



Jaewon Lee

ROBOTICS · MULTI-ROBOT · SLAM

25, Galmaejungang-ro, Guri-si, Gyeonggi-do, 11902, Rep. of KOREA

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“Passion is the genesis of genius.”

Summary

This is Jaewon Lee, who wants to be a Robotics researcher and engineer. I am interested in Robotics, SLAM, Multi-Robot System. I think Robotics can help the development of the world a lot. I want to study a lot and approach the world.

Research Interests

Multi-Robot SLAM, Loop Closing, Pose Estimation

SLAM LiDAR-Inertial SLAM, Localization

Education

Yonsei University

INTEGRATED M.S./PH.D. IN ELECTRICAL AND ELECTRONIC ENGINEERING (ADVISOR: PROF. EUNTAI KIM)

Seoul, S.Korea

Mar. 2024(Expected) -

KwangWoon University

B.S. IN SCHOOL OF ROBOTICS

- GPA : 4.11/4.50, Major GPA : 4.28/4.50
- Club : BARAM Robotics (Robotics Academic Group) - [2022 Vice President], Mar.2020-Feb.2024

Seoul, S.Korea

Mar. 2020 - Feb. 2024

Work Experience

CILAB @Yonsei Univ

UNDERGRADUATE LAB INTERN (ADVISOR : PROF. EUNTAI KIM)

- Multi Robot System
- LiDAR Inertial SLAM

Seoul, S.Korea

Jul. 2023 - Present

ROBOMATION

R&D INTERN

- I developed an automation system for soccer games using multi-robot.
- I developed multi-robot coordination and pose system using Aruco Marker.

Seoul, S.Korea

Jun. 2022 - Aug. 2022

Robotics A.I. LAB. @KwangWoon Univ

UNDERGRADUATE LAB INTERN (ADVISOR : PROF. JUNGHYUN OH)

- I studied visual SLAM and visual odometry
- I studied Multi-Robot system and implemented Multi-Robot exploration

Seoul, S.Korea

Jan. 2022 - Jun. 2022

Honors & Awards

AWARDS

2023.12 **2023 Hanium ICT Mentoring Competition**, Silver Award

Ministry of Science
and ICT, IITP, FKii

2023.10 **ICCV 2023 SLAM Challenge**,
Fourth place in LiDAR-Inertial Track - Taeyoung Kim, Jaewon Lee, Beomsoo Kim, Euntai Kim

ICCV 2023

2023.06 **Undergraduate Paper Award**, Paper - Autonomous multi robot parking system

ICROS 2023

2022.10 **Dean's list**, for Academic Excellence

Kwangwoon Univ.

HONORS

2022.10 **Full Tuition Scholarship**, for the first place in last semester

Kwangwoon Univ.

Publication

DOMESTIC CONFERENCE

2023.06 **"Autonomous Multi Robot Parking System",**
Jaewon Lee, Hyosuk Joo, Chung-gil Ahn, Hyedo Kim, Junghyun Oh - **[Paper]**

ICROS 2023

Skills

Programming C++/C, Python, MATLAB
DevOps ROS/ROS2, Docker, Git
Framework PyTorch, Tensorflow, Keras, Unity

Extracurricular Activity

Technical Blog - lee-jaewon.github.io

Personal Tech Blog

WRITER

Jul. 2021 - Present

- I have been writing posts about the paper review, development, the study of Interests.
- To study through writing and sharing.
- The blog is available at [\[here\]](#).

Technical Team Blog - ropiens.tistory.com

Team Tech Blog

CO-WRITER

Jul. 2022 - Present

- I have been writing posts about the paper review, development, the study of Interests.
- To study through writing and sharing.
- The blog is available at [\[here\]](#).

Autonomous Multi Robot Parking System

Kwangwoon Univ.

CAPSTONE DESIGN

Jan.2023 - Jun.2023

- Implement a multi-robot system and implement various technologies necessary for mobile robots.
- The source code for the project is available at [\[my GitHub repository\]](#).

2022 Open Source Contribution Academy

Ministry of Science and ICT, NIPA

MENTEE

Jul. 2022 - Oct. 2022

- I contributed to translating PyTorch Hub English documents into Korean at the PyTorch Korean User's Group.

Multi Robot Collision Avoidance with Velocity Obstacle

BARAM Robotics

PERSONAL PROJECT

Sep.2022 - Nov.2022

- I implemented collision avoidance with Velocity Obstacle using multi-robot.
- The source code for the project is available at [\[my GitHub repository\]](#).

Autonomous Driving Simulation with Reinforcement Learning

BARAM Robotics

PERSONAL PROJECT

Sep.2021 - Nov.2021

- I implemented an Autonomous-driving system through DQN algorithm for the high-way situation.
- I implemented a simulator with Unity. And I managed the reward using Laser Sensor.
- The source code for the project is available at [\[my GitHub repository\]](#).

Frontier Based Multi-Robot Exploration

BARAM Robotics

PERSONAL PROJECT

Mar.2022 - Jun.2022

- I implemented ROS-based multi-robot frontier exploration.
- I implemented a multi-robot SLAM system using open sources.
- The source code for the project is available at [\[my GitHub repository\]](#).

House Interior Classifier and Automatic Recommendation

2022 Deep Learning Lecture

DEEP-LEARNING PROJECT

Mar.2022 - Jun.2022

- I implemented House Interior Classifier using Inception-Resnet-V2 in Keras.
- I implemented a system that can automatically search on the actual shopping site with the classified result.
- The source code for the project is available at [\[my GitHub repository\]](#).