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| PIN 13  servoLeft | PIN 12  servoRight | Description | Behaviour |
| 1700 | 1300 | LEFT servo: CLOCKWISE  RIGHT servo: Ant-clockwise | One servo was rotating slightly slower than the other. |
| 1300 | 1700 | LEFT servo: Anti-clockwise  RIGHT servo: Clockwise | The same behaviour as above reversed. |
| 1700 | 1700 | LEFT & RIGHT: Anti-clockwise | Both rotating quite fast. |
| 1300 | 1300 | LEFT & RIGHT: Anti-clockwise | Both rotating slower than they were at 1.7ms. |
| 1500 | 1700 | RIGHT Servo: Anti-clockwise | Quite fast rotations. |
| 1300 | 1500 | LEFT Servo: Clockwise | Slow rotations |
| 1500 | 1500 | RIGHT Servo: Clockwise | Very slow rotations |
| 1520 | 1480 | LEFT Servo: Anti-clockwise  RIGHT Servo: Clockwise | One rotated significantly slower than the other |
| 1540 | 1460 | LEFT Servo: Anti-clockwise  RIGHT Servo: Clockwise | One rotated slightly slower than the other |
| 1700 | 1450 | LEFT Servo: Anti-clockwise  RIGHT Servo: Clockwise | The left servo rotated ‘at speed’, the right servo rotated slowly. |
| 1550 | 1300 | LEFT Servo: Anti-clockwise  RIGHT Servo: Clockwise | The right servo rotated a slight bit fast**er** than the left. |