DEPARTMENT OF ELECTRICAL AND ELECTRONIC ENGINEERING **EXAMINATIONS 2003** 

## SIGNALS AND LINEAR SYSTEMS

Monday, 2 June 2:00 pm

Time allowed: 2:00 hours

There are FIVE questions on this paper.

Answer THREE questions.

**Corrected Copy** 

Any special instructions for invigilators and information for candidates are on page 1.

Examiners responsible

First Marker(s):

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Consider the cascade interconnection of three linear time invariant (LTI) systems, as in Figure 1.1. The impulse response  $h_1[n]$  is

$$h_1[n] = \delta[n-3]$$

and the impulse response  $h_2[n]$  is

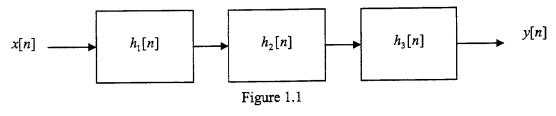
$$h_2[n] = \delta[n-5]$$

where  $\delta[n]$  is the discrete unit impulse function defined as

$$\delta[n] = \begin{cases} 1, & n = 0 \\ 0, & \text{otherwise} \end{cases}$$

The impulse response  $h_3[n]$  is unknown.

The overall impulse response is as shown in Figure 1.2.



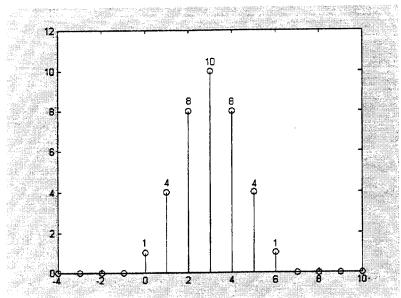


Figure 1.2

(a) Find the impulse response  $h_3[n]$ .

[10]

(b) Find the output of the overall system to the input  $x[n] = \delta[n-1] - \delta[n-2]$  where  $\delta[n]$  is as defined above.

[10]

- 2.
- (a) Consider the discrete, real and odd signal  $x_1[n]$  that is periodic with period N=7 and fundamental frequency  $\omega_0 = \frac{2\pi}{N}$ . The Fourier series coefficients  $c_k$  of  $x_1[n]$  are odd, purely imaginary and given by

 $c_k = \frac{1}{N} \sum_{n=0}^{N-1} x_1 [n] e^{-jk(2\pi/N)n}$ 

(i) Show that  $c_k$  are periodic with respect to k with period N=7.

[2]

(ii) Given that

$$c_{15} = j$$
,  $c_{16} = 2j$ ,  $c_{17} = 3j$ 

determine the values of  $c_0$ ,  $c_{-1}$ ,  $c_{-2}$ ,  $c_{-3}$ .

[5]

(b) Find the Fourier Transform of the discrete signal  $x_2[n] = a^n u[n], |a| < 1$ , where u[n] is the discrete unit step function defined as

$$u[n] = \begin{cases} 1, & n \ge 0 \\ 0, & \text{otherwise} \end{cases}$$

You may wish to use the relationship  $\sum_{n=0}^{+\infty} x^n = \frac{1}{1-x}$ , if |x| < 1.

[5]

(c) Consider the discrete signal  $x_3[n]$  that is aperiodic. Find the Fourier transform of the signal  $y[n] = x_3[n - n_0]$  where  $n_0$  is a constant.

[3]

(d) The input x[n] and output y[n] of a stable and causal LTI system are related by the difference equation

$$y[n] - \frac{3}{4}y[n-1] + \frac{1}{8}y[n-2] = 2x[n]$$

Find the impulse response of this system.

[5]

3.

The output y(t) of a LTI system is related to the input x(t) by the differential equation

$$\frac{d^{2}y(t)}{dt^{2}} + 2\frac{dy(t)}{dt} + y(t) = \frac{dx(t)}{dt} + 2x(t)$$

(a) Determine the transfer function of the system and sketch the Bode plots associated with it.

[13]

(b) If  $x(t) = e^{-2t}u(t)$ , determine the output of the system in the frequency domain.

[7]

- 4.
- (a) Consider a continuous time LTI system. Assume the input to the system to be  $x(t) = e^{s_0 t}$ , where  $s_0$  is a constant and show that if the transfer function of the system is H(s) then the output is  $e^{s_0 t}H(s_0)$ .
  - [7]
- (b) A causal LTI system with impulse response g(t) has the following properties:
  - 1. When the input to the system is  $x(t) = e^{2t}$  for all t, the output is  $y(t) = \frac{1}{6}e^{2t}$  for all t.
  - 2. The impulse response g(t) satisfies the differential equation:

$$\frac{dg(t)}{dt} + 2g(t) = e^{-4t}u(t) + bu(t)$$

where b is an unknown constant.

Determine the Laplace transform G(s) of the impulse response of the system, consistent with the information above. There should be no unknown constants in your answer; that is, the constant b should not appear in your answer.

[13]

- 5.
- (a) (i) Find the analytical expression and the region of convergence (ROC) of the z-transform of the discrete causal signal  $x[n] = a^n u[n]$ , with a real and u[n] the discrete unit step function defined as

$$u[n] = \begin{cases} 1, & n \ge 0 \\ 0, & \text{otherwise} \end{cases}$$

- [3]
- (ii) Find the analytical expression and the region of convergence (ROC) of the z-transform of the discrete anti-causal signal  $x[n] = -a^n u[-n-1]$ , with a real and u[n] the discrete unit step function.

[3]

- For parts a(i)-a(ii) you may wish to use the relationship  $\sum_{n=0}^{+\infty} x^n = \frac{1}{1-x}$ , if |x| < 1.
- (b) Consider a LTI system with input x[n] and output y[n] related with the difference equation

$$y[n-2] - \frac{5}{2}y[n-1] + y[n] = x[n]$$

Determine the impulse response and its z-transform in the following three cases:

- (i) The system is causal.
- (ii) The system is stable.
- (iii) The system is neither stable nor causal.

[14]

(a) Find the impulse response  $h_3[n]$ .

$$h_1[n] * h_2[n] = \delta[n-8]$$

$$\delta[n-8] * h_3[n] = \delta[n] + 4\delta[n-1] + 8\delta[n-2] + 10\delta[n-3] + 8\delta[n-4] + 4\delta[n-5] + \delta[n-6] \Rightarrow$$

$$h_3[n] = \delta[n+8] + 4\delta[n+7] + 8\delta[n+6] + 10\delta[n+5] + 8\delta[n+4] + 4\delta[n+3] + \delta[n+2]$$

(b) Find the output of the overall system to the input

$$x[n] = \delta[n-1] - \delta[n-2]$$

where  $\delta[n]$  is the discrete unit impulse function defined above.

$$(\delta[n] - \delta[n-1]) * (\delta[n] + 4\delta[n-1] + 8\delta[n-2] + 10\delta[n-3] + 8\delta[n-4] + 4\delta[n-5] + \delta[n-6]) =$$

$$\delta[n] + 4\delta[n-1] + 8\delta[n-2] + 10\delta[n-3] + 8\delta[n-4] + 4\delta[n-5] + \delta[n-6] -$$

$$(\delta[n-1] + 4\delta[n-2] + 8\delta[n-3] + 10\delta[n-4] + 8\delta[n-5] + 4\delta[n-6] + \delta[n-7]) =$$

$$\delta[n] + 3\delta[n-1] + 4\delta[n-2] + 2\delta[n-3] - 2\delta[n-4] - 4\delta[n-5] - 3\delta[n-6] - \delta[n-7])$$

2.

(a) Consider the discrete, real and odd signal x[n] that is periodic with period N=7 and fundamental frequency  $\omega_0 = \frac{2\pi}{N}$ . Suppose that the Fourier series coefficients of x(t) are  $c_k$ .

(i)

$$c_{k+N} = \frac{1}{N} \sum_{n=0}^{N-1} x_1 [n] e^{-j(k+N)(2\pi/N)n} = \frac{1}{N} \sum_{n=0}^{N-1} x_1 [n] e^{-jk(2\pi/N)n} e^{-j2\pi n} = c_k$$

(ii) Since the signal is real and odd, the Fourier series coefficients  $c_k$  will be purely imaginary and odd. Given that

$$c_{15} = j$$
,  $c_{16} = 2j$ ,  $c_{17} = 3j$ 

determine the values of  $c_0$ ,  $c_{-1}$ ,  $c_{-2}$ ,  $c_{-3}$ .

$$c_0 = 0$$

$$c_{-1} = -c_1 = -c_{15} = -j$$

$$c_{-2} = -c_2 = -c_{16} = -2j$$

$$c_{-3} = -c_3 = -c_{16} = -3j$$

(b) Find the Fourier transform of the discrete signal  $x[n] = a^n u[n], |a| < 1$ .

In this case 
$$X(e^{j\omega}) = \sum_{n=-\infty}^{+\infty} a^n u[n] e^{-j\omega n} = \sum_{n=0}^{+\infty} (ae^{-j\omega})^n = \frac{1}{1 - ae^{-j\omega}}, |a| < 1$$

(c) Consider the discrete signal x[n] that is aperiodic. Find the Fourier transform of the signal  $y[n] = x[n-n_0].$ 

In this case 
$$\sum_{n=-\infty}^{+\infty} x[n-n_0] e^{-j\omega(n-n_0)} e^{-j\omega n_0} = e^{-j\omega n_0} X(e^{j\omega})$$

(d) The input and output of a stable and causal LTI system are related by the differential equation

$$y[n] - \frac{3}{4}y[n-1] + \frac{1}{8}y[n-2] = 2x[n]$$

Find the impulse response of this system.

We take the Fourier transform in both sides:

$$Y(e^{j\omega}) - \frac{3}{4}e^{-j\omega}Y(e^{j\omega}) + \frac{1}{8}e^{-2j\omega}Y(e^{j\omega}) = 2X(e^{j\omega}) \Rightarrow$$

$$\frac{Y(e^{j\omega})}{X(e^{j\omega})} = H(e^{j\omega}) = \frac{2}{1 - \frac{3}{4}e^{-j\omega} + \frac{1}{8}e^{-2j\omega}} = \frac{2}{(1 - \frac{1}{4}e^{-j\omega})(1 - \frac{1}{2}e^{-j\omega})} = \frac{2}{(1 - \frac{1}{4}e^{-j\omega})(1 - \frac{1}{4}e^{-j\omega})(1 - \frac{1}{4}e^{-j\omega})(1 - \frac{1}{4}e^{-j\omega})} = \frac{2}{(1 - \frac{1}{4}e^{-j\omega})(1 - \frac{1}{4}e^{-$$

$$\frac{2[2(1-\frac{1}{4}e^{-j\omega})-(1-\frac{1}{2}e^{-j\omega})]}{(1-\frac{1}{4}e^{-j\omega})(1-\frac{1}{2}e^{-j\omega})} = \frac{4}{(1-\frac{1}{2}e^{-j\omega})} - \frac{2}{(1-\frac{1}{4}e^{-j\omega})} \Rightarrow h[n] = [4(\frac{1}{2})^n - 2(\frac{1}{4})^n]u[n]$$

3.

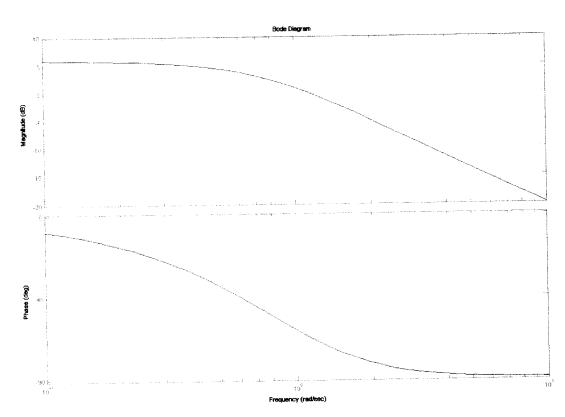
The output y(t) of a causal LTI system is related to the input x(t) by the differential equation

$$\frac{d^{2}y(t)}{dt^{2}} + 2\frac{dy(t)}{dt} + y(t) = \frac{dx(t)}{dt} + 2x(t)$$

(a) Determine the frequency response of the system, then find and sketch its Bode plots.

$$(j\omega)^{2}Y(e^{j\omega}) + 2j\omega Y(e^{j\omega}) + Y(e^{j\omega}) = j\omega X(e^{j\omega}) + 2X(e^{j\omega}) \Rightarrow$$

$$\frac{Y(e^{j\omega})}{X(e^{j\omega})} = \frac{j\omega + 2}{(j\omega)^2 + 2j\omega + 1} = \frac{j\omega + 2}{(j\omega + 1)^2}$$



(b) If  $x(t) = e^{-2t}u(t)$ , determine the output of the system in the frequency domain.

$$X(e^{j\omega}) = \frac{1}{2+j\omega} \Rightarrow Y(e^{j\omega}) = \frac{1}{(j\omega)^2 + 2j\omega + 1}$$

(a) Consider a continuous time LTI system. Find the response of the system to a complex exponential input  $e^{s_0t}$ , as a function of the Laplace transform of the impulse response of the system.

$$y(t) = \int_{-\infty}^{+\infty} h(\tau)e^{s_0(t-\tau)}d\tau = e^{s_0t} \int_{-\infty}^{+\infty} h(\tau)e^{-s_0\tau}d\tau = e^{s_0t}H(s_0)$$

(b) A causal LTI system with impulse response h(t) has the following properties:

When the input to the system is  $x(t) = e^{2t}$  for all t, the output is  $y(t) = \frac{1}{6}e^{2t}$  for all t.

The impulse response satisfies the differential equation:

$$\frac{dh(t)}{dt} + 2h(t) = e^{-4t}u(t) + bu(t)$$

where b is an unknown constant.

Determine the Laplace transform of the impulse response of the system H(s), consistent with the information above. There should be no unknown constants in your answer; that is, the constant bshould not appear in your answer.

$$\frac{dh(t)}{dt} + 2h(t) = e^{-4t}u(t) + bu(t) \Rightarrow (s+2)H(s) = \frac{1}{s+4} + \frac{b}{s} \Rightarrow$$

$$H(s) = \frac{s+b(s+4)}{(s+2)(s+4)s}$$

$$H(2) = \frac{2+6b}{48} = \frac{1}{6} \Rightarrow \frac{2+6b}{8} = 1 \Rightarrow b=1 \Rightarrow H(s) = \frac{2}{(s+4)s}$$

(a) (i) Find the analytical expression and the region of convergence (ROC) of the z-transform of the discrete causal signal  $x[n] = a^n u[n]$ , with a real and u[n] the discrete unit step function.

$$X(z) = \frac{z}{z-a}, \ |z| > |a|$$

(ii) Find the analytical expression and the region of convergence (ROC) of the z-transform of the discrete anti-causal signal  $x[n] = -a^n u[-n-1]$ , with a real and u[n] the discrete unit step function.

$$X(z) = \frac{z}{z - a}, \ |z| < |a|$$

(b) Determine the impulse response and the z-transform of the impulse response, for the LTI system with input x[n] and output y[n] related with the difference equation

$$y[n-2] - \frac{5}{2}y[n-1] + y[n] = x[n]$$

$$y[n-2] - \frac{5}{2}y[n-1] + y[n] = x[n]$$

$$y[n-2] - \frac{5}{2}y[n-1] + y[n] = x[n] \Rightarrow (z^{-2} - \frac{5}{2}z^{-1} + 1)Y(z) = X(z) \Rightarrow$$

$$\frac{Y(z)}{X(z)} = \frac{1}{z^{-2} - \frac{5}{2}z^{-1} + 1} = \frac{1}{(z^{-1} - 2)(z^{-1} - \frac{1}{2})} = \frac{\frac{2}{3}[(z^{-1} - \frac{1}{2}) - (z^{-1} - 2)]}{(z^{-1} - 2)(z^{-1} - \frac{1}{2})} = \frac{\frac{2}{3}}{(z^{-1} - 2)} - \frac{\frac{2}{3}}{(z^{-1} - 2)}$$

Impulse response that corresponds to the term  $\frac{\frac{2}{3}}{(z^{-1}-2)} = \frac{2}{3} \frac{z}{1-2z} = \frac{1}{3} \frac{z}{1/2-z} = (-\frac{1}{3}) \frac{z}{z-1/2}$  can

be

• 
$$h_1[n] = (-\frac{1}{3})(\frac{1}{2})^n u[n]$$
 or

• 
$$h_2[n] = \frac{1}{3} (\frac{1}{2})^n u[-n-1]$$

Impulse response that corresponds to the term  $\frac{-\frac{2}{3}}{(z^{-1} - \frac{1}{2})} = (-\frac{2}{3})\frac{z}{1 - \frac{1}{2}z} = \frac{2}{3}\frac{z}{\frac{1}{2}z - 1} = \frac{4}{3}\frac{z}{z - 2} \text{ can be}$ 

• 
$$h_3[n] = \frac{4}{3} 2^n u[n]$$
 or

• 
$$h_4[n] = -\frac{4}{3}2^n u[-n-1]$$

In order for the system to be stable:

$$h[n] = (-\frac{1}{3})(\frac{1}{2})^n u[n] - \frac{4}{3}2^n u[-n-1]$$

In order for the system to be causal:

$$h[n] = \left(-\frac{1}{3}\right)\left(\frac{1}{2}\right)^n u[n] + \frac{4}{3}2^n u[n]$$

In order for the system to be neither stable not causal the remaining two combinations should be considered.