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## 如何在caffe中增加layer以及caffe中triple loss layer的实现

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关于triplet loss的原理，目标函数和梯度推导在上一篇博客中已经讲过了，具体见：triplet loss原理以及梯度推导，这篇博文主要是讲caffe下实现triplet loss，编程菜鸟，如果有写的不够优化的地方，欢迎指出。

## 1.如何在caffe中增加新的layer

新版的caffe中增加新的layer，变得轻松多了，概括说来，分四步：

- 1) 在./src/caffe/proto/caffe.proto 中增加 对应layer的paramter message；
  - 2) 在./include/caffe/\*\*\*layers.hpp中增加该layer的类的声明，\*\*\*表示有common\_layers.hpp, data\_layers.hpp, neuron\_layers.hpp, vision\_layers.hpp 和loss\_layers.hpp等；
  - 3) 在./src/caffe/layers/目录下新建.cpp和.cu文件，进行类实现。
  - 4) 在./src/caffe/gtest/中增加layer的测试代码，对所写的layer前传和反传进行测试，测试还包括速度。
- 最后一步很多人省了，或者没意识到，但是为保证代码正确，建议还是严格进行测试，磨刀不误砍柴功。

## 2.caffe中实现triplet loss layer

### 1.caffe.proto中增加triplet loss layer的定义

首先在message LayerParameter中追加 optional TripleLossParameter triple\_loss\_param = 138; 其中138是我目前LayerParameter message中现有元素的个数，具体是多少，可以看LayerParameter message上面注释中的：

```
//LayerParameter next available layer-specific ID: 134 (last added: reshape_param)
```

然后增加Message：

```
message TripletLossParameter {  
    // margin for dissimilar pair  
    optional float margin = 1 [default = 1.0];  
}
```

其中 margin就是定义triplet loss原理以及梯度推导所讲的alpha。

### 2.在./include/caffe/loss\_layers.hpp中增加triplet loss layer的类的声明

具体解释见注释，主要的是定义了一些变量，用来在前传中存储中间计算结果，以便在反传的时候避免重复计算。

```

/**
 * @brief Computes the triplet loss
 */
template <typename Dtype>
class TripletLossLayer : public LossLayer<Dtype> {
public:
    explicit TripletLossLayer(const LayerParameter& param)
        : LossLayer<Dtype>(param){}
    virtual void LayerSetUp(const vector<Blob<Dtype>*>& bottom,
        const vector<Blob<Dtype>*>& top);

    virtual inline int ExactNumBottomBlobs() const { return 4; }
    virtual inline const char* type() const { return "TripletLoss"; }
    /**
     * Unlike most loss layers, in the TripletLossLayer we can backpropagate
     * to the first three inputs.
     */
    virtual inline bool AllowForceBackward(const int bottom_index) const {
        return bottom_index != 3;
    }

protected:
    virtual void Forward_cpu(const vector<Blob<Dtype>*>& bottom,
        const vector<Blob<Dtype>*>& top);
    virtual void Forward_gpu(const vector<Blob<Dtype>*>& bottom,
        const vector<Blob<Dtype>*>& top);

    virtual void Backward_cpu(const vector<Blob<Dtype>*>& top,
        const vector<bool>& propagate_down, const vector<Blob<Dtype>*>& bottom);
    virtual void Backward_gpu(const vector<Blob<Dtype>*>& top,
        const vector<bool>& propagate_down, const vector<Blob<Dtype>*>& bottom);

    Blob<Dtype> diff_ap_; // cached for backward pass
    Blob<Dtype> diff_an_; // cached for backward pass
    Blob<Dtype> diff_pn_; // cached for backward pass

    Blob<Dtype> diff_sq_ap_; // cached for backward pass
    Blob<Dtype> diff_sq_an_; // tmp storage for gpu forward pass

    Blob<Dtype> dist_sq_ap_; // cached for backward pass
    Blob<Dtype> dist_sq_an_; // cached for backward pass

    Blob<Dtype> summer_vec_; // tmp storage for gpu forward pass
    Blob<Dtype> dist_binary_; // tmp storage for gpu forward pass
};

```

### 3. 在./src/caffe/layers/目录下新建triplet\_loss\_layer.cpp,实现类

主要实现三个功能：

LayerSetUp：主要是做一些CHECK工作，然后根据bottom和top对类中的数据成员初始化。

Forward\_cpu：前传，计算loss

Backward\_cpu：反传，计算梯度。

```
/*
 * triple_loss_layer.cpp
 *
 * Created on: Jun 2, 2015
 * Author: tangwei
 */

#include <algorithm>
#include <vector>

#include "caffe/layer.hpp"
#include "caffe/loss_layers.hpp"
#include "caffe/util/io.hpp"
#include "caffe/util/math_functions.hpp"

namespace caffe {

template <typename Dtype>
void TripletLossLayer<Dtype>::LayerSetUp(
    const vector<Blob<Dtype>*> & bottom, const vector<Blob<Dtype>*> & top) {
    LossLayer<Dtype>::LayerSetUp(bottom, top);
    CHECK_EQ(bottom[0]->num(), bottom[1]->num());
    CHECK_EQ(bottom[1]->num(), bottom[2]->num());
    CHECK_EQ(bottom[0]->channels(), bottom[1]->channels());
    CHECK_EQ(bottom[1]->channels(), bottom[2]->channels());
    CHECK_EQ(bottom[0]->height(), 1);
    CHECK_EQ(bottom[0]->width(), 1);
    CHECK_EQ(bottom[1]->height(), 1);
    CHECK_EQ(bottom[1]->width(), 1);
    CHECK_EQ(bottom[2]->height(), 1);
    CHECK_EQ(bottom[2]->width(), 1);

    CHECK_EQ(bottom[3]->channels(),1);
    CHECK_EQ(bottom[3]->height(), 1);
    CHECK_EQ(bottom[3]->width(), 1);

    diff_ap_.Reshape(bottom[0]->num(), bottom[0]->channels(), 1, 1);
    diff_an_.Reshape(bottom[0]->num(), bottom[0]->channels(), 1, 1);
    diff_pn_.Reshape(bottom[0]->num(), bottom[0]->channels(), 1, 1);

    diff_sq_ap_.Reshape(bottom[0]->num(), bottom[0]->channels(), 1, 1);
    diff_sq_an_.Reshape(bottom[0]->num(), bottom[0]->channels(), 1, 1);
    dist_sq_ap_.Reshape(bottom[0]->num(), 1, 1, 1);
    dist_sq_an_.Reshape(bottom[0]->num(), 1, 1, 1);
}
```

```

// vector of ones used to sum along channels
summer_vec_.Reshape(bottom[0]->channels(), 1, 1, 1);
for (int i = 0; i < bottom[0]->channels(); ++i)
    summer_vec_.mutable_cpu_data()[i] = Dtype(1);
dist_binary_.Reshape(bottom[0]->num(), 1, 1, 1);
for (int i = 0; i < bottom[0]->num(); ++i)
    dist_binary_.mutable_cpu_data()[i] = Dtype(1);
}

template <typename Dtype>
void TripletLossLayer<Dtype>::Forward_cpu(
    const vector<Blob<Dtype>*>& bottom,
    const vector<Blob<Dtype>*>& top) {
    int count = bottom[0]->count();
    const Dtype* sampleW = bottom[3]->cpu_data();
    caffe_sub(
        count,
        bottom[0]->cpu_data(), // a
        bottom[1]->cpu_data(), // p
        diff_ap_.mutable_cpu_data()); // a_i-p_i
    caffe_sub(
        count,
        bottom[0]->cpu_data(), // a
        bottom[2]->cpu_data(), // n
        diff_an_.mutable_cpu_data()); // a_i-n_i
    caffe_sub(
        count,
        bottom[1]->cpu_data(), // p
        bottom[2]->cpu_data(), // n
        diff_pn_.mutable_cpu_data()); // p_i-n_i
    const int channels = bottom[0]->channels();
    Dtype margin = this->layer_param_.triple_loss_param().margin();

    Dtype loss(0.0);
    for (int i = 0; i < bottom[0]->num(); ++i) {
        dist_sq_ap_.mutable_cpu_data()[i] = caffe_cpu_dot(channels,
            diff_ap_.cpu_data() + (i*channels), diff_ap_.cpu_data() + (i*channels));
        dist_sq_an_.mutable_cpu_data()[i] = caffe_cpu_dot(channels,
            diff_an_.cpu_data() + (i*channels), diff_an_.cpu_data() + (i*channels));
        Dtype mdist = sampleW[i]*std::max(margin + dist_sq_ap_.cpu_data()[i] - dist_sq_an_.cpu_data()[i],
Dtype(0.0));
        loss += mdist;
    }
    if(mdist==Dtype(0)){
        //dist_binary_.mutable_cpu_data()[i] = Dtype(0);
        //prepare for backward pass
        caffe_set(channels, Dtype(0), diff_ap_.mutable_cpu_data() + (i*channels));
        caffe_set(channels, Dtype(0), diff_an_.mutable_cpu_data() + (i*channels));
        caffe_set(channels, Dtype(0), diff_pn_.mutable_cpu_data() + (i*channels));
    }
}

```

```

    }
}

loss = loss / static_cast<Dtype>(bottom[0]->num()) / Dtype(2);
top[0]->mutable_cpu_data()[0] = loss;
}

```

```

template <typename Dtype>
void TripletLossLayer<Dtype>::Backward_cpu(const vector<Blob<Dtype>*>& top,
      const vector<bool>& propagate_down, const vector<Blob<Dtype>*>& bottom) {
    //Dtype margin = this->layer_param_.contrastive_loss_param().margin();
    const Dtype* sampleW = bottom[3]->cpu_data();
    for (int i = 0; i < 3; ++i) {
        if (propagate_down[i]) {
            const Dtype sign = (i < 2) ? -1 : 1;
            const Dtype alpha = sign * top[0]->cpu_diff()[0] /
                static_cast<Dtype>(bottom[i]->num());
            int num = bottom[i]->num();
            int channels = bottom[i]->channels();
            for (int j = 0; j < num; ++j) {
                Dtype* bout = bottom[i]->mutable_cpu_diff();
                if (i==0) { // a
                    //if(dist_binary_cpu_data()[j]>Dtype(0)){
                        caffe_cpu_axpby(
                            channels,
                            alpha*sampleW[j],
                            diff_pn_cpu_data() + (j*channels),
                            Dtype(0.0),
                            bout + (j*channels));
                    //}else{
                    //  caffe_set(channels, Dtype(0), bout + (j*channels));
                    //}
                } else if (i==1) { // p
                    //if(dist_binary_cpu_data()[j]>Dtype(0)){
                        caffe_cpu_axpby(
                            channels,
                            alpha*sampleW[j],
                            diff_ap_cpu_data() + (j*channels),
                            Dtype(0.0),
                            bout + (j*channels));
                    //}else{
                    //  caffe_set(channels, Dtype(0), bout + (j*channels));
                    //}
                } else if (i==2) { // n
                    //if(dist_binary_cpu_data()[j]>Dtype(0)){
                        caffe_cpu_axpby(
                            channels,
                            alpha*sampleW[j],
                            diff_an_cpu_data() + (j*channels),

```

```

        Dtype(0.0),
        bout + (j*channels));

    //}else{
    //  caffe_set(channels, Dtype(0), bout + (j*channels));
    //}

    }

    } // for num
  } //if propagate_down[i]
} //for i
}

#ifdef CPU_ONLY
STUB_GPU(TripletLossLayer);
#endif

INSTANTIATE_CLASS(TripletLossLayer);
REGISTER_LAYER_CLASS(TripletLoss);

} // namespace caffe

```

#### 4.在./src/caffe/layers/目录下新建triplet\_loss\_layer.cu,实现GPU下的前传和反传

在GPU下实现前传和反传

```

/*
 * triplet_loss_layer.cu
 *
 * Created on: Jun 2, 2015
 * Author: tangwei
 */

#include <algorithm>
#include <vector>

#include "caffe/layer.hpp"
#include "caffe/util/io.hpp"
#include "caffe/util/math_functions.hpp"
#include "caffe/vision_layers.hpp"

namespace caffe {

template <typename Dtype>
void TripletLossLayer<Dtype>::Forward_gpu(
    const vector<Blob<Dtype>*> & bottom, const vector<Blob<Dtype>*> & top) {
    const int count = bottom[0]->count();
    caffe_gpu_sub(
        count,
        bottom[0]->gpu_data(), // a

```

```

    bottom[1]->gpu_data(), // p
    diff_ap_.mutable_gpu_data()); // a_i-p_i
caffe_gpu_sub(
    count,
    bottom[0]->gpu_data(), // a
    bottom[2]->gpu_data(), // n
    diff_an_.mutable_gpu_data()); // a_i-n_i
caffe_gpu_sub(
    count,
    bottom[1]->gpu_data(), // p
    bottom[2]->gpu_data(), // n
    diff_pn_.mutable_gpu_data()); // p_i-n_i

caffe_gpu_powx(
    count,
    diff_ap_.mutable_gpu_data(), // a_i-p_i
    Dtype(2),
    diff_sq_ap_.mutable_gpu_data()); // (a_i-p_i)^2
caffe_gpu_gemv(
    CblasNoTrans,
    bottom[0]->num(),
    bottom[0]->channels(),
    Dtype(1.0), //alpha
    diff_sq_ap_.gpu_data(), // (a_i-p_i)^2 // A
    summer_vec_.gpu_data(), // x
    Dtype(0.0), //belta
    dist_sq_ap_.mutable_gpu_data()); // \Sum (a_i-p_i)^2 //y

caffe_gpu_powx(
    count,
    diff_an_.mutable_gpu_data(), // a_i-n_i
    Dtype(2),
    diff_sq_an_.mutable_gpu_data()); // (a_i-n_i)^2
caffe_gpu_gemv(
    CblasNoTrans,
    bottom[0]->num(),
    bottom[0]->channels(),
    Dtype(1.0), //alpha
    diff_sq_an_.gpu_data(), // (a_i-n_i)^2 // A
    summer_vec_.gpu_data(), // x
    Dtype(0.0), //belta
    dist_sq_an_.mutable_gpu_data()); // \Sum (a_i-n_i)^2 //y

Dtype margin = this->layer_param_.triple_loss_param().margin();
Dtype loss(0.0);
const Dtype* sampleW = bottom[3]->cpu_data();
for (int i = 0; i < bottom[0]->num(); ++i) {
    loss += sampleW[i]*std::max(margin + dist_sq_ap_.cpu_data()[i] - dist_sq_an_.cpu_data()[i], Dtype(0.

```

```

0));
}

loss = loss / static_cast<Dtype>(bottom[0]->num()) / Dtype(2);
top[0]->mutable_cpu_data()[0] = loss;
}

template <typename Dtype>
__global__ void CLLBackward(const int count, const int channels,
    const Dtype margin, const Dtype alpha, const Dtype* sampleW,
    const Dtype* diff, const Dtype* dist_sq_ap_, const Dtype* dist_sq_an_,
    Dtype *bottom_diff) {
    CUDA_KERNEL_LOOP(i, count) {
        int n = i / channels; // the num index, to access dist_sq_ap_ and dist_sq_an_
        Dtype mdist(0.0);
        mdist = margin + dist_sq_ap_[n] - dist_sq_an_[n];
        if (mdist > 0.0) {
            bottom_diff[i] = alpha*sampleW[n]*diff[i];
        } else {
            bottom_diff[i] = 0;
        }
    }
}

template <typename Dtype>
void TripletLossLayer<Dtype>::Backward_gpu(const vector<Blob<Dtype>*> & top,
    const vector<bool> & propagate_down, const vector<Blob<Dtype>*> & bottom) {
    Dtype margin = this->layer_param_.triple_loss_param().margin();
    const int count = bottom[0]->count();
    const int channels = bottom[0]->channels();

    for (int i = 0; i < 3; ++i) {
        if (propagate_down[i]) {
            const Dtype sign = (i < 2) ? -1 : 1;
            const Dtype alpha = sign * top[0]->cpu_diff()[0] /
                static_cast<Dtype>(bottom[0]->num());
            if(i==0){
                // NOLINT_NEXT_LINE(whitespace/operators)
                CLLBackward<Dtype><<<CAFFE_GET_BLOCKS(count), CAFFE_CUDA_NUM_THREADS>>>
(
                    count, channels, margin, alpha,
                    bottom[3]->gpu_data(),
                    diff_pn_gpu_data(), // the cached eltwise difference between p and n
                    dist_sq_ap_gpu_data(), // the cached square distance between a and p
                    dist_sq_an_gpu_data(), // the cached square distance between a and n
                    bottom[i]->mutable_gpu_diff());
                CUDA_POST_KERNEL_CHECK;
            }else if(i==1){
                // NOLINT_NEXT_LINE(whitespace/operators)

```



```

CLLBackward<Dtype><<<CAFFE_GET_BLOCKS(count), CAFFE_CUDA_NUM_THREADS>>>
(
    count, channels, margin, alpha,
    bottom[3]->gpu_data(),
    diff_ap_gpu_data(), // the cached eltwise difference between a and p
    dist_sq_ap_gpu_data(), // the cached square distance between a and p
    dist_sq_an_gpu_data(), // the cached square distance between a and n
    bottom[i]->mutable_gpu_diff());
    CUDA_POST_KERNEL_CHECK;
} else if(i==2){
    // NOLINT_NEXT_LINE(whitespace/operators)
    CLLBackward<Dtype><<<CAFFE_GET_BLOCKS(count), CAFFE_CUDA_NUM_THREADS>>>
(
    count, channels, margin, alpha,
    bottom[3]->gpu_data(),
    diff_an_gpu_data(), // the cached eltwise difference between a and n
    dist_sq_ap_gpu_data(), // the cached square distance between a and p
    dist_sq_an_gpu_data(), // the cached square distance between a and n
    bottom[i]->mutable_gpu_diff());
    CUDA_POST_KERNEL_CHECK;

}
}
}
}

INSTANTIATE_LAYER_GPU_FUNCS(TripletLossLayer);

} // namespace caffe

```

## 5. 在./src/caffe/test/目录下增加test\_triplet\_loss\_layer.cpp

```

/*
 * test_triplet_loss_layer.cpp
 *
 * Created on: Jun 3, 2015
 * Author: tangwei
 */

#include <algorithm>
#include <cmath>
#include <cstdlib>
#include <cstring>
#include <vector>

#include "gtest/gtest.h"

#include "caffe/blob.hpp"
#include "caffe/common.hpp"

```

```

#include "caffe/filler.hpp"
#include "caffe/vision_layers.hpp"

#include "caffe/test/test_caffe_main.hpp"
#include "caffe/test/test_gradient_check_util.hpp"

namespace caffe {

template <typename TypeParam>
class TripletLossLayerTest : public MultiDeviceTest<TypeParam> {
    typedef typename TypeParam::Dtype Dtype;

protected:
    TripletLossLayerTest()
        : blob_bottom_data_i_(new Blob<Dtype>(512, 2, 1, 1)),
          blob_bottom_data_j_(new Blob<Dtype>(512, 2, 1, 1)),
          blob_bottom_data_k_(new Blob<Dtype>(512, 2, 1, 1)),
          blob_bottom_y_(new Blob<Dtype>(512, 1, 1, 1)),
          blob_top_loss_(new Blob<Dtype>()) {
        // fill the values
        FillerParameter filler_param;
        filler_param.set_min(-1.0);
        filler_param.set_max(1.0); // distances ~ 1.0 to test both sides of margin
        UniformFiller<Dtype> filler(filler_param);
        filler.Fill(this->blob_bottom_data_i_);
        blob_bottom_vec_.push_back(blob_bottom_data_i_);
        filler.Fill(this->blob_bottom_data_j_);
        blob_bottom_vec_.push_back(blob_bottom_data_j_);
        filler.Fill(this->blob_bottom_data_k_);
        blob_bottom_vec_.push_back(blob_bottom_data_k_);
        for (int i = 0; i < blob_bottom_y->count(); ++i) {
            blob_bottom_y->mutable_cpu_data()[i] = caffe_rng_rand() % 2; // 0 or 1
        }
        blob_bottom_vec_.push_back(blob_bottom_y_);
        blob_top_vec_.push_back(blob_top_loss_);
    }

    virtual ~TripletLossLayerTest() {
        delete blob_bottom_data_i_;
        delete blob_bottom_data_j_;
        delete blob_bottom_data_k_;
        delete blob_top_loss_;
    }

    Blob<Dtype>* const blob_bottom_data_i_;
    Blob<Dtype>* const blob_bottom_data_j_;
    Blob<Dtype>* const blob_bottom_data_k_;
    Blob<Dtype>* const blob_bottom_y_;
    Blob<Dtype>* const blob_top_loss_;

```

```
vector<Blob<Dtype>*> blob_bottom_vec_;
vector<Blob<Dtype>*> blob_top_vec_;
};
```

```
TYPED_TEST_CASE(TripletLossLayerTest, TestDtypesAndDevices);
```

```
TYPED_TEST(TripletLossLayerTest, TestForward) {
    typedef typename TypeParam::Dtype Dtype;
    LayerParameter layer_param;
    TripletLossLayer<Dtype> layer(layer_param);
    layer.SetUp(this->blob_bottom_vec_, this->blob_top_vec_);
    layer.Forward(this->blob_bottom_vec_, this->blob_top_vec_);
    // manually compute to compare
    const Dtype margin = layer_param.triple_loss_param().margin();
    const int num = this->blob_bottom_data_i->num();
    const int channels = this->blob_bottom_data_i->channels();
    Dtype loss(0);
    for (int i = 0; i < num; ++i) {
        Dtype dist_sq_ij(0);
        Dtype dist_sq_ik(0);
        for (int j = 0; j < channels; ++j) {
            Dtype diff_ij = this->blob_bottom_data_i->cpu_data()[i*channels+j] -
                this->blob_bottom_data_j->cpu_data()[i*channels+j];
            dist_sq_ij += diff_ij*diff_ij;
            Dtype diff_ik = this->blob_bottom_data_i->cpu_data()[i*channels+j] -
                this->blob_bottom_data_k->cpu_data()[i*channels+j];
            dist_sq_ik += diff_ik*diff_ik;
        }
        loss += std::max(Dtype(0.0), margin+dist_sq_ij-dist_sq_ik);
    }
    loss /= static_cast<Dtype>(num) * Dtype(2);
    EXPECT_NEAR(this->blob_top_loss->cpu_data()[0], loss, 1e-6);
}
```

```
TYPED_TEST(TripletLossLayerTest, TestGradient) {
    typedef typename TypeParam::Dtype Dtype;
    LayerParameter layer_param;
    TripletLossLayer<Dtype> layer(layer_param);
    layer.SetUp(this->blob_bottom_vec_, this->blob_top_vec_);
    GradientChecker<Dtype> checker(1e-2, 1e-2, 1701);
    // check the gradient for the first two bottom layers
    checker.CheckGradientExhaustive(&layer, this->blob_bottom_vec_,
        this->blob_top_vec_, 0);
    checker.CheckGradientExhaustive(&layer, this->blob_bottom_vec_,
        this->blob_top_vec_, 1);
}
```

```
} // namespace caffe
```

### 3.编译测试

重新 make all 如果出错，检查代码语法错误。

make test

make runtest 如果成功，全是绿色的OK 否则会给出红色提示，就得看看是不是实现逻辑上出错了。

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