## Lab 1 Report

In the header, we have many libraries included in order for the code to work. We have 3 global variables, one of which is a shared variable. As the threads get created, the shared variable will be the one getting accessed across the multiple threads. We also have a lock of a pthread mutex type and a barrier of a pthread barrier type, in which both are used in the SimpleThread method. In the SimpThread method, an integer value is being passed in which is the number of threads to be created in the main function. In our implementation of the method after the loop which was given to us, a mutex lock is created and the reference of the lock global variable is passed in to ensure that the other threads are not interrupting the shared variable for running our code with synchronization. After, we increment the shared variable into the variable val. The mutex lock is unlocked and the pthread\_barrier\_wait is created to pass in the global barrier variable in which it waits for the other threads to finish. If you run this code without the -DPTHREAD\_SYNC, the lock and the barrier will not be implemented and the shared variable will be interrupted in which the final value will not be the same.

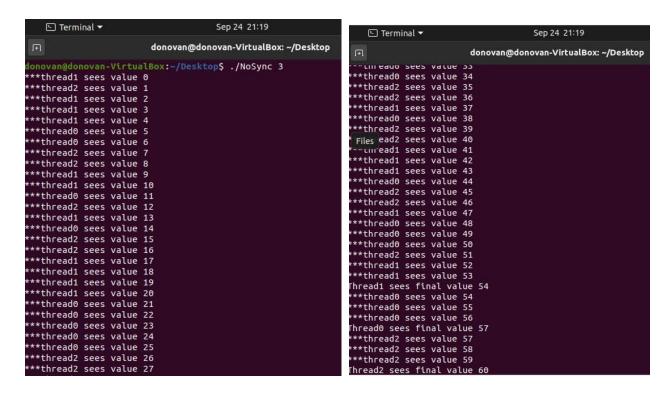
For our ThreadID function, we take in a void parameter because our pthread\_create method creates an entry point for threads to run in. We cast our parameter as a long so we can run it in our SimpleThread function.

We implemented our ThreadID this way because pthread\_create needed a void function to take in so that it can read an i value that was double casted as a void and a long.

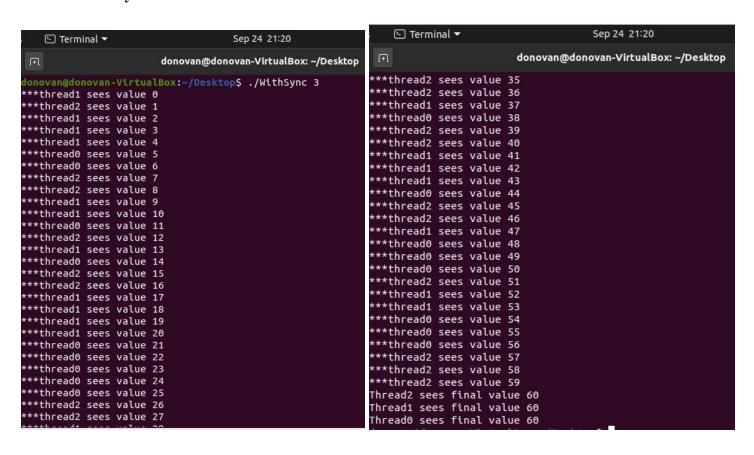
For the main function, it takes in a parameter and is checked with validations to see if there was only one parameter given and if the parameter is a positive number. After the parameter is checked we put it into a variable and initialize the first barrier to run the threads. We created 2 for loops, one for loop creates the threads and the other for loop stops the next thread's execution so the first thread can finish.

We implemented the main like this because we have to check if the parameter the user gives us is a good parameter or else the file won't run. Then we initialize a barrier so threads can be separated and let in one by one. With our pthread\_join, it makes our thread run one by one so nothing is mixed allowing the ending threads to be synced.

## Pthreads without synchronization



## Pthreads with synchronization



The difference between the pthread with no synchronization and pthread with synchronization is that when you don't enter in the -DPTHREAD\_SYNC to run the terminal, the program will not have synchronization as the lock/unlock and the pthread\_barrier\_wait method will not be implemented. The reason being is that these blocks of code are specific to a scope of synchronization, with #ifdef PTHREAD\_SYNC and #endif, meaning it will only run synchronized once you enter in the right command in the terminal. This is why the shared variable gets interrupted by other threads and the final value is not the same without synchronization.

## **Contributions**

We contributed the same amount of work because we were doing it at the same time over a communication platform, giving each other inputs on how to approach certain things in the lab.