

B.ENG. AND M.ENG. EXAMINATIONS 2011

PART II Paper 3 : MATHEMATICS (ELECTRICAL ENGINEERING)

Date Wednesday 8th June 2011 2.00 - 5.00 pm

DO NOT OPEN THIS PAPER UNTIL THE INVIGILATOR TELLS YOU TO.

Answer EIGHT questions.

Please answer questions from Section A and Section B in separate answer-books.

A mathematical formulae sheet is provided.

Statistical data sheets are provided.

[Before starting, please make sure that the paper is complete; there should be NINE pages, with a total of TWELVE questions. Ask the invigilator for a replacement if your copy is faulty.]

SECTION A**[E2.8 (Maths 3) 2011]**

1. (i) Consider the mapping

$$w = \frac{1}{(z-1)^2}$$

from the z -plane to the w -plane where $w = u + iv$. Show that the circle

$$(x-1)^2 + y^2 = R^2$$

in the z -plane, maps to the circle

$$u^2 + v^2 = R^{-4}$$

in the w -plane.

- (ii) Now consider

$$w = \frac{1}{z}.$$

For the class of circles

$$(x-1)^2 + (y-1)^2 = r^2,$$

show that when $r = \sqrt{2}$ the circle maps to the straight line $v = u - \frac{1}{2}$ in the $u-v$ plane whereas when $r = 1$ it maps to the circle $(u-1)^2 + (v+1)^2 = 1$.

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[E2.8 (Maths 3) 2011]

2. (i) Use the Residue Theorem to show that

$$\oint_C \frac{z \, dz}{(z-1)^2(z-i)} = 0,$$

where the contour C is the circle of radius 2 centred at the origin. What is the answer when C is changed to be the rectangle with vertices at $\pm\frac{1}{2} + 2i$ and $\pm\frac{1}{2} - 2i$?

- (ii) The closed contour C is a circle of arbitrary finite radius r centred at the origin, Show that the value of the complex integral

$$\oint_C \frac{dz}{z} = 2\pi i$$

in three different ways:

- (a) By the Residue Theorem;
- (b) By evaluating the integral as a line integral around the circle $z = r \exp(i\theta)$;
- (c) By direct integration.

The residue of a complex function $f(z)$ at a pole $z = a$ of multiplicity m is given by the expression

$$\lim_{z \rightarrow a} \frac{1}{(m-1)!} \left[\frac{d^{m-1}}{dz^{m-1}} \{(z-a)^m f(z)\} \right].$$

3. Consider the contour integral

$$\oint_C \frac{e^{iz}}{(z^2 + 1)^2} dz,$$

where the closed contour C consists of a semi-circle in the upper half of the complex plane and the real axis. Use the Residue Theorem to show that

$$\int_{-\infty}^{\infty} \frac{\cos x}{(x^2 + 1)^2} dx = \pi/e.$$

The residue of a complex function $f(z)$ at a pole $z = a$ of multiplicity m is given by

$$\lim_{z \rightarrow a} \frac{1}{(m-1)!} \left[\frac{d^{m-1}}{dz^{m-1}} \{(z-a)^m f(z)\} \right].$$

[E2.8 (Maths 3) 2011]

4. The sawtooth function $\Pi(t)$, the tent function $\Lambda(t)$, and the sinc-function $\text{sinc}(t)$ are defined respectively by

$$\Pi(t) = \begin{cases} 1, & -1/2 \leq t \leq 1/2, \\ 0, & \text{otherwise,} \end{cases}$$

$$\Lambda(t) = \begin{cases} 1+t, & -1 \leq t \leq 0, \\ 1-t, & 0 \leq t \leq 1, \end{cases}$$

and

$$\text{sinc}(t) = \frac{\sin(t/2)}{(t/2)}.$$

Show that the Fourier transforms of the above functions are

$$(i) \quad \bar{\Pi}(\omega) = \text{sinc}(\omega),$$

$$(ii) \quad \bar{\Lambda}(\omega) = \text{sinc}^2(\omega).$$

Use Parseval's equality to show that

$$(iii) \quad \int_{-\infty}^{\infty} \text{sinc}^2(\omega) d\omega = 2\pi,$$

$$(iv) \quad \int_{-\infty}^{\infty} \text{sinc}^4(\omega) d\omega = 4\pi/3.$$

Parseval's equality is given by

$$\int_{-\infty}^{\infty} |f(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |\bar{f}(\omega)|^2 d\omega.$$

5. Given that $\bar{f}(s) = \mathcal{L}\{f(t)\}$ is the Laplace transform of $f(t)$, prove that when a is a real constant

$$\mathcal{L}\{e^{at}f(t)\} = \bar{f}(s-a), \quad \text{Re}(s) > a.$$

A 2nd order ordinary differential equation, with initial values, takes the form

$$\frac{d^2x}{dt^2} + 4\frac{dx}{dt} + 8x = \delta(t-1), \quad x = \frac{dx}{dt} = 0 \text{ when } t=0,$$

where δ represents the Dirac delta function. Use the Laplace convolution theorem to show that the solution for $x(t)$ is

$$x(t) = \begin{cases} \frac{1}{2}e^{-2(t-1)} \sin[2(t-1)] & t > 1, \\ 0 & 0 \leq t \leq 1. \end{cases}$$

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[E2.8 (Maths 3) 2011]

6. A function $f(t)$ has Laplace transform $\bar{f}(s) = \mathcal{L}\{f(t)\}$. Prove that

$$\mathcal{L}\left\{\int_0^t f(u) du\right\} = \frac{\bar{f}(s)}{s}.$$

Show that if

$$\bar{f}(s) = \frac{1}{(1+s^2)^2}$$

then

$$f(t) = \frac{1}{2} (\sin t - t \cos t).$$

Hence show that

$$\mathcal{L}^{-1}\left\{\frac{1}{s(1+s^2)^2}\right\} = 1 - \cos t - \frac{1}{2}t \sin t.$$

7. P and Q are continuous functions of x and y with continuous first partial derivatives in a simply connected region R with a piecewise smooth boundary C . Green's Theorem in a plane states that

$$\oint_C (Pdx + Qdy) = \iint_R \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dxdy.$$

Find a two-dimensional vector \mathbf{u} , defined in terms of P and Q , to show that Green's theorem can be re-expressed as the two-dimensional version of the Divergence Theorem

$$\oint_C \mathbf{u} \cdot \mathbf{n} ds = \iint_R (\operatorname{div} \mathbf{u}) dxdy,$$

where \mathbf{n} is the unit normal to the curve C .

If \mathbf{u} is given by $\mathbf{u} = ix^2 + jy^2$ and R is the first quadrant of the circle of unit radius, evaluate the right hand side of the Divergence Theorem to show that

$$\iint_R (\operatorname{div} \mathbf{u}) dxdy = 4/3.$$

[E2.8 (Maths 3) 2011]

8. Consider a metal plate occupying a region \mathcal{R} in the first quadrant of the xy -plane bounded by the curves

$$xy = 1, \quad x^2 - y^2 = 1, \quad y = 0 \quad \text{and} \quad y = x.$$

If the mass/unit area of the plate is $f(x, y) = \exp(x^2 - y^2)$ then the moment of inertia of the plate about the z -axis is

$$I_{0z} = \int \int_{\mathcal{R}} (x^2 + y^2) \exp(x^2 - y^2) dx dy.$$

Using new variables u and v such that $u = xy$ and $v = x^2 - y^2$, show that the Jacobian of the transformation from (u, v) to (x, y) satisfies

$$|J| = 2(x^2 + y^2),$$

and hence that the Jacobian for the transformation from (x, y) to (u, v) is

$$|J'| = \frac{1}{2(x^2 + y^2)}.$$

Then show that

$$I_{0z} = \int \int_{\mathcal{R}^*} \frac{1}{2} e^v du dv,$$

where the region \mathcal{R}^* in the uv -plane is to be determined.

Sketch the region \mathcal{R} in the xy -plane and the new region \mathcal{R}^* in the uv -plane and then evaluate I_{0z} .

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9. (i) The scalar field $\phi(\mathbf{r})$ is given by

$$\phi(\mathbf{r}) = \frac{\phi_0}{8\pi R} \left(3 - \frac{r^2}{R^2} \right) \quad \text{for } r < R$$

and

$$\phi(\mathbf{r}) = \frac{\phi_0}{4\pi r} \quad \text{for } r > R$$

where ϕ_0 is a constant, R is a fixed radius, $\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$ and $r = (x^2 + y^2 + z^2)^{1/2}$.

Calculate $\operatorname{grad} \phi$ when $r < R$ and also when $r > R$.

Show that $\operatorname{div} \operatorname{grad} \phi = -\frac{3\phi_0}{4\pi R^3}$ for $r < R$ and $\operatorname{div} \operatorname{grad} \phi = 0$ for $r > R$.

- (ii) The vector field $\mathbf{A}(\mathbf{r})$ is given by

$$\mathbf{A}(\mathbf{r}) = -\frac{I}{4\pi a^2} (x^2 + y^2)\mathbf{k} \quad \text{for } x^2 + y^2 < a^2$$

and

$$\mathbf{A}(\mathbf{r}) = -\frac{I}{4\pi} \left[1 + \ln \left(\frac{x^2 + y^2}{a^2} \right) \right] \mathbf{k} \quad \text{for } x^2 + y^2 > a^2,$$

where I is a constant and a is a fixed radius.

Calculate $\operatorname{curl} \mathbf{A}$ when $x^2 + y^2 < a^2$ and also when $x^2 + y^2 > a^2$.

N.B. $\nabla \cdot \mathbf{A} = \operatorname{div} \mathbf{A}$, $\nabla \times \mathbf{A} = \operatorname{curl} \mathbf{A}$, $\nabla \phi = \operatorname{grad} \phi$.

[E2.8 (Maths 3) 2011]

10. Write down the condition for the line integral

$$\int_{\mathcal{P}} [f(x, y) dx + g(x, y) dy]$$

to be independent of the path \mathcal{P} joining the initial point A to the final point B .

Show that

$$\int_{\mathcal{P}} [(x e^y + b \sin x) dx + (ax^2 e^y + c \cos y) dy]$$

is independent of the path \mathcal{P} for any values of b and c if $a = 1/2$.

Find the potential function $V(x, y)$ such that

$$\frac{\partial V}{\partial x} = xe^y + b \sin x$$

and

$$\frac{\partial V}{\partial y} = ax^2 e^y + c \cos y$$

for $a = 1/2$ and arbitrary b and c .

Hence evaluate the integral when A is the point $(0, \pi/2)$ and B is the point $(\pi/2, 0)$.

Evaluate the integral also by using a particular path \mathcal{P} of your own choice joining A to B and verify that the two methods give the same answer.

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SECTION B

[E 2.8 (Maths 3) 2011]

11. A factory produces engine piston and cylinder units. The diameter of the pistons is normally distributed with mean 88mm and standard deviation 0.7mm. Independently, the diameter of the cylinders is normally distributed with mean 91mm and standard deviation 1mm. A piston and cylinder unit is acceptable if the piston fits inside the cylinder, and its diameter is within 5mm of that of the cylinder.

- (i) We have a cylinder with diameter 89.7mm and we select a piston at random. What is the probability they form an acceptable unit?
- (ii) We select a piston and a cylinder at random. Show that the probability that they form an acceptable unit is 0.942.
- (iii) For a sample of 10 such piston/cylinder pairs (as in part (ii)), what is the distribution of the number of acceptable units? Compute the probability there are more than two unacceptable units in our sample.

12. Consider the autoregressive process

$$y_t = \frac{5}{6} y_{t-1} - \frac{1}{6} y_{t-2} + \frac{1}{6} e_t ,$$

where $\{e_t\}$ is white noise with $E(e_t) = 0$ and $\text{Var}(e_t) = 1$.

- (i) What is the order of the autoregression?
- (ii) Define the backshift operator B and show that

$$(2 - B)(3 - B)y_t = e_t.$$

What is $E(y_t)$?

- (iii) Prove that

$$[(2 - B)(3 - B)]^{-1} = \frac{1}{2 - B} - \frac{1}{3 - B}$$

and hence show that $\text{Var}(y_t) = 7/120$. You may use the result

$$(k - B)^{-1} = \frac{1}{k} \sum_{j=0}^{\infty} \left(\frac{B}{k} \right)^j .$$

END OF PAPER

M A T H E M A T I C S D E P A R T M E N T

MATHEMATICAL FORMULAE

1. VECTOR ALGEBRA

$$\mathbf{a} = a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k} = (a_1, a_2, a_3)$$

Scalar (dot) product: $\mathbf{a} \cdot \mathbf{b} = a_1b_1 + a_2b_2 + a_3b_3$

Vector (cross) product:

$$\mathbf{a} \times \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

Scalar triple product:

$$[\mathbf{a}, \mathbf{b}, \mathbf{c}] = \mathbf{a} \cdot \mathbf{b} \times \mathbf{c} = \mathbf{b} \cdot \mathbf{c} \times \mathbf{a} = \mathbf{c} \cdot \mathbf{a} \times \mathbf{b} = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$

Vector triple product: $\mathbf{a} \times (\mathbf{b} \times \mathbf{c}) = (\mathbf{c} \cdot \mathbf{a})\mathbf{b} - (\mathbf{b} \cdot \mathbf{a})\mathbf{c}$

2. SERIES

$$(1+x)^\alpha = 1 + \alpha x + \frac{\alpha(\alpha-1)}{2!} x^2 + \frac{\alpha(\alpha-1)(\alpha-2)}{3!} x^3 + \dots \quad (\alpha \text{ arbitrary, } |x| < 1)$$

$$e^x = 1 + x + \frac{x^2}{2!} + \dots + \frac{x^n}{n!} + \dots ,$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots + (-1)^n \frac{x^{2n}}{(2n)!} + \dots ,$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots + (-1)^n \frac{x^{2n+1}}{(2n+1)!} + \dots ,$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \dots + (-1)^n \frac{x^{n+1}}{(n+1)} + \dots \quad (-1 < x \leq 1)$$

3. TRIGONOMETRIC IDENTITIES AND HYPERBOLIC FUNCTIONS

$$\sin(a + b) = \sin a \cos b + \cos a \sin b ;$$

$$\cos(a + b) = \cos a \cos b - \sin a \sin b .$$

$$\cos iz = \cosh z ; \quad \cosh iz = \cos z ; \quad \sin iz = i \sinh z ; \quad \sinh iz = i \sin z .$$

4. DIFFERENTIAL CALCULUS

(a) Leibniz's formula:

$$D^n(fg) = f D^n g + {}^n_1 Df D^{n-1} g + \dots + {}^n_r D^r f D^{n-r} g + \dots + D^n f g .$$

(b) Taylor's expansion of $f(x)$ about $x = a$:

$$f(a + h) = f(a) + hf'(a) + h^2 f''(a)/2! + \dots + h^n f^{(n)}(a)/n! + \epsilon_n(h) ,$$

$$\text{where } \epsilon_n(h) = h^{n+1} f^{(n+1)}(a + \theta h)/(n+1)! , \quad 0 < \theta < 1 .$$

(c) Taylor's expansion of $f(x, y)$ about (a, b) :

$$f(a+h, b+k) = f(a, b) + [hf_x + kf_y]_{a,b} + 1/2! \left[h^2 f_{xx} + 2hk f_{xy} + k^2 f_{yy} \right]_{a,b} + \dots$$

(d) Partial differentiation of $f(x, y)$:

$$\text{i. If } y = y(x), \text{ then } f = F(x), \text{ and } \frac{dF}{dx} = \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} \frac{dy}{dx} .$$

$$\text{ii. If } x = x(t), y = y(t), \text{ then } f = F(t), \text{ and } \frac{dF}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} .$$

iii. If $x = x(u, v)$, $y = y(u, v)$, then $f = F(u, v)$, and

$$\frac{\partial F}{\partial u} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial u}, \quad \frac{\partial F}{\partial v} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial v} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial v} .$$

(e) Stationary points of $f(x, y)$ occur where $f_x = 0$, $f_y = 0$ simultaneously.

Let (a, b) be a stationary point: examine $D = [f_{xx}f_{yy} - (f_{xy})^2]_{a,b}$.

If $D > 0$ and $f_{xx}(a, b) < 0$, then (a, b) is a maximum;

If $D > 0$ and $f_{xx}(a, b) > 0$, then (a, b) is a minimum;

If $D < 0$ then (a, b) is a saddle-point.

(f) Differential equations:

i. The first order linear equation $dy/dx + P(x)y = Q(x)$ has an integrating factor $I(x) = \exp[\int P(x)(dx)]$, so that $\frac{d}{dx}(Iy) = IQ$.

ii. $P(x, y)dx + Q(x, y)dy = 0$ is exact if $\partial Q/\partial x = \partial P/\partial y$.

5. INTEGRAL CALCULUS

- (a) An important substitution: $\tan(\theta/2) = t$:
 $\sin \theta = 2t/(1+t^2)$, $\cos \theta = (1-t^2)/(1+t^2)$, $d\theta = 2dt/(1+t^2)$.

- (b) Some indefinite integrals:

$$\int (a^2 - x^2)^{-1/2} dx = \sin^{-1} \left(\frac{x}{a} \right), \quad |x| < a.$$

$$\int (a^2 + x^2)^{-1/2} dx = \sinh^{-1} \left(\frac{x}{a} \right) = \ln \left\{ \frac{x}{a} + \left(1 + \frac{x^2}{a^2} \right)^{1/2} \right\}.$$

$$\int (x^2 - a^2)^{-1/2} dx = \cosh^{-1} \left(\frac{x}{a} \right) = \ln \left| \frac{x}{a} + \left(\frac{x^2}{a^2} - 1 \right)^{1/2} \right|.$$

$$\int (a^2 + x^2)^{-1} dx = \left(\frac{1}{a} \right) \tan^{-1} \left(\frac{x}{a} \right).$$

6. NUMERICAL METHODS

- (a) Approximate solution of an algebraic equation:

If a root of $f(x) = 0$ occurs near $x = a$, take $x_0 = a$ and
 $x_{n+1} = x_n - [f(x_n)/f'(x_n)]$, $n = 0, 1, 2 \dots$

(Newton Raphson method).

- (b) Formulae for numerical integration: Write $x_n = x_0 + nh$, $y_n = y(x_n)$.

i. Trapezium rule (1-strip): $\int_{x_0}^{x_1} y(x) dx \approx (h/2) [y_0 + y_1]$.

ii. Simpson's rule (2-strip): $\int_{x_0}^{x_2} y(x) dx \approx (h/3) [y_0 + 4y_1 + y_2]$.

- (c) Richardson's extrapolation method: Let $I = \int_a^b f(x) dx$ and let I_1 , I_2 be two

estimates of I obtained by using Simpson's rule with intervals h and $h/2$.

Then, provided h is small enough,

$$I_2 + (I_2 - I_1)/15,$$

is a better estimate of I .

7. LAPLACE TRANSFORMS

Function	Transform	Function	Transform
$f(t)$	$F(s) = \int_0^\infty e^{-st} f(t) dt$	$af(t) + bg(t)$	$aF(s) + bG(s)$
df/dt	$sF(s) - f(0)$	d^2f/dt^2	$s^2F(s) - sf(0) - f'(0)$
$e^{at}f(t)$	$F(s-a)$	$tf(t)$	$-dF(s)/ds$
$(\partial/\partial\alpha)f(t, \alpha)$	$(\partial/\partial\alpha)F(s, \alpha)$	$\int_0^t f(t)dt$	$F(s)/s$
$\int_0^t f(u)g(t-u)du$	$F(s)G(s)$		
1	$1/s$	$t^n (n = 1, 2 \dots)$	$n!/s^{n+1}, (s > 0)$
e^{at}	$1/(s-a), (s > a)$	$\sin \omega t$	$\omega/(s^2 + \omega^2), (s > 0)$
$\cos \omega t$	$s/(s^2 + \omega^2), (s > 0)$	$H(t-T) = \begin{cases} 0, & t < T \\ 1, & t > T \end{cases}$	$e^{-sT}/s, (s, T > 0)$

8. FOURIER SERIES

If $f(x)$ is periodic of period $2L$, then $f(x+2L) = f(x)$, and

$$f(x) = \frac{1}{2}a_0 + \sum_{n=1}^{\infty} a_n \cos \frac{n\pi x}{L} + \sum_{n=1}^{\infty} b_n \sin \frac{n\pi x}{L}, \text{ where}$$

$$a_n = \frac{1}{L} \int_{-L}^L f(x) \cos \frac{n\pi x}{L} dx, \quad n = 0, 1, 2, \dots, \text{ and}$$

$$b_n = \frac{1}{L} \int_{-L}^L f(x) \sin \frac{n\pi x}{L} dx, \quad n = 1, 2, 3, \dots$$

Parseval's theorem

$$\frac{1}{L} \int_{-L}^L [f(x)]^2 dx = \frac{a_0^2}{2} + \sum_{n=1}^{\infty} (a_n^2 + b_n^2).$$

1. Probabilities for events

For events A , B , and C

$$P(A \cup B) = P(A) + P(B) - P(A \cap B)$$

More generally $P(\bigcup A_i) =$

$$\sum P(A_i) - \sum P(A_i \cap A_j) + \sum P(A_i \cap A_j \cap A_k) - \dots$$

The odds in favour of A

$$P(A) / P(\bar{A})$$

Conditional probability

$$P(A | B) = \frac{P(A \cap B)}{P(B)} \quad \text{provided that } P(B) > 0$$

Chain rule

$$P(A \cap B \cap C) = P(A) P(B | A) P(C | A \cap B)$$

Bayes' rule

$$P(A | B) = \frac{P(A) P(B | A)}{P(A) P(B | A) + P(\bar{A}) P(B | \bar{A})}$$

A and B are independent if

$$P(B | A) = P(B)$$

A , B , and C are independent if

$$P(A \cap B \cap C) = P(A)P(B)P(C), \text{ and}$$

$$P(A \cap B) = P(A)P(B), \quad P(B \cap C) = P(B)P(C), \quad P(C \cap A) = P(C)P(A)$$

2. Probability distribution, expectation and variance

The probability distribution for a discrete random variable X is called the probability mass function (pmf) and is the complete set of probabilities $\{p_x\} = \{P(X = x)\}$

Expectation $E(X) = \mu = \sum_x x p_x$

For function $g(x)$ of x , $E\{g(X)\} = \sum_x g(x)p_x$, so $E(X^2) = \sum_x x^2 p_x$

Sample mean $\bar{x} = \frac{1}{n} \sum_k x_k$ estimates μ from random sample x_1, x_2, \dots, x_n

Variance $\text{var}(X) = \sigma^2 = E\{(X - \mu)^2\} = E(X^2) - \mu^2$

Sample variance $s^2 = \frac{1}{n-1} \left\{ \sum_k x_k^2 - \frac{1}{n} \left(\sum_j x_j \right)^2 \right\}$ estimates σ^2

Standard deviation $\text{sd}(X) = \sigma$

If value y is observed with frequency n_y

$$n = \sum_y n_y, \quad \sum_k x_k = \sum_y y n_y, \quad \sum_k x_k^2 = \sum_y y^2 n_y$$

Skewness $\beta_1 = E\left(\frac{X - \mu}{\sigma}\right)^3$ is estimated by $\frac{1}{n-1} \sum \left(\frac{x_i - \bar{x}}{s}\right)^3$

Kurtosis $\beta_2 = E\left(\frac{X - \mu}{\sigma}\right)^4 - 3$ is estimated by $\frac{1}{n-1} \sum \left(\frac{x_i - \bar{x}}{s}\right)^4 - 3$

Sample median \tilde{x} or x_{med} . Half the sample values are smaller and half larger

If the sample values x_1, \dots, x_n are ordered as $x_{(1)} \leq x_{(2)} \leq \dots \leq x_{(n)}$,

then $\tilde{x} = x_{(\frac{n+1}{2})}$ if n is odd, and $\tilde{x} = \frac{1}{2}(x_{(\frac{n}{2})} + x_{(\frac{n+2}{2})})$ if n is even

α -quantile $Q(\alpha)$ is such that $P(X \leq Q(\alpha)) = \alpha$

Sample α -quantile $\widehat{Q}(\alpha)$ Proportion α of the data values are smaller

Lower quartile $Q1 = \widehat{Q}(0.25)$ one quarter are smaller

Upper quartile $Q3 = \widehat{Q}(0.75)$ three quarters are smaller

Sample median $\tilde{x} = \widehat{Q}(0.5)$ estimates the population median $Q(0.5)$

3. Probability distribution for a continuous random variable

The cumulative distribution function (cdf) $F(x) = P(X \leq x) = \int_{x_0=-\infty}^x f(x_0)dx_0$

The probability density function (pdf) $f(x) = \frac{dF(x)}{dx}$

$E(X) = \mu = \int_{-\infty}^{\infty} x f(x)dx$, $\text{var}(X) = \sigma^2 = E(X^2) - \mu^2$, where $E(X^2) = \int_{-\infty}^{\infty} x^2 f(x)dx$

4. Discrete probability distributions

Discrete Uniform $Uniform(n)$

$$p_x = \frac{1}{n} \quad (x = 1, 2, \dots, n) \quad \mu = (n+1)/2, \quad \sigma^2 = (n^2 - 1)/12$$

Binomial distribution $Binomial(n, \theta)$

$$p_x = \binom{n}{x} \theta^x (1-\theta)^{n-x} \quad (x = 0, 1, 2, \dots, n) \quad \mu = n\theta, \quad \sigma^2 = n\theta(1-\theta)$$

Poisson distribution $Poisson(\lambda)$

$$p_x = \frac{\lambda^x e^{-\lambda}}{x!} \quad (x = 0, 1, 2, \dots) \quad (\text{with } \lambda > 0) \quad \mu = \lambda, \quad \sigma^2 = \lambda$$

Geometric distribution $Geometric(\theta)$

$$p_x = (1-\theta)^{x-1}\theta \quad (x = 1, 2, 3, \dots) \quad \mu = \frac{1}{\theta}, \quad \sigma^2 = \frac{1-\theta}{\theta^2}$$

5. Continuous probability distributions

Uniform distribution $Uniform(\alpha, \beta)$

$$f(x) = \begin{cases} \frac{1}{\beta - \alpha} & (\alpha < x < \beta), \\ 0 & (\text{otherwise}). \end{cases} \quad \mu = (\alpha + \beta)/2, \quad \sigma^2 = (\beta - \alpha)^2/12$$

Exponential distribution $Exponential(\lambda)$

$$f(x) = \begin{cases} \lambda e^{-\lambda x} & (0 < x < \infty), \\ 0 & (-\infty < x \leq 0). \end{cases} \quad \mu = 1/\lambda, \quad \sigma^2 = 1/\lambda^2$$

Normal distribution $N(\mu, \sigma^2)$

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{-\frac{1}{2}\left(\frac{x-\mu}{\sigma}\right)^2\right\} \quad (-\infty < x < \infty), \quad E(X) = \mu, \quad \text{var}(X) = \sigma^2$$

Standard normal distribution $N(0,1)$

$$\text{If } X \text{ is } N(\mu, \sigma^2), \text{ then } Y = \frac{X - \mu}{\sigma} \text{ is } N(0,1)$$

6. Reliability

For a device in continuous operation with failure time random variable T having pdf $f(t)$ ($t > 0$)

$$\text{The reliability function at time } t \quad R(t) = P(T > t)$$

$$\text{The failure rate or hazard function} \quad h(t) = f(t)/R(t)$$

$$\text{The cumulative hazard function} \quad H(t) = \int_0^t h(t_0) dt_0 = -\ln\{R(t)\}$$

$$\text{The Weibull}(\alpha, \beta) \text{ distribution has} \quad H(t) = \beta t^\alpha$$

7. System reliability

For a system of k devices, which operate independently, let

$$R_i = P(D_i) = P(\text{"device } i \text{ operates"})$$

The system reliability, R , is the probability of a path of operating devices

A system of devices in series operates only if every device operates

$$R = P(D_1 \cap D_2 \cap \dots \cap D_k) = R_1 R_2 \dots R_k$$

A system of devices in parallel operates if any device operates

$$R = P(D_1 \cup D_2 \cup \dots \cup D_k) = 1 - (1 - R_1)(1 - R_2) \dots (1 - R_k)$$

8. Covariance and correlation

The covariance of X and Y $\text{cov}(X, Y) = E(XY) - \{E(X)\}\{E(Y)\}$

$$\text{From pairs of observations } (x_1, y_1), \dots, (x_n, y_n) \quad S_{xy} = \sum_k x_k y_k - \frac{1}{n} (\sum_i x_i)(\sum_j y_j)$$

$$S_{xx} = \sum_k x_k^2 - \frac{1}{n} (\sum_i x_i)^2, \quad S_{yy} = \sum_k y_k^2 - \frac{1}{n} (\sum_j y_j)^2$$

$$\text{Sample covariance} \quad s_{xy} = \frac{1}{n-1} S_{xy} \quad \text{estimates cov}(X, Y)$$

$$\text{Correlation coefficient} \quad \rho = \text{corr}(X, Y) = \frac{\text{cov}(X, Y)}{\text{sd}(X) \cdot \text{sd}(Y)}$$

$$\text{Sample correlation coefficient} \quad r = \frac{S_{xy}}{\sqrt{S_{xx} S_{yy}}} \quad \text{estimates } \rho$$

9. Sums of random variables

$$E(X + Y) = E(X) + E(Y)$$

$$\text{var}(X + Y) = \text{var}(X) + \text{var}(Y) + 2 \text{cov}(X, Y)$$

$$\text{cov}(aX + bY, cX + dY) = (ac)\text{var}(X) + (bd)\text{var}(Y) + (ad + bc)\text{cov}(X, Y)$$

If X is $N(\mu_1, \sigma_1^2)$, Y is $N(\mu_2, \sigma_2^2)$, and $\text{cov}(X, Y) = c$, then $X + Y$ is $N(\mu_1 + \mu_2, \sigma_1^2 + \sigma_2^2 + 2c)$

10. Bias, standard error, mean square error

If t estimates θ (with random variable T giving t)

$$\underline{\text{Bias}} \text{ of } t \quad \text{bias}(t) = E(T) - \theta$$

$$\underline{\text{Standard error}} \text{ of } t \quad \text{se}(t) = \text{sd}(T)$$

$$\underline{\text{Mean square error}} \text{ of } t \quad \text{MSE}(t) = E\{(T - \theta)^2\} = \{\text{se}(t)\}^2 + \{\text{bias}(t)\}^2$$

If \bar{x} estimates μ , then $\text{bias}(\bar{x}) = 0$, $\text{se}(\bar{x}) = \sigma/\sqrt{n}$, $\text{MSE}(\bar{x}) = \sigma^2/n$, $\widehat{\text{se}}(\bar{x}) = s/\sqrt{n}$

Central limit property If n is fairly large, \bar{x} is from $N(\mu, \sigma^2/n)$ approximately

11. Likelihood

The likelihood is the joint probability as a function of the unknown parameter θ .

For a random sample x_1, x_2, \dots, x_n

$$\ell(\theta; x_1, x_2, \dots, x_n) = P(X_1 = x_1 \mid \theta) \cdots P(X_n = x_n \mid \theta) \quad (\text{discrete distribution})$$

$$\ell(\theta; x_1, x_2, \dots, x_n) = f(x_1 \mid \theta) f(x_2 \mid \theta) \cdots f(x_n \mid \theta) \quad (\text{continuous distribution})$$

The maximum likelihood estimator (MLE) is $\hat{\theta}$ for which the likelihood is a maximum

12. Confidence intervals

If x_1, x_2, \dots, x_n are a random sample from $N(\mu, \sigma^2)$ and σ^2 is known, then

the 95% confidence interval for μ is $(\bar{x} - 1.96 \frac{\sigma}{\sqrt{n}}, \bar{x} + 1.96 \frac{\sigma}{\sqrt{n}})$

If σ^2 is estimated, then from the Student t table for t_{n-1} we find $t_0 = t_{n-1, 0.05}$

The 95% confidence interval for μ is $(\bar{x} - t_0 \frac{s}{\sqrt{n}}, \bar{x} + t_0 \frac{s}{\sqrt{n}})$

13. Standard normal table Values of pdf $\phi(y) = f(y)$ and cdf $\Phi(y) = F(y)$

y	$\phi(y)$	$\Phi(y)$	y	$\phi(y)$	$\Phi(y)$	y	$\phi(y)$	$\Phi(y)$	y	$\Phi(y)$
0	.399	.5	.9	.266	.816	1.8	.079	.964	2.8	.997
.1	.397	.540	1.0	.242	.841	1.9	.066	.971	3.0	.999
.2	.391	.579	1.1	.218	.864	2.0	.054	.977	0.841	.8
.3	.381	.618	1.2	.194	.885	2.1	.044	.982	1.282	.9
.4	.368	.655	1.3	.171	.903	2.2	.035	.986	1.645	.95
.5	.352	.691	1.4	.150	.919	2.3	.028	.989	1.96	.975
.6	.333	.726	1.5	.130	.933	2.4	.022	.992	2.326	.99
.7	.312	.758	1.6	.111	.945	2.5	.018	.994	2.576	.995
.8	.290	.788	1.7	.094	.955	2.6	.014	.995	3.09	.999

14. Student t table Values $t_{m,p}$ of x for which $P(|X| > x) = p$, when X is t_m

m	$p = .10$	$.05$	$.02$	$.01$	m	$p = .10$	$.05$	$.02$	$.01$
1	6.31	12.71	31.82	63.66	9	1.83	2.26	2.82	3.25
2	2.92	4.30	6.96	9.92	10	1.81	2.23	2.76	3.17
3	2.35	3.18	4.54	5.84	12	1.78	2.18	2.68	3.05
4	2.13	2.78	3.75	4.60	15	1.75	2.13	2.60	2.95
5	2.02	2.57	3.36	4.03	20	1.72	2.09	2.53	2.85
6	1.94	2.45	3.14	3.71	25	1.71	2.06	2.48	2.78
7	1.89	2.36	3.00	3.50	40	1.68	2.02	2.42	2.70
8	1.86	2.31	2.90	3.36	∞	1.645	1.96	2.326	2.576

15. Chi-squared table Values $\chi^2_{k,p}$ of x for which $P(X > x) = p$, when X is χ_k^2 and $p = .995, .975, \text{etc}$

k	.995	.975	.05	.025	.01	.005	k	.995	.975	.05	.025	.01	.005
1	.000	.001	3.84	5.02	6.63	7.88	18	6.26	8.23	28.87	31.53	34.81	37.16
2	.010	.051	5.99	7.38	9.21	10.60	20	7.43	9.59	31.42	34.17	37.57	40.00
3	.072	.216	7.81	9.35	11.34	12.84	22	8.64	10.98	33.92	36.78	40.29	42.80
4	.207	.484	9.49	11.14	13.28	14.86	24	9.89	12.40	36.42	39.36	42.98	45.56
5	.412	.831	11.07	12.83	15.09	16.75	26	11.16	13.84	38.89	41.92	45.64	48.29
6	.676	1.24	12.59	14.45	16.81	18.55	28	12.46	15.31	41.34	44.46	48.28	50.99
7	.990	1.69	14.07	16.01	18.48	20.28	30	13.79	16.79	43.77	46.98	50.89	53.67
8	1.34	2.18	15.51	17.53	20.09	21.95	40	20.71	24.43	55.76	59.34	63.69	66.77
9	1.73	2.70	16.92	19.02	21.67	23.59	50	27.99	32.36	67.50	71.41	76.15	79.49
10	2.16	3.25	13.31	20.48	23.21	25.19	60	35.53	40.48	79.08	83.30	88.38	91.95
12	3.07	4.40	21.03	23.34	26.22	28.30	70	43.28	48.76	90.53	95.02	100.4	104.2
14	4.07	5.63	23.68	26.12	29.14	31.32	80	51.17	57.15	101.9	106.6	112.3	116.3
16	5.14	6.91	26.30	28.85	32.00	34.27	100	67.33	74.22	124.3	129.6	135.8	140.2

16. The chi-squared goodness-of-fit test

The frequencies n_y are grouped so that the fitted frequency \hat{n}_y for every group exceeds about 5.

$$X^2 = \sum_y \frac{(n_y - \hat{n}_y)^2}{\hat{n}_y} \text{ is referred to the table of } \chi_k^2 \text{ with significance point } p,$$

where k is the number of terms summed, less one for each constraint, eg matching total frequency, and matching \bar{x} with μ

17. Joint probability distributions

Discrete distribution $\{p_{xy}\}$, where $p_{xy} = P(\{X = x\} \cap \{Y = y\})$.

Let $p_{x\bullet} = P(X = x)$, and $p_{\bullet y} = P(Y = y)$, then

$$p_{x\bullet} = \sum_y p_{xy} \quad \text{and} \quad P(X = x \mid Y = y) = \frac{p_{xy}}{p_{\bullet y}}$$

Continuous distribution

$$\text{Joint cdf} \quad F(x, y) = P(\{X \leq x\} \cap \{Y \leq y\}) = \int_{x_0=-\infty}^x \int_{y_0=-\infty}^y f(x_0, y_0) dx_0 dy_0$$

$$\text{Joint pdf} \quad f(x, y) = \frac{\partial^2 F(x, y)}{\partial x \partial y}$$

$$\text{Marginal pdf of } X \quad f_X(x) = \int_{-\infty}^{\infty} f(x, y_0) dy_0$$

$$\text{Conditional pdf of } X \text{ given } Y = y \quad f_{X|Y}(x|y) = \frac{f(x, y)}{f_Y(y)} \quad (\text{provided } f_Y(y) > 0)$$

18. Linear regression

To fit the linear regression model $y = \alpha + \beta x$ by $\hat{y}_x = \hat{\alpha} + \hat{\beta}x$ from observations $(x_1, y_1), \dots, (x_n, y_n)$, the least squares fit is $\hat{\alpha} = \bar{y} - \bar{x}\hat{\beta}$, $\hat{\beta} = \frac{S_{xy}}{S_{xx}}$

$$\text{The residual sum of squares} \quad \text{RSS} = S_{yy} - \frac{S_{xy}^2}{S_{xx}}$$

$$\widehat{\sigma^2} = \frac{\text{RSS}}{n-2} = \frac{n-2}{\sigma^2} \widehat{\sigma^2} \text{ is from } \chi_{n-2}^2$$

$$E(\hat{\alpha}) = \alpha, \quad E(\hat{\beta}) = \beta,$$

$$\text{var}(\hat{\alpha}) = \frac{\sum x_i^2}{n S_{xx}} \sigma^2, \quad \text{var}(\hat{\beta}) = \frac{\sigma^2}{S_{xx}}, \quad \text{cov}(\hat{\alpha}, \hat{\beta}) = -\frac{\bar{x}}{S_{xx}} \sigma^2$$

$$\hat{y}_x = \hat{\alpha} + \hat{\beta}x, \quad E(\hat{y}_x) = \alpha + \beta x, \quad \text{var}(\hat{y}_x) = \left\{ \frac{1}{n} + \frac{(x - \bar{x})^2}{S_{xx}} \right\} \sigma^2$$

$$\frac{\hat{\alpha} - \alpha}{\widehat{\text{se}}(\hat{\alpha})}, \quad \frac{\hat{\beta} - \beta}{\widehat{\text{se}}(\hat{\beta})}, \quad \frac{\hat{y}_x - \alpha - \beta x}{\widehat{\text{se}}(\hat{y}_x)} \text{ are each from } t_{n-2}$$

E2.8 (Maths 3)

E2.11(?) ①

2011

Solution

(i) $w = u + iv = [(x - 1) + iy]^{-2}$ gives

$$u = \frac{(x - 1)^2 - y^2}{[(x - 1)^2 + y^2]^2} \quad v = -\frac{2(x - 1)y}{[(x - 1)^2 + y^2]^2} [3]$$

$$u^2 + v^2 = \frac{[(x - 1)^2 + y^2]^2}{[(x - 1)^2 + y^2]^4} = \frac{1}{[(x - 1)^2 + y^2]^2} \cdot [3]$$

Thus on $(x - 1)^2 + y^2 = R^{-2}$ we have $u^2 + v^2 = R^{-4}$. [2]

(ii) For $w = z^{-1}$ we have $u = \frac{x}{x^2+y^2}$ & $v = -\frac{y}{x^2+y^2}$ and $u^2 + v^2 = (x^2 + y^2)^{-1}$ [2], which makes

$$(x - 1)^2 + (y - 1)^2 = r^2 \quad *$$

into

$$\frac{1 - 2(u - v)}{u^2 + v^2} = r^2 - 2. [4]$$

Thus when $r^2 = 2$, we have $v = u - 1/2$. [3]

When $r^2 = 1$, we have $u^2 + v^2 + 1 - 2(u - v) = 0$ from which we obtain

$$(u - 1)^2 + (v + 1)^2 = 1. [3]$$

It is possible to do this the other way round (but longer) by writing $z = w^{-1}$ where $x = \frac{u}{u^2+v^2}$ and $y = -\frac{v}{u^2+v^2}$ and then substitute this into * and re-arrange.

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EE2

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Parts

a) $F(z) = \frac{z}{(z-1)^2(z-i)}$

$z=1$ is a double pole
 $z=i$ is a single pole

$$\text{Residue at } z=i \text{ is } \lim_{z \rightarrow i} \left\{ \frac{(z-i)z}{(z-1)^2(z-i)} \right\} = \frac{i}{(i-1)^2} = -\frac{1}{2}$$

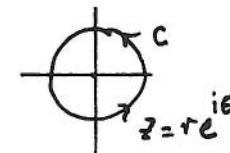
$$\therefore \text{Residue at } z=1 \text{ is } \lim_{z \rightarrow 1} \frac{d}{dz} \left\{ \frac{(z-1)^2 z}{(z-1)^2(z-i)} \right\} = \frac{-i}{(i-1)^2} = \frac{1}{2}$$

$$\text{From the Residue Theorem } \oint_{C_1} f(z) dz = 2\pi i \left(-\frac{1}{2} + \frac{1}{2} \right) = 0$$

The rectangle R_2 contains only $z=i$

$$\text{so } \oint_{C_2} f(z) dz = 2\pi i \left(-\frac{1}{2} \right) = -\pi i$$

b) i) $\oint_C \frac{dz}{z^2} = 2\pi i \times \{\text{Res of } z^{-1} \text{ at } z=0\}$
 $= 2\pi i$



ii) $\oint_C \frac{dz}{z} = i \oint_C \frac{z d\theta}{z^2} = i \oint_C d\theta \quad z=re^{i\theta}, dz=izd\theta$
 $= i \int_0^{2\pi} d\theta = 2\pi i$

iii) $\oint_C \frac{dz}{z} = \left[\ln z \right]_C = \left[\ln r + i\theta \right]_C$
 $= i[\theta]_0^{2\pi} = 2\pi i$

Setter's initials

VDG

Checker's initials

AOG

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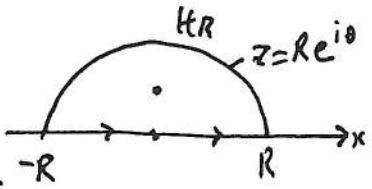
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Parts

$\oint_C e^{iz} F(z) dz$ with $F(z) = \frac{1}{(z^2+1)^2}$

$F(z)$ has a double pole at $z=i$ in the upper half-plane. Thus the residue of $e^{iz} F(z)$ at $z=i$ is



$$\lim_{z \rightarrow i} \left\{ \frac{d}{dz} \frac{e^{iz}(z-i)^2}{(z-i)^2(z+i)^2} \right\} = \left\{ e^{iz} \left[\frac{i(z+i)-2}{(z+i)^3} \right] \right\}_{z=i} = -\frac{1}{2}ie^{-1}$$

Using the R.T. we have

$$2\pi i \times \{-\frac{1}{2}ie^{-1}\} = \oint_C e^{iz} F(z) dz = \int_{-R}^R e^{inx} F(x) dx + \oint_{HR}$$

Now $\lim_{R \rightarrow \infty} \oint_{HR} e^{iz} F(z) dz = 0$ i) $m=1 > 0$
 Jordan's Lemma ii) Only sing. are poles
iii) $|F(z)| \rightarrow 0$ as $R \rightarrow \infty$.

Taking $R \rightarrow \infty$

$$\therefore \int_{-\infty}^{\infty} e^{inx} F(x) dx = \pi/e$$

Moreover $\int_{-\infty}^{\infty} \sin x F(x) dx = 0$ because the integrand is odd resulting in cancellation.

$$\therefore \int_{-\infty}^{\infty} \frac{\cos nx}{(x^2+1)^2} dx = \pi/e$$

Setter's initials

JDG

Checker's initials

ADG

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Question EE4		Marks & seen/unseen
Parts		
i)	$\bar{\pi}(\omega) = \int_{-\frac{1}{\omega}}^{\frac{1}{\omega}} e^{-i\omega t} 1 \cdot dt = -\frac{1}{i\omega} (e^{-\frac{t}{\omega}} - e^{\frac{t}{\omega}})$ $= \frac{2}{\omega} \sin \frac{t}{\omega} = \sin \omega$	2
ii)	$\bar{\Lambda}(\omega) = \int_{-1}^0 (1+t) e^{-i\omega t} dt + \int_0^1 (1-t) e^{-i\omega t} dt$ $= \int_{-1}^1 e^{-i\omega t} dt - 2 \int_0^1 t \cos \omega t dt$ $= \frac{1}{i\omega} (e^{i\omega} - e^{-i\omega}) - \frac{2}{\omega} \int_0^1 t d(\sin \omega t)$ $= \frac{2}{\omega} \sin \omega - \frac{2}{\omega} [(t \sin \omega t)'_0 - \int_0^1 \sin \omega t dt]$ $= \frac{2}{\omega} \left\{ \sin \omega - \sin \omega + \frac{1}{\omega} (t \cos \omega) \right\}$ $= \frac{4}{\omega^2} \sin^2 \frac{1}{2}\omega = \sin^2 \omega$	10
iii)	Parceval gives $\int_{-\infty}^{\infty} \text{sinc}^2 \omega d\omega = 2\pi \int_{-\infty}^{\infty} \bar{\pi}(\omega) ^2 d\omega$ $= 2\pi \int_{-\frac{1}{\omega}}^{\frac{1}{\omega}} 1 \cdot dt = 2\pi$	2
iv)	Also $\int_{-\infty}^{\infty} \text{sinc}^4 \omega d\omega = 2\pi \int_{-\infty}^{\infty} \bar{\Lambda}(\omega) ^2 d\omega$ $= 2\pi \int_{-1}^0 (1+t)^2 dt + 2\pi \int_0^1 (1-t)^2 dt$ $= 4\pi \int_0^1 (1-t)^2 dt$ $= 4\pi [t - t^2 + \frac{1}{3}t^3]'_0$ $= 4\pi/3$	6
	Setter's initials JDE	Checker's initials ADG
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	EXAMINATION QUESTIONS/SOLUTIONS 2010-11	Course EE2 paper 3
Question EES		Marks & seen/unseen
Parts	$\mathcal{L}(e^{at} f(t)) = \int_0^\infty e^{-(s-a)} f(t) dt$ $= \bar{f}(s-a) \quad \operatorname{Re}(s) > a$ <p>Now L.T. the ODE with ICs $x(0) = \dot{x}(0) = 0$</p> $\mathcal{L}(\ddot{x} + 4\dot{x} + 8x) = \mathcal{L}(\delta(t-1)) = \int_0^\infty e^{-st} f(t-1) dt$ $\therefore (s^2 + 4s + 8)\bar{x}(s) = e^{-s}$ $\therefore \bar{x}(s) = \frac{e^{-s}}{(s+2)^2 + 4} = \frac{\frac{1}{2} e^{-s}}{\frac{(s+2)^2 + 2^2}{f(s)}} \quad \text{Completing square}$ $\therefore \bar{f}(s) = \frac{1}{2} e^{-s} \rightarrow f(t) = \frac{1}{2} \delta(t-1)$ $\bar{g}(s) = \frac{2}{(s+2)^2 + 2^2} \rightarrow g(t) = e^{-2t} \sin 2t \quad \text{using Shift Thm}$ <p>If $\bar{x}(s) = \bar{f}(s) \bar{g}(s)$ then by the Convolution</p> $x(t) = \mathcal{L}^{-1}\{\bar{f}(s) \bar{g}(s)\} = \int_0^t f(t') g(t-t') dt'$ $= \int_0^t \frac{1}{2} \delta(t'-1) e^{-2(t-t')} \sin 2(t-t') dt'$ $= \begin{cases} \frac{1}{2} e^{-2(t-1)} \sin 2(t-1) & t > 1 \\ 0 & 0 \leq t \leq 1 \end{cases}$	Unseen 2 3 3 1 3 4 4
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	EXAMINATION QUESTIONS/SOLUTIONS 2010-11	Course EE2 Paper 3
Question EE6		Marks & seen/unseen
Parts	$\mathcal{L} \left(\int_0^t f(u) du \right) = \mathcal{L} \left(\int_0^t 1 \cdot f(u) du \right) = \mathcal{L} (1 \leftrightarrow f) \quad \text{Conv. Thm}$ $= \mathcal{L}(1) \mathcal{L}[f(t)] = \frac{1}{s} \bar{f}(s)$ <p>If $f(s) = [\bar{g}(s)]^2$ with $\bar{g}(s) = \frac{1}{s^2+1} \rightarrow g(t) = \sin t$</p> $\therefore f(t) = \mathcal{L}^{-1}[\bar{g}(s)\bar{g}(s)] = g(t) \leftrightarrow g(t)$ $= \int_0^t \sin u \sin(t-u) du$ $= \frac{1}{2} \int_0^t \{ \cos(2u-t) - \cos t \} du$ $= \frac{1}{2} \{ \left[\frac{1}{2} \sin(2u-t) - u \cos t \right]_0^t \}$ $f(t) = \frac{1}{2} (\sin t - t \cos t) \quad \text{---(1)}$ <p>Thus</p> $\mathcal{L}^{-1}\left\{\frac{1}{s} \bar{f}(s)\right\} = \int_0^t f(u) du$ <p>with $\bar{f}(s) = \frac{1}{(1+s^2)^2} + f(t)$ as in (1)</p> $\therefore \mathcal{L}^{-1}\left\{\frac{\bar{f}(s)}{s}\right\} = \int_0^t \frac{1}{2} (\sin u - u \cos u) du$ $= -\frac{1}{2} [\cos u]_0^t - \frac{1}{2} \int_0^t u \cos u du$ $= \frac{1}{2} (1 - \cos t) - \frac{1}{2} [u \sin u + \cos u]_0^t$ $= 1 - \cos t - \frac{1}{2} t \sin t$	Seen 5 Unseen 7 Unseen 8
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EE7

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Parts

Choose $\underline{u} = \hat{i}\varrho - \hat{j}P$ so $\operatorname{div} \underline{u} = \varrho_x - P_y$

Tangent unit vector is $\hat{t} = \frac{\hat{r}}{ds}$

$$\therefore \hat{t} = \hat{i} \frac{dx}{ds} + \hat{j} \frac{dy}{ds} \text{ & use } \hat{t} \cdot \hat{n}$$

$$\hat{n} = \pm \left(\hat{i} \frac{dy}{ds} - \hat{j} \frac{dx}{ds} \right) \text{ to construct}$$

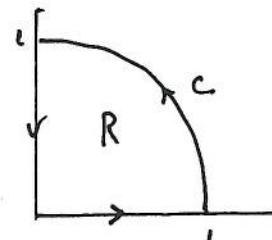
$$ds(\underline{u} \cdot \hat{n}) = P dx + Q dy$$

$$\text{Thus G.T. becomes } \oint_C \underline{u} \cdot \hat{n} ds = \iint_R (\varrho_x - P_y) dx dy \\ = \iint_A \operatorname{div} \underline{u} dx dy.$$

With $\underline{u} = \hat{i}x^2 + \hat{j}y^2$ and

$$\operatorname{div} \underline{u} = 2(x+y); \text{ thus.}$$

$$\iint_R (\operatorname{div} \underline{u}) dx dy = 2 \iint_R (x+y) dx dy$$



Use polar form where $dx dy = r dr d\theta$.

$$\therefore \iint_R \operatorname{div} \underline{u} dx dy = 2 \iint_R r(\cos \theta + \sin \theta) r dr d\theta.$$

$$= 2 \int_0^1 r^2 dr \int_0^{\pi/2} (\cos \theta + \sin \theta) d\theta$$

$$= \frac{2}{3} [\sin \theta - \cos \theta]_0^{\pi/2}$$

$$= \frac{2}{3} [(1-0) - (0-1)]$$

$$= \frac{4}{3}$$

(The line integral $\oint_C -y^2 dx + x^2 dy = \frac{4}{3}$ if evaluated over all 3 segments.)

unseen

2+2(pi)

2

4

2

2

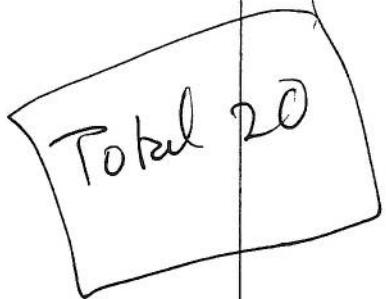
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Page number

	EXAMINATION QUESTIONS/SOLUTIONS 2010-2011	Course
Solution		
Question	C3	Marks & seen/unseen
Parts	$J = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix} = \begin{vmatrix} y & x \\ 2x & -2y \end{vmatrix}$ $= -2y^2 - 2x^2$ $\therefore J = 2(x^2 + y^2)$ <p>Now $du dv \rightarrow J^1 dx dy$ $dx dy \rightarrow J^1 du dv$</p> <p>Thus $J^1 = 1/ J = \frac{1}{2(x^2 + y^2)}$</p>	ALL UNSEEN
	$I_{OZ} = \iint_{R^*} (x^2 + y^2) \exp(x^2 - y^2) J^1 du dv$ <p>where x, y must be written in terms of u and v and R^* must be determined.</p> <p>Thus $I_{OZ} = \iint_{R^*} (x^2 + y^2) \frac{1}{2(x^2 + y^2)} e^v du dv$</p>	3
	Setter's initials RLW	Checker's initials AOG
		Page number 1/3

	EXAMINATION QUESTIONS/SOLUTIONS 2010-2011	Course
Question		Marks & seen/unseen
Parts	<p>Sketch in xy-plane</p> <p>Region R is shaded</p>	5
	<p>Sketch in uv-plane is obtained by noting that</p> <p>when (1) $y=0 \rightarrow u=0$</p> <p>(2) $y=x \rightarrow v=0$</p> <p>(3) $xy=1 \rightarrow u=1$</p> <p>(4) $x^2-y^2=1 \rightarrow v=1$</p> <p>Thus</p>	7
	Setter's initials RWT	Checker's initials AOG
		Page number 213

	EXAMINATION QUESTIONS/SOLUTIONS 2010-2011	Course
Solution		
Question		Marks & seen/unseen
C3		
Parts	<p>Finally</p> $\begin{aligned} P_{0z} &= \int_0^1 \int_0^1 \frac{1}{2} e^v dudv \\ &= \frac{1}{2} \cdot 1 \left[e^v \right]_0^1 = \frac{1}{2}(e-1) , \end{aligned}$ 3	
		
	Setter's initials RLJ	Checker's initials AOG
		Page number 3/3

	EXAMINATION QUESTIONS/SOLUTIONS 2010-2011	Course Core 4
Solution	Question C4	Marks & seen/unseen
Parts	(a) For $r < R$ $\phi(r) = \frac{Q}{8\pi R} \left(3 - \frac{x^2 + y^2 + z^2}{R^2} \right)$ (ALL UNSEEN)	
	$\therefore \text{grad } \phi(r) = \frac{Q}{8\pi R} \frac{2(x_i + y_j + z_k)}{R^2}$ (1) 3	
	For $r > R$ $\phi(r) = \frac{Q}{4\pi} \frac{1}{(x^2 + y^2 + z^2)^{1/2}}$	
	$\therefore \text{grad } \phi = \frac{Q}{4\pi} \left(-\frac{1}{2} \right) \cdot \frac{2(x_i + y_j + z_k)}{(x^2 + y^2 + z^2)^{3/2}}$	
	$= -\frac{Q}{4\pi} \frac{\sum_{i,j,k} r_i r_j r_k}{r^3}$ (2) 3	
	For $r < R$ use (1) to get	
	$\text{div grad } \phi = -\frac{Q}{8\pi R^3} 2 \cdot 3 = -\frac{Q}{4\pi R^3/3}$ 3 X	
	For $r > R$ use (2) to get	
	$\text{div grad } \phi = -\frac{Q}{4\pi} \left\{ \frac{\partial}{\partial x} \left[\frac{x}{(x^2 + y^2 + z^2)^{3/2}} \right] + \frac{\partial}{\partial y} \left[\frac{y}{(x^2 + y^2 + z^2)^{3/2}} \right] + \frac{\partial}{\partial z} \left[\frac{z}{(x^2 + y^2 + z^2)^{3/2}} \right] \right\}$	
	\Rightarrow Next page	
	Setter's initials RLJ	Checker's initials Ade
		Page number 1/2

	EXAMINATION QUESTIONS/SOLUTIONS 2010-2011	Course Core 4
Solution Question		
Parts		
C4	$\text{div grad } \varphi = -\frac{Q}{4\pi} \left\{ \frac{1}{(x^2+y^2+z^2)^{3/2}} - \frac{3x^2}{2(x^2+y^2+z^2)^{5/2}} \right.$ $+ \frac{1}{(x^2+y^2+z^2)^{3/2}} - \frac{3y^2}{2(x^2+y^2+z^2)^{5/2}}$ $+ \frac{1}{(x^2+y^2+z^2)^{3/2}} - \frac{3z^2}{2(x^2+y^2+z^2)^{5/2}} \left. \right\}$ $= -\frac{Q}{4\pi} \left\{ \frac{3}{r^3} - \frac{3(x^2+y^2+z^2)}{r^5} \right\} = 0$	X 5
(b) For $x^2+y^2 < a^2$ and $\vec{A} =$	$\begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & -\frac{I}{4\pi a^2} (x^2+y^2) \end{vmatrix}$ $= -\frac{I}{4\pi a^2} (i^2 y - j^2 x)$	X 3
For $x^2+y^2 > a^2$	$\text{curl } \vec{A} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & -\frac{I}{4\pi a^2} [1 + \ln \frac{x^2+y^2}{a^2}] \end{vmatrix}$ $= -\frac{I}{4\pi} \frac{2y i - 2x j}{x^2+y^2}$	X 3
	Total 20	
Setter's initials RW	Checker's initials AOG	Page number 2/2

EXAMINATION QUESTIONS/SOLUTIONS 2010-2011		Course Core 5
Solution	Question Q1	Marks & seen/unseen
Parts	<p>The condition is that $\frac{\partial f}{\partial y} = \frac{\partial g}{\partial x}$ everywhere inside a simply-connected region R containing A, B and the path P.</p> <p>In the particular case $f = x e^y + b \sin y$</p> <p>$y = ax^2 e^y + c \cos y$</p> <p>so $\frac{\partial f}{\partial y} = x e^y$, $\frac{\partial g}{\partial x} = 2ax e^y$</p> <p>thus for condition to be satisfied $a = \frac{1}{2}$</p> <p>but b and c can be anything.</p>	
	<p>Potential $V(x, y)$ satisfies</p> $\frac{\partial V}{\partial x} = x e^y + b \sin x, \quad \frac{\partial V}{\partial y} = \frac{1}{2} x^2 e^y + c \cos y.$ <p>Thus $V = \frac{1}{2} x^2 e^y - b \cos x + h(y)$</p> <p>from (1) $\frac{\partial h}{\partial y} = c \cos y$</p> <p>using (2) $\frac{1}{2} x^2 e^y + \frac{dh}{dy} = c \cos y + \frac{1}{2} x^2 e^y$</p> <p>$\therefore h = c \sin y + d$ ← arbitrary const.</p> <p>$\therefore V(x, y) = \frac{1}{2} x^2 e^y - b \cos x + c \sin y + d$</p> <p>Int $\rightarrow V(\pi/2, 0) - V(0, \pi/2) = \frac{1}{2} (\frac{\pi}{2})^2 + b - c$ (*)</p>	(UNSEEN) 2

	EXAMINATION QUESTIONS/SOLUTIONS 2010-2011	Course Core 5
Question CJ		Marks & seen/unseen
Parts	<p><i>solution</i></p> <p>Simplest path</p> <p>$\int \int$</p> <p> $\int_{\frac{\pi}{2}}^0 c \cos y dy + \int_0^b (x - b \sin x) dx$ $= [c \sin y]_{\frac{\pi}{2}}^0 + \left[\frac{x^2}{2} - b \cos x \right]_0^{\frac{\pi}{2}}$ $= -c + \left(\frac{\pi}{2} \right)^2 + b$ </p> <p style="text-align: right;">6</p> <p>Same as previous (*)</p>	(UNSEEN)
	Setter's initials RLJ	Checker's initials Aob
		Page number 2/2

TOTAL 20

10) i) $f_x = f_y$ everywhere inside a S -closed region R
containing A, B & the path.

2

ii) $f = xe^y + b \sin x; g = ax^2 e^y + c \cos y$

$$2axe^y = xe^y \Rightarrow a = \frac{1}{2}, b+c \text{ anything.}$$

5

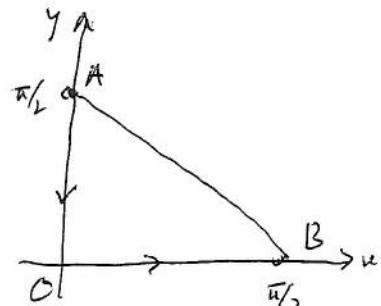
iii) $V_x = xe^y + b \sin x \Rightarrow V = \frac{1}{2}x^2 e^y - b \cos x + h(y)$

$$V_y = ax^2 e^y + c \cos y \Rightarrow V = ax^2 e^y + c \sin y + i(x)$$

$$\therefore a = \frac{1}{2} \quad \therefore h(y) = (b \cos x + c \sin x + i(x))_x$$

5

$$\therefore V = \frac{1}{2}x^2 e^y - b \cos x + c \sin x + d$$



a) $A = (0, \pi/2) \text{ & } B = (\pi/2, 0)$

$$f = V_x, \quad g = V_y.$$

$$\therefore I = \int_P V_x dx + V_y dy = \int_P dV = [V]_A^B$$

$$\begin{aligned} &= V[\pi/2, 0] - V[0, \pi/2] = \left[\frac{1}{2} \left(\frac{\pi}{2} \right)^2 + b \cdot \frac{\pi}{2} + d \right] - [-b + c + d] \\ &= \frac{\pi^2}{8} + b - c. \end{aligned}$$

2

b) Path \vec{AO} then \vec{OB} : $\int_{AO} = V[0, 0] - V[\pi/2, 0]$ as before.

6

Actual evaluation $\int_{AO} = V[\pi/2, 0] - V[0, 0]$

$$\int_{AO} = \int \{(ne^y + b \sin x) dx + (\frac{1}{2}x^2 e^y + c \cos y) dy\} = c \int \cos y dy = -c$$

$$\int_{OB} = \int \{(\) dx + (\) dy\} = \int_0^{\pi/2} (n + b \sin x) dx = \frac{\pi^2}{8} + b \text{ as before}$$

E 2.8 (Maths 3) 2011 — Solutions

11. (a) Pistons: $X \sim N(88, 0.7^2)$.

$$\begin{aligned}P(\text{'acceptable'}) &= P(89.7 - 5 < X < 89.7) \\&= P\left(\frac{84.7 - 88}{0.7} < Z < \frac{89.7 - 88}{0.7}\right) \\&= P(-4.71 < Z < 2.43) \\&= \Phi(2.43) - \Phi(-4.71) = 0.992 - 0 = 0.992\end{aligned}$$

Seen similar — 5 MARKS

(b) Cylinders: $Y \sim N(91, 1)$, so

$$Y - X \sim N(91 - 88, 1 + 0.7^2) \Rightarrow Y - X \sim N(3, 1.49).$$

$$\begin{aligned}P(\text{'acceptable'}) &= P(0 < Y - X < 5) = P\left(\frac{0 - 3}{\sqrt{1.49}} < Z < \frac{5 - 3}{\sqrt{1.49}}\right) \\&= P(-2.46 < Z < 1.64) = 0.949 - 0.007 = 0.942\end{aligned}$$

Unseen — 6 MARKS

(c) If A is the number of acceptable units, then

$$A \sim \text{Bin}(10, 0.942)$$

and the probability of there being more than 2 unacceptable units is

$$\begin{aligned}P(A < 8) &= 1 - P(A \geq 8) \\&= 1 - P(A = 8) - P(A = 9) - P(A = 10) \\&= 1 - \binom{10}{8} 0.942^8 (1 - 0.942)^2 + \binom{10}{9} 0.942^9 (1 - 0.942)^1 + 0.942^{10} \\&= 1 - 0.094 - 0.339 - 0.550 \\&= 0.017\end{aligned}$$

Seen similar — 9 MARKS

12. (a) This is a second-order autoregression (or AR(2) process), because of the presence of the term y_{t-2} .

Seen similar — 1 MARKS

- (b) For any process $\{x_t\}$, the backshift operator B is defined as $Bx_t = x_{t-1}$.

From the LHS:

$$\begin{aligned}(2 - B)(3 - B)y_t &= (6 - 5B + B^2)y_t = 6y_t - 5y_{t-1} + y_{t-2} \\ &= 6(y_t - \frac{5}{6}y_{t-1} + \frac{1}{6}y_{t-2}) = 6\frac{1}{6}e_t = e_t\end{aligned}$$

$E(y_t) = 0$, because the errors $\{e_t\}$ all have mean 0.

Seen similar — 5 MARKS

- (c) From the LHS:

$$\frac{1}{2-B} - \frac{1}{3-B} = \frac{3-B-(2-B)}{(2-B)(3-B)} = \frac{1}{(2-B)(3-B)}.$$

Hence:

$$\begin{aligned}y_t &= (2 - B)^{-1}e_t - (3 - B)^{-1}e_t \\ &= \frac{1}{2} \sum_{j=0}^{\infty} \left(\frac{B}{2}\right)^j e_t - \frac{1}{3} \sum_{j=0}^{\infty} \left(\frac{B}{3}\right)^j e_t \\ &= \sum_{j=0}^{\infty} \left(\frac{1}{2}\right)^{j+1} B^j e_t - \sum_{j=0}^{\infty} \left(\frac{1}{3}\right)^{j+1} B^j e_t \\ &= \sum_{j=0}^{\infty} \left(\frac{1}{2}\right)^{j+1} e_{t-j} - \sum_{j=0}^{\infty} \left(\frac{1}{3}\right)^{j+1} e_{t-j} \\ &= \sum_{j=0}^{\infty} \left[\left(\frac{1}{2}\right)^{j+1} - \left(\frac{1}{3}\right)^{j+1} \right] e_{t-j}.\end{aligned}$$

Seen similar — 7 MARKS

The errors are uncorrelated, so the variance of their sum is equal to the sum of their variances. The variance of y_t is thus:

$$\begin{aligned}\text{Var}(y_t) &= \sum_{j=0}^{\infty} \left[\left(\frac{1}{2}\right)^{j+1} - \left(\frac{1}{3}\right)^{j+1} \right]^2 \text{Var}(e_{t-j}) \\ &= \sum_{j=0}^{\infty} \left[\left(\frac{1}{4}\right)^{j+1} - 2\left(\frac{1}{6}\right)^{j+1} + \left(\frac{1}{9}\right)^{j+1} \right] \\ &= \frac{1/4}{1-1/4} - 2\frac{1/6}{1-1/6} + \frac{1/9}{1-1/9} = \frac{7}{120}\end{aligned}$$

Seen similar — 7 MARKS