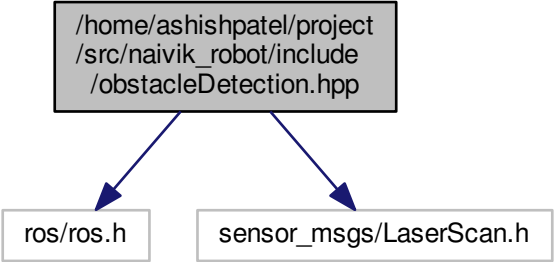


/home/ashishpatel/project
/src/naivik_robot/include
/obstacleDetection.hpp



```
graph TD; A["/home/ashishpatel/project  
/src/naivik_robot/include  
/obstacleDetection.hpp"] --> B["ros/ros.h"]; A --> C["sensor_msgs/LaserScan.h"]
```

The diagram illustrates the include dependencies for the file `/home/ashishpatel/project/src/naivik_robot/include/obstacleDetection.hpp`. Two blue arrows point from the top box to the bottom boxes, indicating that the top file includes the two files listed below.

ros/ros.h

sensor_msgs/LaserScan.h