

| Captain::DMode::DriveModel |
|----------------------------|
| # m_leaderVehicle |
| # m_elapsedCycle |
| # m_active |
| + DriveModel() |
| + ~DriveModel() |
| + DriveModel() |
| + DriveModel() |
| + operator=() |
| + operator=() |
| + operator>()() |
| + IsActivated() |
| + Activate() |
| + Deactivate() |
| and 7 more... |
| # m_getSafetyDistance() |
| # m_evaluateLCPosition() |
| # m_getMinimumConstraint() |
| # m_getMaximumConstraint() |

| Captain::DMode::IAutomatically Deactivated |
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| + IAutomaticallyDeactivated() |
| + ~IAutomaticallyDeactivated() |
| + IAutomaticallyDeactivated() |
| + IAutomaticallyDeactivated() |
| + operator=() |
| + operator=() |
| # m_deactivateIfDone() |

| Captain::DMode::Approach Station |
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| |
| + ApproachStation() |
| + operator>()() |
| + SetTargetPosition() |

