**Captain::DMode::DriveModel**

# m_leaderVehicle

# m_elapsedCycle

# m_active

+ DriveModel()

+ ~DriveModel()

+ DriveModel()

+ DriveModel()

+ operator=()

+ operator=()

+ operator()()

+ IsActivated()

+ Activate()

+ Deactivate()

and 7 more...

# m_getSafetyDistance()

# m_evaluateLCPosition()

# m_getMinimumConstraint()

# m_getMaximumConstraint()

**Captain::DMode::CV**

+ CV()

+ ~CV()

+ operator()()