

Captain::DMode::DriveModel
m_leaderVehicle
m_elapsedCycle
m_active
+ DriveModel()
+ ~DriveModel()
+ DriveModel()
+ DriveModel()
+ operator=()
+ operator=()
+ operator>()()
+ IsActivated()
+ Activate()
+ Deactivate()
and 7 more...
m_getSafetyDistance()
m_evaluateLCPosition()
m_getMinimumConstraint()
m_getMaximumConstraint()

Captain::DMode::IMultiple VehicleTrackable
m_trackingVehicleList
+ IMultipleVehicleTrackable()
+ ~IMultipleVehicleTrackable()
+ IMultipleVehicleTrackable()
+ IMultipleVehicleTrackable()
+ operator=()
+ operator=()
+ GetTargetLeaderList()
+ SetTargetLeaderList()
+ SetTargetLeader()
+ AddTrackingVehicle()
+ RemoveTrackingVehicle()
+ Clear()
+ NumTrackingVehicles()

Captain::DMode::CCF
+ CCF()
+ ~CCF()
+ operator>()()

