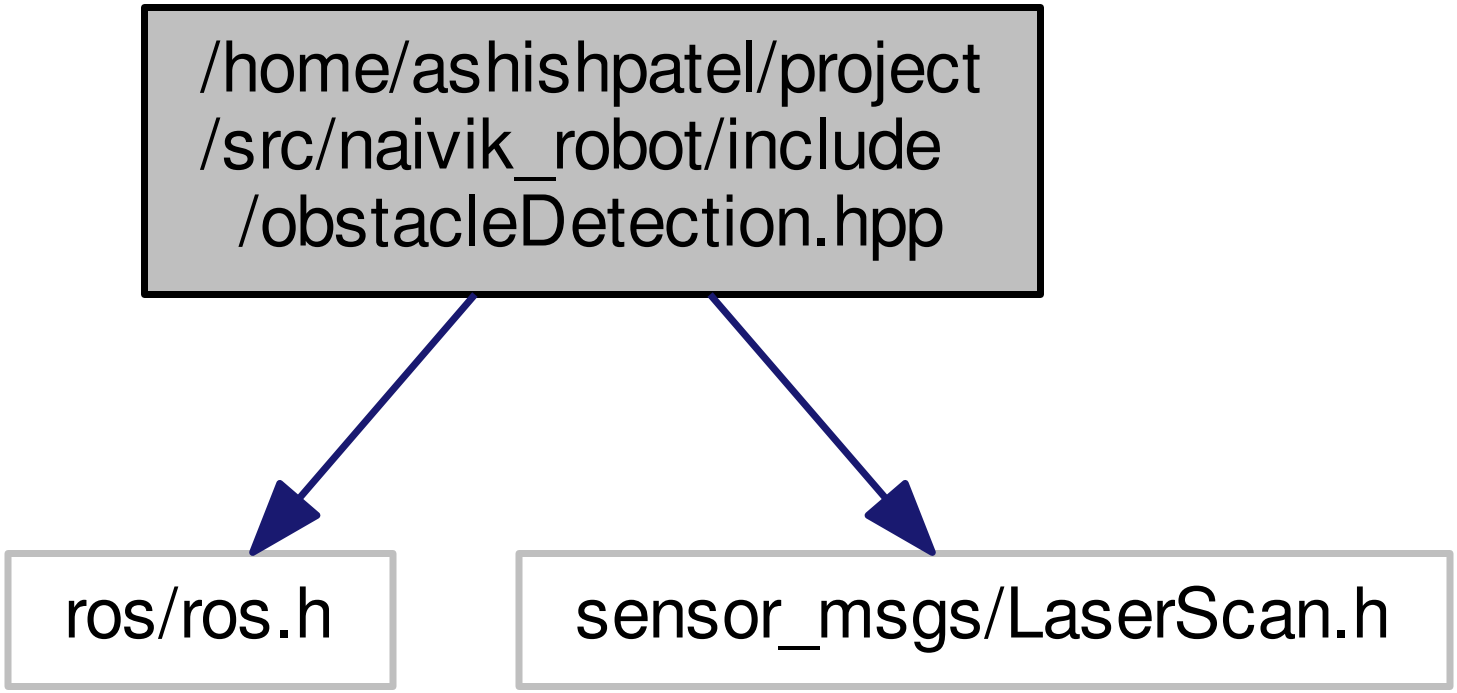
/home/ashishpatel/project
/src/naivik_robot/include
/obstacleDetection.hpp
ros/ros.h
sensor_msgs/LaserScan.h