# Automata and Formal Languages

October 14, 2019

## 1 Register Machines and Computability

Books: PTJ (Chapter 4)

Note: Here  $\mathbb{N} = \{0, 1, 2, ...\}$ 

A register machine (RM) consists of:

- 1. A sequence of **registers**  $R_1, R_2, R_3, \ldots$  where at discrete time steps  $t = 0, 1, 2, \ldots$  have  $R_i(t) \in \mathbb{N}$ , In fact, we only have finitely many registers, and regard  $R_i \equiv 0$  for all  $i \geq I$ .
- 2. A finite **program** consisting of a fixed number of **states**  $S_0$  (HALT),  $S_1$  (START),  $S_2, \ldots, S_n$ . Each state comes with a fixed instruction performed when in state  $S_i$ . When the computer reaches HALT, we get the output from  $R_1$ . Otherwise, for  $1 \le i \le n$  we have 2 types of **commands**:
  - (a) Increment  $R_j$ , then move to state  $S_k$ . We write this  $S_i:(j,+,k)$ .
  - (b) If  $R_j \neq 0$  then decrement  $R_j$ , then move to state  $S_k$ . Otherwise move to state  $S_l$ . We write this  $S_i : (j, -, k, l)$ .

A sequence of instructions for a RM is the ordered list of the instructions for the program. An input for a RM is, for some  $k \geq 1$ , a finite k-tuple  $(n_1, \ldots, n_k) \in \mathbb{N}^k$  which are the initial values of  $R_1, \ldots, R_k$ . The other registers are set to 0.

A **program diagram** for a RM is a directed graph with vertices being the states of the machine and the labelled arrows denote the instructions:  $S_i : (j, +, k)$ 

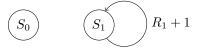
We can then use these to describe programs:

For any k > 0 a program P halts on input  $(m_1, m_2, ..., m_k) \in \mathbb{N}^k$  if it ever reaches state  $S_0$ , written  $P(m_1, ..., m_k) \downarrow$ 

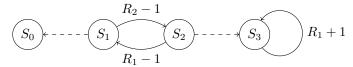
The **halting set**  $\Omega(P)$  is a set of inputs on which P halts.

$$\Omega(P) = \bigcup_{k>0} \{ (m_1, \dots, m_k) : P(m_1, \dots, m_k) \downarrow \}$$

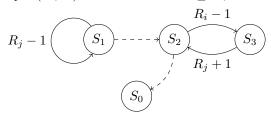




(a) Repeatedly increment  $R_1$ , never halting



(b) For input  $(n_1, n_2)$  returns  $n_1 - n_2$  if  $n_1 \ge n_2$ , else never halt



(c) Transfer  $R_i$  to  $R_j$ , emptying  $R_i$ 

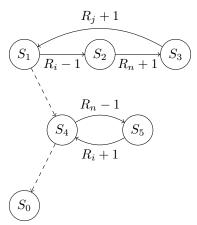
If P does not halt, we write  $P(m_1, \ldots, m_k) \uparrow$ .

For each program P, the *upper register index* upper(P) is the largest index of a register appearing in the instructions for P. So if i > upper(P) then  $R_i$  never changes.

A partial function  $f: \mathbb{N}^k \to \mathbb{N}$  is one where the domain of f is a subset of  $\mathbb{N}^k$ , and undefined otherwise. If f is defined everywhere then we call it a **total function**. This lets us define these programs as functions - we say f is **partial computable** by a program P such that  $\forall (m_1, \ldots, m_k) \in \text{dom}(f)$  have  $P(m_1, \ldots, m_k) \downarrow \text{ with } f(m_1, \ldots, m_k) = R_1$  on halting, and  $\forall (m_1, \ldots, m_k) \notin \text{dom}(f)$  we have  $P(m_1, \ldots, m_k) \uparrow$ . Hence any program P and k > 0 gives a partial function  $f: \mathbb{N}^k \to \mathbb{N}$ .

**Lemma 1.1.** We can add  $R_i$  to  $R_j$  leaving  $R_i$  unchanged.

Proof.



Thus by setting (i = 2, j = 1) we see that  $(n_1, n_2) \mapsto n_1 + n_2$  is total computable.

We have already seen that the function  $n \mapsto 0$  is also computable. This can be done with the machine:

$$R_1 - 1$$
  $S_1$   $\cdots$   $S_0$ 

Corollary 1.2. There exists a routine which can copy  $R_i$  to  $R_j$  leaving  $R_i$  unchanged.

*Proof.* First empty  $R_j$ , then use **1.1** to add  $R_i$  to  $R_j$ .

We can use these as subroutines to join with other programs P. Use registers  $R_n$  s.t. n > upper(P) and largest input register. Then replace the halt state of P with the start state of the subroutine. In fact we have already done this - if you look carefully at the adding machine, you can see that the middle section is the same as the machine in (c) of the examples - this is the part where we replace the value in  $R_i$  from its temporary location in  $R_n$ .

### **Partial Recursive Functions**

Partial computable functions have good closure properties.

#### Theorem 1.3.

- 1. For  $i \leq k$ , the **projection function**  $(n_1, \ldots, n_k) \mapsto n_i$  is computable.
- 2. The zero function  $n \mapsto 0$  and successor function  $n \mapsto n+1$  are computable
- 3. (Composition) If  $f: \mathbb{N}^k \to \mathbb{N}$  and  $g_1, \ldots, g_k : \mathbb{N}^l \to \mathbb{N}$  are all partial computable then so is the composition function  $h(n_1, \ldots, n_l) = f(g_1(n_1, \ldots, n_l), \ldots, g_k(n_1, \ldots, n_l))$  where defined. If  $f, g_1, \ldots, g_k$  are total functions, so is h.
- 4. (Recursion) If f on k variables and g on k+2 variables are partial computable, then so is the partial function  $h: \mathbb{N}^{k+1} \to \mathbb{N}$  defined inductively as:

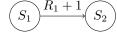
$$h(n_1, \dots, n_k, 0) = f(n_1, \dots, n_k)$$
  
$$h(n_1, \dots, n_k, n_{k+1} + 1) = g(n_1, \dots, n_{k+1}, h(n_1, \dots, n_{k+1}))$$

Moreover, f, g total  $\implies h$  total.

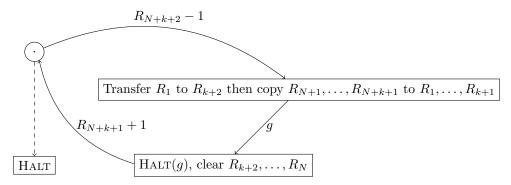
5. (Minimisation) If f on k+1 variables is partial computable then so is the partial function  $g: \mathbb{N}^k \to \mathbb{N}$  defined by  $g(n_1, \ldots, n_k) = n$  if  $f(n_1, \ldots, n_k, n) = 0$  and  $f(n_1, \ldots, n_k, m) > 0$  for all m < n, and is undefined if no zero is ever found. Note that f total  $\Rightarrow g$  total.

#### Proof.

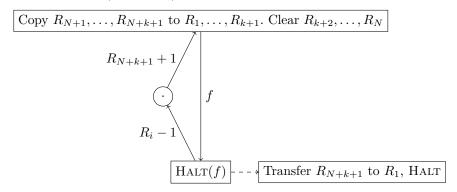
- 1. We can use the program Transfer  $R_i$  to  $R_1$ , HALT.
- 2. Zero function has already been seen. For successor function, use:



- 3. First transfer  $R_1, \ldots, R_l$  to  $R_{N+1}, \ldots, R_{N+l}$  where N is large enough to not be needed in other subroutines. Then for each  $1 \leq i \leq k$  in turn, copy  $R_{N+1}, \ldots, R_{N+l}$  to  $R_{k+1}, \ldots, R_{k+l}$ , perform  $g_i$  but with all registers shifted up by k and then transfer answer from  $R_{k+1}$  to  $R_i$ , then clear  $R_{k+2}, \ldots, R_N$ . Finally, apply f.
- 4. Copy  $R_1, \ldots, R_k$  to  $R_{N+1}, \ldots, R_{N+k}$ , transfer  $R_{k+1}$  to  $R_{N+k+2}$  ("counts down"), then do f. Then:



5. Copy  $R_1, \ldots, R_k$  to  $R_{N+1}, \ldots, R_{N+k}$ . Then



The class of partial recursive functions is the smallest class of partial functions from  $\mathbb{N}^k$  to N over all k > 1 closed under the operations 1.3 (1) to (5). That is, f can be constructed from basic functions and applications of (3), (4), (5) a finite number of times.

So 1.3 says that partial recursive  $\implies$  partial computable.

A partial function is *primitive recursive* if we never use 1.3 (5) its construction. Note that primitive recursive  $\implies$  total recursive, as (5) was the only construction that breaks the totality of the function. [The converse implication is not true: the Ackermann function. ]

Example: + and  $\times$  are primitive recursive:

+: Let h(m,0) = m, h(m,n+1) = h(m,n) + 1 = g(m,n,h(m,n)), where g(x,y,z) = z + 1.

 $\times$ : H(m,0) = 0, H(m,n+1) = H(m,n) + m = g(m,n,H(m,n)) for g(x,y,z) = x + z.

Example:  $(m, n) \mapsto m^n$  is primitive recursive - left as exercise.

We need to be able to "encode" finite sequences of arbitrary length in  $\mathbb{N}$ . For n > 0 and  $i \in \mathbb{N}$ , write  $p_i$  for the (i+1)th prime (so  $p_0 = 2$ ). Write  $(n)_i$  for the largest power of the prime  $p_i$  that divides n.