Project 2: Digital Inputs and Interrupts Solution

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May 25, 2022

Overview

Students will be considered to have completed the project when they demonstrate the following tasks:

- 1. integrated three buttons inputs and three LED outputs with their Arduino
 - one button must have an unfiltered input
 - one button must have a software-regulated input
 - one button must have a hardware RC low-pass filter circuit
- 2. implemented three appropriate Interrupt Service Routines (ISRs) into their program
 - each ISR must increment a counter for each button pressed
 - each ISR must send the counter through the Serial port with an appropriate label
- 3. showed that the LED state switches and the counter is printed to the serial monitor with every button press

Grading

Category	No Credit	Half Credit	Full Credit
Efficacy	Student did not demonstrate	student demonstrated a	student demonstrated a
	their working project	working project, but it did	feature-complete project
		not meet all of the require-	that accomplished all of the
		ments specified in the project	goals specified in the project
		handout	handout
3 types of input	Student did not implement		Student implemented enough
filtering	enough unique filters		filters
Printout of Se-	Student did not provide a	Student provided a printout,	Student provided an accept-
rial monitor	printout of the Serial moni-	but it was not appropriately	able printout
	tor	labeled or incoherrent	
Schematic neat-	Student did not provide a	Student provided a	Student provided a schematic
ness	schematic, or it is illegible	schematic, but it is diffi-	that is easy to read and un-
		cult to read or understand	derstand
Mystery extra	Student did not request extra		Student successfully imple-
credit	credit or reach the necessary		mented a button hold feature
	thresholds		

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Extra Credit

Students will be granted extra credit if they demonstrated that they record a button press *after* a certain time period and follow the rest of the requirements following the detected press.

Guide

Wiring the Breadboard

Students should have three buttons and three LEDs on their breadboard connected to the Arduino's GPIO pins. The GND pin of the Arduino should be connected to the negative (blue) rail of the breadboard. Each LED should have a current-limiting resistor in series with the anode (long wire) and the Arduino output pin with the cathode (short pin) connected to the negative rail. Two buttons should have a 10k-ohm pulldown resistor on one contact end to the negative rail and the other contact end conected directly to an interrupt-capable input pin. The third button should have an RC circuit in series with the Arduino input wire as shown in Figure 1.

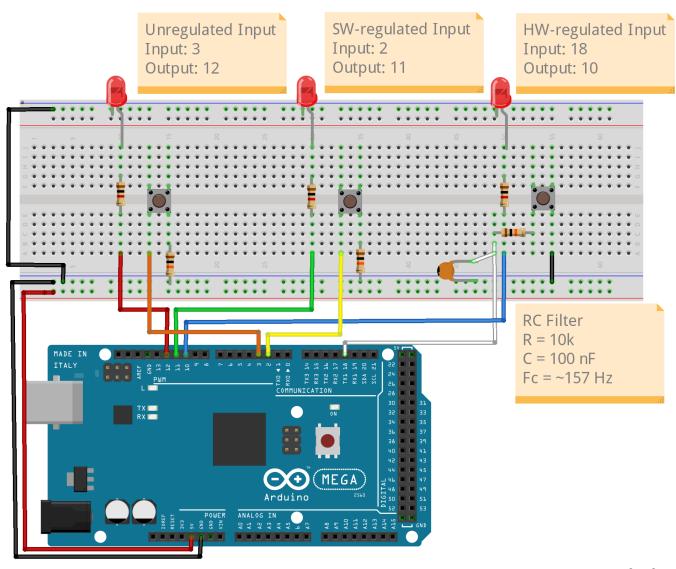
Arduino Code

Students should have a well-organized and thought out program for this project. Firstly, they must declare and initialize the input and output pins being used as well as the counters for the number of button presses. Then, they must have created ISRs to perform the counter increments and printing for each button as well as change the LED state from on to off or vice versa. These interrupts must be attached to the appropriate input pins and, ideally, be triggered on the FALLING edge of the signal - though RISING could also work. The main loop of this function should just be setting the LED state for each LED since most of the logic will be handled asynchronously by the ISRs.

For the sample code provided below, the pins are defined using the #define pre-compiler instruction and the LED states and counters are initialized. In setup() The Serial port is opened and the modes for the inputs and outputs are declared. Afterwards, the ISRs defined at the bottom of the code are attached to the input pins and set to trigger on the FALLING edge of the pin's signal (i.e. when the button is pressed and the voltage on the pin go towards 0).

In loop(), the various LED states are written to the LED pins based on the global variable. The ISR code executes asynchronously, so nothing else is reugired in this section

Both unregBtnISR() and hwregBtnISR() do the same thing because the debouncing is either not handled or done so externally to the program. The software trick comes inside swregBtnISR(). Here, a static variable is initialized that will retain its value after the ISR is finished executing. This value holds the last known millisecond reading of the ress detection logic. Then, the current millisecond reading is captured and used to compare with the previous value. If 100 ms have passed since the ISR was last executed, then the code block assumes it was a valid button press and increments the counter, changes the LED state, and prints out the counter to the Serial port. If an appropriate time has not passed, then the ISR assumes the detection was a bounce and resets the last millisecond reading before exiting.



fritzing

Figure 1: The breadboard layout for Project 2

```
* OCE4531 Project 2: Digital Inputs and Interrupts Solution
   * @brief This is the solution for OCE4531's second project, Digital Inputs and Interrupts.
3
   * This should not be considered the absolute correct answer that all of the students must
   * but it is the ball park they should be within.
   * See handout for more information
6
   * @author Braidan Duffy
10
   * @date May 25, 2022
11
12
   * @version v1.0
13
14
_{15} // Define button pins according to schematic
16 #define HWREG_BUTTON_PIN 18 // Button that is regulated by a RC low-pass filter
17 #define SWREG_BUTTON_PIN 3 // Button that is regulated by a software debounce
18 #define UNREG_BUTTON_PIN 2 // Button that has an unregulated input
20 // Define LED pins according to schematic
21 #define HWREG_LED_PIN 10
22 #define SWREG_LED_PIN 11
23 #define UNREG_LED_PIN 12
_{25} // Initialize LED states
bool hwregLEDState = false;
27 bool swregLEDState = false;
28 bool unregLEDState = false;
30 // Initialize counters
31 long hwregBtnPresses = 0;
32 long swregBtnPresses = 0;
33 long unregBtnPresses = 0;
34
35 void setup() {
      Serial.begin(115200);
36
      while(!Serial); // Wait for Serial connection
37
38
      // Set button pins to inputs with internal pullup resistors
39
      pinMode(HWREG_BUTTON_PIN, INPUT_PULLUP);
pinMode(SWREG_BUTTON_PIN, INPUT_PULLUP);
40
41
      pinMode(UNREG_BUTTON_PIN, INPUT_PULLUP);
42
43
      // Attach Interrupt Service Routines (ISRs) to pins
44
      attachInterrupt(digitalPinToInterrupt(HWREG_BUTTON_PIN), hwregBtnISR, FALLING);
45
       attachInterrupt(digitalPinToInterrupt(SWREG_BUTTON_PIN), swregBtnISR, FALLING);
46
      attachInterrupt(digitalPinToInterrupt(UNREG_BUTTON_PIN), unregBtnISR, FALLING);
47
      // Set LED pins to outputs
49
      pinMode(HWREG_LED_PIN, OUTPUT);
pinMode(SWREG_LED_PIN, OUTPUT);
50
51
      pinMode(UNREG_LED_PIN, OUTPUT);
52
53 }
54
  void loop() {
55
      // Hardware-regulated button LED code
56
      digitalWrite(HWREG_LED_PIN, hwregLEDState);
57
58
       // Software-regulated button LED code
59
      digitalWrite(SWREG_LED_PIN, swregLEDState);
60
61
       // Un-regulated button LED code
62
      digitalWrite(UNREG_LED_PIN, unregLEDState);
63
64 }
66 // =============
67 // === INTERRUPT SERVICE ROUTINES ===
```

```
68 // ============
69
70 void hwregBtnISR() {
      hwregBtnPresses++; // Increment button presses
71
      Serial.println("Hardware-regulated button pressed!");
72
      Serial.print("It has been pressed "); Serial.print(hwregBtnPresses); Serial.println("
73
      times!");
      Serial.println();
74
      hwregLEDState = !hwregLEDState; // Change LED state
75
76 }
77
78 void swregBtnISR() {
79
      static unsigned long _lastInterruptTime = 0;
      unsigned long _curInterruptTime = millis();
80
81
      if (_curInterruptTime - _lastInterruptTime > 100) { // If interrupts come faster than
      100ms, assume it's a bounce and ignore
          swregBtnPresses++; // Increment button presses
82
          {\tt Serial.println("Software-regulated button pressed!");}\\
83
          Serial.print("It has been pressed "); Serial.print(swregBtnPresses); Serial.println(
84
      " times!");
          Serial.println();
85
          swregLEDState = !swregLEDState; // Change LED state
86
87
      _lastInterruptTime = _curInterruptTime;
88
89 }
90
91
  void unregBtnISR() {
      unregBtnPresses++; // Increment button presses
92
      Serial.println("Un-regulated button pressed!");
93
      Serial.print("It has been pressed "); Serial.print(unregBtnPresses); Serial.println("
94
      times!");
95
      Serial.println();
      unregLEDState = !unregLEDState; // Change LED state
96
```