•智能地球物理 •

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基于迭代启发网络算法的非平稳随机噪声压制

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摘要 常规滤波方法常常放大了噪声的影响,同时噪声的存在也限制了分辨率的提升,并"平滑"了地震数据中的不连续信息。为此,提出了基于迭代启发网络(IIN)算法的非平稳随机噪声压制方法,利用迭代启发网络压制非平稳随机噪声,网络结构简单、紧凑。IIN 由交替方向乘子算法的迭代过程推导而来,利用 L_1 范数优化变分模型。在训练阶段,通过增加一个新的辅助变量,将目标函数的极值转化为增广拉格朗日格式,使用 L-BFGS(Large-Broyden Fletcher Goldforb Shanno)算法判别、训练所有网络参数,最终得到最优去噪模型。理论模型及实际资料的去噪结果表明:①由训练得到的去噪模型根据有效信号的特征,在去噪的同时可保留同相轴的形状特征;采用的迭代网络简单、紧凑,加快了网络的收敛速度,能够用相对较小的数据集和较短的训练时间快速训练去噪模型,达到预期的去噪效果。②所提方法具有较强的适应性,有效地压制了常规地震数据中的非平稳随机噪声。

关键词 深度学习 迭代启发网络 非平稳随机噪声 去噪模型

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0 引言

实际地震数据由于采集仪器或者环境等因素的 影响,往往存在非平稳随机噪声[1],在地震数据中以 脉冲形式出现,具有较强的能量,主要包括猝发脉 冲、异常扰动、声波干扰等[2],很难用人工方法完全 剔除野值和串状干扰[3]。如果中、深层地震资料中 存在强能量干扰,则叠前时间偏移剖面会出现不同 程度的"画弧"现象[4]。现代地震资料处理的目标是 既能衰减噪声、提高地震资料的信噪比,又能保留和 增强有效不连续地震反射信息及储层流体信息[5]。 常规滤波方法常常放大了噪声的影响,同时噪声的 存在也限制了分辨率的提升[6],并"平滑"了地震数 据中的不连续信息。通过自动识别地震记录中的强 能量干扰,确定噪声出现的空间位置,根据定义的阈 值和衰减系数用适当的方式压制非平稳随机噪 声[7]。在动校正后或同相轴相对平直的地震剖面 上,中值滤波器具有压制强能量干扰的能力[8-9],但 很难选取合适的阈值算子兼顾保护有效信号和压制噪声^[10]。由于异常噪声既不连续也不相关,采用局部中值简单地代替噪声位置处的数据,容易压制有效信号,尤其在同相轴弯曲和间断处^[11]。为此,Boashash等^[12]提出了一种瞬时频率估计算法——时频峰值滤波算法,基于时频分析理论压制非平稳随机噪声,将含噪信号调制为解析信号的瞬时频率信号,然后取解析信号时频分布的峰值估计有效信号,经时频峰值滤波后信号得到增强,噪声被压制。林红波等^[13]提出了基于绝对级差统计量(ROAD)的径向时频峰值滤波和径向时频峰值滤波压制地震非平稳随机噪声。

近年来机器学习算法发展迅速,深度学习算法 在数据去噪领域的应用也越来越广泛。Burger等^[14] 推出了具有三层网络的多层感知机模型(MLP),虽然 网络结构不深,但是处理效果较好。Schmidt等^[15]、 Chen等^[16]分别提出联合收缩方法(CSF)、反应扩散 模型(TNRD),这两种方法的信噪比提高和边缘保

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护效果超过了块匹配方法(BM3D)。 Mao 等[17] 利用机器学习算法实现了地震数据处理、属性提取、断层预测等方面的云地震数据分析平台。 Zhang 等[18] 受迭代收缩阈值算法(ISTA)的启发,提出了一种新的结构化深度网络(Iterative Shrinkage-Thresholding Algorithm Network, ISTA-net),能快速、准确地实现数据的去噪和压缩感知重建。

本文利用深度学习算法中的监督数据驱动算法——迭代启发网络(Iterative scheme inspired network,IIN)压制非平稳随机噪声[19],该网络结构简单、紧凑。IIN 由交替方向乘子算法(Alternating Direction of Method of Multipliers, ADMM)的迭代过程推导而来,利用 L_1 范数优化变分模型。在训练阶段,通过增加一个新的辅助变量,将目标函数的极值转化为增广拉格朗日格式,使用 L-BFGS 算法判别、训练所有网络参数,最终得到最优去噪模型参数。在实验阶段,首先利用模型数据和实际数据建立训练数据库,使用训练阶段得到的去噪模型去噪。实验结果表明,与现有的压制非平稳随机噪声方法相比,文中方法具有明显的优势。

1 基本理论与技术流程

1.1 迭代收缩一阈值启发网络算法

噪声消除的目的是从采集到的含噪数据 y 中恢复无噪数据。传统压缩感知(Compressive Sensing, CS)方法通过求解以下优化问题恢复无噪数据,其目标函数为[20]

$$x = \min_{x} \frac{1}{2} \| \boldsymbol{\phi}_{x} - \mathbf{y} \|_{2}^{2} + \lambda \| \boldsymbol{\Psi}_{x} \|_{1} \qquad (1)$$

式中: x 为无噪数据的估计值; Φ 为变化矩阵,将 x 变换到不同域; Ψ 为非线性变换函数; λ 为正则化参数。

ISTA-net 网络算法结合 CS 算法,网络由固定的层数组成,每层中一次迭代采用传统 ISTA 算法,该网络结合了 ISTA 和 CS 的优势 $^{[21]}$ 。该网络通过 迭代两个更新步骤

$$\begin{cases} \boldsymbol{r}^{(k)} = \boldsymbol{x}^{(k-1)} - \boldsymbol{s}^{(k)} \boldsymbol{\Phi}^{\mathrm{T}} [\boldsymbol{\Phi} \boldsymbol{x}^{(k-1)} - \boldsymbol{y}] \\ \boldsymbol{x}^{(k)} = \arg\min_{x \in \mathbb{R}} \frac{1}{2} \| \boldsymbol{x} - \boldsymbol{r}^{(k)} \|_{2}^{2} + T \| F(\boldsymbol{x}) \|_{1} \end{cases}$$
(2)

估计去噪数据[22]。式中: k 为迭代次数; $s^{(k)}$ 为步长,根据之前的步长参数由学习确定; T 为软阈值算

子的阈值; F(x) 为参数可学习的非线性变换函数。 1.2 IIN 算法

非平稳随机噪声主要表现为脉冲噪声,以不规则脉冲或噪声"尖峰"的形式随机出现在地震数据中,持续时间短,具有谱密度较宽和振幅相对较高的特点 $[^{23}]$ 。由于 L_2 范数对局部异常值的检测不稳定,在压制非平稳随机噪声时会限制算法的处理效果。因此本文采用的 IIN 算法在迭代收缩一阈值启发网络算法的基础上,采用 L_1 范数优化噪声压制方程,增强对局部强能量噪声的敏感度 $[^{24}]$,结合ADMM 网络 $(ADMM-net)^{[25]}$,通过优化问题

$$\mathbf{x} = \arg\min_{\mathbf{x}} \left(\| \mathbf{x} - \mathbf{y} \|_{1} + \sum_{l=1}^{L} \lambda_{l} \| \mathbf{D}_{l} \mathbf{x} \|_{1} \right) \quad (3)$$

得到去噪数据。式中 $l \in [1,2,\cdots,L]$ 为滤波器序号,L 为单层滤波器的总数。滤波器 D 的参数由网络进行训练。

引入变量 t=x-y, z=Dx,则式(3)的增广拉格朗日函数为[26]

$$\xi_{\varepsilon,\rho}(x,t,z,\boldsymbol{\alpha},\boldsymbol{\omega})$$

$$= \| \boldsymbol{t} \|_{1} + \frac{\varepsilon}{2} \| \boldsymbol{t} - (\boldsymbol{x} - \boldsymbol{y}) \|_{2}^{2} -$$

$$\langle \boldsymbol{\omega}, \boldsymbol{t} - (\boldsymbol{x} - \boldsymbol{y}) \rangle + \sum_{l=1}^{L} \lambda_{l} \| \boldsymbol{z}_{l} \|_{1} +$$

$$\sum_{l=1}^{L} \frac{\rho_l}{2} \| \mathbf{z}_l - \mathbf{D}_l \mathbf{x} \|_2^2 - \sum_{l=1}^{L} \langle \mathbf{\alpha}_l, \mathbf{z}_l - \mathbf{D}_l \mathbf{x} \rangle$$
 (4)

式中: $\epsilon \setminus \rho$ 为权重系数; $\alpha \setminus \omega$ 为拉格朗日乘数矩阵。根据 ADMM 算法,引入变量 $p = \omega/\epsilon$, $\beta_l = \alpha_l/\rho_l$,则式(4)分解为 6 个问题

$$\mathbf{x}^{(n)} = \left[\boldsymbol{\varepsilon}^{(n)} \mathbf{I} + \sum_{l=1}^{L} \rho_{l}^{(n)} \mathbf{H}_{l}^{(n)T} \mathbf{H}_{l}^{(n)} \right]^{-1} \times \left\{ \boldsymbol{\varepsilon}^{(n)} \left[\mathbf{t}^{(n-1)} - \mathbf{p}^{(n-1)} + \mathbf{y} \right] + \right\}$$

$$\sum_{l=1}^{L} \rho_{l}^{(n)} \boldsymbol{H}_{l}^{(n)T} \left[\boldsymbol{z}_{l}^{(n-1)} - \boldsymbol{\beta}_{l}^{(n-1)} \right]$$
 (5a)

$$c_{l}^{(n)} = D_{l}^{(n)} x^{(n)} \tag{5b}$$

$$\mathbf{z}_{l}^{(n)} = S\left[\mathbf{c}_{l}^{(n)} + \mathbf{\beta}_{l}^{(n-1)}; \frac{\lambda_{l}}{\rho_{l}}\right]$$
 (5c)

$$\boldsymbol{\beta}_{l}^{(n)} = \boldsymbol{\beta}_{l}^{(n-1)} + \eta_{l}^{(n)} \left[\boldsymbol{c}_{l}^{(n)} - \boldsymbol{z}_{l}^{(n)} \right]$$
 (5d)

$$t^{(n)} = S \left[x^{(n)} - y + p^{(n-1)}; \frac{1}{\varepsilon} \right]$$
 (5e)

$$\boldsymbol{p}^{\scriptscriptstyle(n)} = \boldsymbol{p}^{\scriptscriptstyle(n-1)} + \boldsymbol{\tau}^{\scriptscriptstyle(n)} \lceil \boldsymbol{x}^{\scriptscriptstyle(n)} - \boldsymbol{t}^{\scriptscriptstyle(n)} - \boldsymbol{y} \rceil \tag{5f}$$

式中: n 为层数; $S(\bullet)$ 为非线性收缩函数; I 为各元素为 1 的矩阵; H_i^n 为第 n 层中第 l 个滤波器矩阵;

 $\tau \setminus \eta$ 为可学习的权重参数,控制学习速率,在网络训练中逐层修正。

1.3 技术流程

在 IIN 网络算法中,每层有 6 个计算节点(对应式(5)),具体步骤如下。

(1)利用式(5a)重构输入的地震数据。若该层 是第一层(n=1)时,式(5a)变为

$$\boldsymbol{x}^{(1)} = \left[\boldsymbol{\varepsilon}^{(1)}\boldsymbol{I} + \sum_{l=1}^{L} \rho_{l}^{(1)}\boldsymbol{H}_{l}^{(n)T}\boldsymbol{H}_{l}^{(1)}\right]^{-1} \left[\boldsymbol{\varepsilon}^{(1)}\boldsymbol{y}\right] \quad (6)$$

- (2)对重构数据 $x^{(n)}$ 进行滤波处理。
- (3)根据式(5c)对滤波数据进行非线性变换,其中 $S[\cdot]$ 为分段函数,其形式为

$$S[a, u_i, w_{l,i}^{(n)}]$$

$$= \begin{cases} a + w_{l,1}^{(n)} - u_1 & a < u_1 \\ a + w_{l,N_C}^{(n)} - u_{N_c} & a > u_{N_C} \\ w_{l,m}^{(n)} + \frac{(a - u_m) \left[w_{l,m+1}^{(n)} - w_{l,m}^{(n)} \right]}{u_{m+1} - u_k} & u_1 \leqslant a \leqslant u_{N_C} \end{cases}$$

$$(7)$$

由于分段线性函数拟合性程度高,可以根据数据的特点,学习更加合适的非线性变换函数。其中

$$m = \left| \frac{a - u_1}{u_2 - u_1} \right|$$

式中: $\lfloor \ \rfloor$ 表示取不大于 $\frac{a-u_1}{u_2-u_1}$ 的最大整数,a 为滤波数据; u_i 表示把 $\lfloor -1,1 \rfloor$ 分割成 N_c-1 段后第 i 个断点的位置, N_c 为断点个数; $w_i^{(n)}$ 为第 n 层中第 l 个滤波器在第 i 断点处的值,该值由权重系数 λ_l/ρ_l 决定, $i \in [1,2,\cdots,N_c]$ 。如果 n=1,即为第 1 层时,令 $\boldsymbol{\beta}_i^{(n-1)} = \mathbf{0}$ 。

- (4)根据式(5d)更新乘数 $\boldsymbol{\beta}_{l}^{(n)}$ 。
- (5)对重构数据按步骤(3)进行非线性变换,如果 n=1,即为第 1 层时,令 $p^{(n-1)}=0$ 。
 - (6)根据式(5f)更新乘数 $p^{(n)}$ 。
 - 图 1 为第 k 层正向传播流程。

在网络训练过程中,通过计算估计数据与输入数据之间的误差作为损失函数

$$E(\boldsymbol{\Theta}) = \left| 10 \left| \lg \frac{\sum_{\mathbf{y}} \sum_{\mathbf{\Theta}} [\mathbf{x} - \hat{\mathbf{x}}(\mathbf{y}, \boldsymbol{\Theta})]^{2}}{\sum_{\mathbf{y}} \sum_{\mathbf{\Theta}} \mathbf{x}^{2}} \right| \right|^{-1}$$
(8)

式中 Θ 表示上述流程中各个参数的集合。在反向传播过程中计算损失函数 $E(\Theta)$ 对参数集 Θ 的梯

度,利用 L-BFGS 算法,通过最小化式(8)的取值,优化去噪数据 $\hat{x}(y,\Theta)$ 的参数集 Θ 。通过不断循环反向传播过程,使 $E(\Theta)$ 的值不再下降、保持稳定为止,以保证在去噪的同时不压制有效信号。

图 2 为第 k 层反向传播流程。通过反向传播计算得到去噪网络参数模型,利用该模型对输入地震数据进行正向传播便可得到去噪后的地震数据。

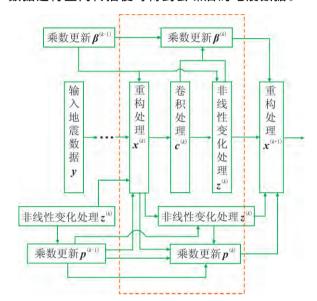


图 1 第 k 层正向传播流程

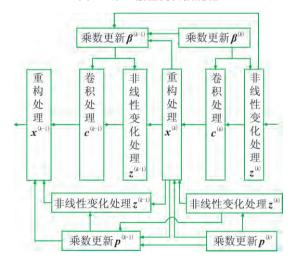


图 2 第 k 层反向传播流程

2 理论模型试算

为了验证上述去噪算法的可行性和有效性,分别对模型数据和实际地震数据进行去噪实验。通过比较不同层数的网络处理效果设置网络总层数,过多的层容易导致过拟合,过少的层数不能有效去

除噪声。综合去噪效果和计算时间设置单层滤波器总数目。根据经验设置 N_c 值,关系到分段线性函数的拟合程度。合成地震数据添加了非平稳随机噪声,生成含噪数据作为输入数据,无噪数据作为输出数据;单炮叠前地震数据作为实际数据,存在大量的非平稳随机噪声,采用空变中值滤波和时变中值滤波去噪得到去噪后数据,再选择去噪效果理想的数据作为数据库数据。通过水平翻转和 90° 旋转将训练数据集扩充,以增加数据的多样性。然后对上述数据训练得到去噪模型。图 3 为训练库部分数据。

图 4 为损失函数曲线与峰值信噪比(PSNR)曲线。由图可见:①在第 6 次迭代之前,损失函数值呈明显下降趋势,当迭代次数大于 6 后,损失函数值收敛于小值,说明去噪误差达到最小值,并且其变化

趋于平稳,证明训练模型去噪结果稳定(图 4a)。②前几次迭代生成的去噪模型的去噪能力不强,经过几次迭代之后,去噪能力趋于稳定,尤其在迭代次数大于 7 之后,去噪数据的 PSNR 较高且稳定(图 4b)。由于采用简单、紧凑的网络结构,因此曲线收敛速度较快,表明文中方法用相对较小的数据集和较少的训练时间得到了稳定的去噪模型。

根据模型中有效信号的能量在合成数据(图 5a)加入非平稳随机噪声得到含噪数据(图 5b),再利用训练好的网络模型去噪得到去噪结果(图 5c)。可见,经过去噪后噪声被压制,去除的噪声(图 5d)中基本不存在有效信号,提高了信噪比。为了对比对叠后模型的去噪效果,分别利用本文方法与传统中值滤波方法对含噪模型(图 6a)去噪,结果表明:本文方法的去噪结果(图6b)没有残留噪声,去除的噪

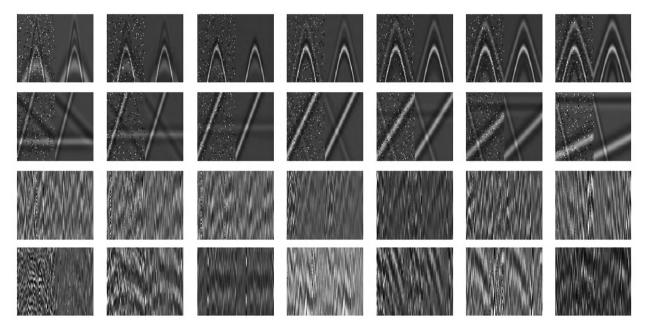


图 3 训练库部分数据

设置网络总层数 n=13,单层滤波器总数目 L=8,单个滤波器矩阵设为 3×3 阶。根据经验将 N_C 值设为 501,即 把[-1,1]平均分成 500 段。训练库数据的单个大小为 200×200 ,用 2000 组数据作为训练库,200 组数据作为验证库,数据库中 80%为实际地震数据,20%为合成地震数据。每组数据的左侧为含噪数据,右侧为无噪数据

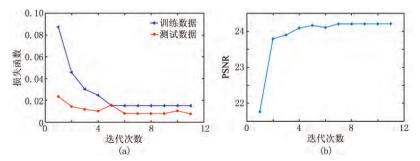
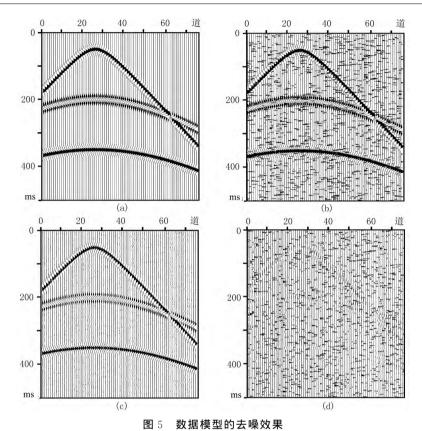
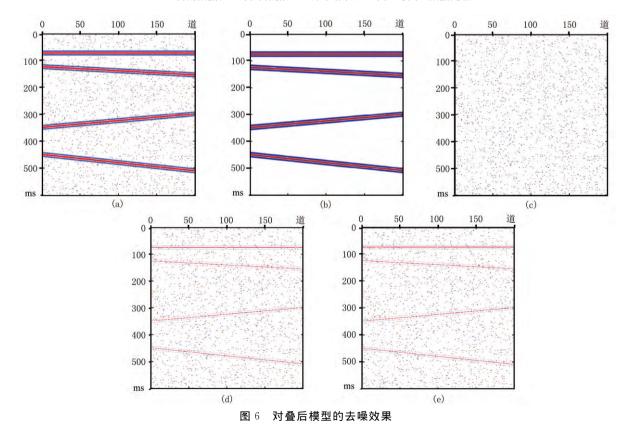


图 4 损失函数曲线(a)与峰值信噪比(PSNR)曲线(b)



(a)合成数据;(b)含噪数据;(c)去噪结果;(d)图 c 与图 b 数据之差



(a)含噪模型;(b)本文方法去噪结果;(c)图 b 与图 a 数据之差;(d)中值滤波去噪结果;(e)图 d 与图 a 数据之差

声(图 6c)中不存在有效信号;中值滤波方法的阈值 设置影响了去噪结果(图 6d),部分有效信号被压制,如果阈值设置太大,则会残留噪声,很难选取合 适的阈值有效地压制噪声。

图 7 为图 6 第 10 道数据去噪前、后对比。由图可见:由于本文方法噪声压制方程的保真项采用 L_1 范数,可更敏感地检测地震数据中的非平稳随机噪声并进行压制(图 7a);中值滤波去噪结果中有效信号也被压制,去噪效果不理想(图 7b)。

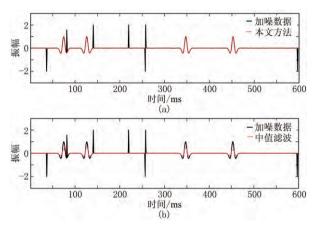


图 7 图 6 第 10 道数据去噪前、后对比 (a)本文方法:(b)中值滤波

3 实际地震数据的应用

分别采用时频峰值滤波方法和本文方法对实际 地震数据去噪并分析去噪结果。图 8 为 F 区实际 地震数据去噪结果。由图可见:86 道实际地震记录 中有几道含有较强的非平稳随机噪声,干扰有效信 号并影响弱有效信号的拾取(图 8a);时频峰值滤波 对图 8a 的去噪结果中残留噪声(图 8b);经本文方 法对图 8a 去噪后有效压制了噪声,没有破坏有效信 号且很好地保护了弱有效信号(图 8d)。

单点高密度地震资料信号频带宽、波场信息丰富,反映了地下真实的反射信息,但同时也存在大量的噪声,因此出现信噪比较低、有效信号与噪声混杂的问题,不易发挥高密度资料的潜在优势。为了检验本文方法对单点高密度地震数据的去噪效果,在训练库中增加相应的单点高密度数据,并选取 G 区的单点高密度单炮道集进行去噪实验。图 9 为 G 区单点高密度地震数据去噪结果。由图可见:经本文方法对单点高密度地震数据(图9a)去噪后,在压

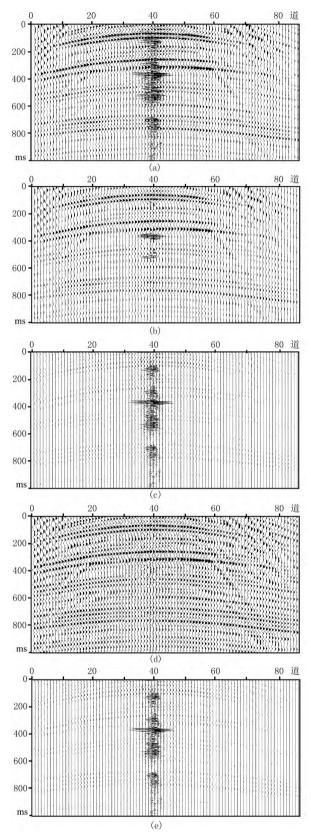


图 8 F 区实际地震数据去噪结果
(a)实际地震数据;(b)时频峰值滤波;(c)图 b 与图 a
数据之差;(d)本文方法;(e)图 d 与图 a 数据之差

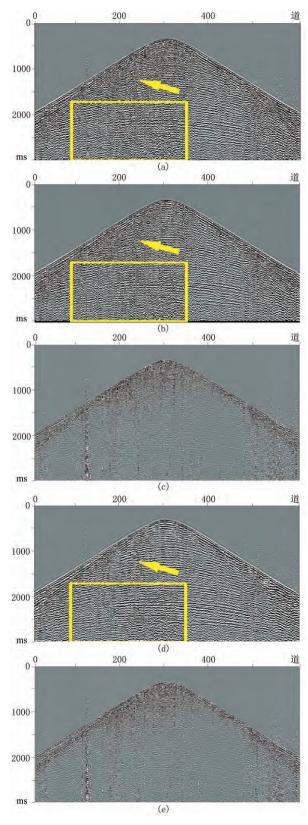


图 9 G 区单点高密度地震数据去噪结果 $\begin{array}{lll} (a) \, \dot{\mu} \, \text{点高密度地震数据}; \, (b) \, \text{时频峰值滤波}; \, (c) \, \textbf{图} \, \textbf{b} \, \textbf{5} \\ \textbf{图} \, \textbf{a} \, \textbf{数据} \, \textbf{ZE}; \, (d) \, \textbf{本文方法}; \, (e) \, \textbf{B} \, \textbf{d} \, \textbf{5} \, \textbf{B} \, \textbf{a} \, \textbf{数据} \, \textbf{ZE}, \\ \textbf{共有} \, \textbf{610} \, \ddot{\textbf{d}}, \text{采样时间为} \, \textbf{3s.}, \textbf{时间采样间隔为} \, \textbf{0.01s} \\ \end{array}$

制非平稳随机噪声的同时,保护了有效信号(图 9d 箭头处);时频峰值滤波方法对图 9a 的去噪结果中残留噪声(图 9b 箭头处)。图 10 为图 9 的局部放大。由图可见:时频峰值滤波处理结果中残留噪声(图 10b);本文方法去噪结果的同相轴清晰、连续,有效压制了噪声(图 10c)。

理论模型试算和实际地震数据去噪结果表明, 本文方法有效减小了信号畸变,较好地压制了各种 非平稳随机干扰,且对实际数据具有较强适应性。

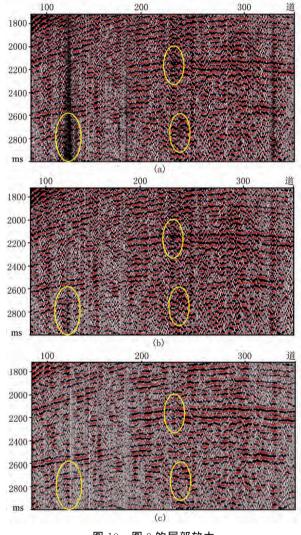


图 10 图 9 的局部放大 (a)图 9a; (b)图 9b; (c)图 9d

4 结束语

针对地震数据中的非平稳随机噪声,本文提出了采用基于迭代启发网络算法的去噪方法,采用深度学习算法,利用 L₁ 范数对目标函数进行优化,可

更敏感地检测并压制地震数据中的非平稳随机噪声,同时较好地保护有效信号。理论模型及实际资料的去噪结果表明:

- (1)利用迭代启发网络(IIN)算法,通过构建包含不同形态有效信号同相轴的数据,并结合实际地震数据建立训练数据库,由训练得到的去噪模型根据有效信号的特征,在去噪的同时可保留同相轴的形状特征;采用的迭代网络简单、紧凑,加快了网络的收敛速度,用相对较小的数据集和较少的训练时间快速训练去噪模型,去噪效果较好。
- (2)本文方法具有较强的适应性,有效压制了常规地震数据中的非平稳随机噪声。对于单点高密度地震数据,较传统的时频峰值滤波算法,可有效减小信号畸变,较好地压制各种非平稳随机干扰。

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ABSTRACTS

Detection of microseismic events based on convolutional neural network. WANG Weibo¹, XU Xilong¹, SHENG Li¹, and GAO Ming¹. Oil Geophysical Prospecting, 2020, 55(5):939–949.

Conventional detection methods for microseismic events are almost based on calculating the features of signals. The accuracy of events detection depends on the parameters of algorithms, so it is greatly affected by the changes in the features of signals and signal-to-noise ratio. This paper proposes a method for microseismic event detection based on a convolutional neural network (CNN). To train and test the CNN, a sample set is constructed on the microseismic data monitored by multiple stations in an oil well that was hydraulically fractured. The data consist of effective event signals and ineffective background noises and their classifications. Then the CNN is trained and tested by the sample data set, and an optimal CNN model is obtained with best accuracy of event detection. To test the performance of the CNN model, synthesized microseismic signals with different signalto-noise ratios, and actual microseismic signals from several oil and gas wells are fed into the CNN model. The processing results demonstrate that the CNN model can automatically and effectively detect microseismic events. It has good abilities for noise suppressing and generalization.

Keywords: microseismic events, event detection, convolutional neural network, model training, real-time data processing

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Automatic fault recognition with residual network and transfer learning. ZHANG Zheng¹, YAN Zhe¹, and GU Hanming¹. Oil Geophysical Prospecting, 2020,55(5):950-956.

The application of machine learning algorithms in the field of geophysics has been expanded and deepened. In fault recognition on seismic data, the main approach is training a shallow convolutional neural network to achieve fault recognition using actual or synthetical fault samples. Actual fault samples require manual marking, which is very time-consuming. Synthetic fault samples are easy to obtain, but the effect of the trained network model is inadequate when applied to actual seismic

data. For this reason, this paper combines a deep residual network with transfer learning to fault recognition. First train synthetical fault samples by constructing a deep residual network with better performance, then use a small number of actual fault samples for transfer learning. This way the generalization ability of the network can be enhanced, and the recognition results can be optimized. After transfer learning, the network can more effectively improve the recognition accuracy of actual faults than ever before. Actual seismic data have proved the feasibility and effectiveness of the method.

Keywords: seismic data interpretation, fault recognition, deep residual network, transfer learning, network structure optimization

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Iterative scheme inspired network for non-stationary random denoising. ZHANG Wenzheng¹, TANG Jie¹, LIU Yingchang¹, MENG Tao¹, and CHEN Xueguo². Oil Geophysical Prospecting, 2020, 55(5): 957–964, 972.

Conventional filtering methods often magnify the influence of noise, which in return impedes the improvement of resolution and "smooths" discontinuous information in seismic data. We introduce a non-stationary random noise filtering method based on an iterative scheme-inspired network (IIN) which has a simple and tight structure and can be used to smooth non-stationary random noises. The L1 norm is used to optimize the objective function of the alternating directional multiplier algorithm which the IIN is derived from. A new auxiliary variable is added to transform the extreme value of the objective function into an augmented Lagrange form, and using the L-BFGS algorithm to distinguish and train all the network parameters. Finally an optimal denoising model is obtained. Applications to model and real data show that: 1 the trained denoising model can effectively suppress noises while maintaining the characteristics of events according to the features of useful signals; and the simple and tight iterative network can speed up the rate of convergence and rapidly finish denoising and achieve expected results using a smaller database and shorter training time; 2 the

method proposed has a good adaptability and can suppress non-stationary random noises in conventional seismic data.

Keywords: deep learning, iterative scheme inspired network, non-stationary random noises, denoising model

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A new deep-towed, multi-channel high-resolution seismic system and its preliminary application in the South China Sea. WEI Zhengrong^{1,2,3}, PEI Yanliang^{2,3,4}, and LIU Baohua^{4,5}. Oil Geophysical Prospecting, 2020, 55(5):965-972.

The proprietary deep-towed, multi-channel high-resolution seismic system (Kuiyang-ST2000) consisting of a plasma electric spark source with the advantages of high sound source level, wide frequency band, and multichannel receiver array (48 channel, interval 3, 125m) is capable of operating at 2000m in ocean. During operating, the source and the receiving cable are towed to the offshore floor (less than 100m). This shortens the distance between the system and the detected target, reduces the absorption and attenuation of seawater during the propagation of seismic signals, and can overcome multiples, bubbles and ocean noises caused by towing streamers on sea surface. The first test on the ST2000 system was completed in the E sea area of the South China Sea (the regional sea floor is about 1500m deep, and the system working depth is about 1400m). The final imaging profile after fine processing of test data has verified the superiority of the Kuiyang-ST2000 system, which overcomes the shortcomings of insufficient resolution of conventional marine multi-channel seismic systems.

Keywords: deep-towed seismic system, plasma spark source, multi-channel cable, high resolution seismic, vertical resolution, horizontal resolution

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Selecting spatial samples based on seismic migration of dip formation, CAI Xiwei¹, HE Baoqing¹, ZHANG Yang¹, WANG Yan¹, and TANG Donglei¹. Oil Geophysical Prospecting, 2020, 55(5):973-978.

The size of spatial sample is an important parameter for seismic data acquisition and processing. At present, the formula for calculating spatial sampling sizes only considers the aliasing-free samplesof reflected wave, or diffracted wave in the migration aperture, but it is not suitable for the imaging requirements of dip formations. In this paper, the time-distance equation of reflected wave is established based on the essence of seismic migration imaging and the distribution characteristics of diffracted wave field, then the spatial sampling formula for migration imaging of dip formations is derived based on the principle of seismic wave inphase superposition, and finally, the spatial sampling of seismic imaging with different dips and different frequencies is analyzed. The result provides a reliable basis of spatial sampling selection for seismic data acquisition design and migration imaging.

Keywords: spatial sampling, dip formation, diffracted wave field, time-distance equation of reflection wave, in-phase stacking

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Automatic pick-up of seismic P-wave first arrivals via fuzzy C-means method constrained by super-virtual interferometry, TAN Jiawei¹, LI Jing¹, LI Feida², and ZENG Zhaofa¹. Oil Geophysical Prospecting, 2020, 55(5):979-990,

In seismic data processing, such as static correction and seismic tomography, accurate and quick pick-up of first arrivals is the basic premise of velocity structure imaging and comprehensive interpretation of seismic data. It is difficult to finish big data through manual picking, and manual method may cause man-made errors. For seismic data with low signal-to-noise ratio (SNR), conventional automatic picking methods, such as correlation method, energy ratio method (STA/LTA), and fractal method, should keep adjusting parameters to achieve desired accuracy, therefore resulting in poor stability. This paper proposes a method to automatically pick up first arrivals based on fuzzy Cmeans and super-virtual interferometry. Fuzzy Cmeans (FCM) clustering analysis is an unsuper-