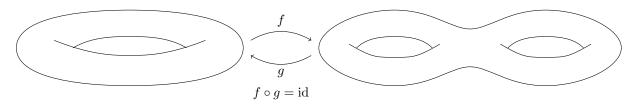
# Algebraic Topology

### October 14, 2019

# 0 Introduction

The fundamental problem of topology is to establish whether or not there exist continuous functions f, g going from a topological space X to another space Y and back again. For example, in the case of this torus and double-torus, we know from Geometry that such functions cannot exist by considering the Euler characteristic, but in general this is a hard problem.



If such f,g continuous functions exist, then we say the two spaces are homeomorphic. Basic idea of algebraic topology is that we want to associate to any topological space X a group G(X), and for every continuous function  $f: X \to Y$  a group homomorphism  $G(f): G(X) \to G(Y)$  with  $G(\mathrm{id}) = \mathrm{id}$  and  $G(f \circ g) = G(f) \circ G(g)$ . Thus if  $f: X \to Y$  is a homeomorphism with inverse  $g: Y \to X$ , then  $G(g) \circ G(f) = \mathrm{id}$ ,  $G(f) \circ G(g) = \mathrm{id}$ , so G(f) is an is an isomorphism.

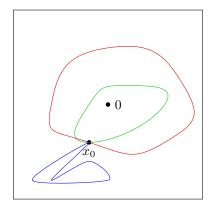
Extension problem: Let X be a topological space,  $A \subseteq X$  a subspace, and  $f: A \to Y$  a continuous function. Does there exist a continuous function  $F: X \to Y$  with  $F|_A = f$ 



**Theorem 0.1.** There is no continuous function

$$f: D^n \to S^{n-1}$$
 with  $f|_{S^{n-1}} = \mathrm{id}$ 

By hand, we can see why this fails for e.g. n=1,2, but it gets hard to generalise. Eventually, we will construct G with  $G(D^n)=0, G(S^{n-1})=\mathbb{Z}$ . Then, if we have  $S^{n-1}\to D^n\to S^{n-1}$  with composition being the identity, then we have maps  $\mathbb{Z}\to 0\to \mathbb{Z}$  being the identity.



Here, the green and red loops are the "same" loop, whilst the blue one is distinct

#### Conventions

A topological space will be referred to as a **space** A continuous function  $f: X \to Y$  will be called a **map** 

# 1 The Fundamental Group

The idea here is that, if X is a space,  $x_0 \in X$  a fixed point, called the **basepoint**, we consider loops based at  $x_0$ , i.e. maps  $\gamma : [0,1] \to X$  with  $\gamma(0) = \gamma(1) = x_0$ .

For example, if we let our space  $X = \mathbb{R}^2 \setminus \{0\}$ 

Then the **fundamental group**  $\pi_1(X) = \pi_1(X, x_0)$  is defined to be the set of loops based at  $x_0$  modulo "deforming loops". Multiplication in this group  $\gamma_1 \cdot \gamma_2$  is given by first traversing  $\gamma_1$  and then  $\gamma_2$ . But what do we mean by "deforming" a loop?

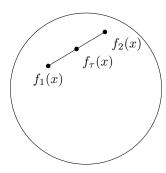
Let  $f_0, f_1: X \to Y$  be maps. A **homotopy** between  $f_0$  and  $f_1$  is a map

$$F: X \times I \to Y$$
 where  $I = [0, 1]$  and  $F(x, 0) = f_0(x)$  and  $F(x, 1) = f_1(x)$ 

We often write  $f_{\tau}(x) = F(x, \tau), f_{\tau} : X \to Y$ .

If such F exists, we say  $f_0$  and  $f_1$  are **homotopic**.

Example: Let  $Y \subseteq \mathbb{R}^2$  be a convex set. Then any  $f_0, f_1 : X \to Y$  are homotopic, via  $F(x,t) = \overline{tf_1(x) + (1-t)f_0(x)} \in Y$  by convexity.



If  $f_0$  is homotopic to  $f_1$ , we write  $f_0 \simeq f_1$ , or  $f_0 \simeq_F f_1$  if we want to be explicit about the homotopy we are using.

Suppose  $f_0 \simeq_F f_1$ , both functions  $X \to Y$ . If  $Z \subseteq X$  and  $f_0(z) = F(z,t) = f_1(z) \forall z \in Z, t \in I$ , then we say  $f_0$  is homotopic to  $f_1$  relative to Z.

**Lemma 1.1.** Let  $Z \subseteq X, Y$  be spaces. Then  $\simeq$  relative to Z is an equivalence relation on the set of maps  $X \to Y$ .

Proof.

• Reflexive:  $f_0 \simeq f_0$  via  $F(x,t) = f_0(x) \forall x, t$ 

• Symmetric: Given  $f_0 \simeq_F f_1$ , then  $f_1 \simeq f_0$  via F'(x,t) = f(x,1-t)

• Transitive: If  $f_0 \simeq_{F_0} f_1$ ,  $f_1 \simeq_{F_1} f_2$ , then  $f_0 \simeq_F f_2$  with:

$$F(x,t) = \begin{cases} F_0(x,2t) & t \le 1/2 \\ F_1(x,2t-1) & t \ge 1/2 \end{cases}$$

All homotopies are relative to Z.

A homotopy equivalence  $f: X \to Y$  is a map with a homotopy inverse  $g: Y \to X$  such that  $f \circ g = \mathrm{id}_Y, g \circ f = \mathrm{id}_X$ . We then write  $X \simeq Y$ .

Remark: Most (all?) invariants in the course are homotopy invariants

Examples:

- 1. Let \* be the one point space,  $f: \mathbb{R}^n \to *$  be the constant map, and let  $g: * \to \mathbb{R}^n; x \mapsto \mathbf{0}$ . Then  $f \circ g = \mathrm{id}_*$ , and  $g \circ f(x) = 0 \forall x \in \mathbb{R}^n$ . Now  $g \circ f \simeq \mathrm{id}_{\mathbb{R}^n}$  via F(x,t) = tx.
- 2. Let  $f: S^{n-1} \hookrightarrow \mathbb{R}^n \setminus \{0\}$  be the inclusion map, and  $g: \mathbb{R}^n \setminus \{0\} \to S^{n-1}; x \mapsto \frac{x}{|x|}$  (i.e. map x to the intersection of  $\overrightarrow{\mathbf{0}}x$  with  $S^{n-1}$ . Then  $g \circ f = \mathrm{id}_{S^{n-1}}$  and  $f \circ g \simeq \mathrm{id}_{\mathbb{R}^n \setminus \{0\}}$  via  $F(x,t) = (1-t)x + t \cdot \frac{x}{|x|}$

If  $X \simeq *$ , then we say X is **contractible**.

Let  $f: X \to Y, g: Y \to X$  be maps. If  $g \circ f = \mathrm{id}_X$ , then we say X is a **retract** of Y, and g is a **retraction**. If in addition  $f \circ g \simeq \mathrm{id}_Y$  relative to f(X), then we say X is a **deformation retract** of Y. Hence, in example 2, we see that  $S^{n-1}$  is a deformation retract of  $\mathbb{R}^n$ .

Lemma 1.2. Homotopy equivalence of spaces is an equivalence relation.

*Proof.* Reflexivity and symmetry are trivial from the definition.

Suppose  $X \simeq Y, Y \simeq Z$  via:



We want to show  $f' \circ f$ ,  $g \circ g'$  induces a homotopy equivalence



Now  $(g \circ g') \circ (f' \circ f) = g \circ (g' \circ f') \circ f$ . We know already that  $g' \circ f' \simeq_{F'} \mathrm{id}_Y$ , and so:

$$(x,t) \mapsto g(F'(f(x),t)) = \begin{cases} g(g'(f'(f(x)))) & t = 0\\ g(f(x)) & t = 1 \end{cases}$$

is a homotopy, as  $g \circ (g' \circ f') \circ f \simeq g \circ f$ , and since  $X \simeq Y$ ,  $g \circ f \simeq \mathrm{id}_X$ . Hence  $(g \circ g') \circ (f' \circ f) \simeq \mathrm{id}_X$  via transitivity of homotopy equivalence for maps. Similarly  $(f' \circ f) \circ (g \circ g') \simeq \mathrm{id}_Z$ 

## Loops and $\pi_1$

If X is a space, a **path** in X is a map  $\gamma: I \to X$ , where  $I = [0,1] \subseteq \mathbb{R}$ . If  $\gamma(0) = x_0, \gamma(1) = x_1$  then we say  $\gamma$  is a path **from**  $x_0$  **to**  $x_1$ .

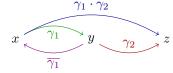
We say  $\gamma_1$  and  $\gamma_2$  are **homotopic** if  $\gamma_1 \simeq \gamma_2$  relative to  $\{0,1\}$ , and we write  $[\gamma]$  for the homotopy equivalence class of  $\gamma$ .

If X is a space with points  $x, y, z \in X$ , and  $\gamma_1$  is a path from x to y,  $\gamma_2$  is a path from y to z, then:

• The *concatenation* of  $\gamma_1$  and  $\gamma_2$  is the path from x to z given by

$$(\gamma_1 \cdot \gamma_2)(s) = \begin{cases} \gamma_1(2s) & 0 \le s \le 1/2\\ \gamma_2(2s-1) & 1/2 \le s \le 1 \end{cases}$$

- The constant path at x is the path  $c_x(s) = x \forall s \in I$
- The *inverse of*  $\gamma_1$  is  $\overline{\gamma_1}(s) = \gamma_1(1-s)$ , a path from y to x.

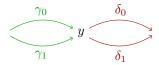


**Theorem 1.3.** Let X be space, and  $x_0 \in X$ . Let  $\pi_1(X, x_0)$  be the set of homotopy classes of loops in X with endpoint  $x_0$  (we say they are **based** at  $x_0$ ). Then  $\pi_1(X, x_0)$  forms a group under the product  $[\gamma_1][\gamma_2] = [\gamma_1 \cdot \gamma_2]$ , with identity  $c_{x_0}$  and inverses  $[\gamma_1]^{-1} = [\overline{\gamma_1}]$ .

This group is called the fundamental group of X (based at  $x_0$ ).

To prove this, we will need the following lemmas:

**Lemma 1.4.** If  $\gamma_0 \simeq \gamma_1$  to y and  $\delta_0 \simeq \delta_1$  from y, then  $\gamma_0 \cdot \delta_0 \simeq \gamma_1 \cdot \delta_1$  and  $\overline{\gamma_0} \simeq \overline{\gamma_1}$ 



*Proof.* Suppose  $\gamma_0 \simeq_F \gamma_1$ , and  $\delta_0 \simeq_G \delta_1$ . Set:

$$H(s,t) = \begin{cases} F(2s,t) & 0 \le s \le 1/2 \\ G(2s-1,t) & 1/2 \le s \le 1 \end{cases}$$

Then  $\gamma_0 \cdot \delta_0 \simeq_H \gamma_1 \cdot \delta_1$ 

Let F'(s,t) = F(1-s,t). Then  $\overline{\gamma_0} \simeq_{F'} \overline{\gamma_1}$ .

**Lemma 1.5.** Let  $\alpha, \beta, \gamma$  be paths from w to x to y to z in X.



Then:

- 1.  $(\alpha \cdot \beta) \cdot \gamma \simeq \alpha \beta \cdot \gamma$
- 2.  $\alpha \cdot c_x \simeq \alpha \simeq c_w \cdot \alpha$
- 3.  $\alpha \cdot \overline{\alpha} \simeq c_w$