

IMPERIAL COLLEGE LONDON

DEPARTMENT OF ELECTRICAL AND ELECTRONIC ENGINEERING  
EXAMINATIONS 2006

EEE/ISE PART II: MEng, BEng and ACGI

**SIGNALS AND LINEAR SYSTEMS**

Corrected Copy

*None*

Wednesday, 7 June 2:00 pm

Time allowed: 2:00 hours

**There are FOUR questions on this paper.**

**Q1 is compulsory.**

**Answer Q1 and any two of questions 2-4.**

**Q1 carries 40% of the marks. Questions 2 to 4 carry equal marks (30% each).**

**Any special instructions for invigilators and information for candidates are on page 1.**

Examiners responsible

First Marker(s) : P.T. Stathaki,

Second Marker(s) : A.G. Constantinides,

1.

Consider the discrete-time system with the following input-output relationship

$$y[n] = \frac{x[n] - x[n-1]}{2} \quad (1)$$

with  $x[n]$  the input of the system and  $y[n]$  the output of the system.

- (i) Is this system linear and time-invariant? Justify your answer. [5]
- (ii) Find the impulse response  $h[n]$  of the system and express it compactly in a mathematical form. Sketch the impulse response. [5]

- (iii) Find the step response  $s[n]$  of the system and express it compactly in a mathematical form. Sketch the step response. [5]

- (iv) By performing the discrete time convolution  $y[n] = x[n] * h[n]$  find the output  $y[n]$  of the system when the input is given by

$$x[n] = \begin{cases} n, & n = 0, 1, 2, 3, 4 \\ 0, & \text{otherwise.} \end{cases} \quad (2)$$

Verify that the output is indeed the output expected from the filter defined in Equation (1) above, when the input is the signal  $x[n]$  defined in Equation (2) above. [5]

- (v) Consider a discrete signal  $x[n]$  with Discrete Time Fourier Transform  $X(e^{j\omega})$ . Find the Discrete Time Fourier Transform of the signal  $x[n - n_0]$  with  $n_0$  any integer. [5]

- (vi) Find the Discrete Time Fourier Transform of the signal  $x[n]$  defined in (iv). [5]

- (vii) Consider a discrete signal  $x[n]$  with z-transform  $X(z)$ . Find the z-transform of the signal  $x[n - n_0]$  with  $n_0$  any integer. [5]

- (viii) Find the z-transform of the output  $y[n]$  of the system defined in Equation (1) above, when the input is the function  $x[n]$  defined in (iv). [5]

2.

- (a) Consider a discrete, real and even signal  $x_1[n]$  that is periodic with period  $N=7$  and fundamental frequency  $\omega_0 = \frac{2\pi}{N}$ .

- (i) Prove that the Fourier series coefficients  $c_k$  of  $x_1[n]$  given by

$$c_k = \frac{1}{N} \sum_{n=0}^{N-1} x_1[n] e^{-jk(2\pi/N)n}$$

are real and even.

[6]

- (ii) Show that the coefficients  $c_k$  are periodic with respect to  $k$  with period  $N=7$ .

[6]

- (iii) Given that

$$c_{15} = 1, c_{16} = 2, c_{17} = 3,$$

determine the values of  $c_{-1}$ ,  $c_{-2}$ ,  $c_{-3}$ .

[6]

**(Definition:** A discrete signal  $x[n]$  is even if  $x[-n] = x[n]$ ).

- (b) Find the Discrete Time Fourier Transform of the discrete signal  $x_2[n] = a^n u[n]$ ,  $|a| < 1$ , where  $u[n]$  is the discrete unit step function defined as

$$u[n] = \begin{cases} 1, & n \geq 0 \\ 0, & \text{otherwise.} \end{cases}$$

You may wish to use the relationship  $\sum_{n=0}^{+\infty} x^n = \frac{1}{1-x}$ , if  $|x| < 1$ .

[6]

- (c) The input  $x[n]$  and output  $y[n]$  of a stable and causal linear, time-invariant system are related by the difference equation

$$y[n] - \frac{5}{6} y[n-1] + \frac{1}{6} y[n-2] = -x[n].$$

Find the impulse response of this system.

[6]

3.

(a) Consider a continuous-time signal  $x(t)$  which is sampled uniformly with sampling period  $T_s$  to obtain the signal  $x_s(t) = x(t) \sum_{k=-\infty}^{+\infty} \delta(t - kT_s)$ , where  $\delta(t)$  is the continuous-time impulse function.

(i) Prove that  $x_s(t) = \frac{1}{T_s} x(t) \sum_{k=-\infty}^{+\infty} e^{jk\frac{2\pi}{T_s}t}$ . [7]

(ii) Prove that the Fourier transform of the sampled signal  $x_s(t)$  is  $X_s(\omega) = \frac{1}{T_s} \sum_{k=-\infty}^{+\infty} X(\omega + k\omega_s)$ ,  $\omega_s = \frac{2\pi}{T_s}$  where  $X(\omega)$  is the Fourier transform of the original signal  $x(t)$ . [8]

(b) Consider a continuous-time signal  $x(t)$  with Fourier transform  $X(\omega) = (1 - \frac{|\omega|}{2\pi \times 10^3}) \Pi(\frac{\omega}{4\pi \times 10^3})$  where  $\omega$  is the angular frequency and  $\Pi(\omega)$  is defined as:

$$\Pi(\omega) = \begin{cases} 1 & |\omega| < 0.5 \\ 0.5 & |\omega| = 0.5 \\ 0 & \text{otherwise.} \end{cases}$$

We sample  $x(t)$  uniformly with sampling period  $T_s$  to obtain the signal  $x_s(t) = x(t) \sum_{k=-\infty}^{+\infty} \delta(t - kT_s)$ .

(i) How large can  $T_s$  be and yet allow perfect reconstruction of the continuous-time signal from its samples? [7]

(ii) Sketch the Fourier transform of  $x_s(t)$ ,  $X_s(\omega)$ , assuming  $T_s = 0.1\text{ms}$ . [8]

4.

- (a) (i) Find the analytical expression and the region of convergence (ROC) of the z-transform of the discrete causal signal  $x[n] = a^n u[n-1]$ , with  $a$  real and  $u[n]$  the discrete unit step function defined as

$$u[n] = \begin{cases} 1, & n \geq 0 \\ 0, & \text{otherwise.} \end{cases}$$

[6]

- (ii) Find the analytical expression and the region of convergence (ROC) of the z-transform of the discrete anti-causal signal  $x[n] = -a^n u[-n]$ , with  $a$  real and  $u[n]$  the discrete unit step function.

[6]

For parts (a) (i), (a) (ii) you may wish to use the relationship  $\sum_{n=0}^{+\infty} x^n = \frac{1}{1-x}$ , if  $|x| < 1$ .

- (b) Consider a linear, time-invariant system with input  $x[n]$  and output  $y[n]$  related by the difference equation

$$y[n] - \frac{9}{2} y[n-1] + 2y[n-2] = -7x[n].$$

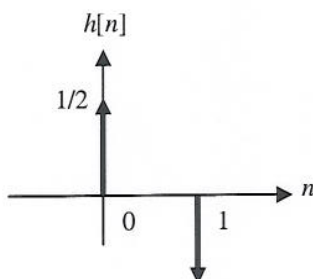
Determine the impulse response and its z-transform in the following three cases:

- (i) The system is causal.
- (ii) The system is stable.
- (iii) The system is neither causal nor stable.

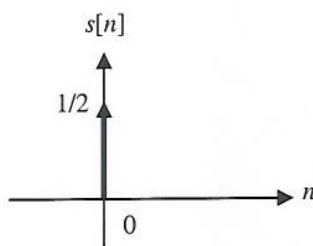
[18]

Answer

- (i) Yes, since if the inputs  $x_1[n]$  and  $x_2[n]$  produce the outputs  $y_1[n]$  and  $y_2[n]$  respectively, the input  $a_1x_1[n] + a_2x_2[n]$  will produce the output  $a_1y_1[n] + a_2y_2[n]$ .
- (ii) The impulse response of the system  $h[n]$  is defined as the output of the system when the input is the impulse function  $\delta[n]$ . Therefore,  $h[n] = \frac{\delta[n] - \delta[n-1]}{2}$ . This function is shown below:



- (iii) The step response of the system  $s[n]$  is defined as the output of the system when the input is the unit step function  $u[n]$ . Therefore,  $s[n] = \frac{u[n] - u[n-1]}{2} = \frac{\delta[n]}{2}$ . This function is shown below:



- (iv) This is defined as  $y[n] = \sum_{k=-\infty}^{+\infty} x[k]h[n-k]$ . In that case  $x[k]$  is non-zero if  $0 \leq k \leq 4$  and  $h[n-k]$  is non-zero if  $0 \leq n-k \leq 1 \Rightarrow -1 \leq -n+k \leq 0 \Rightarrow n-1 \leq k \leq n$ . We may find three separate cases for which the two intervals overlap, and therefore the convolution is non-zero.

1. The lower bound of the function  $x[k]$  lies within the bounds of the function  $h[n-k]$ , i.e.,  $n-1 \leq 0 \leq n \Rightarrow 0 \leq n \leq 1$ .

In that case  $y[n] = \sum_{k=-\infty}^{+\infty} x[k]h[n-k] = \sum_{k=0}^n \frac{1}{2}(\delta[n-k] - \delta[n-k-1])k = \frac{1}{2}n$ . Therefore,

$$y[0] = 0 \text{ and } y[1] = \frac{1}{2}.$$

2. The bounds of the function  $h[n-k]$  are included within the bounds of the function  $x[k]$ ,  $n-1 > 0 \Rightarrow n > 1$  and  $n \leq 4$ , i.e.,  $1 < n \leq 4$

$$\text{In that case } y[n] = \sum_{k=n-1}^n \frac{1}{2}(\delta[n-k] - \delta[n-k-1])k = -\frac{(n-1)}{2} + \frac{n}{2} = \frac{1}{2}.$$

3. The upper bound of the function  $x[k]$  lies within the bounds of the function  $h[n-k]$ , i.e.,  $n-1 \leq 4 < n \Rightarrow 4 < n \leq 5 \Rightarrow n = 5$ .

$$\text{In that case } y[5] = \sum_{k=-\infty}^{+\infty} x[k]h[5-k] = x[5]h[0] + x[4]h[1] = 5\frac{1}{2} - 4\frac{1}{2} = \frac{1}{2}.$$

Thus,



$$y[n] = \begin{cases} 0 & n = 0 \\ \frac{1}{2} & n = 1, 2, 3, 4, 5 \\ 0 & \text{otherwise} \end{cases}$$

From the relationship  $y[n] = \frac{x[n] + x[n-1]}{2}$  we see that for the given function  $x[n]$  we can get  $y[n]$  as above, since:

$$y[0] = \frac{x[0] - x[-1]}{2} = 0, \quad y[1] = \frac{x[1] - x[0]}{2} = \frac{1}{2}, \text{ etc.}$$

$$(v) \quad \sum_{n=-\infty}^{\infty} x[n-n_0]e^{-j\omega n} = \sum_{n=-\infty}^{\infty} x[n-n_0]e^{-j\omega(n-n_0)}e^{-j\omega n_0} = e^{-j\omega n_0} X(e^{j\omega})$$

$$(vi) \quad \sum_{n=1}^4 ne^{-j\omega n} = e^{-j\omega} + 2e^{-2j\omega} + 3e^{-3j\omega} + 4e^{-4j\omega}$$

$$(vii) \quad \sum_{n=-\infty}^{\infty} x[n-n_0]z^{-n} = \sum_{n=-\infty}^{\infty} x[n-n_0]z^{-(n-n_0)}z^{-n_0} = z^{-n_0} X(z)$$

$$(viii) \quad Y(z) = X(z) \frac{1-z^{-1}}{2} = (z^{-1} + 2z^{-2} + 3z^{-3} + 4z^{-4}) \frac{1-z^{-1}}{2}$$

2.

(a) Consider the discrete, real and even signal  $x[n]$  that is periodic with period  $N=7$  and fundamental frequency  $\omega_0 = \frac{2\pi}{N}$ . Suppose that the Fourier series coefficients of  $x(t)$  are  $c_k$ .

$$(i) \quad c_k = \frac{1}{N} \sum_{n=0}^{N-1} x_1[n] e^{-jk(2\pi/N)n} \text{ and also}$$

$$c_k = \frac{1}{N} \sum_{n=-(N-1)}^0 x_1[n] e^{-jk(2\pi/N)n} = \frac{1}{N} \sum_{n=0}^{N-1} x_1[-n] e^{jk(2\pi/N)n} = \frac{1}{N} \sum_{n=0}^{N-1} x_1[n] e^{jk(2\pi/N)n} = c_k^*$$

$$c_{-k} = \frac{1}{N} \sum_{n=0}^{N-1} x_1[n] e^{-jk(2\pi/N)(-n)} = \frac{1}{N} \sum_{n=0}^{-(N-1)} x_1[-n] e^{-jk(2\pi/N)n} = \frac{1}{N} \sum_{n=0}^{-(N-1)} x_1[n] e^{-jk(2\pi/N)n} = c_k$$

(ii)

$$c_{k+N} = \frac{1}{N} \sum_{n=0}^{N-1} x_1[n] e^{-j(k+N)(2\pi/N)n} = \frac{1}{N} \sum_{n=0}^{N-1} x_1[n] e^{-jk(2\pi/N)n} e^{-j2\pi n} = c_k$$

(iii) Since the Fourier series coefficients  $c_k$  will be real and even. Given that

$$c_{15} = 1, \quad c_{16} = 2, \quad c_{17} = 3$$

determine the values of  $c_{-1}$ ,  $c_{-2}$ ,  $c_{-3}$ .

$$c_{-1} = c_1 = c_{15} = 1$$

$$c_{-2} = c_2 = c_{16} = 2$$

$$c_{-3} = c_3 = c_{17} = 3$$

(b) Find the Fourier transform of the discrete signal  $x[n] = a^n u[n]$ ,  $|a| < 1$ .

$$\text{In this case } X(e^{j\omega}) = \sum_{n=-\infty}^{+\infty} a^n u[n] e^{-j\omega n} = \sum_{n=0}^{+\infty} (ae^{-j\omega})^n = \frac{1}{1 - ae^{-j\omega}}, \quad |a| < 1$$

(c) The input and output of a stable and causal LTI system are related by the differential equation

$$y[n] - \frac{5}{6} y[n-1] + \frac{1}{6} y[n-2] = -x[n]$$

Find the impulse response of this system.

We take the Fourier transform in both sides:

$$Y(e^{j\omega}) - \frac{5}{6}e^{-j\omega}Y(e^{j\omega}) + \frac{1}{6}e^{-2j\omega}Y(e^{j\omega}) = -X(e^{j\omega}) \Rightarrow$$

$$\frac{Y(e^{j\omega})}{X(e^{j\omega})} = \frac{-1}{1 - \frac{5}{6}e^{-j\omega} + \frac{1}{6}e^{-2j\omega}} = \frac{-1}{(1 - \frac{1}{2}e^{-j\omega})(1 - \frac{1}{3}e^{-j\omega})} =$$

$$\frac{2}{(1 - \frac{1}{3}e^{-j\omega})} - \frac{3}{(1 - \frac{1}{2}e^{-j\omega})} \Rightarrow$$

$$h[n] = [2(\frac{1}{3})^n - 3(\frac{1}{2})^n]u[n]$$

3.

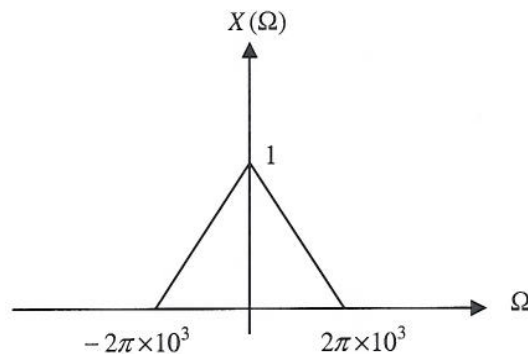
(a)(i) The continuous-time impulse train  $\sum_{k=-\infty}^{\infty} \delta(t - kT_s)$  is a periodic function and therefore it can be

written using Fourier series. The Fourier series coefficients are  $c_k = \frac{1}{T_s} \int_{-\frac{T_s}{2}}^{\frac{T_s}{2}} \delta(t) e^{-jk\omega_s t} dt = \frac{1}{T_s}$ .

Therefore,  $x_s(t) = x(t) \sum_{k=-\infty}^{+\infty} \delta(t - kT_s) = \frac{1}{T_s} x(t) \sum_{k=-\infty}^{+\infty} e^{jk\frac{2\pi}{T_s}t}$

(ii) The Fourier transform of the signal  $e^{j\omega_s t} x(t)$  is  $X(j(\omega - \omega_s))$  and therefore the Fourier transform of the sampled signal  $x_s(t)$  is  $X_s(e^{j\omega}) = \frac{1}{T_s} \sum_{k=-\infty}^{k=+\infty} X(\omega + k\omega_s)$ ,  $\omega_s = \frac{2\pi}{T_s}$ .

(b)(i) The function  $\Pi(\frac{\Omega}{4\pi \times 10^3})$  is equal to 1 if  $-\frac{1}{2} < \frac{\Omega}{4\pi \times 10^3} < \frac{1}{2} \Rightarrow -2\pi \times 10^3 < \Omega < 2\pi \times 10^3$ , equal to  $\frac{1}{2}$  if  $\Omega = \pm 2\pi \times 10^3$  and 0 otherwise. Therefore,  $X(\Omega)$  has the form shown below.

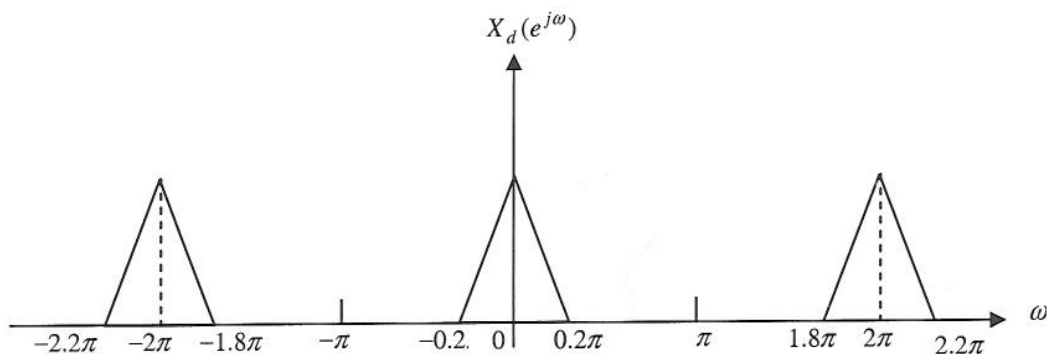


Based on the sampling theorem (called also Nyquist criterion) the sampling frequency must be at twice the maximum frequency of the signal. In that case:

$$\Omega_s = 2\pi f_s \geq 2(2\pi \times 10^3) \Rightarrow f_s \geq 2 \times 10^3 \Rightarrow T_s = \frac{1}{f_s} \leq 0.5 \times 10^{-3}$$

(ii) Based on the analysis given in the first section of this set of notes, the DTFT of  $x[n]$  has the form shown below. The horizontal axis  $\omega$  is the axis  $\Omega$  shown above, multiplied by  $T_s = 10^{-4}$  sec





4.

(a) (i) The z transform expression is

$$X(z) = \sum_{n=1}^{+\infty} a^n z^{-n} = \sum_{n=0}^{+\infty} (az^{-1})^n - 1$$

If  $|az^{-1}| < 1$ , or equivalently,  $|z| > |a|$ , the above sum converges and

$$X(z) = \frac{1}{1 - az^{-1}} - 1 = \frac{z}{z - a} - 1 = \frac{a}{z - a}, |z| > |a|$$

$$x(n) = \begin{cases} -a^n & n < 0 \\ 0 & n \geq 0 \end{cases}$$

(ii) The z transform expression is

$$X(z) = - \sum_{n=-\infty}^0 a^n z^{-n} = - \sum_{n=0}^{+\infty} a^{-n} z^n$$

If  $|a^{-1}z| < 1$ , or equivalently,  $|z| < |a|$ , the above sum converges and

$$X(z) = - \frac{1}{1 - a^{-1}z} = \frac{a}{z - a}, |z| < |a|$$

(b)  $y[n] - \frac{9}{2}y[n-1] + 2y[n-2] = -7x[n] \Rightarrow Y(z) - \frac{9}{2}z^{-1}Y(z) + 2z^{-2}Y(z) = -7X(z)$

$$\Rightarrow H(z) = \frac{-7}{1 - \frac{9}{2}z^{-1} + 2z^{-2}} = \frac{1}{1 - \frac{1}{2}z^{-1}} - \frac{8}{1 - 4z^{-1}} \Rightarrow$$

Causal  $h(n) = (\frac{1}{2})^n u[n] + 4^n u[n]$

Stable  $h(n) = (\frac{1}{2})^n u[n] - 4^n u[-n-1]$

Nether causal nor stable  $h(n) = -(\frac{1}{2})^n u[-n-1] + 4^n u[n]$  or

$$h(n) = -(\frac{1}{2})^n u[-n-1] - 4^n u[-n-1]$$