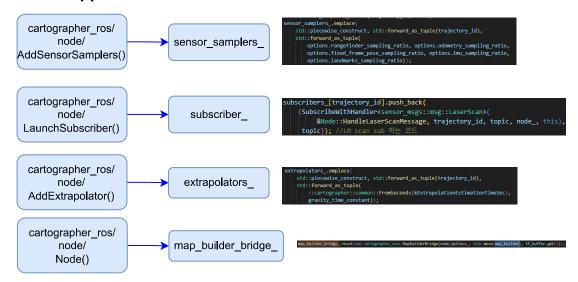
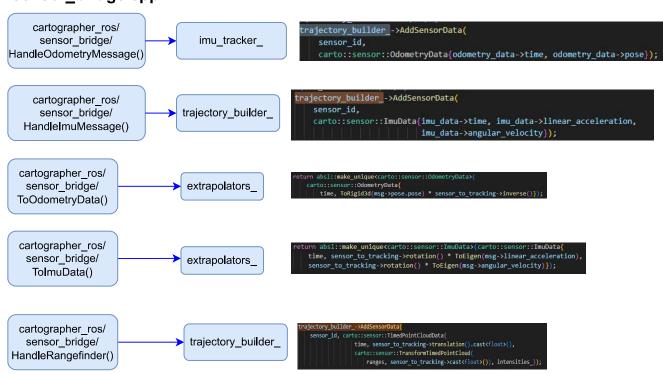


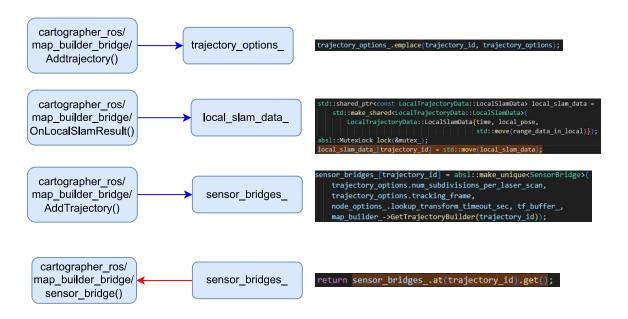
### <node.cpp>



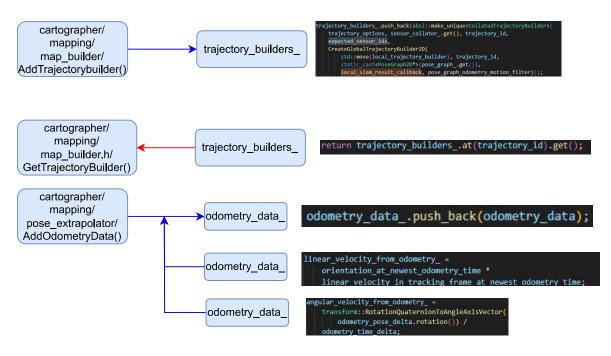
#### <sensor\_bridge.cpp>



#### <map\_builder\_bridge.cpp>



## <map\_builder.cc, .h>



# <pose\_extrapolator.cc>

