

Assignment 6

/*叶俊利 3130100672*/

Bilateral Filtering

First, according to the equation:

$$BF[I]_{\mathbf{p}} = \frac{1}{W_{\mathbf{p}}} \sum_{\mathbf{q} \in S} G_{\sigma_s}(\|\mathbf{p} - \mathbf{q}\|) G_{\sigma_r}(\|I_{\mathbf{p}} - I_{\mathbf{q}}\|) I_{\mathbf{q}}$$

We need to set the two parameters of Gaussian function.

According to the PPT:

Depends on the application. For instance:

- space parameter: proportional to image size
 - e.g., 2% of image diagonal
- intensity parameter: proportional to edge amplitude
 - e.g., mean or median of image gradients
- independent of resolution and exposure

I set the first parameter to be 2% of the diagonal:

```
double dSignal = 0.02*pow((nWidth*nWidth + nHeight*nHeight),0.5);
```

Then, set the second parameter to be mean of the image gradients:

```
double dSigmaR = 0, dSigmaG = 0, dSigmaB = 0;

for (int i = 0; i < nHeight-1; i++)
{
    for (int j = 0; j < nWidth-1; j++)
    {
        pixel = imgBackup.GetPixel(j, i);

        double r = GetRValue(pixel);
        double g = GetGValue(pixel);
        double b = GetBValue(pixel);

        pixel = imgBackup.GetPixel(j + 1, i);

        double r1 = GetRValue(pixel);
```

```

        double g1 = GetGValue(pixel);
        double b1 = GetBValue(pixel);
        pixel = imgBackup.GetPixel(j, i + 1);
        double r2 = GetRValue(pixel);
        double g2 = GetGValue(pixel);
        double b2 = GetBValue(pixel);
        dSigmaR += abs(r - r1) + abs(r - r2);
        dSigmaG += abs(g - g1) + abs(g - g2);
        dSigmaB += abs(b - b1) + abs(b - b2);
    }
}

dSigmaR /= (nHeight - 1)*(nWidth - 1);
dSigmaG /= (nHeight - 1)*(nWidth - 1);
dSigmaB /= (nHeight - 1)*(nWidth - 1);

```

Also, we need to set the size of the windows. In normal distribution, area $[-3\sigma, 3\sigma]$ cover more than 99% of the possibility. Therefore, I set the radius of the windows to be 3σ . I.e. The size of windows is $(6\sigma + 1) * (6\sigma + 1)$. The code is shown:

```
int nWindows = (int) (1 + 2 * ceil(3 * dSigma1));
```

Now, in order to speed up the program, we can pre-calculate the Gaussian matrix.

```

D      ouble* dDistance = new double[nWindows*nWindows]; //计算距离中间点的几何距离

for (int i = 0; i < nWindows*nWindows; i++)
{
    int nNumX = i / nWindows;
    int nNumY = i % nWindows;

    dDistance[i] = ((nWindows - 1) / 2 - nNumX)*((nWindows - 1) / 2 - nNumX) +
        ((nWindows - 1) / 2 - nNumY)*((nWindows - 1) / 2 - nNumY);

    dDistance[i] = exp(-0.5*dDistance[i] / dSigma1 / dSigma1); //距离参数
}

```



OK, we can begin to process the image now:

```
for (int i = 0; i < nHeight; i++)
```

```

{
    for (int j = 0; j < nWidth; j++)
    {
        pixel = imgBackup.GetPixel(j, i);
        double rP = GetRValue(pixel);
        double gP = GetGValue(pixel);
        double bP = GetBValue(pixel);
        double dDataR = 0.0;
        double dTotalR = 0.0;           //用于进行归一化
        double dDataG = 0.0;
        double dTotalG = 0.0;           //用于进行归一化
        double dDataB = 0.0;
        double dTotalB = 0.0;           //用于进行归一化
        for (int m = 0; m < nWindows*nWindows; m++)
        {
            int nNumX = m / nWindows;           //行索引
            int nNumY = m%nWindows;             //列索引
            int nX = i - (nWindows - 1) / 2 + nNumX;
            int nY = j - (nWindows - 1) / 2 + nNumY;
            if ((nY >= 0) && (nY < nWidth) && (nX >= 0) && (nX < nHeight))
            {
                pixel = imgBackup.GetPixel(nY, nX);
                double r = GetRValue(pixel);
                double g = GetGValue(pixel);
                double b = GetBValue(pixel);
                double dRDiff = fabs(rP - r);
                double dGDiff = fabs(gP - g);
                double dBDiff = fabs(bP - b);
                dRDiff = exp(-0.5*dRDiff * dRDiff / dSigmaR / dSigmaR);
                //色参数
            }
        }
    }
}

```

```

        dGDiff = exp(-0.5*dGDiff * dGDiff / dSigmaG / dSigmaG);
        //色参数
        dBDiff = exp(-0.5*dBDiff * dBDiff / dSigmaB / dSigmaB);
        //色参数
        if (m != 4)
        {
            dDataR += r * dRDiff * dDistance[m];
            //距离和色参数综合
            dTotalR += dRDiff * dDistance[m];
            //加权系数求和，进行归一化
            dDataG += g * dGDiff * dDistance[m];
            dTotalG += dGDiff * dDistance[m];
            dDataB += b * dBDiff * dDistance[m];
            dTotalB += dBDiff * dDistance[m];
        }
    }

    dDataR /= dTotalR;
    dDataG /= dTotalG;
    dDataB /= dTotalB;

    imgOriginal.SetPixelRGB(j, i, (byte)dDataR, (byte)dDataG, (byte)dDataB);
}

Invalidate();
UpdateWindow();
}

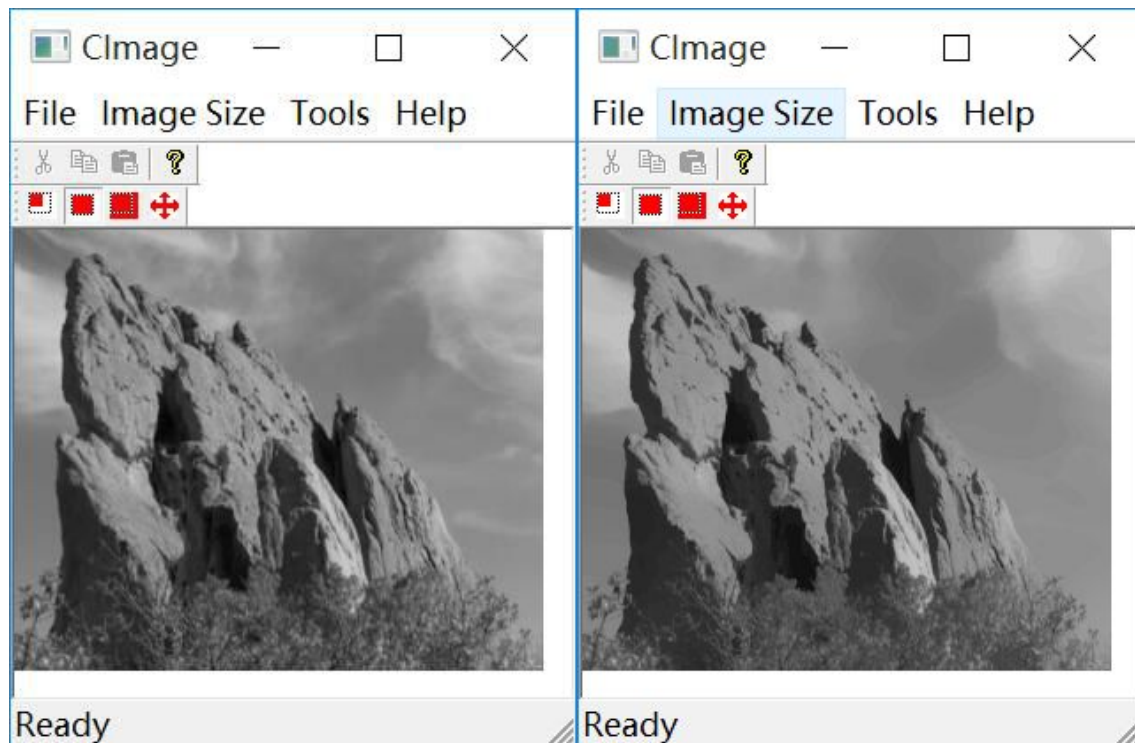
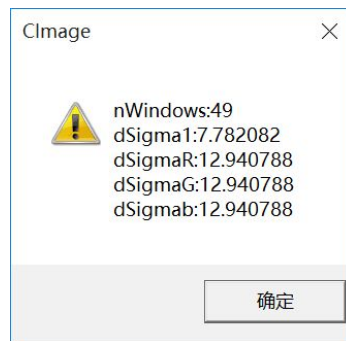
```

Results

First I test a image of $299 * 249$.



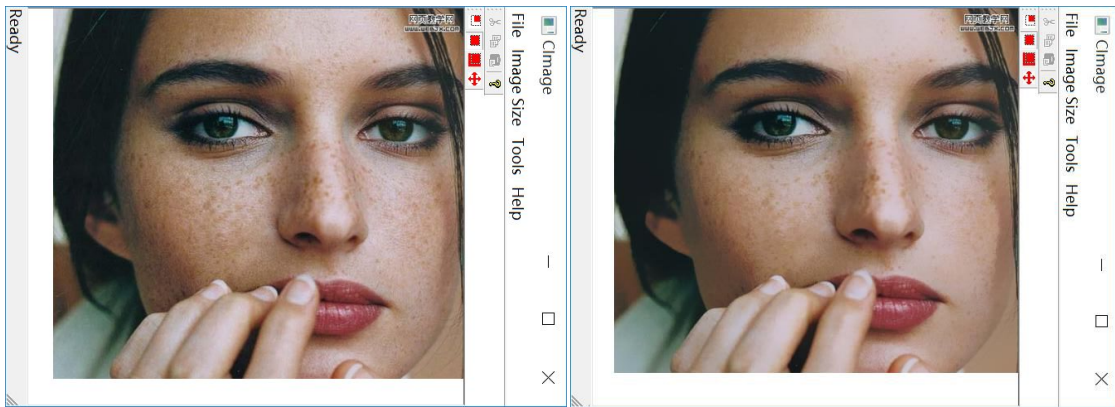
The generated parameters are:



Original

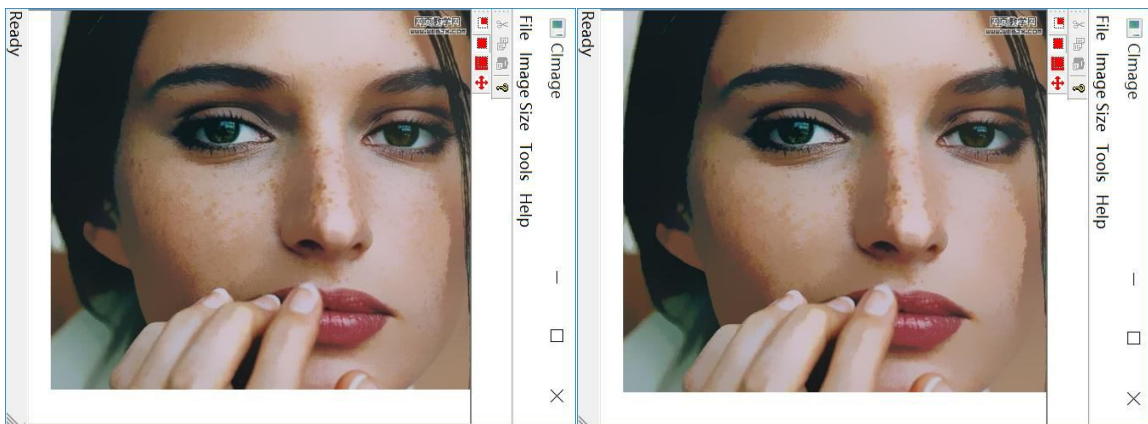
Filtered

Here is another test:



Original

Filtered Once



Filtered Twice

Filtered Three Times