

# Wumpus World Intro

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# Java Expert System Shell (1/3)

- ▶ declarative programming
- ▶ specify rules `defrule`
  - ▶ precondition  $\Rightarrow$  action
  - ▶ rules fire automatically

```
(defrule found-exit
  "If the hunter has gold and finds an exit, she leaves."
  (task act)
  (hunter (agent ?agent) (x ?x) (y ?y) (gold ~0))
  (exit (x ?x)(y ?y))
  =>
  (printout t ?agent " leaves the caves." crlf)
  (halt))
```

## Java Expert System Shell (2/3)

- ▶ has support for functions
- ▶ has support for data structures

```
(deftemplate pit  
  (slot x (type INTEGER))  
  (slot y (type INTEGER)))
```

# Java Expert System Shell (3/3)

- ▶ has support for queries

```
(defquery get-adjacent-wumpus-free
  "find all wumpus-free adjacent fields"
  (declare (variables ?x ?y))
  (adj ?x ?y ?x' ?y') ;; cave is adjacent
  (cave (x ?x') (y ?y') ;; hunter knows about this cave
    (has-wumpus FALSE)))
```

- ▶ can even call Java

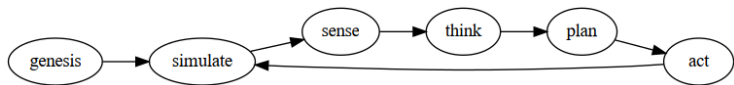
```
(bind ?ht (new java.util.Hashtable)) ;; =>
  ↪ <Java-Object:java.util.Hashtable>
?ht ;; => <Java-Object:java.util.Hashtable>
(?ht put 1 "one")
(?ht get 1) ;; => "one"
```

# Problem Description

- ▶ Hunter explores a cave
- ▶ wants to find gold
- ▶ wants to avoid pits
- ▶ wants to avoid the Wumpus
- ▶ large parts of implementation provided
  - ▶ logical reasoning of Hunter is missing

# Simulation Engine

- ▶ simulation of progress and AI at once
- ▶ process different stages



## Stage 0: Genesis

- ▶ build the world
- ▶ data structures
  - ▶ `hunter(agent, x, y, gold, alive)`
  - ▶ `desire(agent, strength, action, x, y)`
  - ▶ `goal(agent, action, x, y)`
  - ▶ `nocave(x, y)`
  - ▶ `wumpus(x, y, alive)`
  - ▶ `pit(x, y)`
  - ▶ `gold(x, y, amount)`
  - ▶ `exit(x, y)`

# Caves

```
(deftemplate cave
  "Cave objects store the hunter's model of the world"
  (slot x (type INTEGER))           ; coordinates of cave
  (slot y (type INTEGER))           ;
  (slot fromx (default -1))         ; coordinates of cave from
    ↪ which
  (slot fromy (default -1))         ; we first entered the
    ↪ cave.
  (slot visited (default FALSE))    ; Has the hunter been
    ↪ here?
  (slot stench (default UNKNOWN))   ; Does the cave smell?
  (slot breeze (default UNKNOWN))   ; Is it breezy?
  (slot glitter (default UNKNOWN))  ; Is there a glitter in
    ↪ it?
  (slot has-wumpus (default UNKNOWN)); Is there a wumpus here?
  (slot has-pit (default UNKNOWN))  ; Is there a pit here?
  (slot has-gold (default UNKNOWN)) ; Is their gold here?
  (slot has-exit (default UNKNOWN))
  (slot safe (default UNKNOWN)))    ; Is the cave safe?
```

- ▶ neighbors in the *real* world can be queried using adj e.g. for simulation



# Stage 1: Simulate

- ▶ simulate effects of previous actions or genesis
  - ▶ meet the Wumpus

```
(defrule meet-the-wumpus
  "If a hunter and wumpus are in the same cave..."
  (task simulate)
  ?hunter <- (hunter (x ?x) (y ?y) (alive TRUE))
  (wumpus (x ?x) (y ?y) (alive TRUE))
  =>
  (printout t
    ↪ "Aaarrrrggghhhhhh...munch...munch...munch"
    ↪ crlf)
  (modify ?hunter (alive FALSE))
  (halt))
```

- ▶ fall into pit

## Stage 2: Sense

- ▶ perceive effects
  - ▶ notice nearby caves

```
(defrule notice-other-caves
  "If we've just entered a new cave, we notice the
   ↳ other adjacent caves."
  (task sense)
  (hunter (agent ?agent) (x ?x)(y ?y))
  (adj ?x ?y ?x2 ?y2)
  (not (cave (x ?x2)(y ?y2)))
  =>
  (printout t ?agent " notices (" ?x2 "," ?y2 " )
   ↳ nearby." crlf)
  (assert (cave (x ?x2)(y ?y2))))
```

- ▶ breeze of pits
- ▶ stench of wumpus
- ▶ glitter of gold

## Stage 3: think

- ▶ think about perceptions
  - ▶ infer safety of cave positions by
  - ▶ inferring possible positions of pits and the Wumpus
  - ▶ create desires for actions

```
(defrule lust-for-gold
  (task think)
  (hunter (agent ?a) (x ?x) (y ?y))
  (cave (x ?x) (y ?y) (has-gold TRUE))
  =>
  (printout t ?a " wants to pick up the gold in (" ?x
    ↪ ", " ?y ")." crlf)
  (assert (desire (agent ?a) (strength ?*veryhigh*)
    ↪ (action pickupgold))))
```

## Stages 4 and 5: Plan & Act

- ▶ plan
  - ▶ pick highest desire
- ▶ act
  - ▶ perform selected action

# Eclipse Integration

- ▶ only for eclipse *Kepler*
- ▶ does not work with newest JDK
- ▶ prepackaged Eclipse with
  - ▶ suitable JDK in /jre subfolder
  - ▶ and Jess features
- ▶ available from Exchange drive and FileBox
  - ▶ \\fshome\Exchange\MSE\LVA\KI2\Jess
  - ▶ \\fshome\Exchange\IM\LVA\KI2\Jess
  - ▶ \\fshome\Exchange\MCM\LVA\KI2\Jess