

Attributed network embedding

- ❑ Motivations & challenges

- ❑ Mining attributed networks with shallow embedding

- ❑ **Mining attributed networks with deep embedding**

 - Objective function based deep embedding

 - Graph neural networks

- ❑ Human-centric network analysis

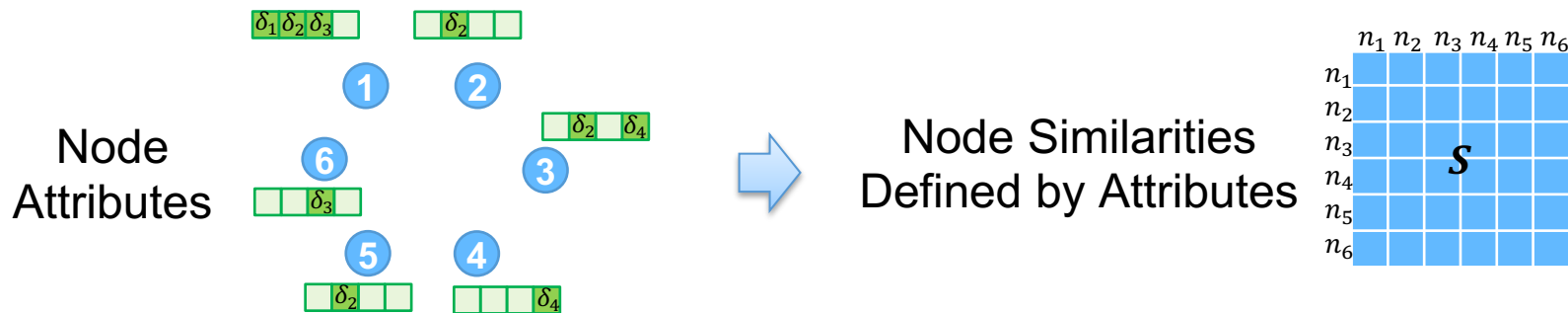
Objective function based deep embedding

- Objective function of DeepWalk:

$$\mathcal{J}_{\text{DeepWalk}} = -\log(\sigma(\mathbf{h}_u^\top \mathbf{h}_v)) - Q \cdot \mathbb{E}_{v_n \sim P_n(v)} \log(\sigma(-\mathbf{h}_u^\top \mathbf{h}_{v_n}))$$

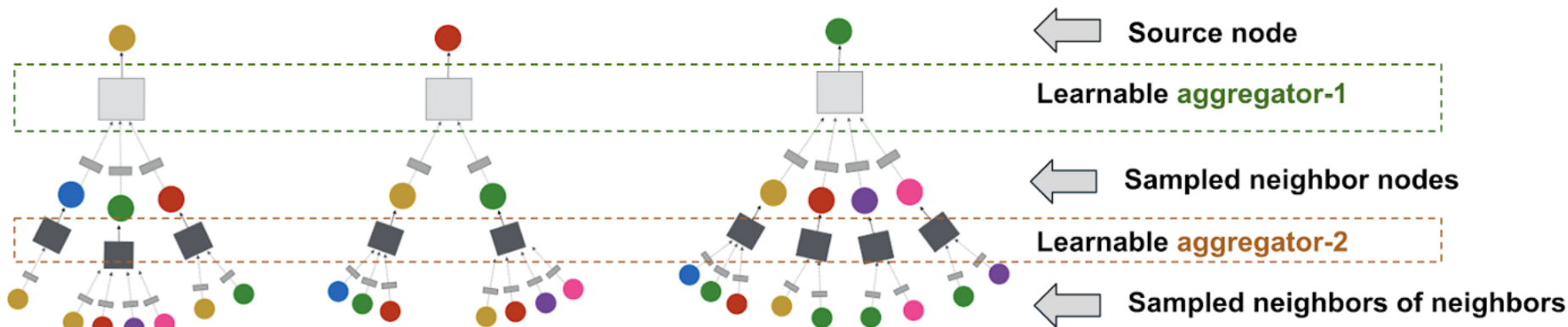
- v is a node that co-occurs near u on fixed-length random walks
- σ is the sigmoid function. Q is the number of negative samples
- $P_n(v)$ is a negative sampling distribution, based on the node frequencies in the entire node sequences
- It trains a unique embedding representation for each node via a representation look-up table
- How to incorporate node attributes in deep architectures?

Property preserving network embedding



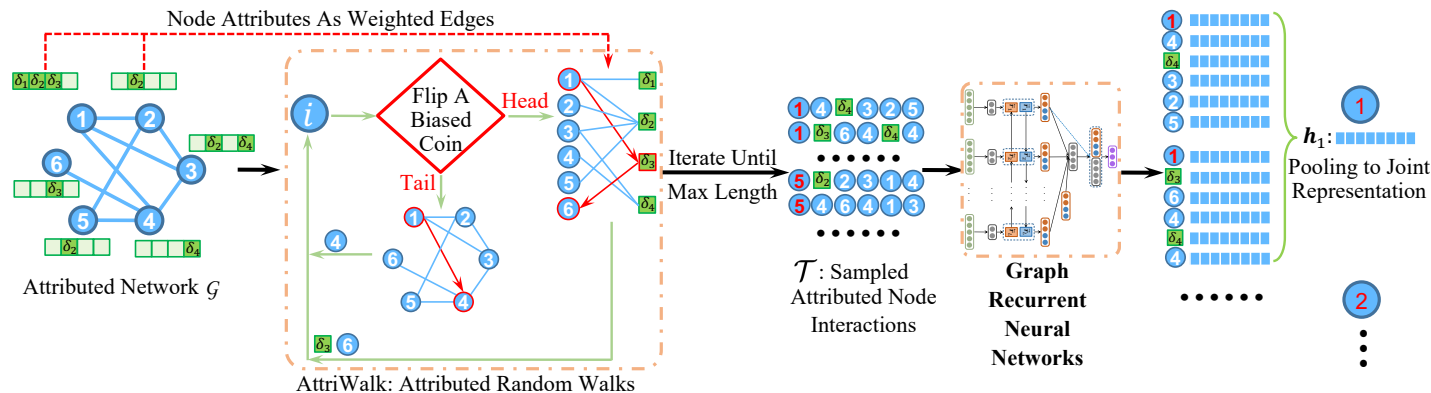
- Compute the node similarity matrix S defined by node attributes
- Objective function: $\mathcal{J} = \mathcal{J}_{\text{DeepWalk}} + \sum_{i \in \text{pos}(v) \cup \text{neg}(v)} d(v, i)$
- S_{vi} is the attribute similarity between u and v
- $d(v, i) = \sqrt{(\mathbf{h}_v - \mathbf{h}_i)^\top (\mathbf{h}_v - \mathbf{h}_i)}$ measures distance in embedding space
- $\text{pos}(v)$ and $\text{neg}(v)$ are sets of top-k similar and dissimilar nodes according to S

Graph neural networks



- Key ideas of graph convolutional networks and GraphSage:
 - Use node attributes or random vectors as initial latent representations
 - Each node's representation is learned via averaging its neighbors' representations in previous layer
- It could be considered as a first-order approximation of spectral graph convolutions

Graph recurrent networks with attributed walks

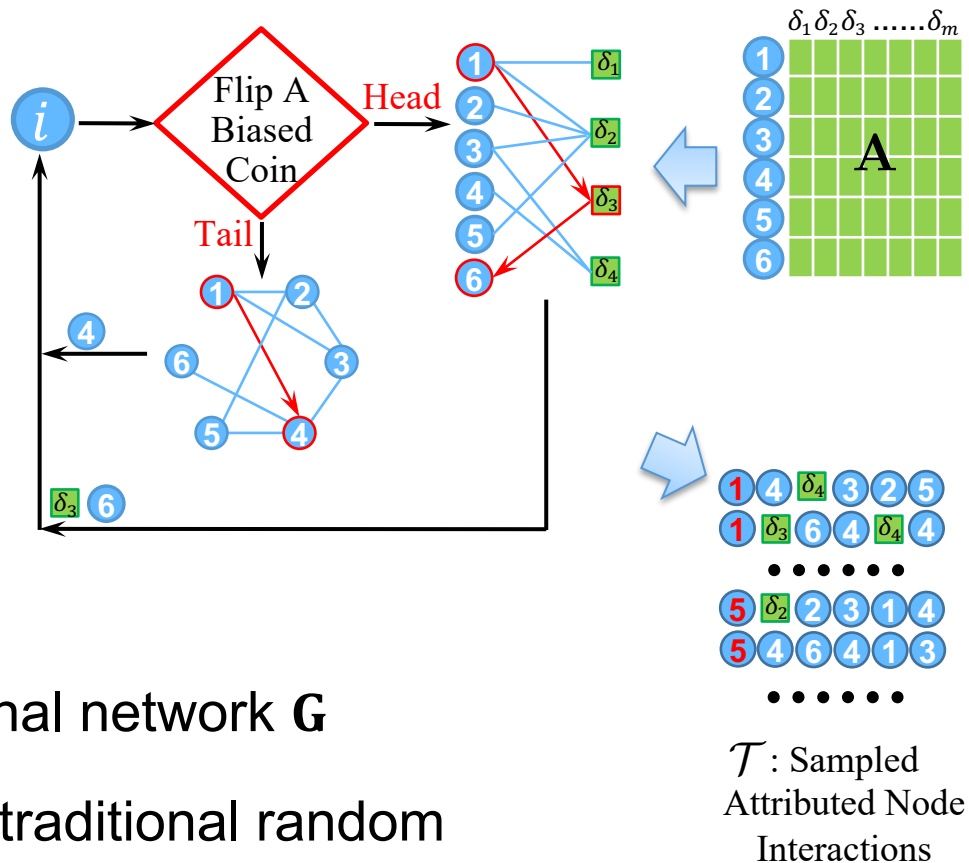


GraphRNA [Huang et al. KDD, 2019]

- A unified walking mechanism is proposed to jointly sample networks and node attributes
- Graph recurrent network (GRN) could preserve node order information
- Nodes are allowed to interact in GRN via the same way as they interact in the original attributed network

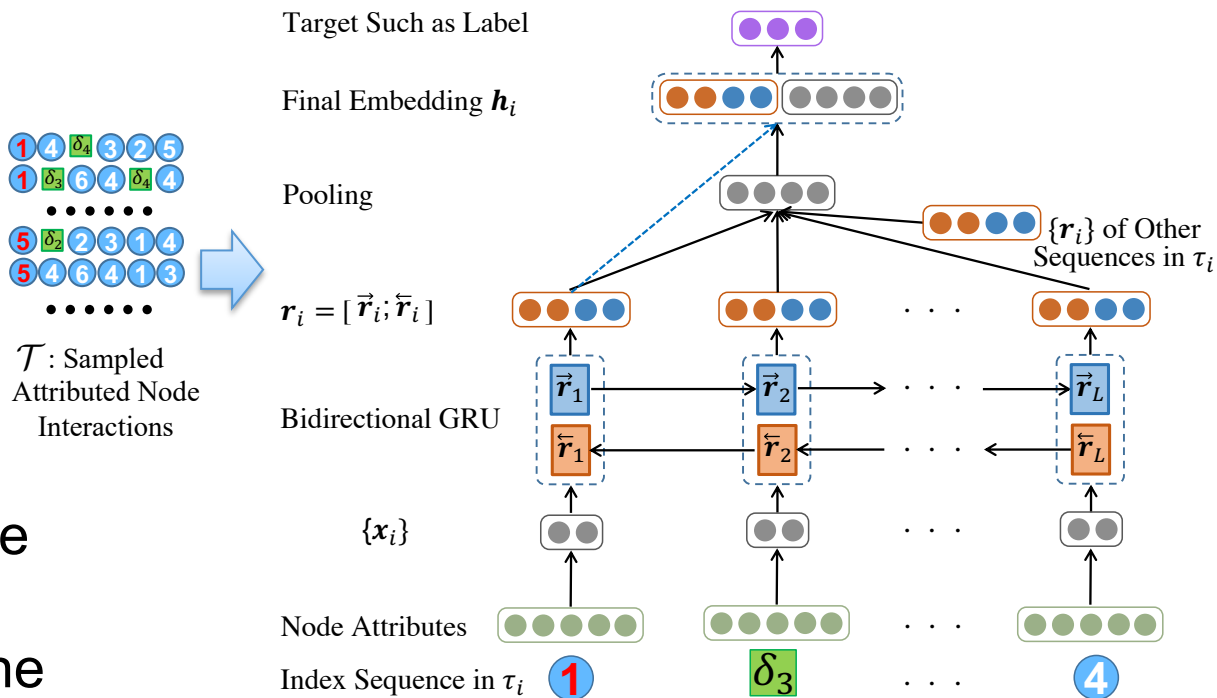
A joint walking mechanism - AttriWalk

- Construct a bipartite network based on \mathbf{A}
- Flip a biased coin in each step
- If head, walk two steps on the bipartite network
 - Jump to an attribute category δ_k
 - From δ_k , jump to a node j
- If tail, walk one step on the original network \mathbf{G}
- Walks on \mathbf{G} inherit properties of traditional random walks; walks on \mathbf{A} increase the diversity and flexibility

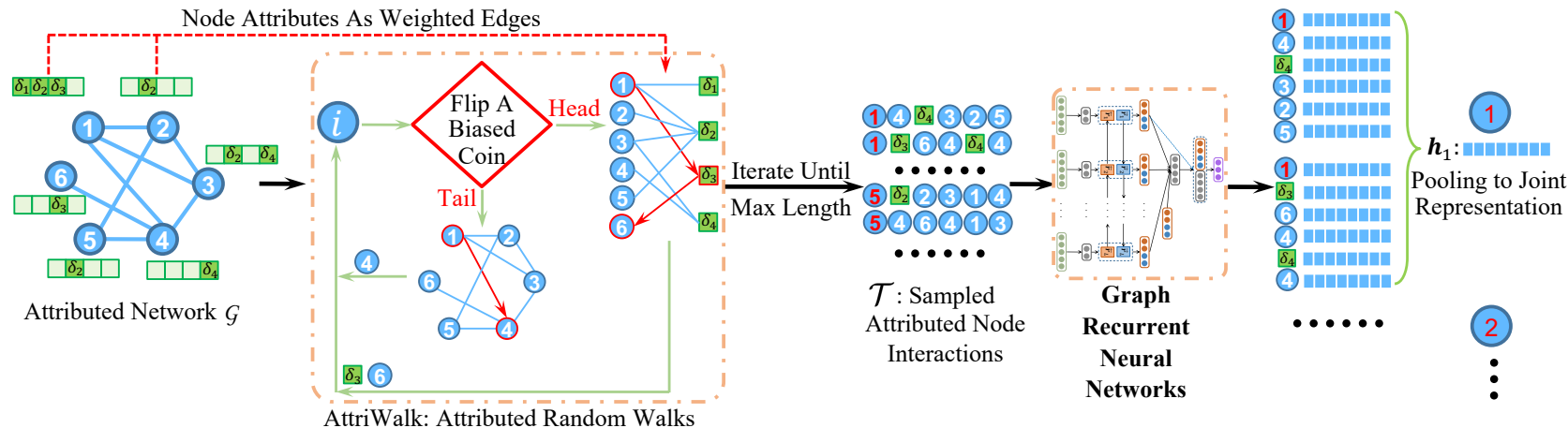


Graph recurrent neural networks - GRN

- Hidden state sequences in RNN naturally accord with sampled node interactions
- Pooling layers combine indices within each sequence, and combine all sequences of each node
- It concatenates the first embedding representation for self loop



Task-specific objective function & multiple sources



- GraphRNA could be trained with an unsupervised, supervised, or task-specific objective functions, e.g.,

$$\mathcal{L} = - \sum_{i \in \mathcal{V}} \mathbf{y}_i^\top \log(\text{softmax}(\sigma(\mathbf{h}_i \mathbf{W}_h + \mathbf{b}_h)))$$

- Graph neural networks could be an embedding model or an end-to-end model for different tasks

Mining attributed networks with deep embedding

- **Focuses:**
Deep architectures for networks & joint learning
- **Methods:**
Objective function based deep embedding
Graph neural networks
- **Architectures:**
Graph convolutional networks
Graph recurrent networks

