```
include(syndex.m4x)dnl
                                                                      include(syndex,m4x)dnl
                                                                      processor (555,p, ABCD,
                processor (555, root, ABCD,
                  SynDEx v5.1c (c) INRIA 2000,
                                                                        SynDEx v5.le (c) INRIA 2000,
                  Thu Mar 16 14:07:12 2000
                                                                        Thu Mar 16 14:07:11 2000
                semaphores (
                                                                      semaphores (
                  B d empty can, B d full can,
                                                                        B d empty can, B d full can,
                  A c empty can, A c full can,
                                                                        A_c_empty_can, A_c_full_can,
                alloc (int, A b)
                                                                      alloc (int,B d)
                                                                      alloc (int, A c)
                alloc (int, A c)
                                                                     alloc (int, C_d)
                alloc (int, B d)
                                                                                  main
                         thread (CAN, can, root, p)
                                                                                    spawn thread (can)
main
                           loadDnto (, p)
                                                                                    Prel (A c empty can)
  spawn_thread_(can)
                           Pre0 (A c empty can)
                                                      thread (CAN, can, root, p)
                                                                                    actuator()
                                                        loadFrom (root)
  sensor()
                           Pre0 (B d empty can)
                                                                                    Prel (B d empty can)
                           100p
  loop
                                                        1000
                                                                                    loop
    Suc0 (A c empty can)
                             Suc1 (A c full can)
                                                                                     Suc0 (A c full can)
                                                          Sucl (A c empty can)
                                                         recv (A c, 555, root, p) compute(A c, C d)
    sensor(A b, A c)
                             send (A_c, 555, root, p)
    Prel (A c full can)
                             Pre0 (A c empty can)
                                                          Pre0 (A c full can)
                                                                                      Prel (A c empty can)
                                                                                    Suco (B d full can)
    Suc0 (8 d empty can)
                           -Sucl (B d full can)
                                                          Sucl (B d empty can)
                                                                                    actuator(B d, C d)
    compute(A b, B d)
                             send (B d, 555, root, p)
                                                          recv (B d, 555, root, b)
    Prel (B d full can)
                             Pre0 (B d empty can)
                                                          Pre0 (B d full can)
                                                                                      Prel (B d empty can)
                           endloop_
                                                        endloop
 endloop
                                                                                    endloop.
                         endthread
                                                      endthread
                                                                                    actuator()
  sensor()
 wait_endthread_(can)
                                                                                    wait endthread (can)
endmain
                                                                                    endmain
                endprocessor
                                                                     endprocessor
```