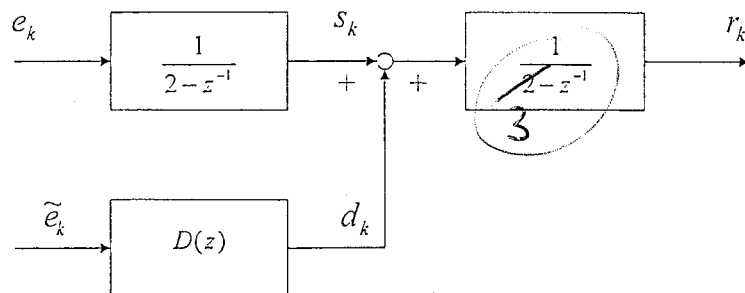


Figure 3



## Prob. &amp; Stoch. Processes Exam, 2001. Model Answers

$$\begin{aligned}
 1(i) \quad P[X=0|Y=0] &= \frac{P[X=0 \& Y=0]}{P[Y=0]} = \frac{P[X=0 \& Y=0|N=0] \cdot P[N=0]}{P[Y=0]} \\
 &= \frac{P[X=0] P[N=0] + P[X=0 \& Z=0] \cdot P[N=1]}{P[Y=0|N=0] P[N=0] + P[Y=0|N=1] P[N=1]} \\
 &= \frac{P[X=0] P[N=0] + P[Z=0|X=0] P[X=0] \cdot P[N=1]}{P[N=0] + P[Z=0] P[N=1]} = \frac{\frac{1}{2}(1-p) + \frac{1}{2} \kappa p}{(1-p) + P[Z=0] p}
 \end{aligned}$$

$$\begin{aligned}
 \text{But } P[Z=0] &= P[Z=0|X=0] P[X=0] + P[Z=0|X=1] P[X=1] \\
 &= \kappa \frac{1}{2} + (1-\kappa) \frac{1}{2} = \frac{1}{2}
 \end{aligned}$$

$$\underline{8} \quad \text{Hence } P[X=0|Y=0] = \frac{\frac{1}{2}(1-p) + \frac{1}{2} \kappa p}{1-p + \frac{1}{2} p} = \frac{1 - (1-\kappa)p}{2-p}$$

(ii) The event "there is a closed path between A and B" is  
 $Q = [(S_1 \cup S_2) \cap (S_3 \cup S_4)] \cup S_5$ . Write  $\bar{Q}$  = "complement of Q", etc.  
 Then  $\bar{Q} = \bar{S}_5 \cap \overline{(S_1 \cup S_2) \cap (S_3 \cup S_4)}$  (Here  $S_i = \{S_i \text{ is closed}\}$ , etc.)  
 But

$$\begin{aligned}
 P[(S_1 \cup S_2) \cap (S_3 \cup S_4)] &= P[S_1 \cup S_2] \cdot P[S_3 \cup S_4] \quad (\text{by independence}) \\
 &= (1 - P[\bar{S}_1 \cap \bar{S}_2]) (1 - P[\bar{S}_3 \cap \bar{S}_4]) \\
 &= (1 - P[\bar{S}_1] \cdot P[\bar{S}_2]) (1 - P[\bar{S}_3] \cdot P[\bar{S}_4]) \quad (\text{by independence}) \\
 &= (1 - (1-q)^2)^2
 \end{aligned}$$

Hence  $P[(S_1 \cup S_2) \cap (S_3 \cup S_4)] = 1 - (1 - [1-q]^2)^2$ . It follows that

$$P[Q] = 1 - P[\bar{Q}] = 1 - P[\bar{S}_5] (1 - (1 - (1-q)^2)^2) \quad (\text{by independence})$$

Then

$$\begin{aligned}
 P(Q) &= 1 - (1-q) (1 - (1-q)^2 + 2(1-q)^2 - (1-q)^4) \\
 &= \underline{1 - (1-q)^3 (2 - (1-q)^2)}
 \end{aligned}$$

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$$\text{If } 1-q = 10^{-6}, \quad P(Q) = 1 - 2 \times 10^{-9}$$

If  $N$  is length of link, we require

$$(1 - 2 \times 10^{-9})^N \geq 0.99$$

$$\text{or } 1 - 2 \times N \times 10^{-9} \geq 0.99$$

$$\underline{3} \quad \text{or } N \geq \frac{1}{2} \times 10^9 \times 10^{-2} = \underline{\underline{\frac{1}{2} \times 10^7 \text{ meters}}}$$

(by independence)  
 (approximately)

$$2. \quad R(x+n) - R(x) = \begin{cases} (x+n)^2 - x^2 & x \geq 0 \\ (x+n)^2 & -n \leq x < 0 \\ 0 & x < -n \end{cases}$$

The power of the rectified output is therefore

$$\begin{aligned} E[|R(X(n)) - R(X)|^2] f_X(x) dx &= \frac{1}{2} \int_{-1}^1 (R(x+n) - R(x))^2 f_X(x) dx \\ &= \frac{1}{2} \int_0^1 [(x+n)^4 - 2(x+n)^2 x^2 + x^4] dx + \frac{1}{2} \int_{-n}^0 (x+n)^4 dx \\ &= \frac{1}{2} \int_0^1 [(x+n)^4 - 2x^4 - 4x^3 n - 2x^2 n^2 + x^4] dx + \frac{1}{2} \int_{-n}^0 (x+n)^4 dx \\ &= \frac{1}{2} \left\{ \frac{1}{5} (x+n)^5 - \frac{2}{5} x^5 - x^4 n - \frac{2}{3} x^3 n^2 + \frac{1}{5} x^5 \right\} \Big|_0^1 + \frac{1}{5} n^5 \Big\} \\ &= \frac{1}{2} \left\{ \frac{1}{5} (1+n)^5 - \frac{1}{5} n^5 - \frac{2}{5} - n - \frac{2}{3} n^2 + \frac{1}{5} + \frac{1}{5} n^5 \right\} \quad \text{o's for terms } n^3, n^4, \dots \\ &\approx \frac{1}{2} \left\{ \frac{1}{5} [1+5n+10n^2] - \frac{2}{5} - n - \frac{2}{3} n^2 + \frac{1}{5} + 0 + 0 \right\} \\ 14 \quad &= \frac{1}{2} \times (2 - \frac{2}{3}) n^2 = \frac{2}{3} n^2 \end{aligned}$$

Also

$$E[X^2] = \frac{1}{2} \int_{-1}^1 x^2 dx = \frac{1}{2} \cdot \frac{x^3}{3} \Big|_{-1}^1 = \frac{1}{3}$$

$$E[X^4] = \frac{1}{2} \int_{-1}^1 x^4 dx = \frac{1}{10}$$

It follows that (for  $n$  small)

$$S_{in} = \frac{n^2}{1/3} = \frac{3n^2}{1} \quad \text{and} \quad S_{out} \approx \frac{20}{3} n^2$$

2. We see that  $S_{in} \neq S_{out}$ .

If  $R(x)$  is replaced by a linear gain,  $z - z^* = K(x+n) - Kx = Kn$  and  $z^* = Kx$ . So

$$S_{out} = \frac{K^2 n^2}{K^2 E[|X|^2]} = \frac{n^2}{E[|X|^2]} = S_{in}$$

4. We have confirmed that  $S_{in} \neq S_{out}$  is a nonlinear phenomenon.

$$3(i) f_Y(y) = (\pi(1-r^2)\frac{1}{2}\sigma^2)^{-1} \int_{-\infty}^{+\infty} \exp\left\{-\frac{|x-ry|^2}{2\sigma^2(1-r^2)}\right\} dx \cdot \exp\left\{-\frac{y^2}{2\sigma^2}\right\}$$

change variables  $x' = x - ry$  (for fixed  $y$ ), giving

$$\int_{-\infty}^{+\infty} \exp\left\{-\frac{|x-ry|^2}{2\sigma^2(1-r^2)}\right\} dx = \int_{-\infty}^{+\infty} \exp\left\{-\frac{|x'|^2}{2\sigma^2(1-r^2)}\right\} dx' = \pi \frac{1}{2} \sqrt{\sigma^2(1-r^2)} \quad (\text{by properties of normal density})$$

Hence  $f_Y(y) = (\pi\sigma^2)^{-1/2} \exp\left\{-\frac{y^2}{2\sigma^2}\right\}$ . So

$$f_{X|Y}(x|y) = \frac{(\pi\sigma^2)^{1/2}}{\pi(1-r^2)^{1/2}\sigma^2} \cdot \exp\left\{-\frac{1}{2\sigma^2}a\right\} \quad \text{where}$$

$$a = \frac{1}{1-r^2} \left( |x-ry|^2 + (1-r^2)y^2 \right) - y^2 = \frac{1}{(1-r^2)} \left( x^2 - 2ryx + r^2y^2 + y^2 - r^2y^2 - y^2 + r^2y^2 \right) = \frac{|x-ry|^2}{1-r^2}$$

We have shown

$$f_{X|Y}(x|y) = \frac{1}{(\pi\sigma^2)^{1/2}} \exp\left\{-\frac{1}{2\sigma^2} |x-\bar{m}|^2\right\}$$

where  $\bar{m} (= m_{X|Y}(y)) = ry$  and  $\sigma^2 (= \text{var}_{X|Y}(y)) = \sigma^2(1-r^2)$

(ii) We require that

$$\text{var}_{X|Y}(y) \leq 0.01 E|X|^2$$

But  $E|X|^2 = \sigma^2$  and  $\text{var}_{X|Y}(y) = \sigma^2(1-r^2)$

Hence

$$\sigma^2(1-r^2) \leq 0.01 \sigma^2$$

It follows  $\text{cost} = \frac{10}{1-r^2} \geq 1000$  (£'s)

So minimum cost (to achieve specifications) is £1,000

4 If  $Y(\omega) = y$  then  $X(\omega)$  can only take values  $y$  and  $y - \frac{1}{2}$ .

For  $\beta = 0$  or  $\frac{1}{2}$

$$m_{X|Y}(X = y - \beta | Y = y) \approx \frac{P[y \leq X + \beta \leq y + \delta_y | y \leq Y \leq y + \delta_y]}{P[y \leq X + N \leq y + \delta_y | N=0] P[N=0] + P[y \leq X + N \leq y + \delta_y | N=\frac{1}{2}] P[N=\frac{1}{2}]}$$

(by Bayes' Rule)

$$= \frac{P[N = \beta] \cdot f_X(y - \beta)}{[P_X(y) p + f_X(y - \frac{1}{2}) (1-p)]}$$

It follows

$$m_{X|Y}(X = x | Y = y) = \begin{cases} \frac{\alpha_1}{\alpha_1 + \alpha_2} & \text{if } x = y \\ \frac{\alpha_2}{\alpha_1 + \alpha_2} & \text{if } x = y - \frac{1}{2} \end{cases}$$

where  $\alpha_1 = p f_X(y)$  and  $\alpha_2 = (1-p) f_X(y - \frac{1}{2})$

Hence, the least squares estimate, which coincides with the conditional mean, is

$$g(y) = \frac{\alpha_1}{\alpha_1 + \alpha_2} y + \frac{\alpha_2}{\alpha_1 + \alpha_2} (y - \frac{1}{2})$$

If  $f_X(x) = \begin{cases} 1 & 0 \leq x \leq 1 \\ 0 & \text{otherwise} \end{cases}$ , then

for  $0 \leq y < \frac{1}{2}$ ,  $\alpha_1 = p$ ,  $\alpha_2 = 0$ , so  $g(y) = y$

for  $\frac{1}{2} \leq y \leq 1$ ,  $\alpha_1 = p$ ,  $\alpha_2 = (1-p)$ , so  $g(y) = py + (1-p)(y - \frac{1}{2})$

for  $1 < y \leq 1\frac{1}{2}$ ,  $\alpha_1 = 0$ ,  $\alpha_2 = (1-p)$  so  $g(y) = y - \frac{1}{2}$

The point here is that, if  $y < \frac{1}{2}$ , then we must have  $N=0$ , and  $X(\omega) = Y(\omega)$  so  $g(y) = y$  is the best estimate of  $X(\omega)$  given  $Y(\omega) = y$ .

If  $y > 1$ , we must have  $N = \frac{1}{2}$ , so  $X(\omega) = Y(\omega) - \frac{1}{2}$ .

Here  $g(y) = y - \frac{1}{2}$  is the best estimate of  $X(\omega)$

For  $\frac{1}{2} \leq y \leq 1$ ,  $g(y)$  is close to  $y$  if  $N(\omega) = 0$  with high probability  
 $g(y)$  is close to  $y - \frac{1}{2}$  if  $N(\omega) = \frac{1}{2}$  with high probability

5. (a) We have  $x_{k+1} = Ax_k + be_k$ . It follows that

$$x_{k+1} x_{k+1}^T = (Ax_k + be_k)(Ax_k + be_k)^T$$

But, from the state equations,  $x_k$  is independent of  $e_k$ . Hence

$$E\{be_k x_k^T b^T\} = 0$$

$$\text{Hence } E\{x_{k+1} x_{k+1}^T\} = E\{A x_k x_k^T A^T\} + 0 + 0 = E\{be_k e_k b^T\}$$

It follows that

$$R_x(0) = A R_x(0) A^T + \sigma^2 b b^T. \quad \text{--- (1)}$$

Also  $x_{k+1} x_k^T = A x_k x_k^T + be_k x_k^T$ . Taking expectations gives

$$R_x(1) = A R_x(0)$$

Similarly  $R_x(l) = A^l R_x(0)$  for  $l=1, 2, \dots$

and  $R_x(l-1) = R_x(0), A^{l-1}$  for  $l=1, 2, \dots$

Then  $R_y(l) = C E\{x_k x_{k-l}^T\} C^T = C R_x(l) C^T$ , for  $l=1, 2, \dots$

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(b) We can regard  $u_k$  and  $v_k$  as components of the 2-vector process

$$\begin{pmatrix} u_{k+1} \\ v_{k+1} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -a & 0 \end{pmatrix} \begin{pmatrix} u_k \\ v_k \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \end{pmatrix} e_k.$$

Write  $R_x(0) = \begin{bmatrix} r_{11} & r_{12} \\ r_{21} & r_{22} \end{bmatrix}$ . Then, by (1),

$$\begin{bmatrix} r_{11} & r_{12} \\ r_{21} & r_{22} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -a & 0 \end{bmatrix} \begin{bmatrix} r_{11} & r_{12} \\ r_{21} & r_{22} \end{bmatrix} \begin{bmatrix} 0 & -a \\ 1 & 0 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \end{bmatrix} \sigma^2$$

$$\Rightarrow \begin{bmatrix} r_{11} & r_{12} \\ r_{21} & r_{22} \end{bmatrix} = \begin{bmatrix} r_{22} & -a r_{21} \\ -a r_{12} & r_{11} \end{bmatrix} + \sigma^2 \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}.$$

Equating matrix entries, we obtain

$$r_{11} = r_{22} + \sigma^2, \quad r_{12} = -a r_{21} + \sigma^2, \quad r_{21} = -a r_{12} + \sigma^2, \quad r_{22} = a^2 r_{11} + \sigma^2.$$

Hence

$$r_{11} = a^2 r_{11} + 2\sigma^2 \Rightarrow r_{11} = \frac{2\sigma^2}{1-a^2}$$

$$r_{22} = \sigma^2 \frac{1+a^2}{1-a^2}$$

Since  $r_{11} = R_u(0)$  and  $r_{22} = R_v(0)$ , we have

$$\frac{5}{8} = R_v(0)/R_u(0) = r_{22}/r_{11} = \frac{1}{2}(1+a^2)$$

12 Hence  $a^2 = \left(\frac{5}{4} - 1\right) \Rightarrow a = \pm \frac{1}{2}$

6(i) The spectral density  $\Phi_r(\omega)$  of  $\{r_k\}$  is

$$\Phi_r(\omega) = \sum_{l=-\infty}^{\infty} R(l) e^{-j\omega l}, \text{ where } R(l) = E\{r_k r_{k-l}\}.$$

If  $r_k = u_k + v_k$ ,

$$\begin{aligned} R_r(l) &= E\{(u_k + v_k)(u_{k-l} + v_{k-l})\} \\ &= E\{u_k u_{k-l}\} + 0 + 0 + E\{v_k v_{k-l}\} \\ &= R_u(l) + R_v(l). \end{aligned}$$

6 It follows that  $\Phi_r(\omega) = \sum_{l=-\infty}^{\infty} [R_u(l) + R_v(l)] e^{-j\omega l} = \Phi_u(\omega) + \Phi_v(\omega)$ .

(ii)  $(2 - z^{-1}) s_k = e_k$ ,  $(3 - z^{-1}) r_k = s_k + d_k$ ,  $d_k = N(z) \tilde{e}_k$  imp.  

$$r_k = \frac{1}{3 - z^{-1}} \left( \frac{e_k}{(2 - z^{-1})} + D(z) \tilde{e}_k \right) = G_1(z) e_k + G_2(z) \tilde{e}_k$$

in which  $G_1(z) = \frac{1}{(2 - z^{-1})(3 - z^{-1})}$  and  $G_2(z) = \frac{D(z)}{(3 - z^{-1})}$

We know:

$$\Phi_r(\omega) = \frac{1 + (17 - 4e^{j\omega} - 4e^{-j\omega})(5 - 2e^{j\omega} - 2e^{-j\omega})}{(5 - 2e^{j\omega} - 2e^{-j\omega})(10 - 3e^{j\omega} - 3e^{-j\omega})}$$

But, writing  $u_k = G_1(z) e_k$ , we have

$$\Phi_u(\omega) = \frac{1}{(2 - z^{-1})(2 - z)(3 - z^{-1})(3 - z)} \Big|_{z=e^{j\omega}} = \frac{1}{(5 - 2e^{j\omega} - 2e^{-j\omega})(10 - 3e^{j\omega} - 3e^{-j\omega})}$$

So, writing  $v_k = G_2(z) e_k$ , we have

$$\begin{aligned} \Phi_v(\omega) &= \Phi_r(\omega) - \Phi_u(\omega) = \frac{(17 - 4e^{j\omega} - 4e^{-j\omega})(5 - 2e^{j\omega} - 2e^{-j\omega})}{(5 - 2e^{j\omega} - 2e^{-j\omega})(10 - 3e^{j\omega} - 3e^{-j\omega})} \\ &= \frac{(4 - z^{-1})}{(3 - z^{-1})} \cdot \frac{(4 - z)}{(3 - z)} \Big|_{z=e^{j\omega}} = G_2(z) G_2(z^{-1}) \Big|_{z=e^{j\omega}} \end{aligned}$$

It follows we can choose  $G_2(z) = \frac{4 - z^{-1}}{3 - z^{-1}}$

Then  $D'(z) = (3 - z^{-1}) G_2(z) = \underline{4 - z^{-1}}$

14 (Note: we cannot choose  $G_2(z) = \frac{1 - 4z^{-1}}{1 - 3z^{-1}}$ , because then  $D(z) = \frac{(3 - z^{-1})(1 - 4z^{-1})}{(1 - 3z^{-1})}$  is an unstable transfer function.