JaeWon **Lee**

Robotics · Multi-Robot · SLAM

25, Galmaejungang-ro, Guri-si, Gyeonggi-do, 11902, Rep. of KOREA

☎ (+82) 10-9114-2756 | ✉ ashcircle@kw.ac.kr | ⌂ https://lee-jaewon.github.io/ | ⌨ Lee-JaeWon

"Passion is the genesis of genius."

Summary

This is JaeWon Lee, who wants to be a Multi-Robot System and Cooperative Autonomous Driving engineer. I am interested in Robotics, Navigation, SLAM, Path Planning, Multi-Robot. I think Multi-Robot, Robotics, and SLAM can help the development of the world a lot. I want to study a lot and approach the world.

Research Interests

Multi-Robot	SLAM, Path Planning, Collision Avoidance, Map Fusion
SLAM	Visual SLAM, Visual Odometry, Optimization

Education

KwangWoon University — *Seoul, S.Korea*

B.S. in School of Robotics — *Mar. 2020 - Feb. 2024(Expected)*

- Current GPA : 3.98/4.50, Current Major GPA : 4.16/4.50
- Club : BARAM Robotics (Robotics Academic Group) - [2022 Vice President], Mar.2020-Current

Work Experience

Robotics A.I. LAB. @KwangWoon Univ — *Seoul, S.Korea*

Undergraduate LAB Intern (Advisor : PROF. Junghyun Oh) — *Jan. 2022 - Present*

- Research on Visual SLAM and Multi-Robot SLAM
- Studying Visual SLAM and implementing Multi-Robot SLAM and Path Planning

Skills

Programming	C++/C, Python
DevOps	ROS1, Git
Framework	Pytorch, Unity
Languages	Korean, English

Extracurricular Activity

Technical Blog - leejaewon.github.io — *Github blog*

Writer — *Jul. 2021 - Present*

- Writing posts about paper review, development, study of Interests.
- Studying through writing and sharing.

Autonomous Driving Simulation with Reinforcement Learning — *BARAM Robotics Group*

Personal toy project — *Sep.2021 - Nov.2021*

- Autonomous-driving simulation through DQN Reinforcement algorithm in self-made simulator with unity.
- Reward management using DQN, CNN, and Laser Sensor.

Multi-Robot SLAM and Path Planning — *BARAM Robotics Group*

Personal toy project — *Apr. 2022 - Present*

- Implementation of ROS-based Multi-Robot SLAM.
- Studying Path-Planning and Map Merging Algorithm.