

Captain::Node::MicroLane
::MoveFromNearbyLane

Captain::Node::MicroLane
::UpdateVehiclePosition

Captain::Util::VehicleQueue
::Sort

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graph LR; A["Captain::Node::MicroLane::MoveFromNearbyLane"] --> C["Captain::Util::VehicleQueue::Sort"]; B["Captain::Node::MicroLane::UpdateVehiclePosition"] --> C;
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The diagram illustrates a dependency or call relationship. Two white rectangular boxes on the left represent the source methods: 'Captain::Node::MicroLane::MoveFromNearbyLane' (top) and 'Captain::Node::MicroLane::UpdateVehiclePosition' (bottom). Two blue arrows originate from the right side of these boxes and point towards a single gray rectangular box on the right, which represents the target method: 'Captain::Util::VehicleQueue::Sort'.