COM S 352 Homework 2

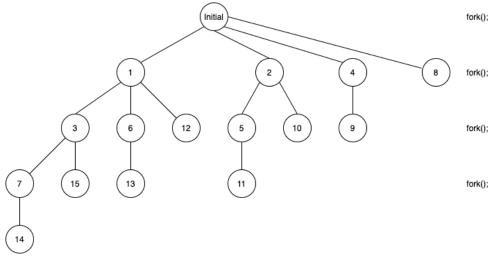
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Question 1

First the operating system saves all data then transfers control the kernal. The kernel saves the context of the old process in its PCB and then grabs the new process and loads the saved data into the new process. Finally the OS transfers control back to user mode.

Question 2



16 total processes created

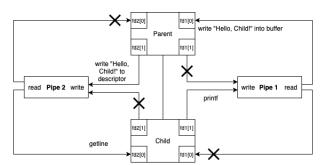
Question 3

The program executes, then runs into the fork() function, where it creates a child process. This child process will enter the else if statement because its pid is 0 then it will hit the exec() function. The exec() function replaces the childs memory space with a new program, in this case it is ls. Now that the child no longer exsists it will not reach the line, printf("LINE J"). However, if the exec() function results in an error and memory is not replaced the child process will run the line printf("LINE J").

Question 4

A: 0 //child B: 2606 //child C: 2606 //parent D: 2603 //parent

Question 5



The program starts with its initializations, $int\ fd1[2]$, $int\ fd2[2]$, and $pid_t\ pid=fork()$ Then the child goes into the if(pid==0) block where it closes a read and write descriptor then turns fd1[1] into a printf and fd2[0] into a getline using the dup2() function. The child then runs the execlp() function and the child process terminates while also allowing the parent to communicate between the two pipes. The parent goes into the else block and closes another read and write then writes "Hello, Child!" to pipe 1, like mentioned before, the execlp("cat", "cat", NULL) allows the parent to read the message "Hello, Child!" from pipe 2 and save it in the buffer. The program then prints out the buffer.

Question 6

```
\delta/(\delta + \sigma)

System A:

\delta = 20 \text{ms}

\sigma = 1 \text{ms}

20/(20 + 1)

= 95.24\%

System B:

\delta = 15 \text{ms}

\sigma = 1 \text{ms}

15/(15 + 1)

= 93.75\%
```

The system with a slice of 20ms will be more efficient by 1.49%

Question 7

1. Running to Waiting

During an I/O or event wait, The process is going to enter a waiting state because it is waiting for I/O input/output.

2. Waiting to Ready

After waiting for an I/O response (completion) it will move to a ready state where it waits for reassignment.

3. Running to Ready

The transition from running to ready will occur when an interrupt is triggered.