

CSE 3320

Operating Systems

Multiprocessor Scheduling

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Recap of the Last Class

- Basic scheduling policies on uniprocessors

- First Come First Serve
- Shortest Job First
- Round Robin
- Priority scheduling
- Multilevel feedback queue



Time-sharing:
Which thread should be
run next ?



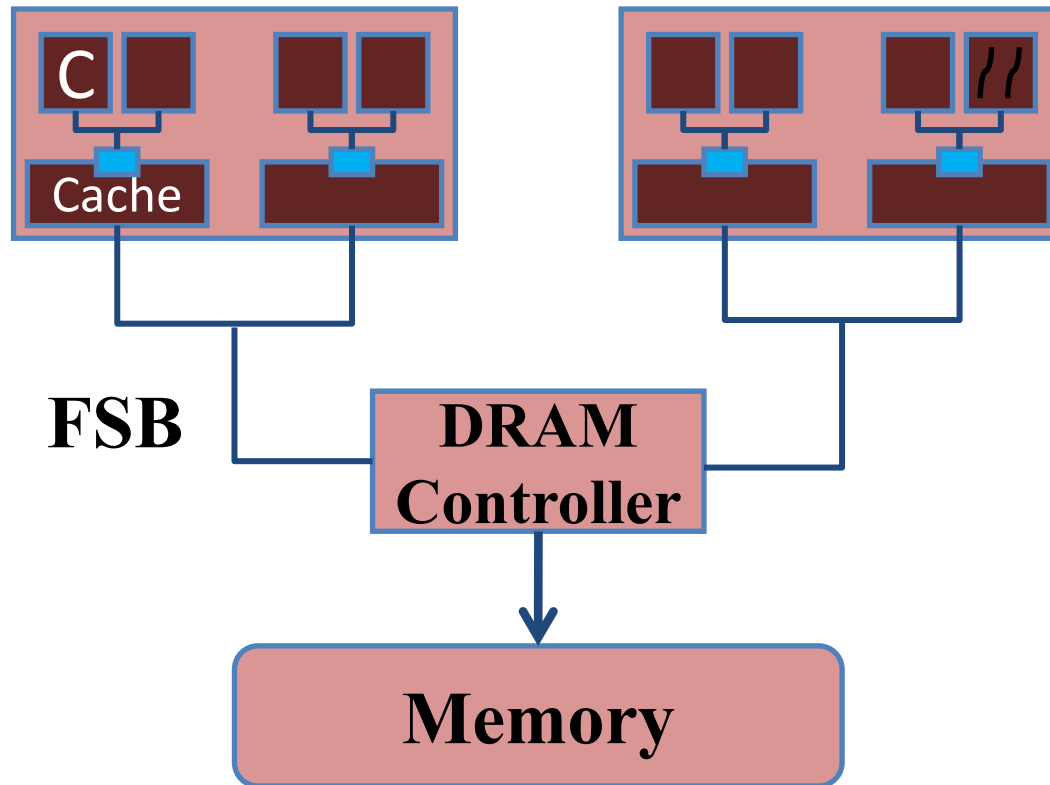
Multiprocessor Scheduling

- Two-dimension scheduling
 - Time-sharing on each processor
 - Load-balancing among multiple processors
- Several issues
 - Why load balancing ? → take advantage of parallelism
 - Simple time-sharing ? → No, may need to consider a group of thds
 - Are all processors/cores equal ? → No, cache affinity, memory Locality, and cache hotness make them different



Multiprocessor Hardware

- Uniform memory access (UMA)



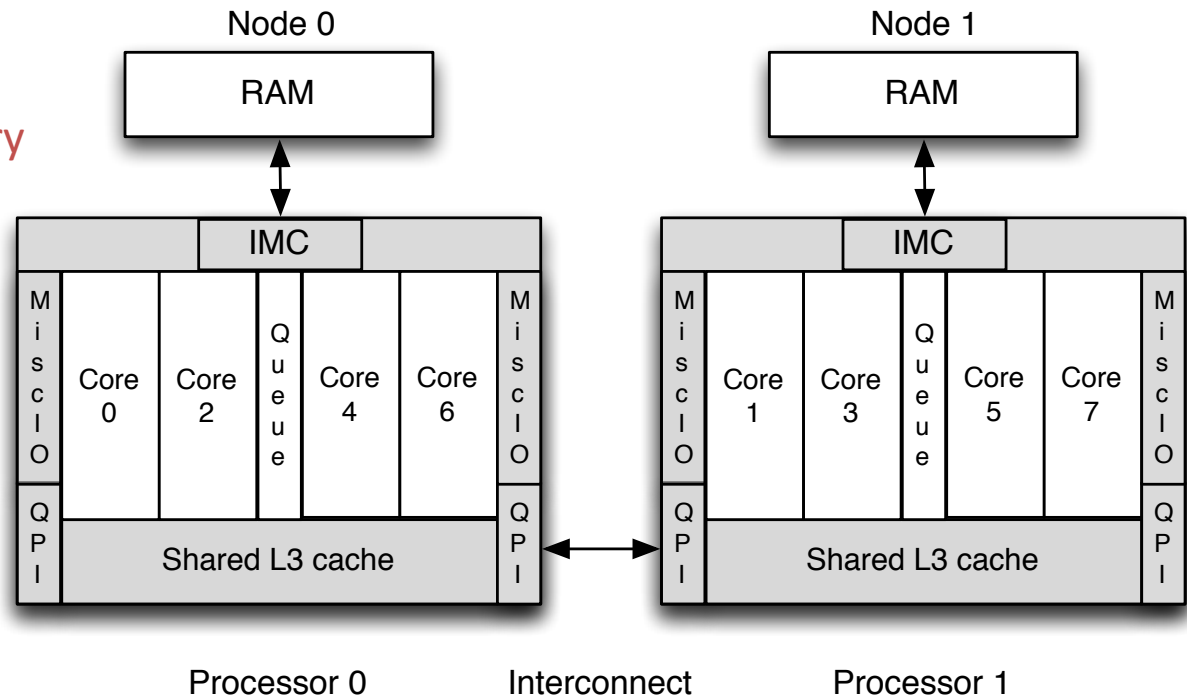
A schematic view of Intel Core 2



Multiprocessor Hardware (cont')

- Non-uniform memory access (NUMA)

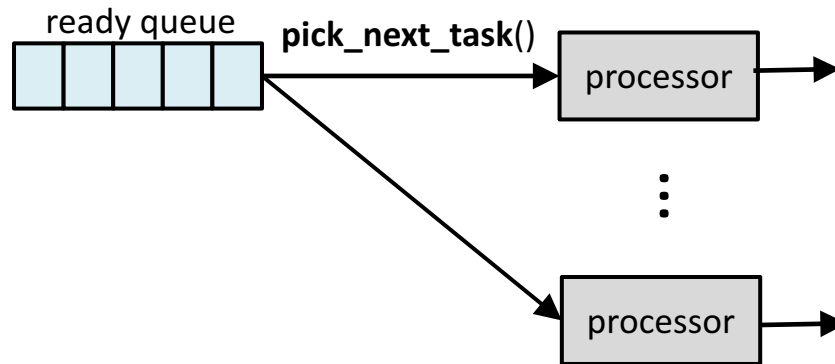
1. Local v.s. remote memory
2. Cache sharing
 1. Constructive
 2. Destructive



A schematic view of Intel Nehalem

Ready Queue Implementation

- A single system-wide ready queue



Pros:

1. Easy to implement
2. Perfect load balancing

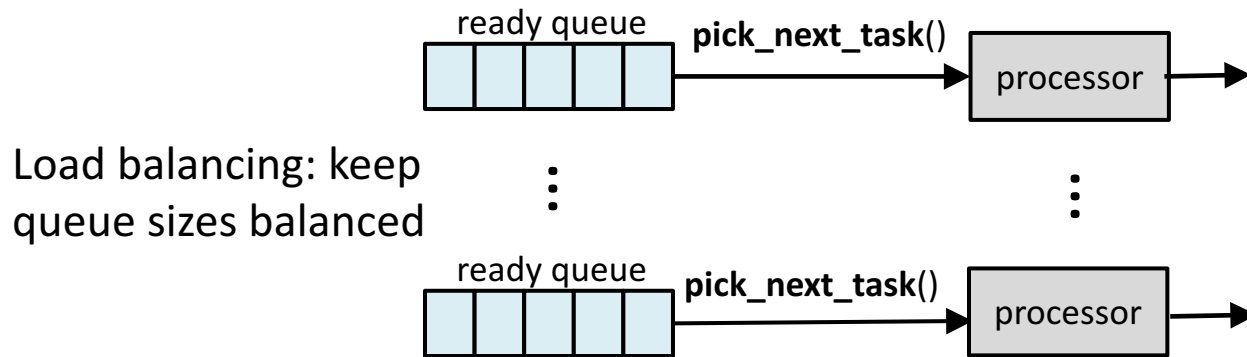
Cons:

1. Scalability issues due to centralized synchronization
2. High overhead and low efficiency
 1. Hard to maintain cache hotness



Ready Queue Implementation (cont')

- Per-CPU ready queue



Pros:

1. Scalable to many CPUs
2. Easy to maintain cache hotness

Cons:

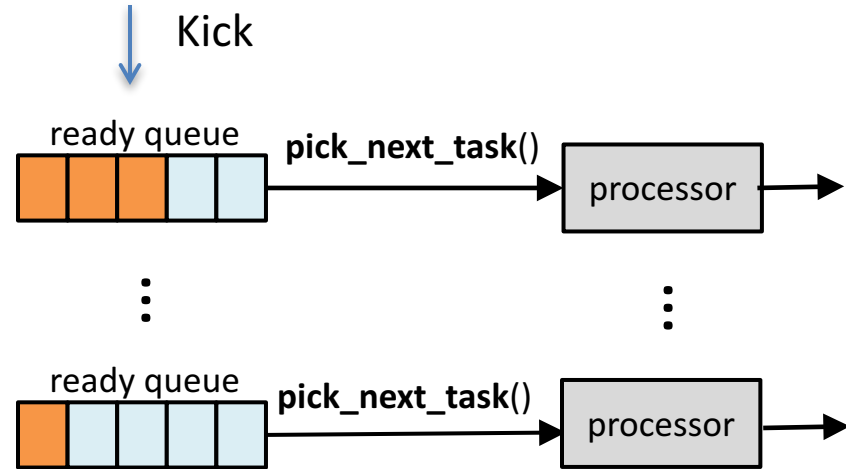
1. More complex to implement
 1. Push model v.s. pull model
2. Not perfect load balancing → not always balanced



Push Model v.s. Pull Model

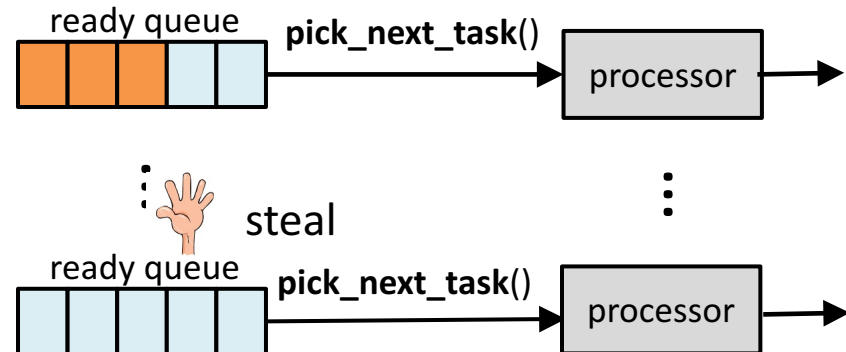
- Push model

Every a while, a kernel thread checks load imbalance and move threads



- Pull model

Whenever a queue becomes empty, steal a thread from non-empty queues



Both are widely used



Scheduling Parallel Programs

- A parallel job
 - A collection of processes/threads that cooperate to solve the **same** problem
 - Scheduling matters in overall job completion time
- Why scheduling matters ?
 - Synchronization on shared data (mutex)
 - Causality between threads (producer-consumer)
 - Synchronization on execution phases (barrier)

The slowest thread delays the entire job



Space Sharing

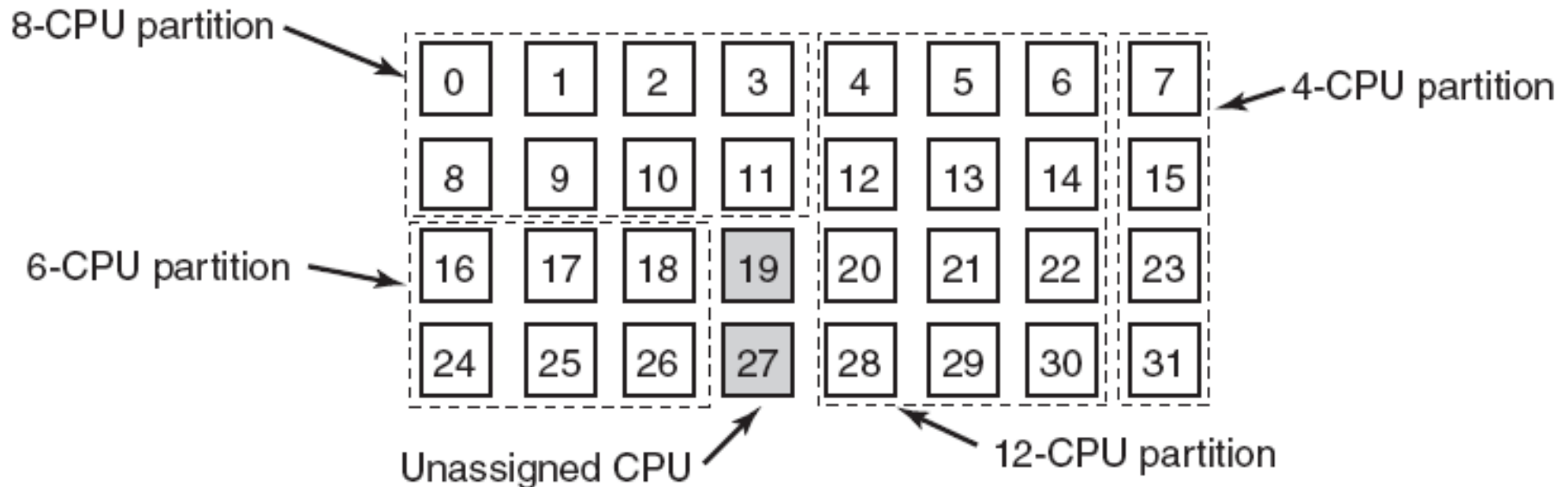
- Divide processor into groups
 - Dedicate each group to a parallel job
 - No preemption before job completion

Pros:

1. Highly efficient, low overhead
2. Strong affinity

Cons:

1. Highly inefficient, cycle waste
2. inflexible



Time Sharing: Gang or Co-Scheduling

- Each processor runs threads from multiple jobs
 - Groups of related threads are scheduled as a unit, a gang
 - All CPUs perform context switch together

		CPU					
		0	1	2	3	4	5
Time slot	0	A ₀	A ₁	A ₂	A ₃	A ₄	A ₅
	1	B ₀	B ₁	B ₂	C ₀	C ₁	C ₂
	2	D ₀	D ₁	D ₂	D ₃	D ₄	E ₀
	3	E ₁	E ₂	E ₃	E ₄	E ₅	E ₆
	4	A ₀	A ₁	A ₂	A ₃	A ₄	A ₅
	5	B ₀	B ₁	B ₂	C ₀	C ₁	C ₂
	6	D ₀	D ₁	D ₂	D ₃	D ₄	E ₀
	7	E ₁	E ₂	E ₃	E ₄	E ₅	E ₆

Gang scheduling (stricter) > co-scheduling



Summary

- Multiprocessor hardware
- Two implementation of the ready queue
 - A single queue v.s. multiple queues
- Load balancing
 - Push model v.s. Pull model
- Parallel program scheduling
 - Space sharing v.s. time sharing
- Additional practice
 - See the load balancer part in
 - <http://www.scribd.com/doc/24111564/Project-Linux-Scheduler-2-6-32>
 - See LINUX_SRC/kernel/sched.c
 - Function `load_balance` and `pull_task`

