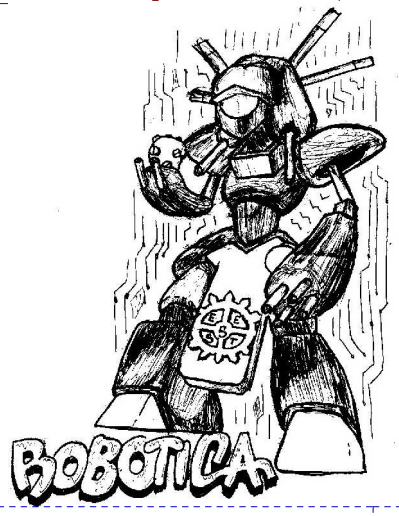
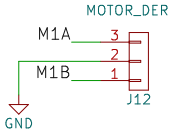
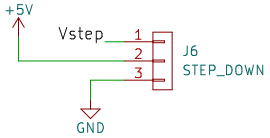
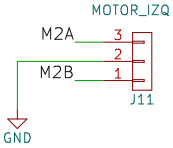


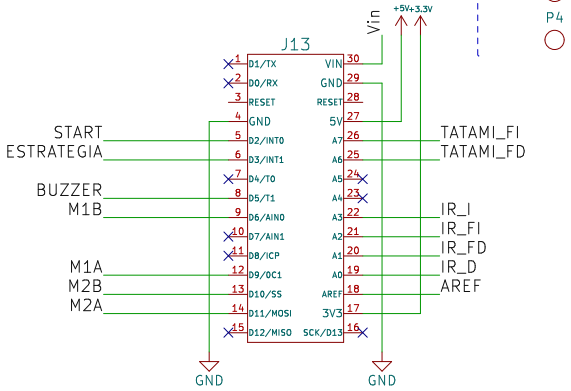
MOTORES:
Las salidas fueron diseñas
para placas Pololu G2-18V17

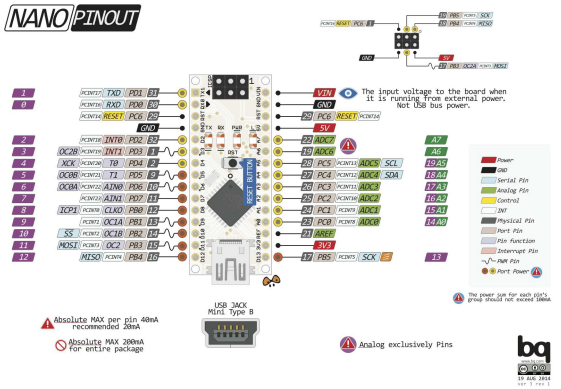




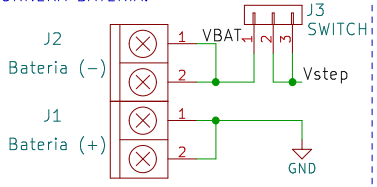


SHIELD FOR ARDUINO NANO:

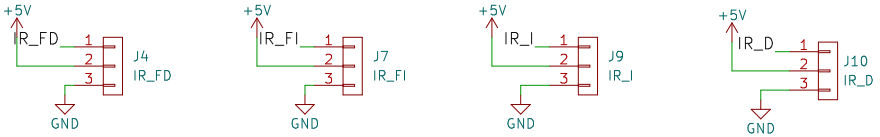




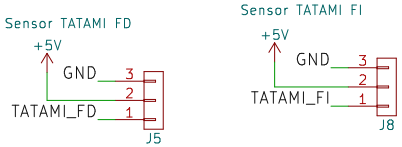
BORNERA BATERIA:



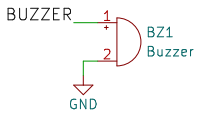
SENSORES DE DISTANCIA:
En esta versión se utilizan 2 sensores de distancia Pololu 38 kHz IR



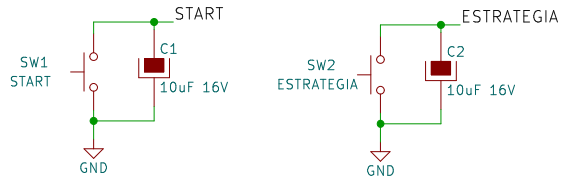
SENSORES DE LÍNEA:



BUZZER:



PULSADORES:



NOTAS:

Club de Robótica
Autor: Ing. Mariano Bustos
E.E.S.T. N°5

open source hardware

Sheet: /
File: 2020 - Sumo - NANO.kicad_sch

Title: Robot Mini Sumo

Size: A4	Date: 2018-05-30	Rev: 1.0
KiCad E.D.A. kicad (6.0.2)		Id: 1/1