

Captain::Node::MicroLane
::MoveFromNearbyLane

Captain::Node::MesoUnit
::MoveLaneChangeWaitingVehicles

Captain::Util::VehicleQueue
::CompareAndInsertByPosition

```
graph LR; A["Captain::Node::MicroLane::MoveFromNearbyLane"] --> C["Captain::Util::VehicleQueue::CompareAndInsertByPosition"]; B["Captain::Node::MesoUnit::MoveLaneChangeWaitingVehicles"] --> C;
```

The diagram illustrates two function calls from different classes pointing to a common utility function. The first call, from `Captain::Node::MicroLane::MoveFromNearbyLane`, is represented by a white box with a black border. The second call, from `Captain::Node::MesoUnit::MoveLaneChangeWaitingVehicles`, is represented by a white box with a black border. Both calls are represented by blue arrows pointing to a gray box with a black border, which represents the target utility function `Captain::Util::VehicleQueue::CompareAndInsertByPosition`.