

LEARNING PITCH INVARIANTS FOR INSTRUMENT RECOGNITION

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ABSTRACT

Musical performance combines a wide range of pitches, nuances, and expressive techniques. Audio-based classification of musical instruments thus requires to build signal representations that are invariant to such transformations. Focusing on pitch invariance, this article investigates the construction of multi-stage architectures for instrument recognition. We show that Mel-frequency cepstral coefficients (MFCC) lack invariance with respect to realistic pitch shifts. In turn, a convolutional neural network (ConvNet) in the time-frequency domain is able to disentangle pitch from timbral information in a subtler way. We extend our method to the recognition of multiple instruments playing simultaneously.

1. INTRODUCTION

Among the cognitive attributes of musical tones, pitch is distinguished by a combination of three properties. First, it is relative: ordering pitches from low to high gives rise to intervals and melodic patterns. Secondly, it is intensive: multiple pitches heard simultaneously produce a chord, not a single unified tone – contrary to loudness, which adds up with the number of sources. Thirdly, it does not depend on instrumentation: this makes possible the transcription of polyphonic music under a single symbolic system [11].

Tuning auditory filters to a perceptual scale of pitches provides a time-frequency representation of music signals that satisfies the first two of these properties. It is thus a starting point for a wide range of MIR applications, which can be separated in two categories: *pitch-relative* (e.g. chord estimation [4]) and *pitch-invariant* (e.g. instrument recognition [6]). Both aim at disentangling pitch from timbral content as independent factors of variability, a goal that is made possible by the first aforementioned property. This is pursued by extracting mid-level features on top of the spectrogram, be them engineered or learned from training data. Both approaches have their limitations: a “bag-of-features” lacks flexibility to represent fine-grain class boundaries, whereas a purely learned pipeline often leads to uninterpretable overfitting, especially in MIR where the quantity of thoroughly annotated data is relatively small.

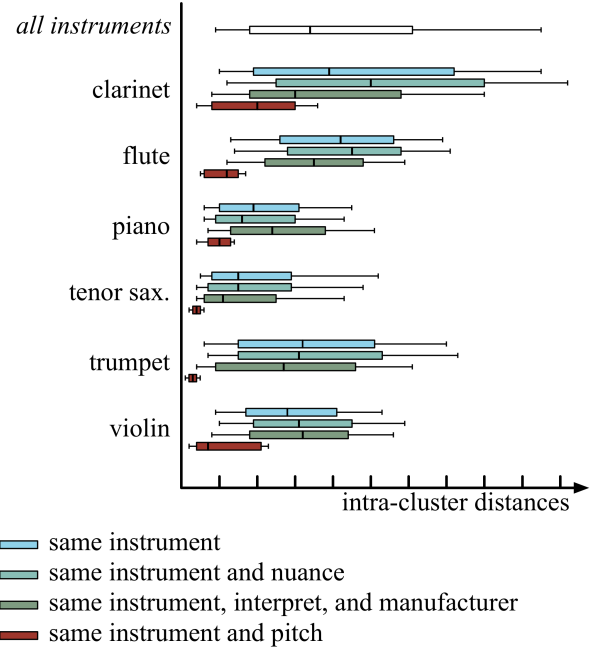


Figure 1: Distributions of squared Euclidean distances among various MFCC clusters in the RWC dataset. Whisker ends denote lower and upper deciles. See text for details.

In this article, we strive to integrate domain-specific knowledge about musical pitch into a deep learning framework, hence bridging the gap between feature engineering and feature learning.

Section 2 demonstrates that pitch is the major factor of variability among musical notes of a given instrument, if described by their mel-frequency cepstra. Section 3 describes a typical deep learning architecture for spectrogram-based classification, consisting of two convolutional layers and one densely connected layer. Section 4 improves the previous architecture by splitting spectrograms into octave-wide frequency bands, training specific convolutional layers over each band in parallel, and gathering feature maps at a later stage. Sections 5 and 6 discuss the effectiveness of the presented systems on a challenging dataset for music instrument recognition.

2. HOW INVARIANT IS THE MEL-FREQUENCY CEPSTRUM ?

The mel scale is a quasi-logarithmic function of acoustic frequency designed such that perceptually similar pitch in-



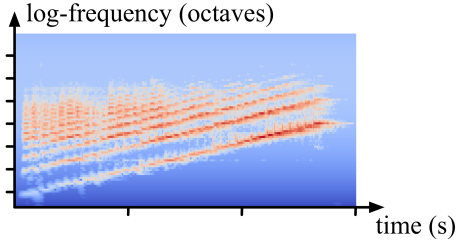


Figure 2: The same property is verified for a wide class of instruments, especially brass and woodwinds. See text for details.

intervals appear equal in width over the full hearing range. The time-frequency domain produced by a constant-Q filter bank tuned to the mel scale is therefore covariant with respect to frequency transposition, in the sense that a pitch interval between sine waves will appear as a translation on the mel-frequency axis. However,

We found that the MFCC cluster corresponding to each instrument is shrunk if decomposed into a mixture of same-pitch clusters, sometimes by an order of magnitude. In other words, most of the variance in an instrument cluster of mel-frequency cepstra is due to pitch transposition. This experiment shows that the mel-frequency cepstrum lacks invariance to realistic pitch shifts, and that there remains a lot to be gained by feature learning in this area.

The MFCCs were extracted from a filterbank of 40 Mel-frequency bands and 13 discrete cosine transform coefficients.

3. DEEP CONVOLUTIONAL NETWORKS

A deep learning system for classification is built by stacking multiple layers of weakly nonlinear transformations, whose parameters are jointly optimized such that the top-level layer fits a training set of labeled examples. This section introduces a typical deep learning architecture for audio classification and describes the functioning of each layer.

The input of our system is a constant-Q wavelet scalogram, which is very comparable to a mel-frequency spectrogram. We used the implementation from the librosa package [13] with $Q = 12$ filters per octave, center frequencies ranging from 55 Hz to 14 kHz (8 octaves from A1 to A9), and a hop size of 23 ms. Furthermore, we applied nonlinear perceptual weighting of loudness in order to reduce the dynamic range between the fundamental partial and its upper harmonics. A 3-second sound excerpt $x[t]$ is represented by a time-frequency matrix $x_1[t, k_1]$ of width $T = 128$ samples and height $K_1 = 96$ frequency bands.

Each layer in a convolutional network typically consists in the composition of three operations: two-dimensional convolutions, application of a pointwise nonlinearity, and local pooling. A convolutional operator is defined as a family $W_2[\tau, \kappa_1, k_2]$ of $K_2 = 32$ two-dimensional filters, whose impulse responses are all constrained to have width

Δt and height Δk_1 . Element-wise biases $b_2[k_2]$ are added to the convolutions, resulting in the three-way tensor

$$\begin{aligned} y_2[t, k_1, k_2] &= b_2[k_2] + W_2[t, k_1, k_2] \overset{t, k_1}{*} x_1[t, k_1] \\ &= b_2[k_2] + \sum_{\substack{0 \leq \tau < \Delta t \\ 0 \leq \kappa_1 < \Delta k_1}} W_2[\tau, \kappa_1, k_2] x_1[t - \tau, k_1 - \kappa_1]. \end{aligned} \quad (1)$$

The pointwise nonlinearity we have chosen the *rectified linear unit* (ReLU) because of its popularity in computer vision and its computational efficiency.

$$y_2^+[t, k_1, k_2] = \max(y_2[t, k_1, k_2], 0) \quad (2)$$

The pooling step consists in retaining the maximal activation among neighboring units in the time-frequency domain (t, k_1) over non-overlapping rectangles of width Δt and height Δk_1 .

$$x_2[t, k_1, k_2] = \max_{\substack{0 \leq \tau < \Delta t \\ 0 \leq \kappa_1 < \Delta k_1}} \{y_2^+[t - \tau, k_1 - \kappa_1, k_2]\} \quad (3)$$

The hidden units in x_2 are in turn fed to a second layer of convolutions, ReLU, and pooling. Observe that the corresponding convolutional operator $W_3[\tau, \kappa_1, k_2, k_3]$ performs a linear combination of time-frequency feature maps in x_2 along the channel variable k_2 .

$$\begin{aligned} y_3[t, k_1, k_3] &= \sum_{k_2} b_3[k_2, k_3] + W_3[t, k_1, k_2, k_3] \overset{t, k_1}{*} x_2[t, k_1, k_2]. \end{aligned} \quad (4)$$

Tensors y_3^+ and x_3 are derived from y_3 by ReLU and pooling, with formulae similar to Eqs. (2) and (3). The third layer consists of the linear projection of x_3 , viewed as a vector of the flattened index (t, k_1, k_3) , over $K_4 = 64$ units:

$$y_4[k_4] = b_4[k_4] + \sum_{t, k_1, k_3} W_4[t, k_1, k_3, k_4] x_3[t, k_1, k_3] \quad (5)$$

We apply a ReLU to y_4 , yielding $x_4[k_4] = y_4^+[k_4]$. $y_5[k_5] = \sum_{k_4} W_5[k_4, k_5] x_4[k_4]$.

$$x_5[k_5] = \frac{\exp y_5[k_5]}{\sum_{\kappa_5} \exp y_5[\kappa_5]} \quad (6)$$

The above ensures that the coefficients of x_5 are non-negative and sum to one, hence can be fit to a probability distribution.

$$\mathcal{L}(x_5, \mathcal{I}) = - \sum_{k_5 \in \mathcal{I}} \log x_5[k_5] + \sum_{m=1}^4 \lambda_m \|W_m\|_2. \quad (7)$$

The goal is to minimize the average loss $\mathcal{L}(x_5, \mathcal{I})$ for across all pairs (x, \mathcal{I}) in the training set.

The network is trained on categorical cross-entropy over shuffled mini-batches of size 512 with uniform class distribution. Each training example is a 3-second spectrogram whose boundaries are selected at random over non-silent

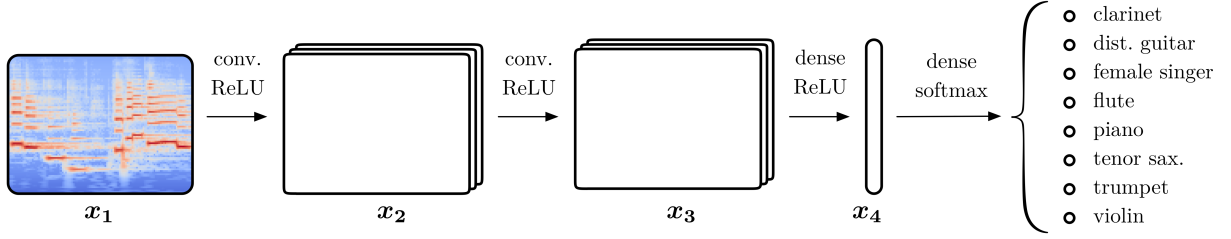


Figure 3: Architecture of a convolutional network with full weight sharing. See text for details.

regions of a song. Each spectrogram within a batch was globally normalized such that the whole batch had unit mean and unit variance. The learning rate policy for each scalar weight in the network is *Adam* [10], a state-of-the-art online optimizer for gradient-based learning. The architecture was built using the Keras library [5], and trained on a graphics processing unit within a few minutes.

4. CONVOLUTIONS ON THE PITCH SPIRAL

”Local neighborhoods in frequency do not share the same relationship”, Humphrey et al. acknowledge in their review of deep learning techniques for MIR. Indeed, since the neighboring partials of a harmonic sound are evenly spaced in frequency, they tend to get closer to each other on a mel scale.

Let $\phi[k_1]$ be a window function of width $2Q$, that is two octaves. We have chosen a Tukey window ($\alpha = 0.5$), which has a flat top of width Q surrounded by cosine tapering lobes of width $Q/2$.

$$\begin{aligned} y_2[t, k_1, k_2] &= b_2[k_2] \\ &+ \sum_{\tau, \kappa_1, j_1} W_2[\tau, \kappa_1, j_1, k_2] \\ &\quad \times x_1[t - \tau, k_1 - \kappa_1] \\ &\quad \times \phi[k_1 - \kappa_1 + Qj_1]. \end{aligned} \quad (8)$$

Compare the above with Equation (1). Limited weight sharing has been introduced by Abdel-Hamid et al. [1].

5. SINGLE-INSTRUMENT CLASSIFICATION

5.1 Experimental design

In order to train the proposed algorithms, we used MedleyDB v1.1. [3], a dataset of 122 multitracks annotated with instrument activations as well as melodic f_0 curves when present. We extracted the monophonic stems corresponding to a selection of eight pitched instruments (see Table 1). Stems with leaking instruments in the background were discarded.

The evaluation set consists of 126 recordings of solo music collected by Joder et al. [8], to which we add 23 stems of electric guitar and female voice from MedleyDB.

	minutes	tracks	minutes	tracks
clarinet	10	7	13	18
dist. guitar	15	14	17	11
female singer	10	11	19	12
flute	7	5	53	29
piano	58	28	44	15
tenor sax.	3	3	6	5
trumpet	4	6	7	27
violin	51	14	49	22
total	158	88	208	139

Table 1

Representation	Error rate (%)
MFCC & random forest	—
ConvNet, full weight sharing	—
ConvNet, limited weight sharing	—

Table 2

In doing so, guitarists and vocalists were thoroughly put either in the training set or the test set, to prevent any artist bias. We discarded recordings with extended instrumental techniques, since they are under-represented in MedleyDB.

Constant-Q spectrograms from the evaluation set were split into half-overlapping, 3-second excerpts.

5.2 Results

Results are charted in Table 2.

6. POLYPHONIC CLASSIFICATION

6.1 Experimental design

6.2 Results

Results are charted in Table 3.

7. CONCLUSIONS

Understanding the influence of pitch in audio streams is paramount to the design of an efficient system for auto-

Representation	Error rate (%)
MFCC & random forest	—
ConvNet, full weight sharing	—
ConvNet, limited weight sharing	—

Table 3

mated classification, tagging, and similarity retrieval in music. We have presented a data-driven, supervised method to address pitch invariance while preserving good timbral discriminability. Future work will be devoted to integrating the proposed scheme with other advances in deep learning for music informatics, such as data augmentation [12], multiscale representations [2, 7], and adversarial training [9].

8. REFERENCES

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