
Algorithm 1 DG (Duality Gap)

Input:

$X \in \mathbb{R}^{n \times p}$ ▷ The design matrix
 $Y \in \mathbb{R}^n$ ▷ The vector of predictors
 $\beta \in \mathbb{R}^n$ ▷ Current β
 $\lambda \in \mathbb{R}$ ▷ Grid element
1: $\epsilon \leftarrow X\beta - Y$
2: $f_\beta \leftarrow \|\epsilon\|_2^2 + \lambda \|\beta\|_1$ ▷ Primal Objective function
3: $\alpha \leftarrow \frac{\lambda}{\|2X^T\epsilon\|_\infty}$
4: $\alpha_0 \leftarrow Y^T \epsilon$
5: $\mathcal{S} \leftarrow \min\{\max\{\alpha, \alpha_0\}, -\alpha\}$ ▷ Dual Point
6: $\tilde{\nu} \leftarrow \frac{-2\mathcal{S}}{\lambda} \epsilon + \frac{2}{\lambda} Y$
7: $d_\nu \leftarrow \frac{1}{4} \lambda^2 \|\tilde{\nu}\|_2^2 - \|Y\|_2^2$ ▷ Dual Objective function
return $f_\beta + d_\nu$

Algorithm 2 DGT (Duality Gap Target)

Input:

$\gamma \in \mathbb{R}$ ▷ ...
 $C \in \mathbb{R}$ ▷ ...
 $rStatsIt \in \mathbb{N}$ ▷ Index of the current grid element (outer loop iteration number)
 $n \in \mathbb{N}$ ▷ Number of rows in the design matrix $X \in \mathbb{R}^{n \times p}$
1: $dgt \leftarrow \gamma C^{2 \frac{rStatsIt}{n}}$
return dgt

Algorithm 3 f_β

Input:

$X \in \mathbb{R}^{n \times p}$ ▷ The design matrix
 $Y \in \mathbb{R}^n$ ▷ The vector of predictors
 $\beta \in \mathbb{R}^n$ ▷ Current β
1: $f \leftarrow X\beta - Y$.
return $\|f\|_2^2$

Algorithm 4 $f_{\tilde{\beta}}$

Input:

$X \in \mathbb{R}^{n \times p}$ ▷ The design matrix
 $Y \in \mathbb{R}^n$ ▷ The vector of predictors
 $\beta \in \mathbb{R}^n$ ▷ The k 'th β vector
 $\beta' \in \mathbb{R}^n$ ▷ The $k - 1$ 'th β vector
 $L \in \mathbb{R}$ ▷ The current Lipschitz constant, as computed by backtracking line search

1: $f \leftarrow X\beta - Y$.
2: $t_0 \leftarrow \|f\|_2^2$
3: $\nabla f \leftarrow 2X^T f$
4: $\Delta_\beta \leftarrow \beta - \beta'$
5: $t_1 \leftarrow \nabla f^T \Delta_\beta$
6: $t_2 \leftarrow \frac{L}{2} \|\Delta_\beta\|_2^2$

return $t_0 + t_1 + t_2$

Algorithm 5 τ (Matrix-wise Soft-Thresholding / Proximal Operator)

Input:

$X \in \mathbb{R}^{n \times m}$ ▷ An arbitrary matrix
 $\lambda \in \mathbb{R}$ ▷ The thresholding parameter

1: $\tilde{X} \leftarrow X$ ▷ Make a copy of X .
2: **for** $\tilde{x}_{i,j} \in \tilde{X}$ **do**
3: $\tilde{x}_{i,j} \leftarrow \text{sign}(\tilde{x}_{i,j}) (|\tilde{x}_{i,j}| - \lambda)^+$
4: **end for**

return \tilde{X}

Algorithm 6 ISTA with backtracking line search and duality gap convergence criteria

Input:

$X \in \mathbb{R}^{n \times p}$ ▷ The design matrix
 $Y \in \mathbb{R}^n$ ▷ The vector of predictors
 $\beta \in \mathbb{R}^n$ ▷ Starting vector
 $L_0 \in \mathbb{R}$ ▷ Initial Lipschitz constant, used by backtracking line search
 $\lambda \in \mathbb{R}$ ▷ Grid element
 $\eta \in \mathbb{R}$ ▷ Step size when updating Lipschitz constant
 $\mathcal{D} \in \mathbb{R}$ ▷ Duality gap target
1: $\tilde{\beta} \leftarrow \beta$ ▷ Make a copy of β that will be updated during back tracking.
2: **do**
3: $\tilde{\beta} \leftarrow \tau(\beta - \frac{1}{L} \nabla f(X, Y, \tilde{\beta}, L))$
4: **while** $f_{\beta}(X, Y, \tilde{\beta}) > f_{\tilde{\beta}}(X, Y, \tilde{\beta}, \beta, L)$ **do**
5: $L \leftarrow \eta L$
6: $\tilde{\beta} \leftarrow \tau(\beta - \frac{1}{L} \nabla f(X, Y, \beta))$
7: **end while**
8: $\beta \leftarrow \tau(\beta - \frac{1}{L} \nabla f(X, Y, \beta, L))$ ▷ Update β once L is sufficiently large.
9: **while** $\text{DG}(X, Y, \beta, \lambda) > \mathcal{D}$
10:
return β

Algorithm 7 Coordinate Descent with duality gap convergence criteria

Input:

$X \in \mathbb{R}^{n \times p}$ ▷ The design matrix
 $Y \in \mathbb{R}^n$ ▷ The vector of predictors
 $\beta \in \mathbb{R}^n$ ▷ Starting vector
 $\lambda \in \mathbb{R}$ ▷ Grid element
 $\mathcal{D} \in \mathbb{R}$ ▷ Duality gap target
1: $\tilde{\beta} \leftarrow \beta$ ▷ Make a copy of β
2: **do**
3: **for** $i \in 1, 2, \dots, p$ **do**
4: $t \leftarrow \frac{\lambda}{2\|X_i\|_2^2}$ ▷ Scale grid element by norm of the i'th column of design matrix
5: $X_{-i} \leftarrow X_{\forall j \neq i}$ ▷ Take all columns of design matrix not equal to i
6: $\tilde{\beta}_{-i} \leftarrow \tilde{\beta}_{\forall j \neq i}$ ▷ Take all elements of predictors vectors not equal to i
7: $r \leftarrow \frac{X_i^T(Y - X_{-i}\tilde{\beta}_{-i})}{\|X_i\|_2^2}$ ▷ Compute the scaled residual
8: $\tilde{\beta}_i \leftarrow \tau(r, t)$ ▷ Update the i'th element of Beta
9: **end for**
10: **while** $\text{DG}(X, Y, \tilde{\beta}, \lambda) > \mathcal{D}$
11:
return $\tilde{\beta}$

Algorithm 8 Coordinate Descent with Lazy Evaluation

Input:

$X \in \mathbb{R}^{n \times p}$ ▷ The design matrix
 $Y \in \mathbb{R}^n$ ▷ The vector of predictors
 $\beta \in \mathbb{R}^n$ ▷ Starting vector
 $\lambda \in \mathbb{R}$ ▷ Grid element
 $\mathcal{D} \in \mathbb{R}$ ▷ Duality gap target
1: $\tilde{\beta} \leftarrow \beta$ ▷ Make a copy of β
2: $R \leftarrow Y - X\tilde{\beta}$ ▷ Initialize Intermediary Residual
3: **do**
4: **for** $i \in 1, 2, \dots, p$ **do**
5: $t \leftarrow \frac{\lambda}{2\|X_i\|_2^2}$ ▷ Scale grid element by norm of the i'th column of design matrix
6: **if** $\tilde{\beta}_i \neq 0$ **then** $R \leftarrow R + X_i\tilde{B}_i$
7: **end if**
8: $\tilde{\beta}_i \leftarrow \tau\left(\frac{X_i^T R}{\|X_i\|_2^2}, t\right)$ ▷ Update the i'th element of Beta
9: **if** $\tilde{\beta}_i \neq 0$ **then** $R \leftarrow R - X_i\tilde{B}_i$
10: **end if**
11: **end for**
12: **while** $\text{DG}(X, Y, \tilde{\beta}, \lambda) > \mathcal{D}$
13:
return $\tilde{\beta}$

Algorithm 9 Coordinate Descent with standardized data

Input:

$X \in \mathbb{R}^{n \times p}$ ▷ The standardized $\bar{X}_i = 0, \sigma_{X_i} = 1$ design matrix
 $Y \in \mathbb{R}^n$ ▷ The vector of predictors
 $\beta \in \mathbb{R}^n$ ▷ Starting vector
 $\lambda \in \mathbb{R}$ ▷ Grid element
 $\mathcal{D} \in \mathbb{R}$ ▷ Duality gap target
1: $\tilde{\beta} \leftarrow \beta$ ▷ Make a copy of β
2: **do**
3: **for** $i \in 1, 2, \dots, p$ **do**
4: $t \leftarrow \frac{\lambda}{2n}$ ▷ Scale grid element by norm of the i'th column of design matrix
5: $X_{-i} \leftarrow X_{\forall j \neq i}$ ▷ Take all columns of design matrix not equal to i
6: $\tilde{\beta}_{-i} \leftarrow \tilde{\beta}_{\forall j \neq i}$ ▷ Take all elements of predictors vectors not equal to i
7: $r \leftarrow \frac{X_i^T(Y - X_{-i}\tilde{\beta}_{-i})}{n}$ ▷ Compute the scaled residual
8: $\tilde{\beta}_i \leftarrow \tau(r, t)$ ▷ Update the i'th element of Beta
9: **end for**
10: **while** $\text{DG}(X, Y, \tilde{\beta}, \lambda) > \mathcal{D}$
11:
return $\tilde{\beta}$

The next algorithm is a modified version of Coordinate Descent that seeks to reduce redunant computations as much as possible. This algorithm relies on the fact that many computation required

by Coordinate Descent can be broken up into constant and non-constant parts. The constant parts of the computation can be performed ahead of time and stored for later use.

Of particular note is the scaled residual computation, which when written down naively reads:

$$r \leftarrow \frac{X_i^T(Y - X_{-i}\tilde{\beta}_{-i})}{\|X_i\|_2^2}.$$

Which we can re-write as,

$$r \leftarrow \frac{X_i^T Y}{\|X_i\|_2^2} - \frac{X_i^T X_{-i}}{\|X_i\|_2^2} \tilde{\beta}_{-i}.$$

Note that since the design matrix X and the vector of predictors Y are fixed, the terms $\frac{X_i^T Y}{\|X_i\|_2^2}$ and $\frac{X_i^T X_{-i}}{\|X_i\|_2^2}$ do not change as the values of $\tilde{\beta}$ are updated. Our strategy will be to compute these values for each column of X and store them in an array of size p , from which they will be accessed as \tilde{B} is updated.

Note for this algorithm we establish the convention that array of a given data type will be declared as follows:

$$(\textit{type}) [\# \textit{elements in array}]$$

As an example an array of real numbers of size $n \in \mathbb{N}$ would be written as:

$$(\mathbb{R}) [n]$$

Algorithm 10 Coordinate Descent with Minimal Data Copying

Input:

$X \in \mathbb{R}^{n \times p}$ ▷ The design matrix
 $Y \in \mathbb{R}^n$ ▷ The vector of predictors
 $\beta \in \mathbb{R}^n$ ▷ Starting vector
 $\lambda \in \mathbb{R}$ ▷ Grid element
 $\mathcal{D} \in \mathbb{R}$ ▷ Duality gap target
1: $\mathbf{1} \leftarrow (\mathbb{R})[p]$ ▷ Initialize array of size p to hold threshold parameters
2: $p_1 \in (\mathbb{R})[p]$ ▷ Blank array for part of residual computation
3: $p_2 \in (\mathbb{R}^{1 \times p})[p]$ ▷ Blank array to row vectors of size p which will be used for part of residual computation
4: **for** $i \in 1, 2, \dots, p$ **do**
5: $\mathbf{1} \leftarrow \frac{1}{\|X_i\|_2^2}$
6: $\mathbf{1}[i] \leftarrow \frac{1}{2}\mathbf{1}$
7: $p_1[i] \leftarrow \mathbf{1}X_i^T Y$
8: $p_2[i] \leftarrow \mathbf{1}X_i^T X$
9: **end for**
10: $\tilde{\beta} \leftarrow \beta$ ▷ Make a copy of β
11: **do**
12: **for** $i \in 1, 2, \dots, p$ **do**
13: $\tilde{\gamma} \leftarrow \tilde{\beta}_j$ **if** $j \neq i$ **else** 0 ▷ Copy all of beta except i'th element which is assigned to 0
14: $r \leftarrow p_1[i] - p_2[i]\tilde{\gamma}$ ▷ Compute the scaled residual
15: $t \leftarrow \lambda\mathbf{1}[i]$ ▷ Compute threshold parameter
16: $\tilde{\beta}_i \leftarrow \tau(r, t)$ ▷ Update the i'th element of Beta
17: **end for**
18: **while** $\text{DG}(X, Y, \tilde{\beta}, \lambda) > \mathcal{D}$
19:
return $\tilde{\beta}$

Algorithm 11 FISTA with backtracking line search and duality gap convergence criteria

Input:

$X \in \mathbb{R}^{n \times p}$ ▷ The design matrix
 $Y \in \mathbb{R}^n$ ▷ The vector of predictors
 $\beta \in \mathbb{R}^n$ ▷ Starting vector
 $L_0 \in \mathbb{R}$ ▷ Initial Lipschitz constant, used by backtracking line search
 $\lambda \in \mathbb{R}$ ▷ Grid element
 $\eta \in \mathbb{R}$ ▷ Step size when updating Lipschitz constant
 $\mathcal{D} \in \mathbb{R}$ ▷ Duality gap target
 $y_{k-1} \in \mathbb{R}^b$ ▷ Beta vector from previous iteration of FISTA
 $x_{k-1} \in \mathbb{R}^b$ ▷ Intermediary vector from previous iteration of FISTA
1: $y_k \leftarrow \beta$
2: **do**
3: $y_{k-1} \leftarrow x_k$
4: $t_k \leftarrow 0$
5: $\tilde{y}_k \leftarrow \tau(\beta - \frac{1}{L} \nabla f(X, Y, y_k))$
6: **while** $f_\beta(X, Y, \tilde{y}_k) > f_{\tilde{\beta}}(X, Y, \tilde{y}_k, y_k, L)$ **do**
7: $L \leftarrow \eta L$
8: $\tilde{y}_k \leftarrow \tau(\beta - \frac{1}{L} \nabla f(X, Y, \beta))$
9: **end while**
10: $x_{k-1} \leftarrow x_k$
11: $x_k \leftarrow \tau(\beta - \frac{1}{L} \nabla f(X, Y, \tilde{y}_k))$
12: $t_{k+1} = \frac{(1 + \sqrt{1 + 4t_k^2})}{2}$
13: $y_k \leftarrow x_k + \frac{(t_k - 1)}{t_{k+1}} (x_k - x_{k-1})$
14: **while** $\text{DG}(X, Y, \beta, \lambda) > \mathcal{D}$
15:
return $y_k, y_{k-1}, x_{k-1}, t_{k+1}$

Algorithm 12 λ GRID

Input:

$X \in \mathbb{R}^{n \times m}$ ▷ The design matrix
 $Y \in \mathbb{R}^n$ ▷ The vector of predictors
 $M \in \mathbb{N}$ ▷ The number of grid elements required
1: $r_{max} \leftarrow 2 \|X^T Y\|_\infty$
2: $r_{min} \leftarrow \frac{1}{1000} r_{max}$
3: $\Delta_r \leftarrow (r_{max} - r_{min})$
4: Let $\Lambda \in \mathbb{R}^M$ ▷ Initialize empty array of size M
5: **for** $i \in [1, 2, \dots, M]$ **do**
6: $\delta_i \leftarrow \Delta_r \frac{i}{M-1} + r_{min}$ ▷ Compute linear step
7: $\Lambda[i] \leftarrow 10^{\delta_i}$ ▷ Convert to logarithmic step
8: **end for**
return Λ

Algorithm 13 SCC: Stats Continuation Condition

Input:

$C \in \mathbb{R}$ ▷ The design matrix
 $statsIt \in \mathbb{N}$ ▷ The vector of predictors
 $\lambda \in \mathbb{R}$ ▷ Current grid element
 $\Lambda \in \mathbb{R}^M$ ▷ Vector of grid elements
 $X \in \mathbb{R}^{n \times p}$ ▷ Vector of grid elements
 $\beta_s \in \mathbb{R}^{n \times M}$ ▷ Betas matrix

1: condition \leftarrow false
2: **for** $i \in [1, 2, \dots, statsIt]$ **do**
3: $r_k \leftarrow \Lambda_k$
4: $\Delta_\beta \leftarrow \beta_{statsIt} - \beta_i$
5: check $\leftarrow \frac{n \|\Delta_\beta\|_\infty}{r_{statsIt} + r_k}$
6: condition \leftarrow condition & (check $\leq C$)
7: **end for**
return condition

Algorithm 14 FOS

Input:

$X \in \mathbb{R}^{n \times p}$ ▷ The design matrix
 $Y \in \mathbb{R}^n$ ▷ The vector of predictors
 $\beta \in \mathbb{R}^n$ ▷ Starting vector
 $L_0 \in \mathbb{R}$ ▷ Initial Lipschitz constant, used by backtracking line search
 $M \in \mathbb{M}$ ▷ Number of grid elements
 $\eta \in \mathbb{R}$ ▷ Step size when updating Lipschitz constant
 $C \in \mathbb{R}$
 $\gamma \in \mathbb{R}$

1: $\tilde{X} \leftarrow \frac{1}{\sigma_X} (X - \mu_X)$ ▷ Normalize X to mean 0 and standard deviation 1.
2: $\tilde{Y} \leftarrow \frac{1}{\sigma_Y} (Y - \mu_Y)$ ▷ Normalize Y.
3: $\Lambda \leftarrow \lambda \text{GRID}(X, Y, M)$ ▷ Initialize grid elements
4: $\beta_s \in \mathbb{R}^{n \times m} = 0_{n, m}$ ▷ Initialize matrix of Betas to zero matrix
5: **while** statsCont & (statsCont < M) **do**
6: $statsIt \leftarrow statsIt + 1$
7: $\tilde{\beta} \leftarrow \beta_{k-1}$ ▷ Initialize old beta vector with the k - 1'th Column of the Betas matrix.
8: $r_{statsIt} \leftarrow \Lambda_k$ ▷ Extract the k'th grid element.
9: **if** $DG(X, Y, \beta_k, r_{statsIt}) \leq DGT(\gamma, C, r_{statsIt}, n)$ **then**
10: $\beta_k \leftarrow \beta_{k-1}$
11: **else**
12: $\beta_k \leftarrow \text{ISTA}(X, Y, \beta_{k-1}, L_0, r_{statsIt}, \eta, gap)$
13: **end if**
14: statsCont \leftarrow SCC (C, statsIt, r_statsIt, Λ , X, β_s)
15: **end while**
return $\beta_{statsIt-1}, \Lambda_{statsIt}, statsIt$

Algorithm 15 DP (Dual Point)

Input:

$X \in \mathbb{R}^{n \times p}$

 \triangleright The design matrix

$Y \in \mathbb{R}^n$

 \triangleright The vector of predictors

$\beta \in \mathbb{R}^p$

 \triangleright Current β

$\lambda \in \mathbb{R}$

 \triangleright Grid element

1: $R \leftarrow Y - X\beta$

2: $\alpha \leftarrow \frac{1}{\|X^T R\|_\infty}$

3: $s \leftarrow \min\{\max\{\frac{Y^T R}{\lambda \|R\|_2^2}, -\alpha\}, \alpha\}$

return sR

Algorithm 16 DG2 (Duality Gap for Problem 1)

Input:

$X \in \mathbb{R}^{n \times p}$

 \triangleright The design matrix

$Y \in \mathbb{R}^n$

 \triangleright The vector of predictors

$\beta \in \mathbb{R}^p$

 \triangleright Current primal point

$\nu \in \mathbb{R}^n$

 \triangleright Current dual point

$\lambda \in \mathbb{R}$

 \triangleright Grid element

1: $f_\beta \leftarrow \frac{1}{2} \|Y - X\beta\|_2^2 + \lambda \|\beta\|_1$

 \triangleright Primal Objective function

2: $d_\nu \leftarrow \frac{1}{2} \|Y\|_2^2 - \frac{\lambda^2}{2} \|\nu - \frac{Y}{\lambda}\|_2^2$

 \triangleright Dual Objective function**return** $f_\beta - d_\nu$

Algorithm 17 SAS (Safe Active Set)

Input:

$X \in \mathbb{R}^{n \times p}$

 \triangleright The design matrix

$c \in \mathbb{R}^n$

 \triangleright Center of the ball

$r \geq 0$

 \triangleright Radius of the ball

1: $\mathcal{A} \leftarrow \emptyset$

 \triangleright Initialize Active Set With Empty Set

2: **for** $j \in \{1, \dots, p\}$ **do**

3: **if** $|X_j^T c| + r \|X_j\|_2 \geq 1$ **then**

4: $\mathcal{A} \leftarrow \mathcal{A} \cup \{j\}$

5: **end if**

6: **end for**

return \mathcal{A}

Algorithm 18 CDSR (Coordinate Descent With Lazy Evaluation and Screening Rule)

Input:

$X \in \mathbb{R}^{n \times p}$	▷ The design matrix
$Y \in \mathbb{R}^n$	▷ The vector of predictors
$\beta \in \mathbb{R}^p$	▷ Starting vector
$\lambda \in \mathbb{R}$	▷ Grid element
$\mathcal{D} \in \mathbb{R}$	▷ Duality gap target
1: $\tilde{\beta} \leftarrow \beta$	▷ Make a copy of β
2: $R \leftarrow Y - X\tilde{\beta}$	▷ Initialize Intermediary Residual
3: $\mathcal{A} \leftarrow \{1, \dots, p\}$	▷ Initialize Active Set
4: $optimCont \leftarrow true$	
5: while $optimCont$ do	
6: $\nu \leftarrow DP(X_{\mathcal{A}}, Y, \tilde{\beta}_{\mathcal{A}}, \lambda)$	▷ Dual point
7: $\mathcal{G} \leftarrow DG2(X_{\mathcal{A}}, Y, \tilde{\beta}_{\mathcal{A}}, \nu, \lambda)$	▷ Duality gap
8: $\mathcal{A} \leftarrow SAS(X, \nu, \sqrt{\frac{2}{\lambda^2}} \mathcal{G})$	▷ Safe Active Set
9: if $\mathcal{G} \leq \mathcal{D}$ then	
10: $optimCont \leftarrow false$	
11: else	
12: for $i \in \mathcal{A}$ do	
13: $t \leftarrow \frac{\lambda}{\ X_i\ _2^2}$	▷ Scale grid element by norm of the i'th column of design matrix
14: if $\tilde{\beta}_i \neq 0$ then $R \leftarrow R + X_i \tilde{\beta}_i$	
15: end if	
16: $\tilde{\beta}_i \leftarrow \tau \left(\frac{X_i^T R}{\ X_i\ _2^2}, t \right)$	▷ Update the i'th element of Beta
17: if $\tilde{\beta}_i \neq 0$ then $R \leftarrow R - X_i \tilde{\beta}_i$	
18: end if	
19: end for	
20: end if	
21: $\tilde{\beta}_{\mathcal{A}^c} = 0$	▷ Set to 0 coefficients not in \mathcal{A}
22: end while	
return $\tilde{\beta}$	

Note that Algorithm 18 solves the problem

$$\arg \min_{\beta \in \mathbb{R}^p} \frac{1}{2} \|Y - X\beta\|_2^2 + \lambda \|\beta\|_1 \quad (1)$$

Algorithm 19 FOS With Screening Rule

Input:

	$X \in \mathbb{R}^{n \times p}$	▷ The design matrix
	$Y \in \mathbb{R}^n$	▷ The vector of predictors
	$M \in \mathbb{N}$	▷ Number of grid elements
	$C > 0$	
	$\gamma > 0$	
1:	$\tilde{X} \leftarrow \frac{1}{\sigma_X} (X - \mu_X)$	▷ Normalize X to mean 0 and standard deviation 1.
2:	$\tilde{Y} \leftarrow \frac{1}{\sigma_Y} (Y - \mu_Y)$	▷ Normalize Y.
3:	$\Lambda \leftarrow \lambda \text{GRID}(\tilde{X}, \tilde{Y}, M)$	▷ Initialize grid elements
4:	$\beta_s \in \mathbb{R}^{p \times M} \leftarrow 0_{p,M}$	▷ Initialize matrix of Betas to zero matrix
5:	$statsCont \leftarrow true$	
6:	$statsIt \leftarrow 1$	
7:	while statsCont & (statsIt < M) do	
8:	$statsIt \leftarrow statsIt + 1$	
9:	$\mathcal{D} \leftarrow DGT(\gamma, C, \Lambda_{statsIt}, n)$	▷ Duality gap target
10:	$\beta_{statsIt} \leftarrow \text{CDSR}(\tilde{X}, \tilde{Y}, \beta_{statsIt-1}, \Lambda_{statsIt}/2, \mathcal{D}/2)$	
11:	$statsCont \leftarrow \text{SCC}(C, statsIt, \Lambda_{statsIt}, \Lambda, X, \beta_s)$	
12:	end while	
	return $\beta_{statsIt-1}, \Lambda_{statsIt-1}, statsIt$	
