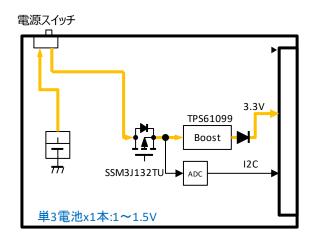
AV03 AA BAT

1. 概要

単 3 電池ホルダーを実装し、1.5V の電池電圧を昇圧電源回路により 3.3V に変換し、3.3V を各リーフに供給するリーフである。 3.3V をオン/オフするためのスイッチを実装している。 また、電池電圧をモニターするための AD コンバーターを実装している。

2. リーフ仕様

2-1. ブロック図



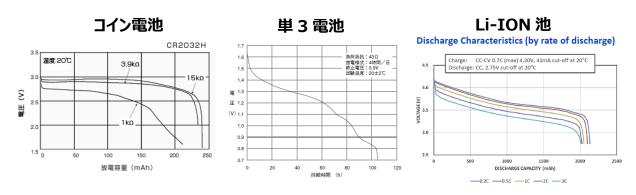
2-2. 電源仕様

| Symbol | Parameter | Condition | Min. | Тур. | Max. |
|--------|-----------------|-----------|-------|------|-------|
| Vbatt | Battery Voltage | - | 0.7V | - | 3.8V |
| Vout | Output Voltage | - | 3.23V | 3.3V | 3.37V |
| Ilim | Current limit | _ | 0.8A | 1A | 1.25A |

2-3. 電池電圧モニター機能

電池リーフには 8bitAD コンバータ (ADC081C027CIMK) を実装し、電池電圧を I2C でモニター可能にするような機能が搭載されている。AD コンバーターのリファレンス電圧は 3.3V で 8bit 分解能であり、AD コンバーターの入力で電圧を 1/2 にしている。よって 3.3V/2^8*2=26mV が AD コンバーター読み値の 1LSB となる。

電池の種類による典型的な放電特性は以下の通り。ただし、負荷がある場合は、ない場合と比べて、電池電圧は低下する点は注意を要する。



参照先

- ① http://biz.maxell.com/ja/primary_batteries/images/i_lineup00108.gif
- ② https://industrial.panasonic.com/cdbs/www-data/pdf2/AAC4000/AAC4000CJ31.pdf
- 3 https://industrial.panasonic.com/cdbs/www-data/pdf2/ACA4000/ACA4000CJ284.pdf

2-4. テスターによる物理的な電池電圧測定手法

電池電圧を測定するパッドが、外観図のように各々の電池リーフ上に用意されているので、テスターで直接測定可能になっている。

2-5. 主要部品

| 部品番号 | 部品名 | 型番 | ベンダー名 | 備考 |
|-------|-----------|----------------|-------------------|----------------------------------|
| IC281 | 昇圧電源 IC | TPS61099YFFR | Texas Instruments | _ |
| IC283 | AD コンバーター | ADC081C027CIMK | Texas Instruments | 電池電圧モニター用 |
| | | | | I2C アドレス:0x50(チッ プ抵抗の付け替えによって |
| | | | | 0x51、0x52 に変更可 |
| | | | | 能) |

※I2C アドレスは 7bit で表記

2-6. 外観



2-7. ピンアウト

| Name | Function |
|------|------------|
| SCL | I2C 通信クロック |
| SDA | I2C 通信データ |
| 3V3 | 3.3V 出力 |
| GND | GND |

3. 昇圧電源 IC(TPS61099YFFR)仕様

3-1. 概要

| 項目 | 内容 |
|--------------------|-------------------|
| 制御方式 | PWM/PFM 自動切替制御 |
| 最大出力電流 | 300mA @3.3V to 5V |
| Protection circuit | 過電流制限/サーマルシャットダウン |

3-2. 電気的特性

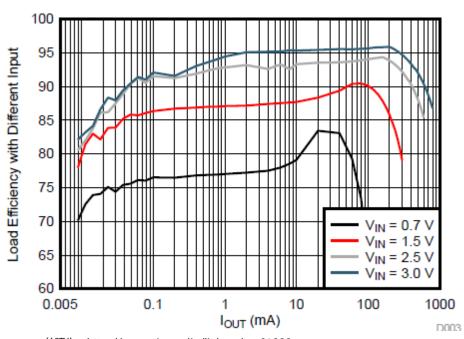
3-2-1. 最大定格

| Parameter | Value |
|---------------------------|---------------|
| Operating Temperature | -40℃ to +150℃ |
| Maximum Operation Voltage | Vin 6.0V |

3-2-2. 定格

| Symbol | Parameter | Parameter Condition | | Тур. | Max. |
|--------|-------------------|---|------|-------|-------|
| Vin | Operating Voltage | ı | 0.7V | - | 5.5V |
| Vout | Output Voltage | Iout =30mA | 1.8V | - | 5.5V |
| Iq | Quiescent Current | IC enabled, no Load, no Switching, Tj=-40°C to 85°C | ı | 0.6uA | 1.5uA |
| Isd | Shutdown current | IC disabled, Vin=3.7V, Vout=0V | - | 0.5uA | 1.6uA |
| Ttso | Thermal Shutdown | | - | 150℃ | - |
| Ilim | Current Limit | - | 0.8A | 1A | 1.25A |

3-3. 効率



参照先: http://www.ti.com/jp/lit/gpn/tps61099

3-4. データシートリンク先

http://www.tij.co.jp/product/jp/TPS61099/

4. AD コンバーター(ADC081C027CIMK)仕様

4-1. 概要

| 項目 | 内容 |
|-------------------|-----------|
| Resolution | 8bit |
| Reference voltage | Vdd(3.3V) |

| Maximum Sample Rate | 188.9kSPS |
|---------------------|-----------|
| Interfaces | I2C |

4-2. 電気的特性

4-2-1. 最大定格

| Parameter | Value |
|---------------------------|---------------|
| Operating Temperature | -40℃ to +105℃ |
| Maximum Operation Voltage | 6.5V |

4-2-2. 定格

| Symbol | Parameter | Condition | Min. | Тур. | Max. |
|--------|------------------------------|---------------------|------|--------|--------|
| Vdd | supply voltage | Internal Oscillator | 2.7V | ı | 5.5V |
| Idd | Automatic Conversion Mode | Vdd=2.7V to 3.6V | - | 0.41mA | 0.59mA |
| | Power down mode | PD1 | - | 0.1uA | 0.2uA |
| | | PD2, fscl=400kHz | - | 13uA | 45uA |

4-3. データシートリンク先

http://www.tij.co.jp/product/jp/adc081c027

4-4. レジスタ

| Name | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|-----------------|----|----|----|----|----|----|--------------|-----|
| Address Pointer | 0 | 0 | 0 | 0 | 0 | R | egister Sele | ect |

Address Pointer Field Descriptions

| D2 | D1 | D0 | REGISTER | |
|----|----|----|---------------------------------|--|
| 0 | 0 | 0 | Conversion Result (read only) | |
| 0 | 0 | 1 | Alert Status (read/write) | |
| 0 | 1 | 0 | Configuration (read/write) | |
| 0 | 1 | 1 | Low Limit (read/write) | |
| 1 | 0 | 0 | High Limit (read/write) | |
| 1 | 0 | 1 | Hysteresis (read/write) | |
| 1 | 1 | 0 | Lowest Conversion (read/write) | |
| 1 | 1 | 1 | Highest Conversion (read/write) | |

| Name | Pointer | D15 | D14 | D13 | D12 | D11 | D10 | D9 | D8 | |
|----------------------|---------|------------|--------------------|-------------|-----|-----|-------------------------|------|----|--|
| Conversion Result | 00h | Alert Flag | lert Flag Reserved | | | | Conversion Result [7:4] | | | |
| | | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | |
| | | C | Conversion | Result [3:0 |] | | Rese | rved | | |

Conversion Result Register Field Descriptions

| Field | Description | | | | | | | |
|----------|---|--|--|--|--|--|--|--|
| D15 | Alert Flag. | | | | | | | |
| | This bit indicates when an alert condition has occurred. When the Alert Bit | | | | | | | |
| | Enable is set in the Configuration Register, this bit will be high if either | | | | | | | |
| | alert flag is set in the Alert Status Register. | | | | | | | |
| | Otherwise, this bit is a zero. The I2C controller will typically read the Alert | | | | | | | |
| | Status register and other data registers to determine the source of the | | | | | | | |
| | alert. | | | | | | | |
| D[14:12] | Reserved. | | | | | | | |
| | Always reads zeros. | | | | | | | |
| D[11:4] | Conversion Result. | | | | | | | |
| | The Analog-to-Digital conversion result. The Conversion result data is a 8- | | | | | | | |
| | bit data word in straight binary format. The MSB is D11. | | | | | | | |
| D[3:0] | Reserved. | | | | | | | |
| | Always reads zeros. | | | | | | | |

| Name | Pointer | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|--------------|---------|----------|----|----|----|----|------------|-------------|----|
| Alert Status | 01h | Reserved | | | | | Over Range | Under Range | |

Alert Status Register Field Descriptions

| Field | Description | | | | | | |
|--------|--|--|--|--|--|--|--|
| וריבום | Reserved. | | | | | | |
| D[7:2] | Always reads zeros. Zeros must be written to these bits. | | | | | | |
| | Over Range Alert Flag. | | | | | | |
| | Bit is set to 1 when the measured voltage exceeds the VHIGH limit stored | | | | | | |
| | in the programmable VHIGH limit register. Flag is reset to 0 when one of | | | | | | |
| | the following two conditions is met: (1) The controller writes a one to this | | | | | | |
| D1 | bit. (2) The measured voltage decreases below the programmed VHIGH | | | | | | |
| | limit minus the programmed VHYST value . The alert will only self-clear if | | | | | | |
| | the Alert Hold bit is cleared in the Configuration register. If the Alert Hold | | | | | | |
| | bit is set, the only way to clear an over range alert is to write a one to this | | | | | | |
| | bit. | | | | | | |
| | Under Range Alert Flag. | | | | | | |
| | Bit is set to 1 when the measured voltage falls below the VLOW limit stored | | | | | | |
| | in the programmable VLOW limit register. Flag is reset to 0 when one of | | | | | | |
| D0 | the following two conditions is met: (1) The controller writes a one to this | | | | | | |
| | bit. (2) The measured voltage increases above the programmed VLOW | | | | | | |
| | limit plus the | | | | | | |
| | programmed VHYST value. The alert will only self-clear if the Alert Hold bit | | | | | | |
| | is cleared in the Configuration register. If the Alert Hold bit is set, the only | | | | | | |
| | way to clear an under range alert is to write a one to this bit. | | | | | | |

| Name | Pointer | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
|---------------|------------------------------------|------------------|------------|------------|------------|-----------|----------|-----------|----|
| Configuration | ر د د د | Cuelo Timo [2.0] | | Alout Hold | Alert Flag | Alert Pin | 0 | Dalasitus | |
| Configuration | Configuration 02h Cycle Time [2:0] | | Alert Hold | Enable | Enable | | Polarity | | |

Configuration Register Field Descriptions

| Field | Description | | | | | | |
|--------|---|--|--|--|--|--|--|
| D[7:5] | Cycle Time. | | | | | | |
| | Configures Automatic Conversion mode. When these bits are set to zeros, | | | | | | |
| | the automatic conversion mode is disabled. This is the case at power-up. | | | | | | |
| | When these bits are set to a non-zero value, the ADC will begin operating | | | | | | |
| | in automatic conversion mode. The Cycle Time table shows how different | | | | | | |
| | values provide various conversion intervals. | | | | | | |
| D4 | Alert Hold. | | | | | | |
| | 0: Alerts will self-clear when the measured voltage moves within the limits | | | | | | |
| | by more than the hysteresis register value. | | | | | | |
| | 1: Alerts will not self-clear and are only cleared when a one is written to | | | | | | |
| | the alert high flag or the alert low flag in the Alert Status register. | | | | | | |
| D3 | Alert Flag Enable. | | | | | | |
| | 0: Disables alert status bit [D15] in the Conversion Result register. | | | | | | |
| | 1: Enables alert status bit [D15] in the Conversion Result register. | | | | | | |
| D2 | Alert Pin Enable. | | | | | | |
| | *This bit does not apply to the ADC081C027. | | | | | | |
| D1 | Reserved. | | | | | | |
| | Always reads zeros. Zeros must be written to these bits. | | | | | | |
| D0 | Polarity. | | | | | | |
| | *This bit does not apply to the ADC081C027. | | | | | | |

Cycle Time Field Descriptions

| D7 | D6 | D5 | Conversion Interval | Typical fconvert[ksps] |
|----|----|----|---------------------|------------------------|
| 0 | 0 | 0 | Mode Disabled | 0 |
| 0 | 0 | 1 | Tconvert x 32 | 27 |
| 0 | 1 | 0 | Tconvert x 64 | 13.5 |
| 0 | 1 | 1 | Tconvert x 128 | 6.7 |
| 1 | 0 | 0 | Tconvert x 256 | 3.4 |
| 1 | 0 | 1 | Tconvert x 512 | 1.7 |
| 1 | 1 | 0 | Tconvert x 1024 | 0.9 |
| 1 | 1 | 1 | Tconvert x 2048 | 0.4 |

4-5. 省電力制御

使用している電源 IC(TPS61099YFFR)は、低負荷時でも、比較的高効率が保たれるものを使用している。

実装されている AD コンバータ(ADC081C027CIMK)は、Active モード(Automatic operation mode)は使わない方が低電力 化を達成できる。Normal mode では、測定後、自動的に Power-down モードに移行するため低電力化が可能である。 Automatic operation mode から Power-down モードに移行するためには、自動変換モードを無効にする(Address: 02h D7-D5: 000)。自動変換モードは電源投入時には無効となっている。

5. 変更履歴

Rev A1.0: 2019年8月初版