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EE3-01
EE9AC1

IMPERIAL COLLEGE LONDON

DEPARTMENT OF ELECTRICAL AND ELECTRONIC ENGINEERING
EXAMINATIONS 2011

MSc and EEE PART III/IV: MEng, BEng. and ACGI

ANALOGUE INTEGRATED CIRCUITS AND SYSTEMS

Tuesday, 10 May 2:30 pm

Time allowed: 3:00 hours

There are SIX questions on this paper.

Answer FOUR questions.

All questions carry equal marks

Any special instructions for invigilators and information for candidates are on page 1.

Examiners responsible First Marker(s) : C. Toumazou
Second Marker(s) : P. Georgiou

1. (a) Figures 1.1 and 1.2 show two popular biasing schemes typically used in analogue integrated systems. Briefly outline the main feature of each of these circuits.

[4]

For the bandgap voltage reference circuit of Figure 1.1, show that $\delta V_0 / \delta T = 0$ (where T is temperature) if $(R_2/R_3) \ln [I_1/I_2] = 29$ for $V_0 = 1.283$ V. Assume the temperature coefficient of V_{BE} to be $-2.5\text{mV}/^\circ\text{C}$, the collector current of transistor Q_3 is $100\mu\text{A}$ and the device saturation current is $I_S = 1.2 \times 10^{-13}$ A. Boltzmann's constant $k = 1.38 \times 10^{-23}$ J/K and the electron charge is $q = 1.6 \times 10^{-19}$ C.

[7]

- (b) Show that the circuit of Figure 1.2 can be developed into a current source with output current directly proportional to absolute temperature and virtually independent of supply voltage. Since it is likely that on power-up the output current will fall into a zero current state, sketch a suitable start-up circuit that ensures that this condition will not occur and explain the operation of the circuit.

[9]

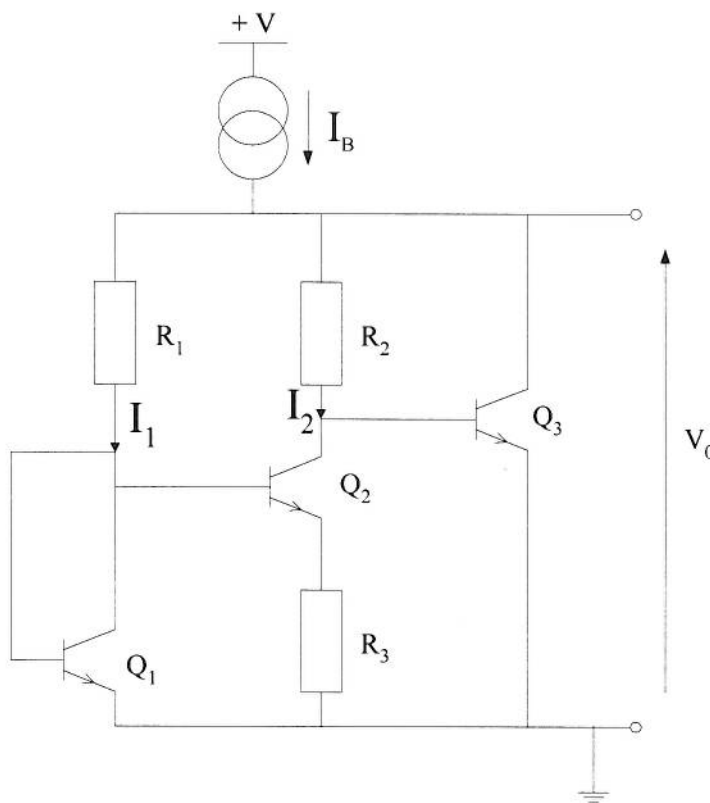


Figure 1.1

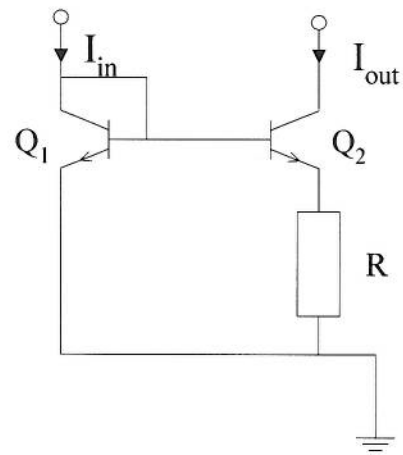


Figure 1.2

2. (a) Sketch a typical circuit diagram for a single-stage fully differential folded cascode CMOS op-amp. Briefly explain the concept of common-mode feedback with reference to your folded cascode op-amp and sketch a common-mode feedback circuit.

[8]

- (b) Estimate the low-frequency differential voltage gain, slew rate and gain-bandwidth product of the two-stage CMOS op-amp shown in Figure 2. Aspect ratios of all devices are shown on the circuit. Assume all bulk effects are negligible. Device model parameters are given below.

[10]

- (c) Explain qualitatively why the addition of a resistor in series with compensation capacitor C_c improves amplifier stability.

[2]

CMOS TRANSISTOR PARAMETERS

MODEL PARAMETERS	K_p ($\mu\text{A/V}^2$)	λ (V^{-1})	V_{T0} (V)
PMOS	20	0.03	-0.8
NMOS	30	0.02	1.0

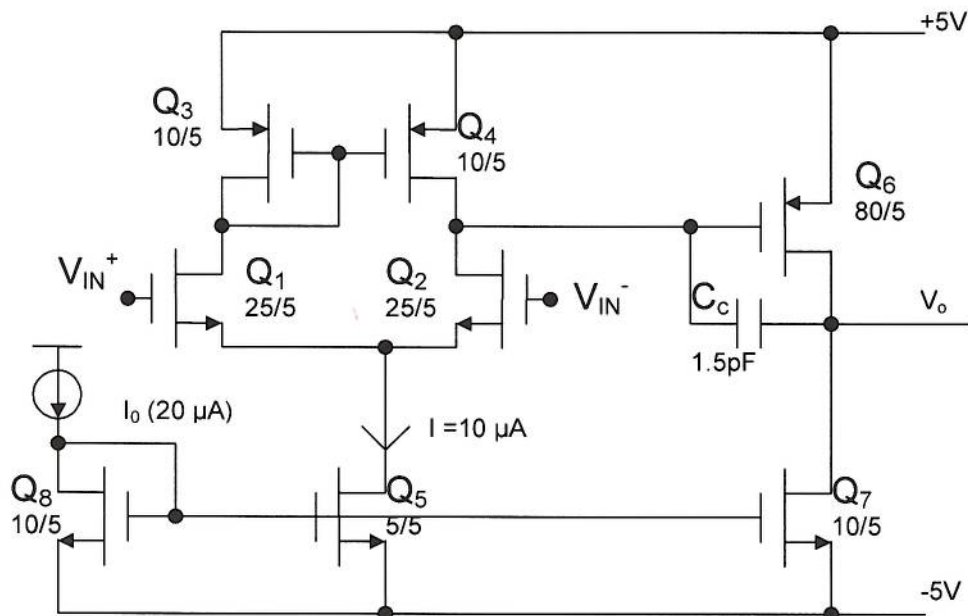


Figure 2

3. (a) Derive an expression for the fundamental limitation imposed on the Dynamic Range (DR) of any high performance A/D converter using the following parameters: V_{ref} is the reference voltage, k is the Boltzmann's constant, T is absolute temperature, R is switch resistance and f_c is the clock frequency of the switch. You may assume that the system settles in 10τ (where τ is the time constant), over one period of the clock frequency.

[8]

- (b) A very high resolution analogue-to-digital converter is the oversampling converter sometimes referred to as the sigma-delta modulator. Explain its principles of operation using a diagram where necessary.

[12]

4. (a) Under what operating conditions does the MOSFET of Figure 4.1 realise a linear floating resistor between terminals *A* and *B*? Explain why the bulk is not connected to the source.
- [6]
- (b) Discuss three sources of non-linearity in the single MOSFET resistor realisation of Figure 4.1 and suggest one suitable circuit design to help eliminate one or more of these non-linear terms. Show all necessary circuit analysis to confirm your design.
- [6]
- (c) Figure 4.2 shows a fully differential continuous time integrator using a balanced double differential linear active transresistor. Derive an expression for the time constant of the integrator. You may ignore all bulk effects, and assume all MOSFETs are operating in the triode region.
- [8]

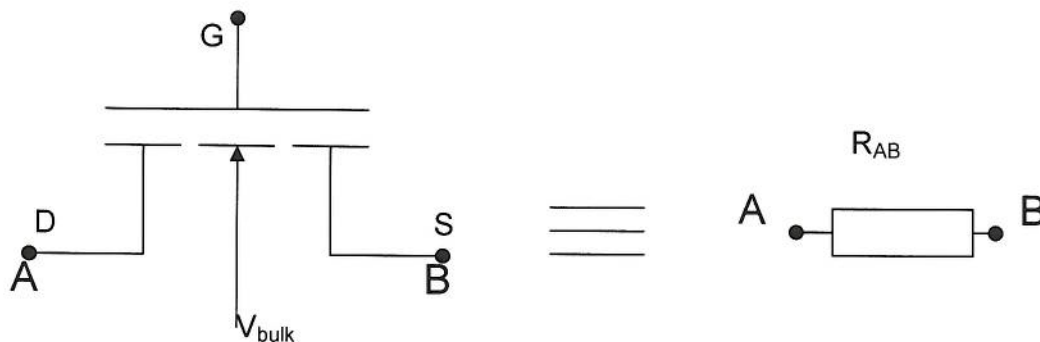


Figure 4.1

5. (a) With the aid of a suitable macromodel, explain the theoretical concept of current feedback and how it results in constant bandwidth amplification. Using a current-feedback op-amp, design a closed-loop non-inverting gain stage with a bandwidth of 10 MHz for a fixed voltage gain of 100. Assume an internal compensation capacitance of 4pF and that the open-loop transresistance gain of the amplifier is very much larger than the amplifier feedback resistor.

[15]

- (b) The circuit shown in Figure 5 is a single bit cell of a current-mode algorithmic analogue to digital converter. Briefly describe the operation of the cell and give reasons why this converter is particularly suitable for mixed-analogue and digital VLSI.

[5]

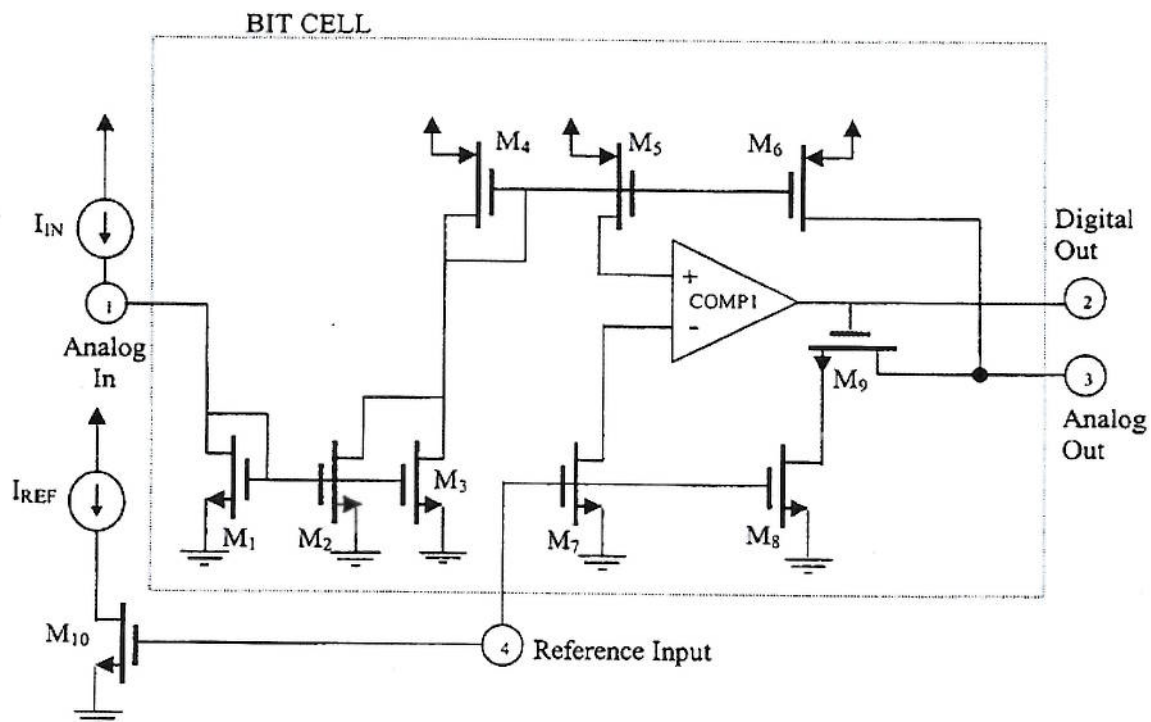


Figure 5

6. (a) Sketch circuits for both a Lossy and differential switched-capacitor integrator. Derive an expression for the transfer function of the differential integrator. Assume clock frequency much higher than the maximum input signal frequency. Also assume the switches are ideal. [10]
- (b) Figure 6 shows one section of a switched capacitor ladder filter. Based on this filter structure, design a 3rd-order Chebyshev low-pass filter with a cut-off frequency of 5 kHz and a 1.0 dB pass band ripple. Assume a clock frequency of 100 kHz. Passive component values for the LC prototype, normalised to 1 rad/s, are $C_1 = C_3 = 2.0236$, $L_2 = 0.994$. In your analysis assume all integrators to be lossless. [10]

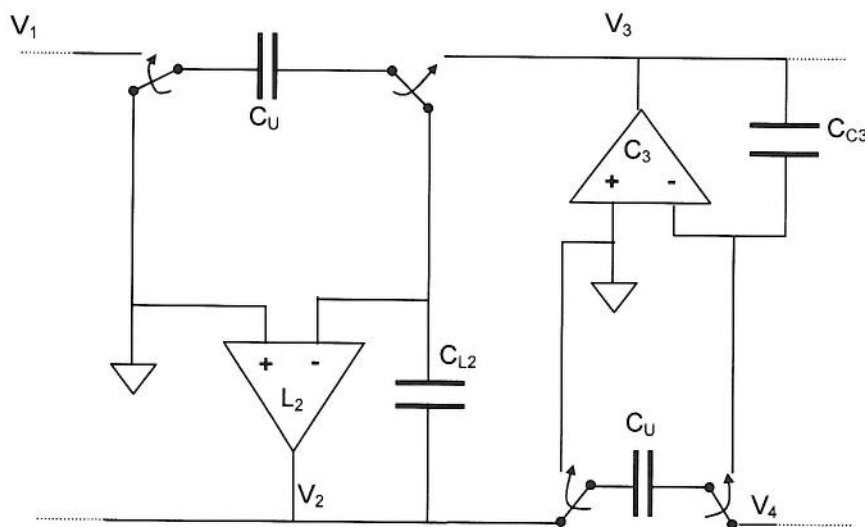


Figure 6

ANALOG - SOLUTIONS

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1
18

Q1/ Bandgap voltage reference circuit has almost zero temperature coefficient. Used mainly as stable voltage reference in ICs.

2

PTAT (Proportional to absolute temperature) current generator. Output current usually insensitive to power supply voltage. Used as a biasing circuit in most precision ICs.

2

For BG reference: $V_{BE1} = V_{BE2} + I_2 R_3$ ($\beta \gg 1$)

Since

$$V_{BE1} - V_{BE2} = V_T \ln(I_1/I_2)$$

$$\text{then } V_0 = V_{BE3} + (R_2/R_3) V_T \ln(I_1/I_2)$$

$V_T \ln(I_1/I_2) \rightarrow$ assume room temp.

$$\text{for } dV_0/dT = 0, \text{ then } dV_{BE3}/dT = \frac{V_T R_2}{T R_3} \ln \frac{I_1}{I_2}$$

$$\text{Since } \frac{dV_{BE}}{dT} = -2.5 \text{ mV}/^\circ\text{C}, \quad \frac{V_T}{T} = \frac{1.38 \times 10^{-23}}{1.6 \times 10^{-19}}$$

$$\text{then } \left(\frac{R_2}{R_3}\right) \ln\left(\frac{I_1}{I_2}\right) = 29 \text{ and so}$$

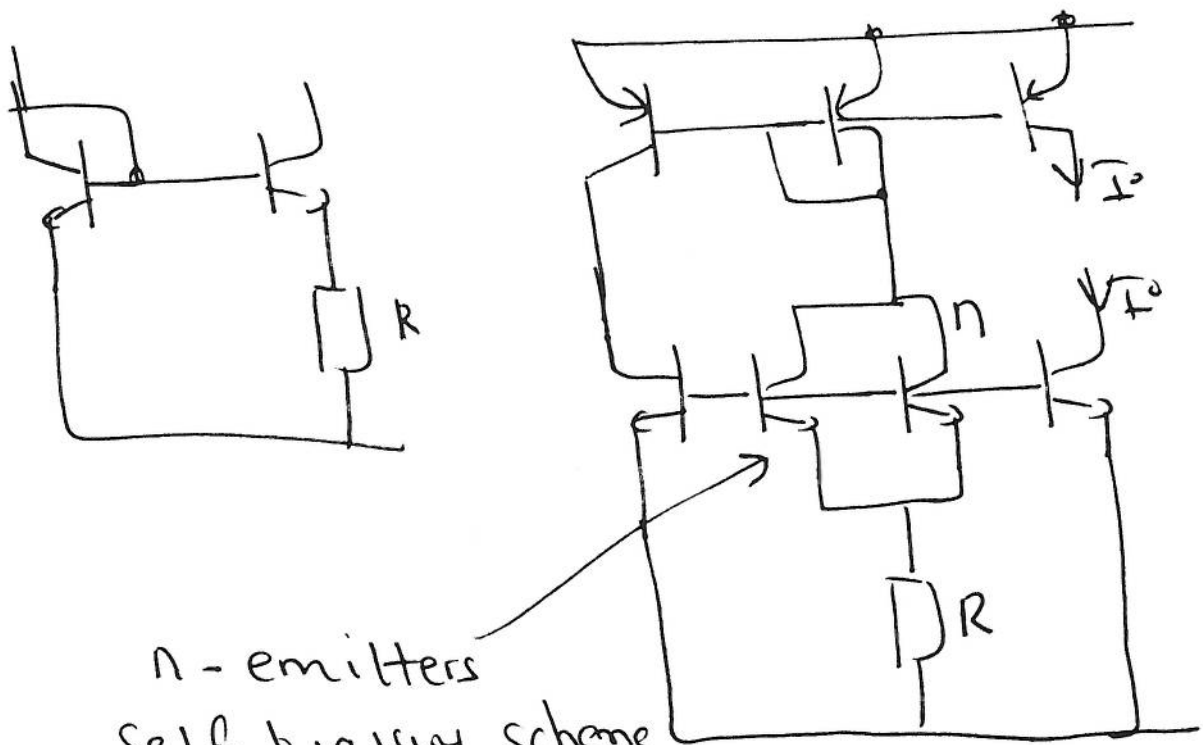
$$V_0 = 1.283 \text{ V}$$

8

(T

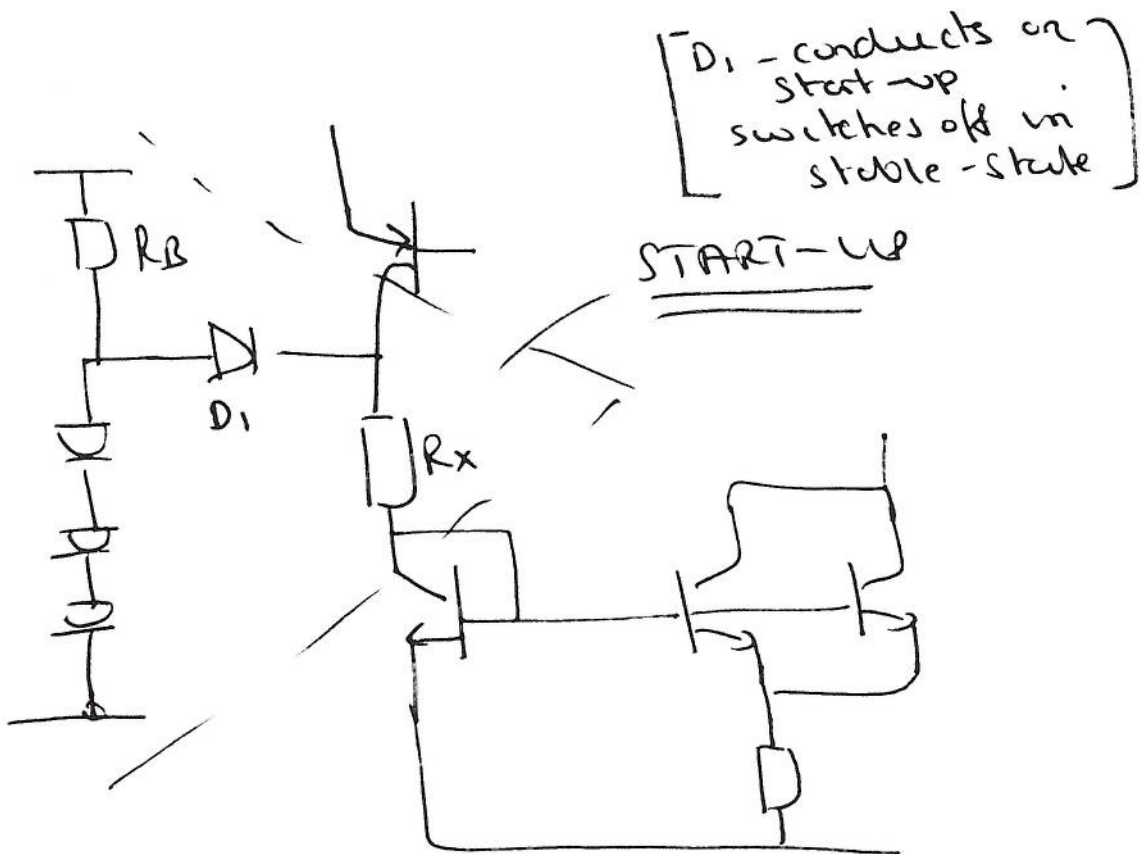
Question 1 continued.

2



n-emitters
self biasing scheme
requires start up.

$$I_0 = \frac{V_T}{R} \ln [n]$$



5

4

CT

3

a/ Cp-Amp.



Common-mode feedback.

(T

Qn2 (cont.)

Single-stage because one current path from input to output.

Node X is low impedance and so very small voltage swing is generated. Only high impedance

node is at the output. (2)
Not necessary to pole split since dominant pole at output not two stages.

Diff output op-amps with high gain have no way of stabilisation since outputs are undefined (voltage that is).

Common-mode feedback - senses common-mode output and via negative feedback controls the current through the output stage to ensure stable quiescent operating point. Circuit shown in the figure. (2)

an 2 cont

b/. OP-Amp

$$\textcircled{2/2} \quad A_{v1} = -g_{m2} / (g_{o2} + g_{o4})$$

$$(g_{o2} + g_{o4}) = I_{D2} (\lambda_n + \lambda_p)$$

$$= 5 \times 10^{-6} \times 0.05 = 2.5 \times 10^{-7} \Omega^{-1}$$

$$g_{m2} = 2 \sqrt{\beta_2 I_D} \Rightarrow \beta_2 = \frac{k_n}{2} \left(\frac{W}{L} \right)_2$$

$$\beta_2 = 7.5 \times 10^{-5} \text{ A/V}$$

$$\therefore g_{m2} = 3.87 \times 10^{-5} \text{ S}$$

$$\textcircled{2/2} \quad A_1 = \underline{\underline{-154.9}}$$

$$A_n = \boxed{-g_{m6} / (g_{o7} + g_{o6})}$$

$$(g_{o6} + g_{o7}) = I_{D6} (\lambda_{np} + \lambda_n)$$

$$= 20 \times 10^{-6} \times 0.05$$

$$= 10 \times 10^{-7} \Omega^{-1}$$

$\textcircled{2/1}$

$$g_{m6} = 1.13 \times 10^{-4}, \quad A_2 = -113.$$

$$A_T = A_1 A_2 = 17503$$

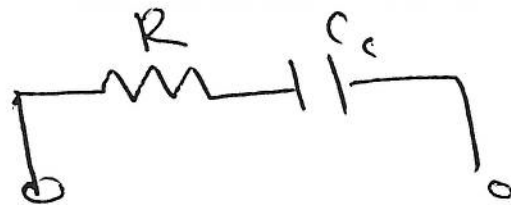
Q2 cont.

$$C.B.P = \frac{g_{m2}}{2\pi C_c} = 4.1 \text{ MHz} \quad - (2)$$

$$S.R = I_0 / C_c = \left(\frac{10}{1.5} \right) \text{ V}/\mu\text{s} \quad - (2)$$

— TOTAL 10/10

Introduce R in series with C_c



provides feedforward compensation and eliminates RHP Zero in the op-amp's transfer function.

Zero is given by $Z = -g_{m6}/C_c$ with R

$$Z = -\frac{1}{(1/g_{m6} - R)C_c} \quad \text{Improves } \phi$$

by setting $Z = P_2 = \text{2nd pole}$ with R .

(2/2)

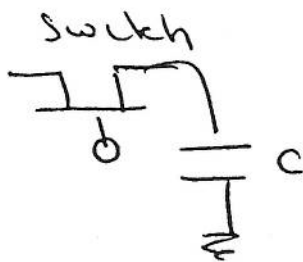
B1

Constraints

Qn 3

7.

a.) Dynamic Range $\Delta V_{ref}/noise = 2^N$



Rms noise of switch
driving Capacitor
 $= \sqrt{\frac{kT}{C}}$

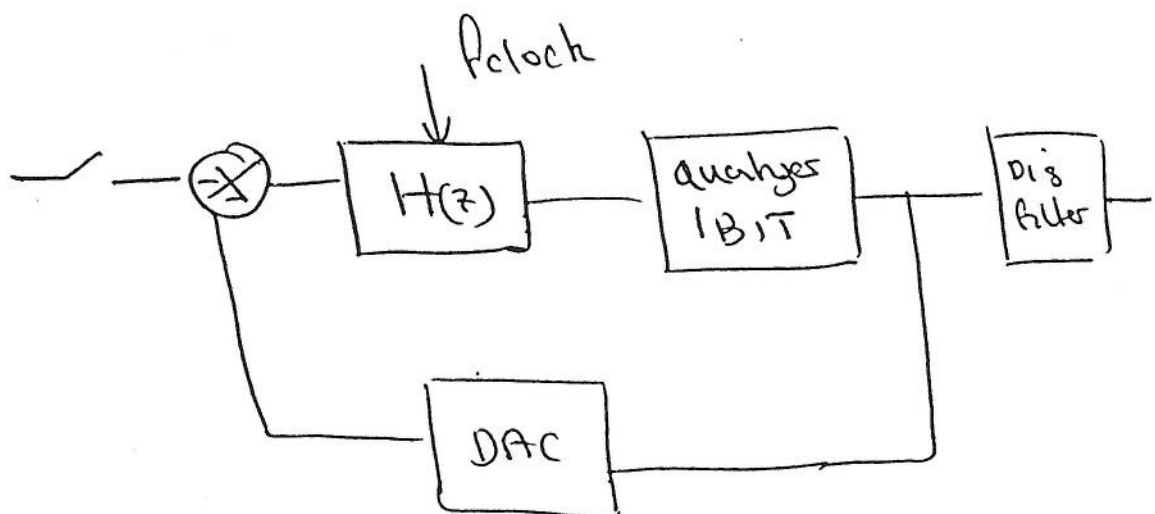
$$\therefore DR = \frac{V_{ref}}{\sqrt{\frac{kT}{C}}} = 2^N$$

Assume $f_c = 1/(10RC)$

then solving for C gives

$$DR = 2^N = V_{ref} / \sqrt{kT \cdot 10RC}$$

b.)



Basic idea is that coarse quantization noise gets shaped by $1/(Hz)$ via feedback

8/8

Ct

Generally $H(z)$ is an Integrator so noise is shaped differentially. This reduces requirements upon component accuracy.

The architecture includes a negative feedback loop producing the coarse estimate that oscillates about the true value of input, the digital filter averages this coarse estimate to produce a finer approximation. The feedback DFE and forward integrator force the quantization error to have a high frequency spectrum. The output of the digital filter is downsampled and given a multibit digital representation. High frequency quantization noise is reduced. Noise shaped away very high (S/N) at low frequency.

QUESTION 4

Q4

- a) Assumption is that if $(V_{DS} \geq 0)$ or $(V_{DS} < (V_{GS} - V_T))$ device acts in linear region. From

$$I_D = \frac{\kappa W}{L} \left[(V_{GS} - V_T) V_{DS} - \frac{V_{DS}^2}{2} \right] (1 + \lambda V_{DS})$$

for $V_{DS} < (V_{GS} - V_T)$, then $\lambda V_{DS} \ll 1$

$$\text{So } I_D = \frac{\kappa W}{L} (V_{GS} - V_T) V_{DS}$$

6/6

$$\text{OR } R_{AB} = V_{DS} / I_D = L / (\kappa W (V_{GS} - V_T))$$

- b) Three sources of non-linearity
- (i) limited due to V_{BS} changing V_T for negative V_{DS} due to body effect.
i.e. $V_T = V_{T0} + \gamma \left[\sqrt{-V_{BS} + 2\phi_F} - \sqrt{2\phi_F} \right]$
 γ = bulk threshold parameter
 ϕ_F = Fermi-level potential

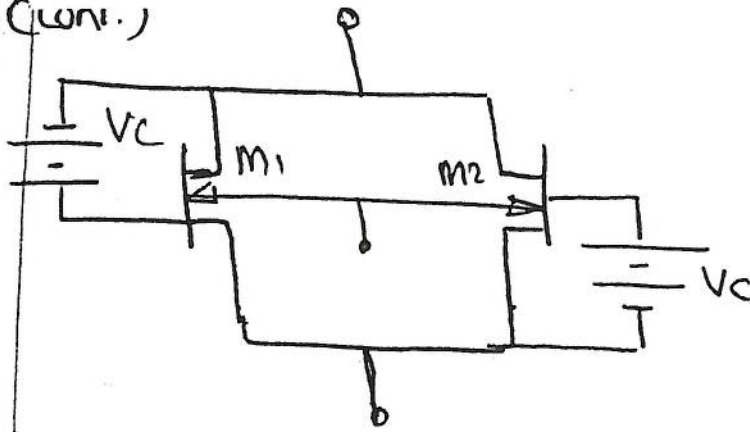
- (ii) limited due to V_{DS} approaching $(V_{GS} - V_T)$ hence saturation region for large positive V_{DS} .

- (iii) For large values of V_{DS} the $V_{DS}^2/2$ term comes in making the resistor quite non-linear.

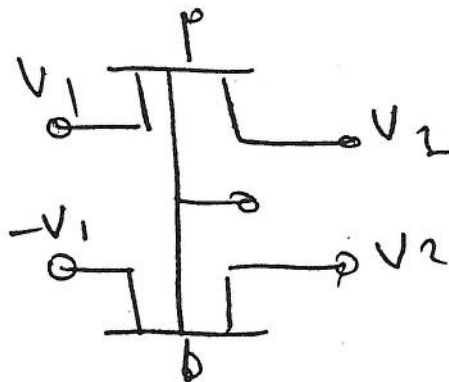
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Q4 (cont.)

10

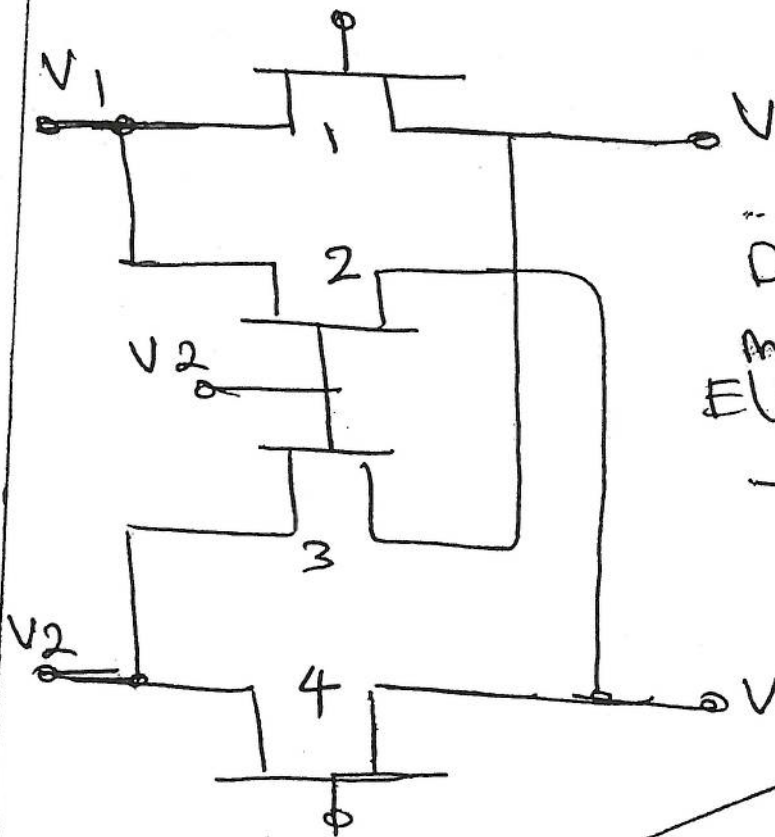


Parallel circuit - eliminates $V_{ds}^2/2$ term.



Differential scheme

Effects of V_{ds} cancelled.



Double differential MOS.
Eliminates
- V_{ds} and V_T term.

Any one of these will do!

2/2

Q4 cont,

Double differential integrals

$$I_{D1} = 2\beta [(V_{C1} - V - V_T)(V_1 - V) - \frac{1}{2}(V_1 - V)^2]$$

$$I_{D2} = 2\beta [(V_{C2} - V - V_T)(V_1 - V) - \frac{1}{2}(V_1 - V)^2]$$

$$I_{D3} = 2\beta [(V_{C2} - V - V_T)(V_2 - V) - \frac{1}{2}(V_2 - V)^2]$$

$$I_{D4} = 2\beta [(V_{C1} - V - V_T)(V_2 - V) - \frac{1}{2}(V_2 - V)^2]$$

Expanding it can be shown that:-

$$(V_1 - V_2)/(I_1 - I_4) = 1/2\beta(V_{C1} - V_{C2}) = R$$

Independent of both V_T and V_{DS} terms

$$\text{Hence } N = \frac{2CR}{1} = \left[\frac{C}{\beta(V_{C1} - V_{C2})} \right]$$

8/8

—————//—————

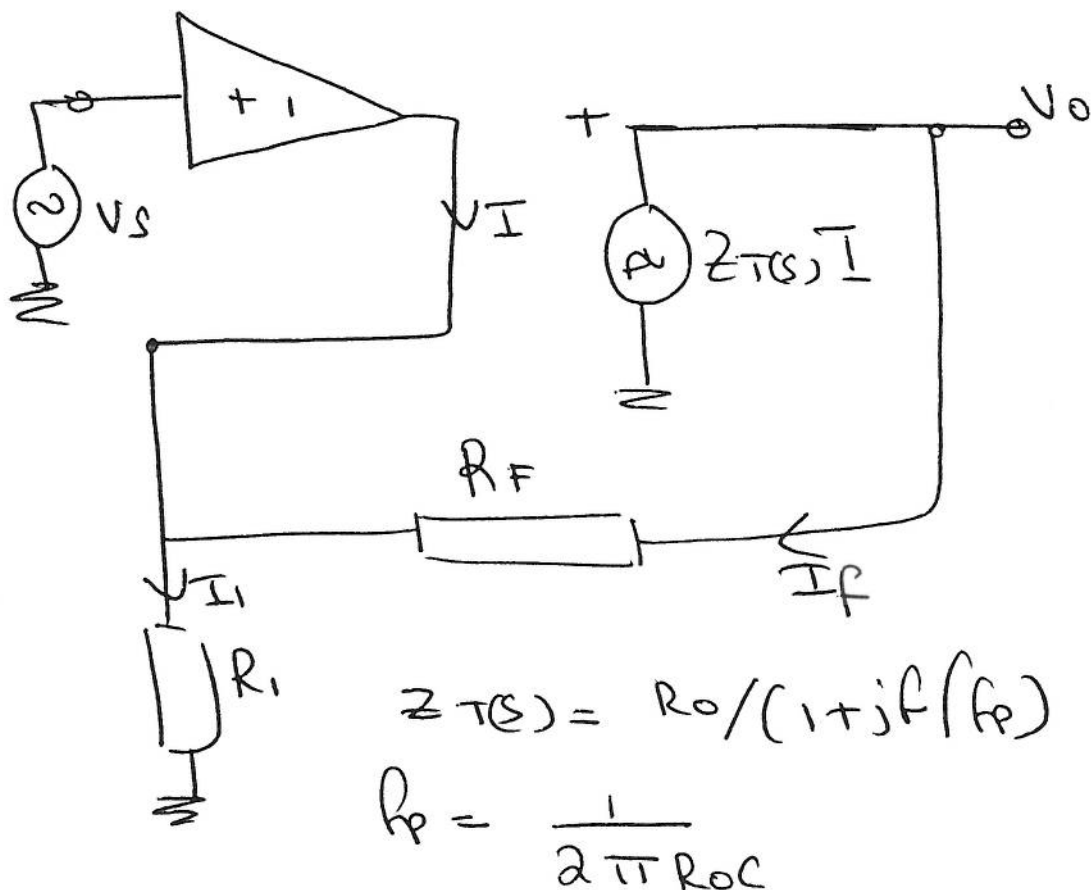
Q5

Advantages of Current-mode

1) High frequency performance, wide dynamic range

low power supply voltages

2



C = compensation capacitor

3 equations

$$I_f = (V_o - V_s) / R_F \quad \text{--- (1)}$$

$$I_1 = V_s / R_1 \quad \text{--- (2)}$$

$$V_o = Z_T(s) I = Z_T(s) [I_1 - I_f] \quad \text{--- (3)}$$

8

15

Q 5 cont/d...

13

Subs ① and ② into ③ gives,

$$(V_o/V_s) = (1 + R_F/R_i) Z_T(s) / (R_F + Z_T(s))$$

Subs for $Z_T(s)$

$$(V_o/V_s)_{sw} = (1 + R_F/R_i) \underbrace{\left[\frac{R_o}{R_o + R_F} \right]}_{\text{gain}} \times \frac{1}{\left(1 + jf / \underbrace{f_p \left[\frac{R_o + R_F}{R_F} \right]}_{\text{BW}} \right)}$$

Assuming $R_o \gg R_F$ BW

Then

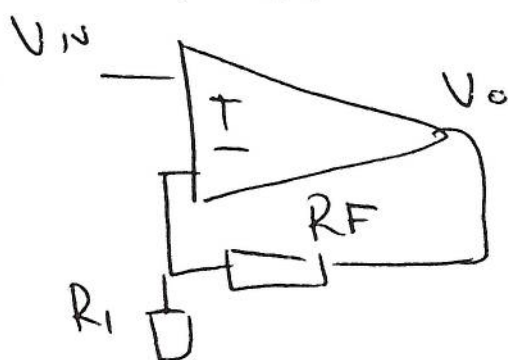
Closed loop gain $\approx (1 + R_F/R_i) - *$

Closed loop Bandwidth $\approx \frac{f_p R_o}{R_F} = \frac{1}{2\pi R_F C}$

Hence R_F sets the amplifier
constant BW

and R_i chosen to set the gain

Lx.



$$BW = \frac{1}{2\pi R_F C} = 10 \text{ MHz}$$

\therefore Given $C = 4 \text{ pF}$

$$R_F = 3.98 \text{ k}\Omega$$

$$\text{Since } A = (1 + R_F/R_i) = 100$$

$R_i = 39.8 \text{ k}\Omega$

5

Q5 cont/d...

Analogue Converters

$2I_{in}$ on +ve terminal of comparator
compared to I_{ref} (-ve) terminal

If $2I_{in} < I_{ref}$, comp output goes low

digital output = 0 and analogue
output = $2I_{in}$

If $2I_{in} > I_{ref}$, comp output goes high

digital output = 1, analogue output
 $2I_{in} - I_{ref}$

Analogue output consequently feeds
into following 'bit' which
performs exactly the same function.

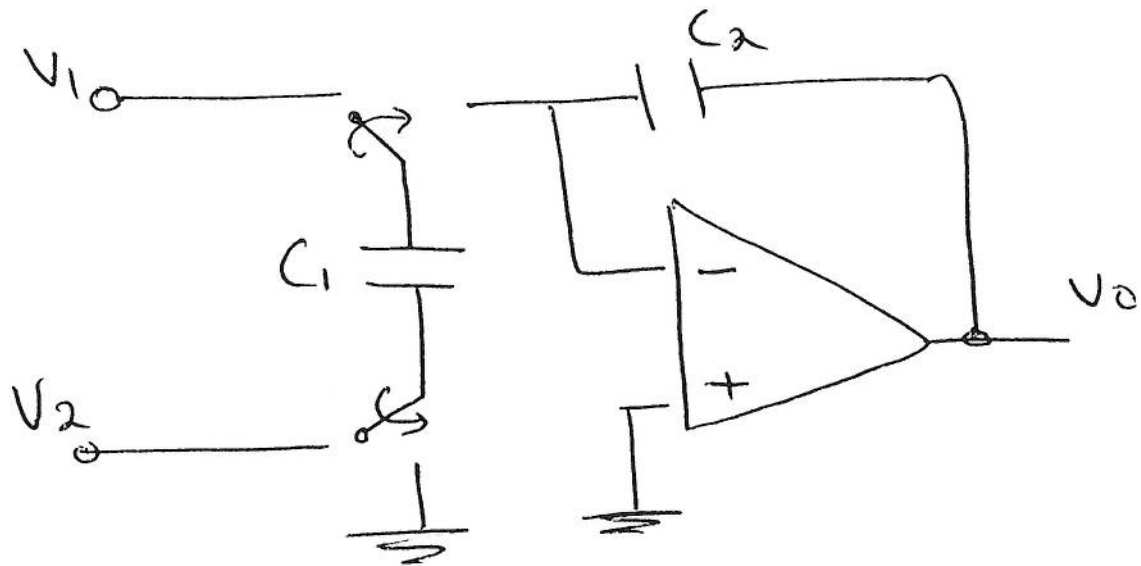
The process is repeated as many times
as necessary to achieve desired
resolution.

Digital VLSI — small size,
low-power
supply voltages
less stringent
upon analogue accuracy

Qu 6/

15

a) Differential Integrator



During ϕ_1 $Q = C_1 [V_1 - V_2]$

$$I_{av} = f_c C_1 [V_1 - V_2]$$

f_c = clock frequency

During $\phi_2 \Rightarrow I_{av} = -f_c (V_1 - V_2) C_1$

$$\therefore V_0 = \frac{-1}{j\omega C_2} f_c C_1 [V_1 - V_2]$$

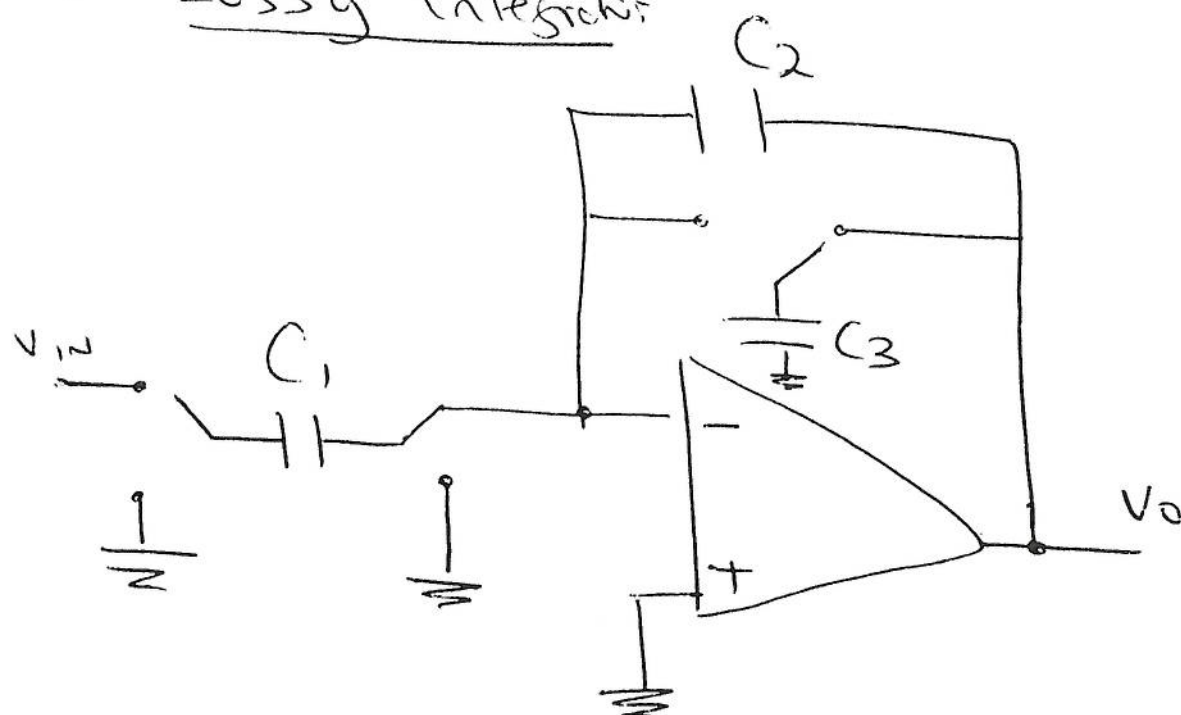
$$\therefore \frac{V_0}{(V_1 - V_2)} = -\frac{f_c}{j\omega} \frac{C_1}{C_2} \approx T = \frac{C_2}{C_1 f_c}$$

(5/5)

LT

Q6 Lossy Integrator

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During ϕ_1 $Q = C_1 V_{in} \Rightarrow I_{avg} = f_c C_1 V_{in}$

During ϕ_2

$$I_{avg} = -[f_c C_3 V_o + j\omega C_2 V_o]$$

$$\therefore f_c C_1 V_{in} = -[f_c C_3 V_o + j\omega C_2 V_o]$$

$$V_{in} = -\left[\frac{C_3}{C_1} V_o + \frac{j\omega C_2}{C_1 f_c} V_o\right]$$

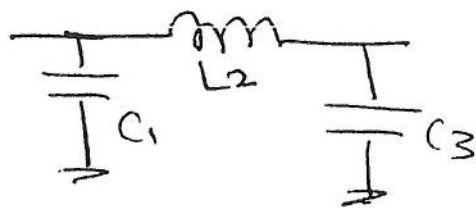
$\therefore \frac{V_o}{V_{in}} = -\frac{C_1}{C_3} \left(\frac{1}{1 + \frac{C_2 j\omega}{C_3 f_c}} \right)$

$\therefore T = \left(\frac{C_2}{C_3} \right) \frac{1}{f_c}$

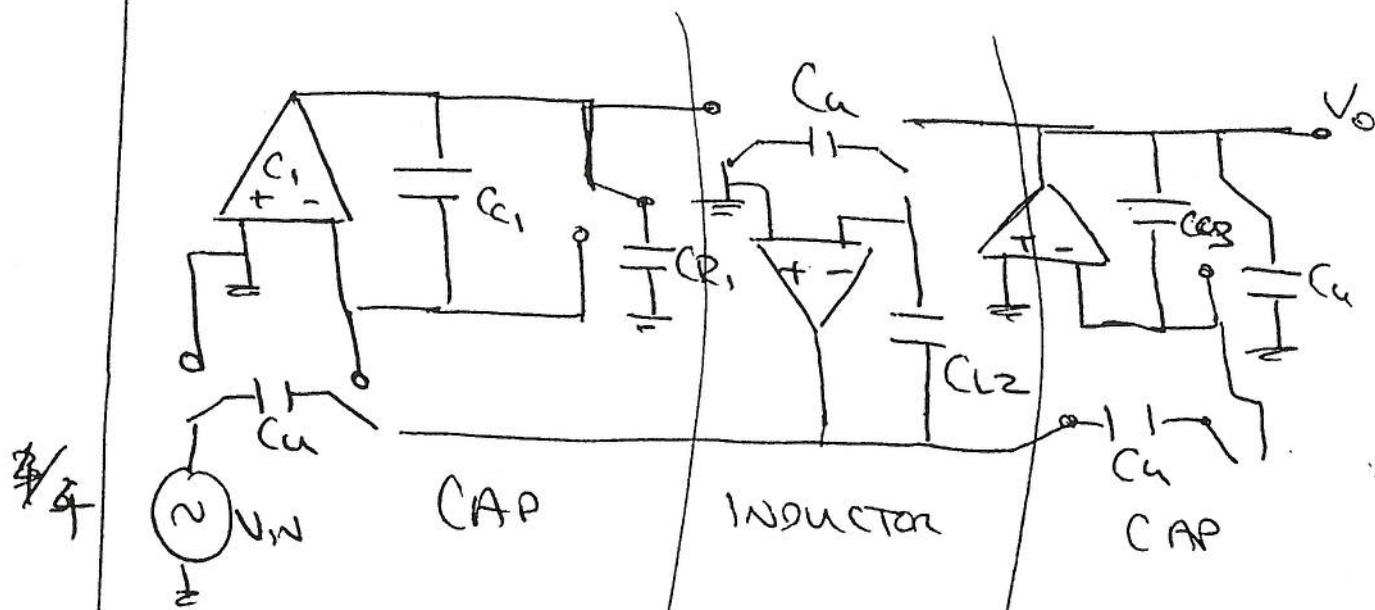
Q6

Q6

Section of LCR prototype.



General transformation Rules (not really required but the bright students may include)



Conversion into differential integrator.

Inductor transformation

$$(L_2/R_s) f_c = C_{12}/C_u$$

Capacitor Transformation.

$$C_3/C_u = f_c R_s C_3$$

where R_s is normalising during scaling resistor. Assuming $R_s = 1$

$$C_1/C_u = f_c C_1$$

$$C_3/C_u = f_c C_3$$

$$C_{12}/C_u = f_c L_2$$

general transformation

and ...

Table values of C_1 , L_2 and C_3
are normalized to $1 \text{ rad/s} \div 2\pi f_p$

$$f_p = 5 \text{ kHz}$$

$$C_1 = C_3 = 2.0236 / (2\pi 5 \times 10^3) \\ = 6.44 \times 10^{-5} \text{ F}$$

$$C_{L2} = 0.994 / (2\pi 5 \times 10^3) \\ = 3.164 \times 10^{-5} \text{ F}$$

For termination R_s

assume $C_{u1} = C_{r1} = C_{r0} = 1 \text{ pF}$

Then

$$\left[\begin{array}{l} C_{L1} = C_{L3} = 6.44 \text{ pF} \\ C_{L2} = 3.164 \text{ pF} \end{array} \right]$$

6/6

to get 20/20