

Captain::Node::MicroLane  
::PopVehicle

```
graph LR; A["Captain::Node::MicroLane  
::PopVehicle"] --> B["Captain::Util::VehicleQueue  
::Dequeue"]; A --> C["Captain::Util::VehicleQueue  
::Size"]
```

The diagram illustrates a function call from the `PopVehicle` method of the `Captain::Node::MicroLane` class to two methods of the `Captain::Util::VehicleQueue` class: `Dequeue` and `Size`. The source function is highlighted in a grey box, while the target methods are in white boxes. Blue arrows indicate the direction of the calls.

Captain::Util::VehicleQueue  
::Dequeue

Captain::Util::VehicleQueue  
::Size