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Q1

A\* expands fewer nodes than Dijkstra because the heuristic guides the search toward the goal. Dijkstra expands nodes evenly in all directions, while A\* focuses on promising paths. Because of fewer expansions, A\* usually runs faster than Dijkstra.

Q2

Multiplying the heuristic by 1.25 makes A\* more greedy (Weighted A\*). It expands fewer nodes and often runs faster. However, the heuristic is no longer admissible, so the solution may not be optimal.

Q3

A\*: No. The Octile heuristic is consistent, so once a node is expanded, its best path is already found.

Weighted A\*: Yes. The heuristic is not consistent, so a cheaper path to a node may be found later, causing reopening.

Q4

No. The search trees do not grow exponentially in practice. The grid limits the branching factor, and obstacles reduce possible expansions. A\* further reduces growth by using a heuristic to guide the search.