

# Supervised Regression

## Design matrix

Let  $\underline{x}_1, \dots, \underline{x}_p$  be our  $p$  feature vectors, then we call the matrix

$$X = \begin{pmatrix} 1 & 1 & 1 \\ 1 & \underline{x}_1 & \dots & \underline{x}_p \end{pmatrix} \in \mathbb{R}^{n \times (p+1)}$$

the **design matrix**.

Furthermore, we define  $\underline{x} = (1, x_1, \dots, x_p)^T \in \mathbb{R}^{p+1}$  and  $\underline{\theta} = (\theta_0, \theta_1, \dots, \theta_p) \in \mathbb{R}^{p+1}$

one row as colvector ( $X$  has  $n$  of those rows), simil.  $\bar{X} = (1, \underline{x})$  for clarity to distinguish intercept / feature vector.

## Setup

We predict  $y \in \mathbb{R}$  as linear combinations of features

$$\hat{y} = f(\underline{x}) = \underline{\theta}^T \underline{x} = \theta_0 + \theta_1 x_1 + \dots + \theta_p x_p$$

This results in the hypothesis space  $H = \{f(\underline{x}) = \underline{\theta}^T \underline{x} \mid \underline{\theta} \in \mathbb{R}^{p+1}\}$

A typical choice for the Loss-function is L2-Loss.

This results in  $R_{\text{emp}}(\underline{\theta}) = \sum_{i=1}^n (y^{(i)} - \underline{\theta}^T \underline{x}^{(i)})^2 = \text{SSE} : \sum_{i=1}^n (\hat{y}^{(i)} - y^{(i)})^2$  MSE:  $\frac{1}{n} \cdot \text{SSE}$ .

## Optimization

We want to find  $\hat{\underline{\theta}} = \arg \min_{\underline{\theta} \in \mathbb{R}^{p+1}} \sum_{i=1}^n (y^{(i)} - \underline{\theta}^T \underline{x}^{(i)})^2 = \arg \min_{\underline{\theta} \in \mathbb{R}^{p+1}} \|y - X\underline{\theta}\|_2^2$

This results in the ordinary-least-squares estimator:

$$\hat{\underline{\theta}} = (X^T X)^{-1} X^T y \quad (\text{MLE}) \quad \text{Gradient: } \nabla_{\underline{\theta}} R_{\text{emp}}(\underline{\theta}) = \frac{\partial}{\partial \underline{\theta}} \|y - X\underline{\theta}\|_2^2 = (y - X\underline{\theta})^T (y - X\underline{\theta}) \\ = -2\underline{\theta}^T X + 2X^T X = -2(y - X\underline{\theta})^T X$$

## ANALYTICAL OPTIMIZATION – PROOF

$$R_{\text{emp}}(\underline{\theta}) = \sum_{i=1}^n (y^{(i)} - \underline{\theta}^T \underline{x}^{(i)})^2 = \underbrace{\|y - X\underline{\theta}\|_2^2}_{=: e^2}, \quad \underline{\theta} \in \mathbb{R}^p \text{ with } p := p+1$$

using L2 loss

$$\begin{aligned} 0 &= \frac{\partial R_{\text{emp}}(\underline{\theta})}{\partial \underline{\theta}} \quad (\text{sum notation}) & 0 &= \frac{\partial R_{\text{emp}}(\underline{\theta})}{\partial \underline{\theta}} \quad (\text{matrix notation}) \\ 0 &= \frac{\partial}{\partial \underline{\theta}} \sum_{i=1}^n e_i^2 & 0 &= \frac{\partial}{\partial \underline{\theta}} \|e\|_2^2 \\ 0 &= \sum_{i=1}^n \frac{\partial e_i^2}{\partial \underline{\theta}} & 0 &= \frac{\partial \underline{\theta}^T e}{\partial \underline{\theta}} \quad (\text{chain rule}) \\ 0 &= \sum_{i=1}^n 2e_i(-1)(\underline{x}^{(i)})^T & 0 &= \frac{\partial e_i}{\partial \underline{\theta}} \cdot \frac{\partial e_i}{\partial \underline{\theta}} \\ 0 &= \sum_{i=1}^n (y^{(i)} - \underline{\theta}^T \underline{x}^{(i)}) (\underline{x}^{(i)})^T & 0 &= 2e^T \cdot (-1) \cdot \underline{X} \\ 0 &= \sum_{i=1}^n \underline{\theta}^T \underline{x}^{(i)} - \underline{\theta}^T \underline{x}^{(i)} \underline{x}^{(i)T} & 0 &= (y - X\underline{\theta})^T \underline{X} \\ \sum_{i=1}^n \underline{\theta}^T \underline{x}^{(i)} - &= \sum_{i=1}^n y^{(i)} (\underline{x}^{(i)})^T & \underline{\theta}^T \underline{X}^T \underline{X} &= \underline{y}^T \underline{X} \quad (\text{transpose}) \\ 0 \sum_{i=1}^n (\underline{x}^{(i)T} \underline{x}^{(i)}) &= \sum_{i=1}^n \underline{x}^{(i)T} y^{(i)} & \underline{X}^T \underline{X} &= \underline{X}^T \underline{y} \\ 0 &= \sum_{i=1}^n (\underline{x}^{(i)T} \underline{x}^{(i)})^{-1} \underline{x}^{(i)T} \underline{x}^{(i)} & \underline{\theta} &= \frac{(\underline{X}^T \underline{X})^{-1} \underline{X}^T \underline{y}}{p \times 1} \end{aligned}$$

disabled

One-Hot-Encoding is basically One-Hot-Enc. with one reference, permanent = 0 (for categorical features).  
Side note: Linear Regression with intercept must use leave one out dummy encoding!  
↳ one redundant level

One-Hot-Encoding (full  $k$  levels for  $k$  categories) leads to "over-parametrization" and thus an indistinguishable non-unique parameter vector, unstable possibly ridiculous  $\underline{\theta}$  estimators.  
But: Regularized Regression requires full encoding, otherwise intercept not penalized!

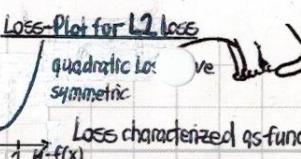
**L2-Loss / Squared Error** penalizes quad: residuals

$$L(y, f(x)) = \frac{1}{2} (y - f(x))^2 \quad \text{or} \quad L(y, f(x)) = (y - f(x))^2$$

Error in Feature Space  $X^T (y - X\underline{\theta}) = 0$

Properties: Convex; differentiable everywhere  $\rightarrow$  easier to optimize

Problem: Outliers have a huge effect on L2.



Loss characterized as function of residuals  $r = y - f(x)$

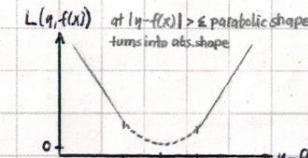
$$L(y, f(x)) = |y - f(x)|$$

**L1-Loss / Absolute Error** penalizes absolute residuals

$$L(y, f(x)) = |y - f(x)|$$

Properties: Convex; Robust against outliers

Problem: Not differentiable, slower to optimize (only numerically)



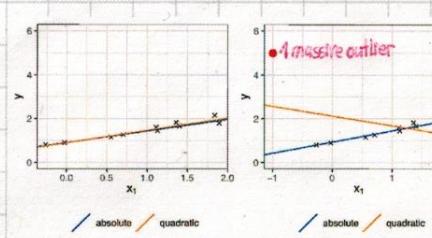
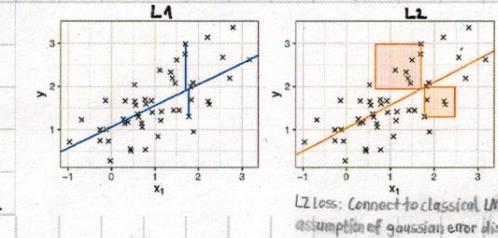
**Huber Loss** Weighted piecewise combo of L1/L2 loss  
 $\epsilon$  marks where L2 transits to L1 loss ( $\epsilon > 0$ )

$$L(y, f(x)) = \begin{cases} \frac{1}{2} (y - f(x))^2 & \text{if } |y - f(x)| \leq \epsilon \\ \frac{1}{2} \epsilon^2 & \text{else} \end{cases}$$

Huber loss combines advantages of both

Its smooth & differentiable like L2 Loss

Doesn't punish large residuals harshly, just as L1 loss  $\Rightarrow$  robust



## Polynomial Regression

### General Linear Model

We predict  $y \in \mathbb{R}$  as linear combinations of basis functions  $\phi_j$ :

$$\hat{y} = f(\underline{x}) = \theta_0 + \theta_1 \phi_1(\underline{x}_1) + \dots + \theta_p \phi_p(\underline{x}_p)$$

If we set  $\phi_j = \text{id}_{x_j}$  we get the usual linear regression model.

! This model is linear in parameters  $\underline{\theta}$  but not in covariates/features  $\underline{x}$ .

$$f(ax + bx^*; \underline{\theta}) \neq a f(\underline{x}; \underline{\theta}) + b f(\underline{x}^*; \underline{\theta}) \quad \text{but} \quad f(\underline{x}; a\underline{\theta} + b\underline{\theta}^*) = a f(\underline{x}; \underline{\theta}) + b f(\underline{x}; \underline{\theta}^*)$$

The design matrix now is defined as  $\underline{X} = \begin{pmatrix} 1 & \phi_1(\underline{x}_1) & \dots & \phi_p(\underline{x}_p) \end{pmatrix}$  with normal equation

### Overfitting risk with complex polynomials / basis functions

How high can/should we go with degree of modelling polynomials? (Hyperparameter  $d$ )

Problem with high degree: Our model will fit the training data excellent, but generally will not perform well on new (test) data

• Data contains random noise that is not part of true data-generating process

$\Rightarrow$  model with overly high capacity learns all those spurious patterns and those will not reappear in new data, leading to poor generalization of our model

• Also higher degrees can lead to instability (oscillation esp. at bounds, "Runge's Phenomenon")

## Polynomial Regression More flexible than simple Linear regression

In the Polynomial Regression we choose the basis functions  $\phi^{(d)}: \mathbb{R} \rightarrow \mathbb{R}, x_i \mapsto \sum_{k=0}^d \underline{\theta}_{j,k} x_j^k$

This results in  $f(\underline{x}) = \theta_0 + \theta_1 \phi_1(\underline{x}) = \theta_0 + \sum_{k=0}^d \underline{\theta}_{1,k} x_1^k$  where  $\underline{\theta}_{j,k} = \underline{\theta}_j \cdot \underline{\beta}_k$ .  $\underline{\theta}_j$  is just param. for full  $\phi^{(d)}(\underline{x})$

$$\underline{X} = \begin{pmatrix} 1 & x_1^{(1)} & (x_1^{(1)})^2 & \dots & (x_1^{(1)})^d \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_1^{(n)} & (x_1^{(n)})^2 & \dots & (x_1^{(n)})^d \end{pmatrix}, \quad \underline{\theta} \in \mathbb{R}^{d+1}$$

For two features we might model like this:

$$f(\underline{x}) = \theta_0 + \theta_1 x_1 + \sum_{k=1}^d \theta_{2,k} x_2^k$$

$$f(\underline{x}^{(i)}) = \sum_{j=1}^p \sum_{k=0}^d \theta_{j,k} (x_j^{(i)})^k$$

linear term  $x_1$

polynomials for  $x_2$

up until grade  $d$

$X = 1 - x_2 - x_3 - \dots - x_p \quad \text{if } k=0, \text{only } x_1=1 \Rightarrow (\beta_0, \beta_1, \dots, \beta_p)$  e.g. using  $X_1 = 1 - x_2$

Analytically:  $X (= X^T X)$  also not invertible  $= (\beta_0 + \beta_1, 0, \beta_2 - \beta_1, \beta_3, \dots, \beta_p)$  due to linear dependency of encoded cat. features

perfect multicollinearity ↳ dummy variable trap