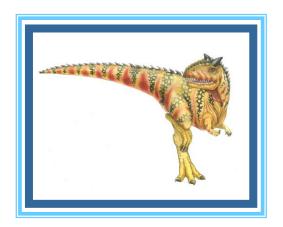
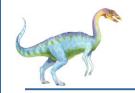
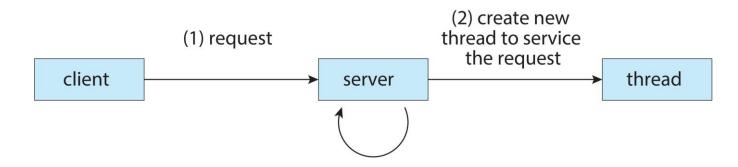
# Chapter 4: Threads & Concurrency





#### **Motivation**

- Most modern applications are multithreaded
  - □ E.g., web browser, word processor, web server
- Multiple tasks within the application can be implemented by separate threads
  - E.g., update display, fetch data, spell checking, answer a network request



(3) resume listening for additional client requests

Multithreaded server architecture





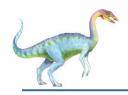
#### What is a Thread?

- A thread is a basic unit of CPU utilization
- A process can contain multiple threads of control
- A thread consists of
  - A thread ID
  - A program counter
  - A register set
  - A stack
- Threads belonging to the same process share
  - code section, data section, heap
  - open files

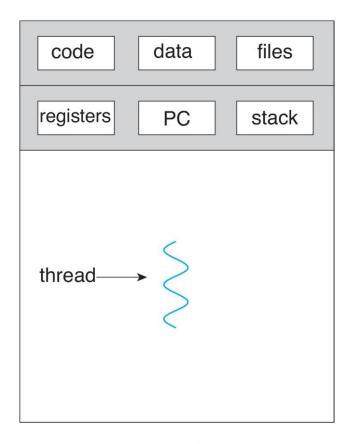
Linux command to display threads in a process

$$ps -T -p < pid>$$

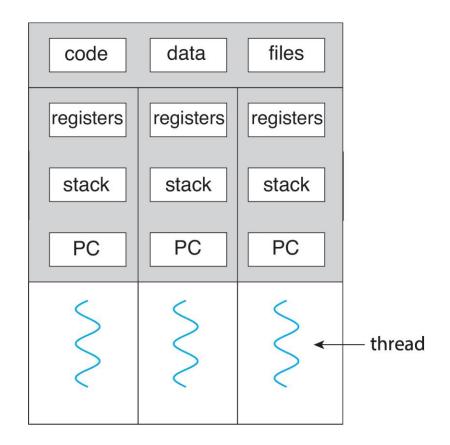




## Single and Multithreaded Processes

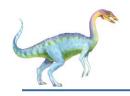


single-threaded process



multithreaded process





## **Thread Control Block (TCB)**

- OS maintains a TCB for each thread
- TCB contains
  - Thread ID
  - Stack pointer
  - Program counter
  - Register values
  - Pointer to PCB of the process that the thread belongs to





## **Benefits of Multithreading**

- Responsiveness may allow continued execution of a program if part of it is blocked or is performing a lengthy operation; especially important for user interfaces
- Resource Sharing threads share resources of process, sharing data easier than shared memory or message passing
- Economy thread creation is cheaper (i.e., consumes less time & memory) than process creation, thread context-switching has lower overhead than process-context switching
  - Thread context-switching involves saving/loading registers and program counter to/from TCB; no need to save/load memory management information
- Scalability multithreaded process can take advantage of multicore architectures
  - Threads may be running in parallel on different processing cores





## **Multicore Programming**

- Recent trend in computer design is to place multiple computing cores on a single processing chip – multicore systems
- Multithreaded programing provides more efficient use of multiple computing cores and improved concurrency
- Parallelism implies a system can perform more than one task simultaneously
- Concurrency supports more than one task making progress
  - Single processor/core: scheduler providing concurrency
  - It is possible to have concurrency without parallelism

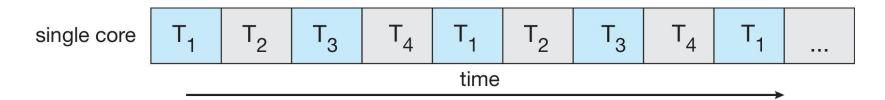




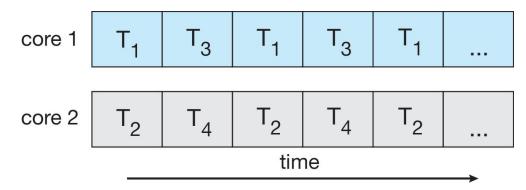
## Concurrency vs. Parallelism

Consider an application with 4 threads:

Concurrent execution on single-core system:



□ Parallelism on a multi-core system:







#### Amdahl's Law

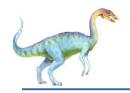
- Identifies performance gains from adding additional computing cores to an application that has both serial and parallel components
- □ S is serial portion of application, N processing cores

$$speedup \le \frac{1}{S + \frac{(1-S)}{N}}$$

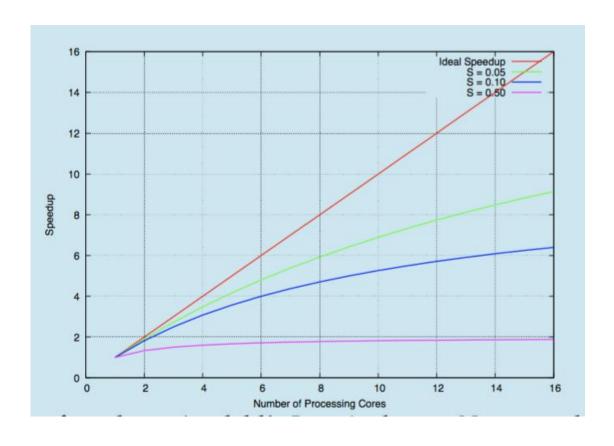
- □ E.g., if application is 75% parallel & 25% serial, moving from 1 to 3 cores results in speedup of 2 times
- As N approaches infinity, speedup approaches 1/S

Serial portion of an application has disproportionate effect on performance gained by adding additional cores





## **Amdahl's Law**







## **User Threads and Kernel Threads**

- User threads supported at the user level, management done by user-level threads library
- Kernel threads supported by the kernel
- Virtually all comptemporary operating systems support kernel threads:
  - Windows
  - Linux
  - macOS
  - iOS
  - Android

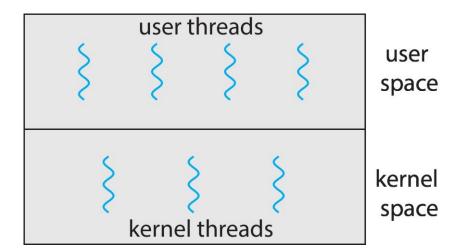
Linux command to see Kernel threads \$ ps -ef



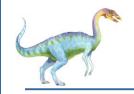


## **Multithreading Models**

- Relationship between user threads and kernel threads
  - Many-to-One
  - One-to-One
  - Many-to-Many

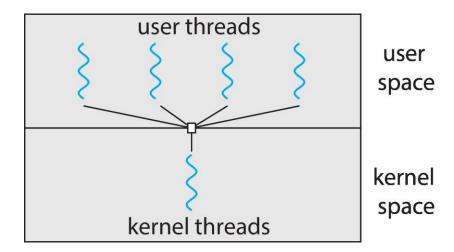






## Many-to-One

- Many user threads mapped to one kernel thread
- □ Thread management done by thread library in user space → efficient
- Entire process will block if a thread makes a blocking system call
- Multiple threads cannot run in parallel on multicore system
- Few systems currently use this model

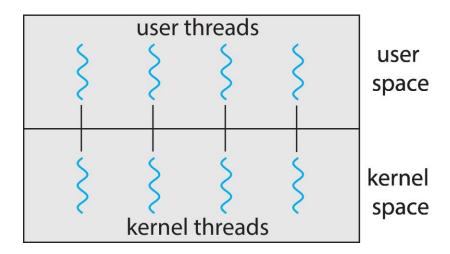






#### **One-to-One**

- Each user thread is mapped to a kernel thread
- Greater concurrency than many-to-one: another thread can run when a thread makes a blocking system call
- Multiple threads can run in parallel on multicore system
- □ Creating a user thread requires creating a kernel thread → expensive
  - Number of threads per process sometimes restricted due to overhead
- Most operating systems now use one-to-one model

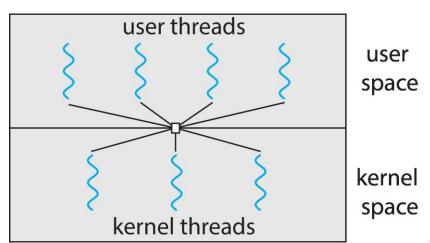






## Many-to-Many Model

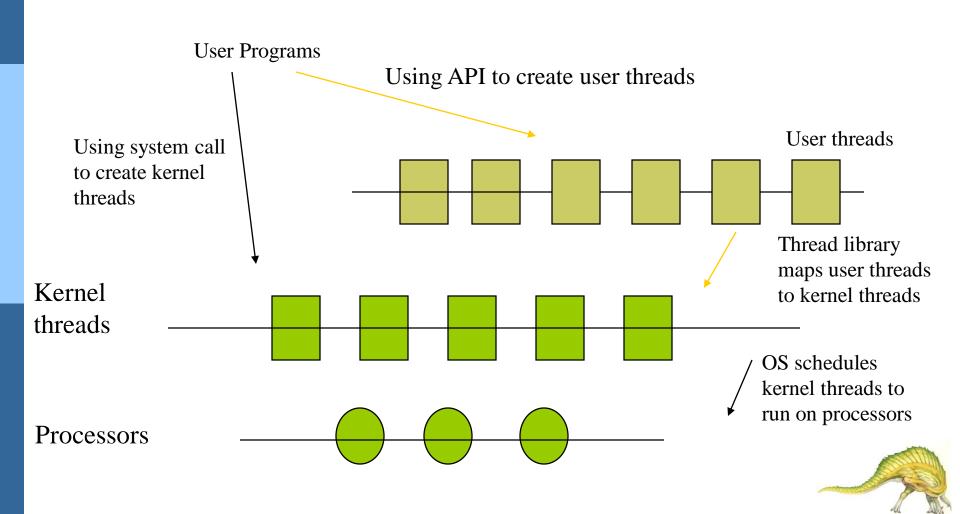
- Many user-level threads are multiplexed to a smaller or equal number of kernel threads
- Application developer can create as many user threads as necessary, corresponding kernel threads can run in parallel on a multicore system
- When a user thread performs a blocking system call, the kernel can schedule another thread for execution
- □ Not very common

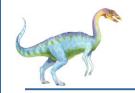






## Threads in a Computer System





#### **Thread Libraries**

- Thread library provides programmer with API for creating and managing threads
- Two primary ways of implementing thread library
  - Library entirely in user space: invoking a library function results in a local function call in user space
  - Kernel-level library supported by the OS: invoking a library function results in a system call to kernel
- Three main thread libraries:
  - POSIX pthreads: can be user level or kernel level
  - Windows threads: kernel level
  - Java threads: implemented using a thread library available on the host system





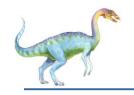
#### **Pthreads**

- pthreads is a Portable Operating System Interface (POSIX) standard API for thread creation and synchronization
  - API specifies behavior of the thread library, implementation is up to development of the library
  - Available on many UNIX-like operating systems (Solaris, Linux, macOS)
- Using pthreads on pyrite:

#include <pthread.h>

Compile and link with the pthread library: gcc pthreads.c - lpthread





## pthread\_create (1)

```
int pthread_create(pthread_t *thread, pthread_attr_t *attr, void * (* start_routine) (void *), void *arg) – create a new thread
```

- thread points to a buffer that stores the ID of the new thread
- attr points to a structure containing the attributes of the new thread
  - If <u>attr</u> is NULL, the thread is created with default attributes
- The new thread starts execution by invoking <u>start\_routine()</u>
- arg is a pointer to the argument of start routine()
  - If multiple arguments are needed, <u>arg</u> points to a data structure that contains all arguments
- Returns 0 on success, returns an error number on error

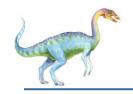




## pthread\_create (2)

- □ The new thread executes concurrently with the parent thread
- The new thread runs until one of the following happens
  - It returns from <u>start\_routine</u>
  - It calls pthread\_exit()
  - Any of the threads in the process calls exit() or the main thread performs a return from main(). This causes the termination of all threads in the process.





## pthread\_create() Example

```
#include <pthread.h>
#include <stdio.h>
#include <unistd.h>
void *my_thread (void *arg)
   char *msg = (char *) arg;
    printf("Thread says \%s\n", msg);
int main (int argc, char *argv[])
   pthread_t t;
   char msg[20] = "Hello World";
   pthread_create(&t, NULL, my_thread, msg);
   sleep(3); //what happens if this statement is removed?
   return 0;
```





## pthread\_exit()

#include <pthread.h>
void pthread\_exit(void \*retval) – terminate calling thread

- The function returns a value via <u>retval</u> that is available to another thread in the same process that calls pthread\_join()
- The function does not return to the caller





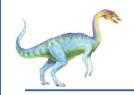
## pthread\_join()

#include <pthread.h>

int pthread\_join(pthread\_t th, void \*\*retval) - wait for a thread to terminate

- □ th: the thread to wait for
- If <u>retval</u> is not NULL, then <u>pthread\_join()</u> copies the exit status of the target thread into the location pointed to by <u>retval</u>
- Returns 0 on success, returns an error number on error
- When a thread terminates, its TCB is not deallocated until another thread performs pthread\_join() on it





## Pthread\_join() Example

```
#include <pthread.h>
#include <stdio.h>
#include <unistd.h>
int N;
void * thread(void *x)
 int *id = (int *)x;
 while (N != *id);
 printf("Thread %d \n", *id);
 N--:
 pthread_exit(NULL);
```

```
int main()
 N = 0;
 int id1=1;
 int id2=2;
 int id3=3;
 pthread t t1, t2, t3;
 printf("Parent creating threads\n");
 pthread_create(&t1, NULL, thread, &id1);
 pthread_create(&t2, NULL, thread, &id2);
 pthread create(&t3, NULL, thread, &id3);
 printf("Threads created\n");
 N = 3;
 pthread_join(t1, NULL);
 pthread_join(t2, NULL);
 pthread_join(t3, NULL);
 printf("Threads are done\n");
 return 0;
```