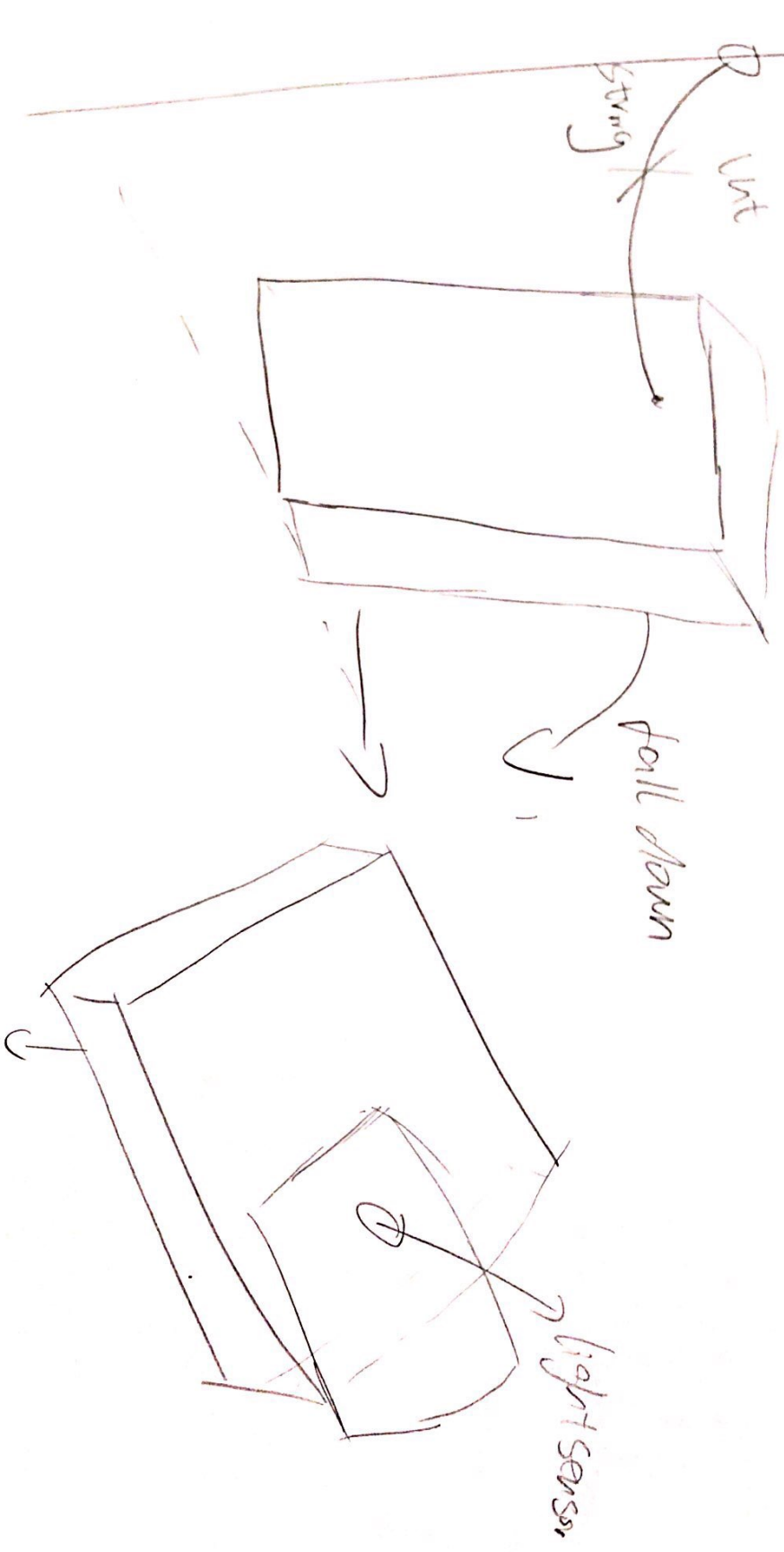


1. light sensor with cover



the board cover the sensor
then the read from sensor can trigger/
turn on/off the switch.



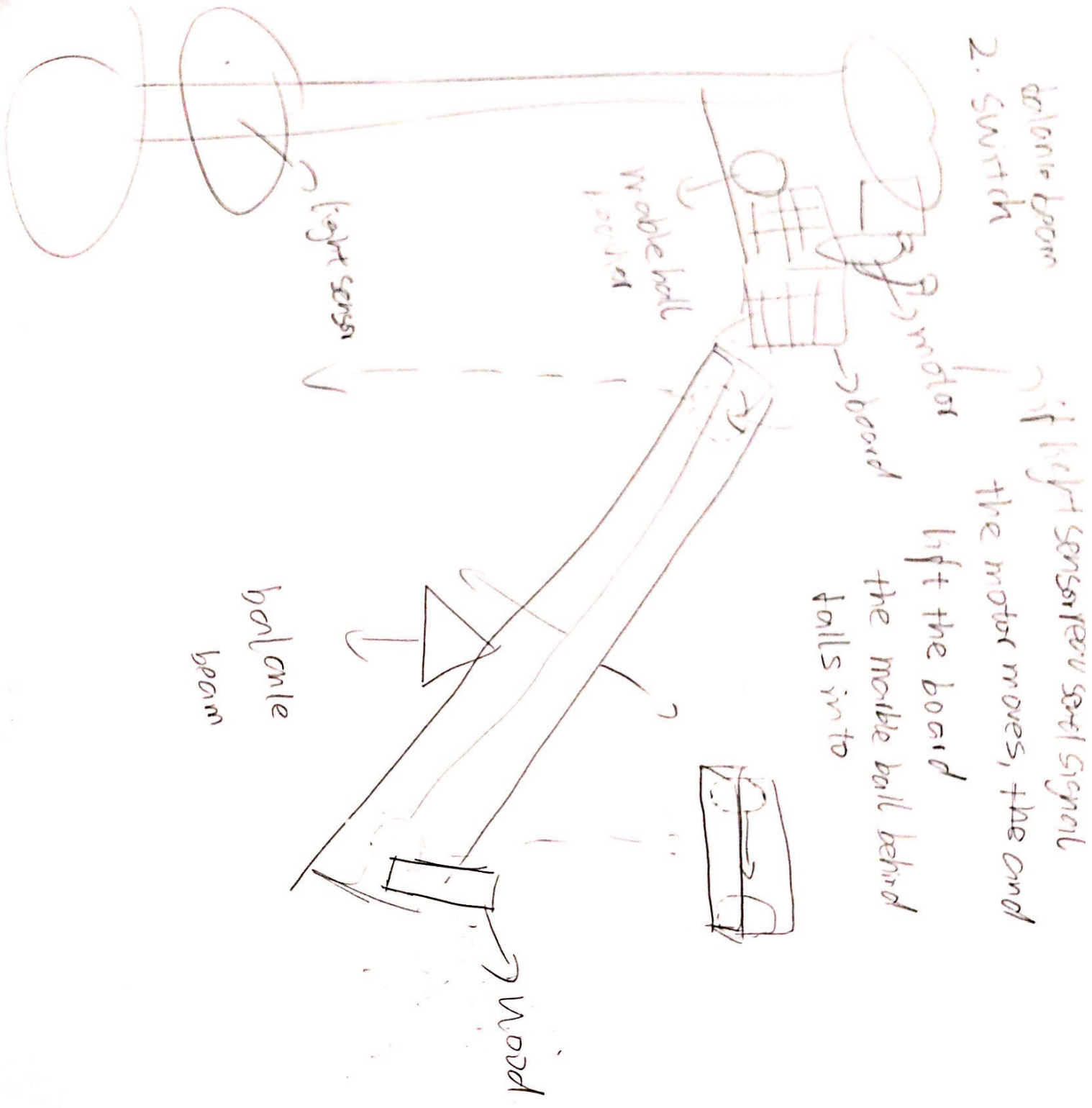
balance beam
2. Switch

if light sensor send signal

the motor moves, the end

lift the board

the mobile ball behind
falls into



3.

balance beam

to

balance beam.

