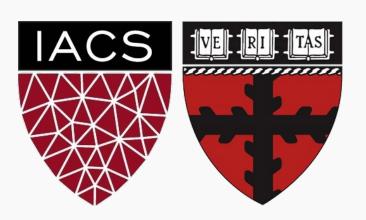
#### Advanced Section: Variational Inference

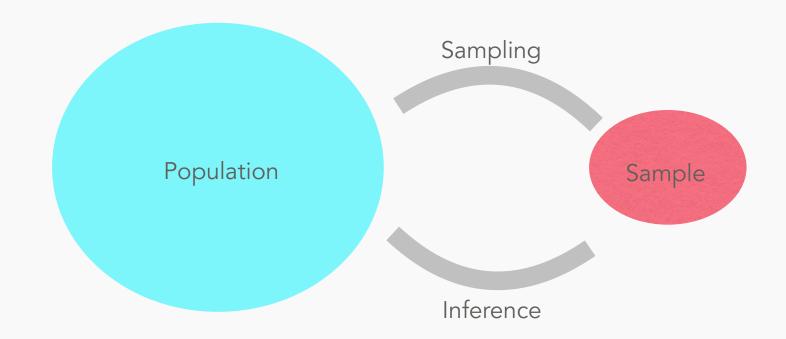
#### CS109B Data Science 2

Pavlos Protopapas, Mark Glickman and Chris Tanner



#### Statistical Inference

Draw conclusions about an underlying distribution of probabilities from a sample





#### Outline

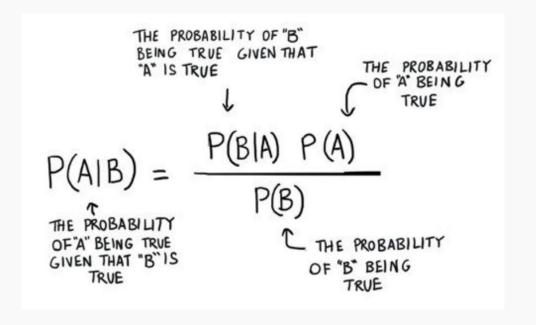
- 1. Bayesian Inference
- 2. Markov Chain Monte Carlo
- 3. Bayesian Neural Networks
- 4. Variational Inference
- 5. Drop Out as a Bayesian Approximation
- 6. Bootstrap for Inference



## Bayesian Inference

Probability as a measure of believability in an event

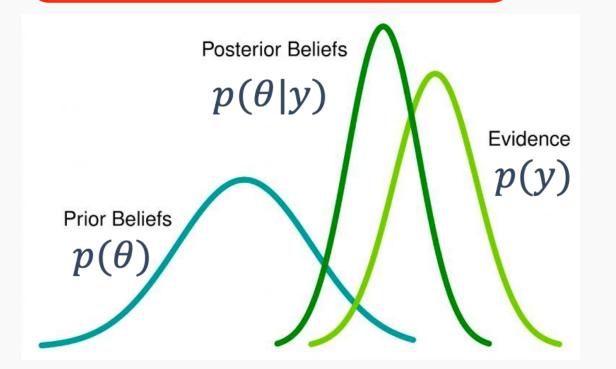
$$p(\theta|y) \propto p(y|\theta)p(\theta)$$
Model Data





### Bayesian Inference

 $n(\theta|v) \propto n(v|\theta)n(t)$ 

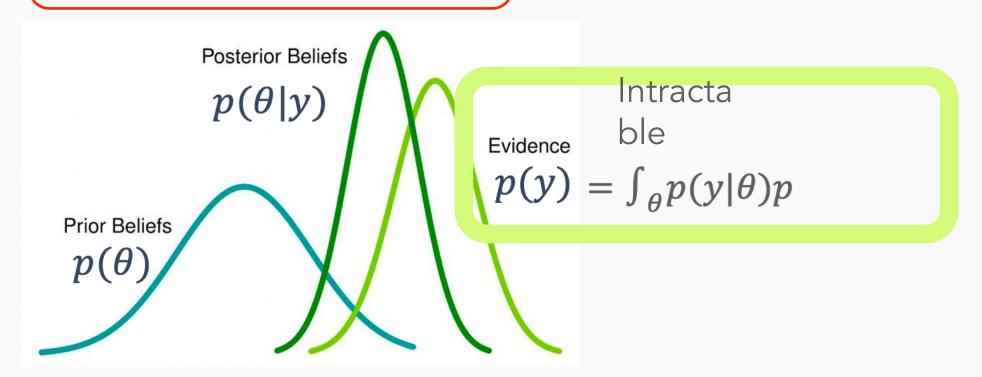


"When the facts change, I change my mind. What do you do, sir? "John Maynard Keynes



### Bayesian Inference

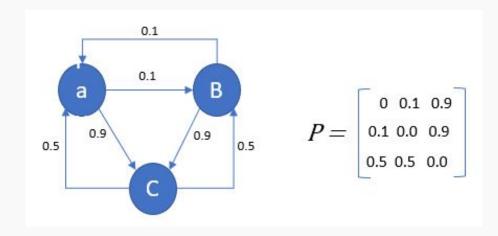
 $n(\theta|v) \propto n(v|\theta)n(t)$ 



"When the facts change, I change my mind. What do you do, sir? "John Maynard Keynes



#### MCMC: Markov Chains

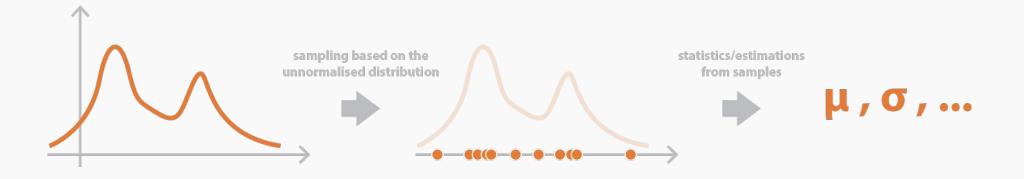


$$p(z^{(m+1)}|z^{(1)},...,z^{(m)}) = p(z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1)}|z^{(m+1$$

$$p(z^{(m+1)}) = \sum_{z^{(m)}} p(z^{(m+1)}|z^{(m)})p$$



# MCMC: Sampling method





**Unnormalised distribution** whose normalisation factor computation is intractable

Samples
that can be obtained with MCMC and
without proceeding to the normalisation
CS109B, PROTOPAPAS, GLICKMAN AND TANNER

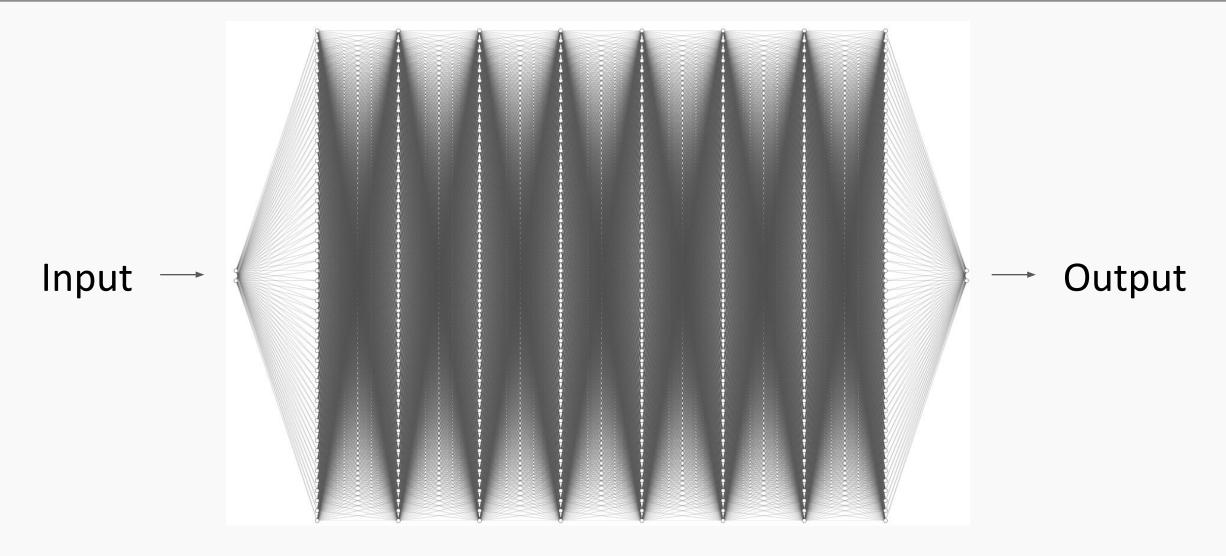
Statistics or estimations that can be computed based on the generated samples

### MCMC

Credit: Towards Data Science

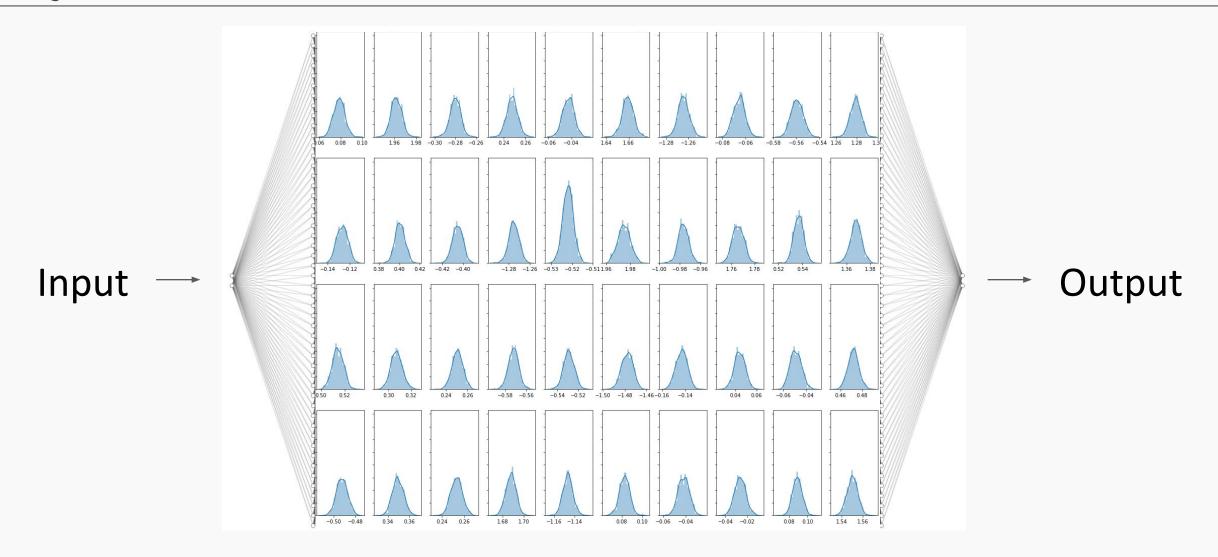


# Bayesian Neural Networks: FCNN



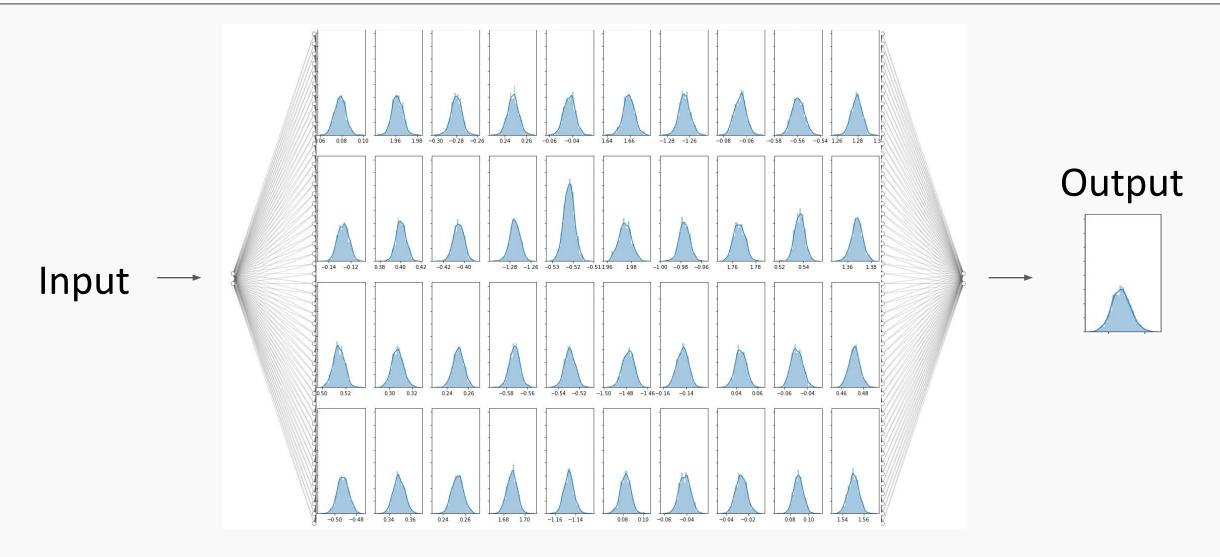


# Bayesian Neural Networks: FCNN





# Bayesian Neural Networks



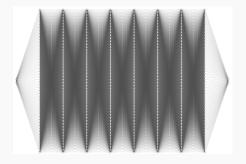


# Bayesian Neural Networks

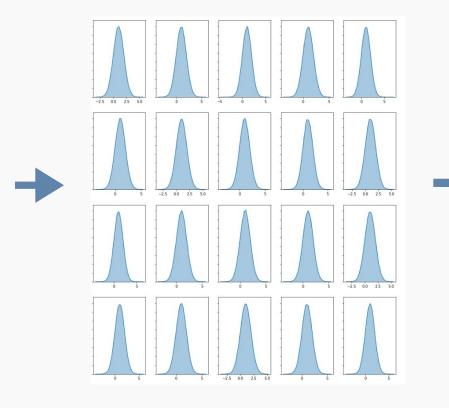
**Priors** 

 $p(\theta) \sim p(y|\theta) = p(\theta|y)$ 





& Scale







### Bayesian Neural Networks

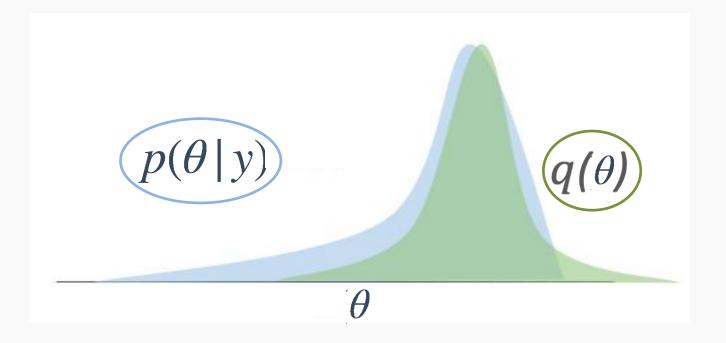
$$n(\theta) \sim n(v|\theta) \sim n(\theta|v)$$

MCMC is eventually accurate, but not scalable to large models
Approximate Bayesian Inference: Variational Inference



Optimization approach -> Q a family of "nice" distributions

$$p(\theta | y) = \frac{p(y | \theta) p(\theta)}{\int p(y, \theta) d\theta}$$

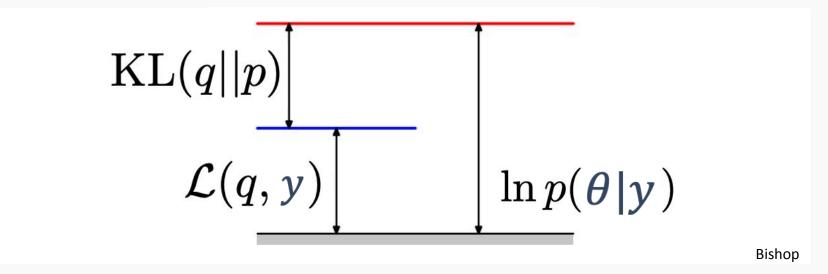




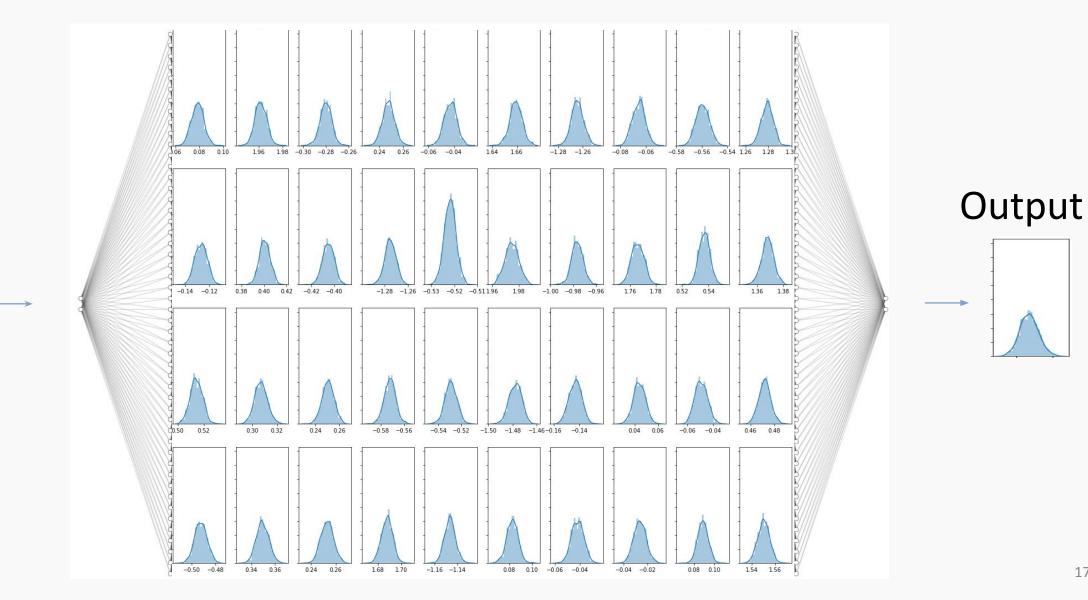
$$p(\theta|y) = \frac{p(y|\theta)p(\theta)}{\int p(y,\theta)d\theta}$$

Kullback-Leibler divergence:

$$p(\theta|y) \approx q *= argmin_{a \in \Omega} f(q(\theta), p(\theta))$$
  
 $argmin_a KL(q, p) \equiv argmax_a EL$ 

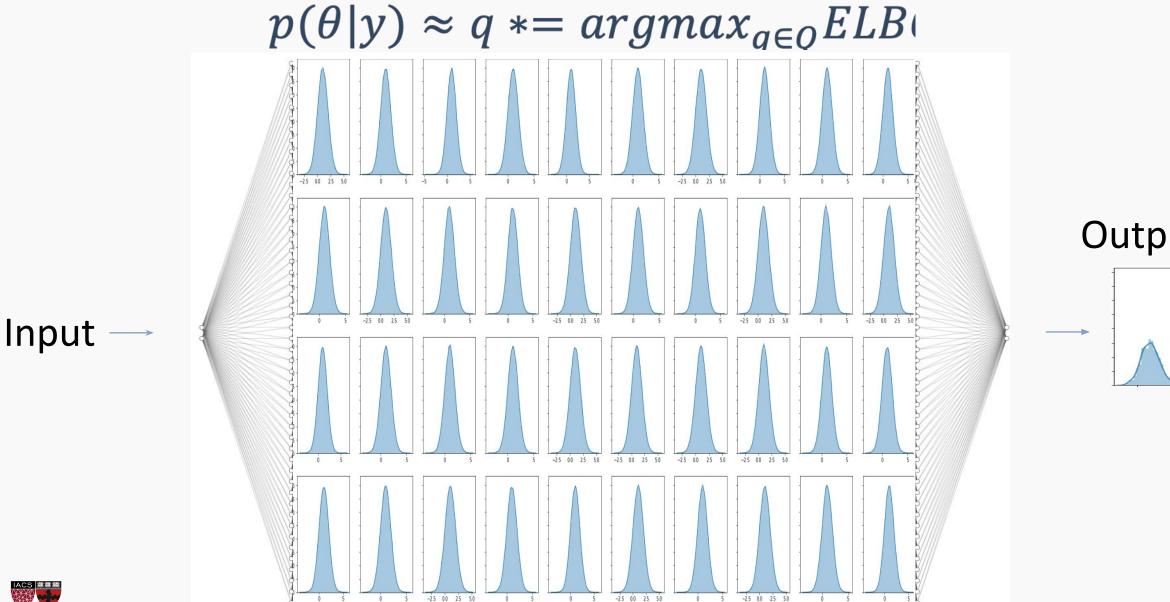




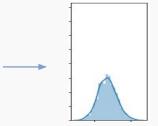




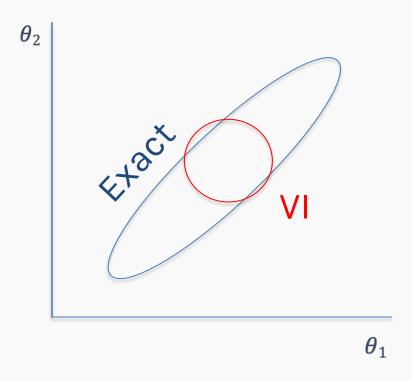
Input











$$KL(q | | p(\cdot | x)) = \int_{\theta} q(\theta) \log \frac{q(\theta)}{p(\theta | x)} d\theta$$
$$q(\theta) = \prod_{i=1}^{J} q_{i}(\theta_{i})$$

Underestimates variance (sometimes severely)



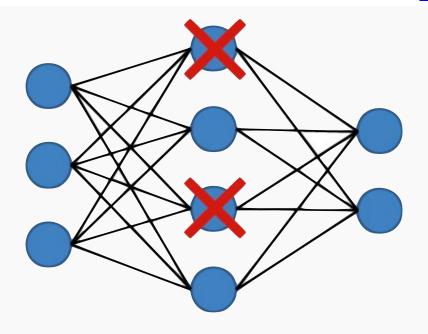
### Dropout

#### Dropout as a Bayesian Approximation: Representing Model Uncertainty in Deep Learning

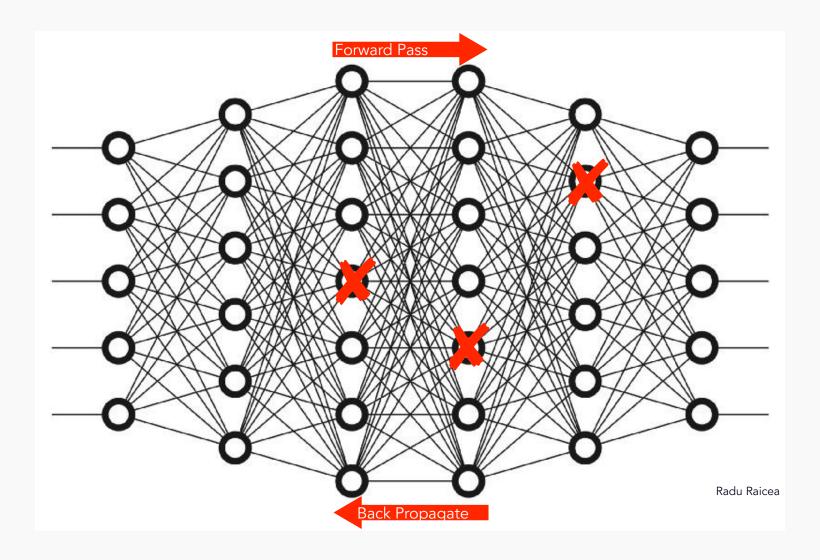
Yarin Gal Zoubin Ghahramani

University of Cambridge

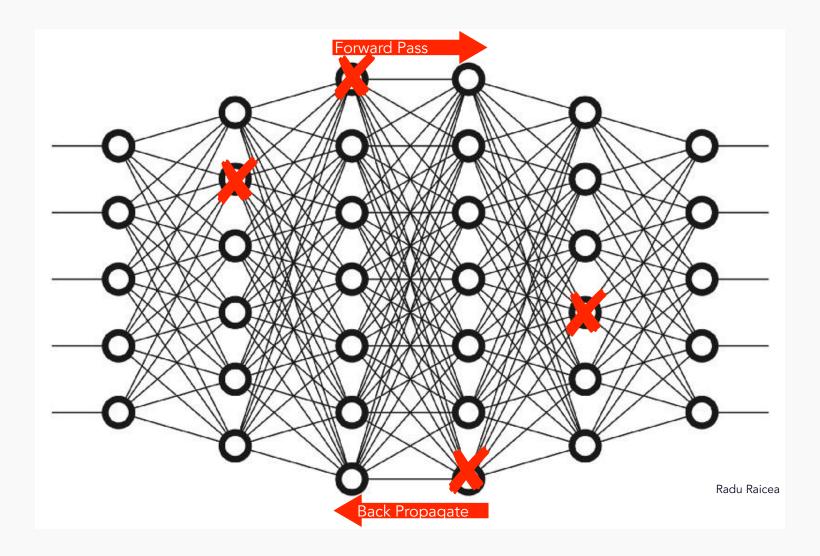
YG279@CAM.AC.UK ZG201@CAM.AC.UK arXiv:1506.02142



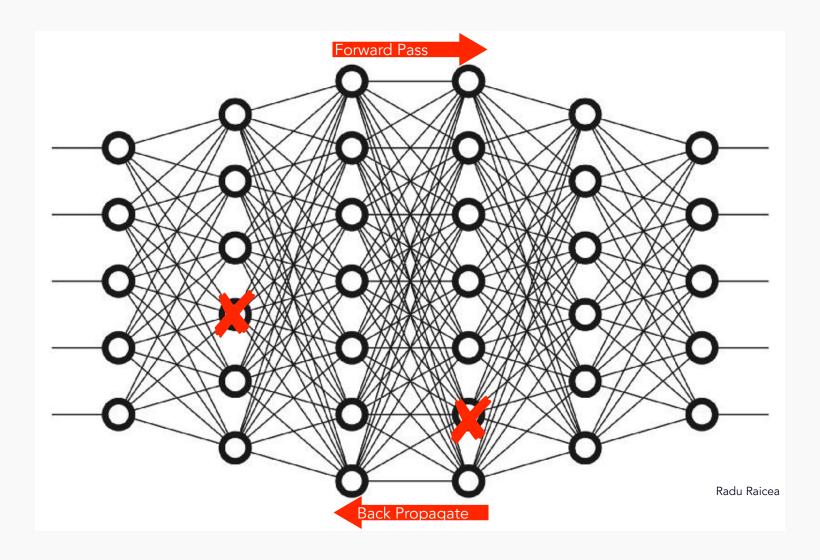




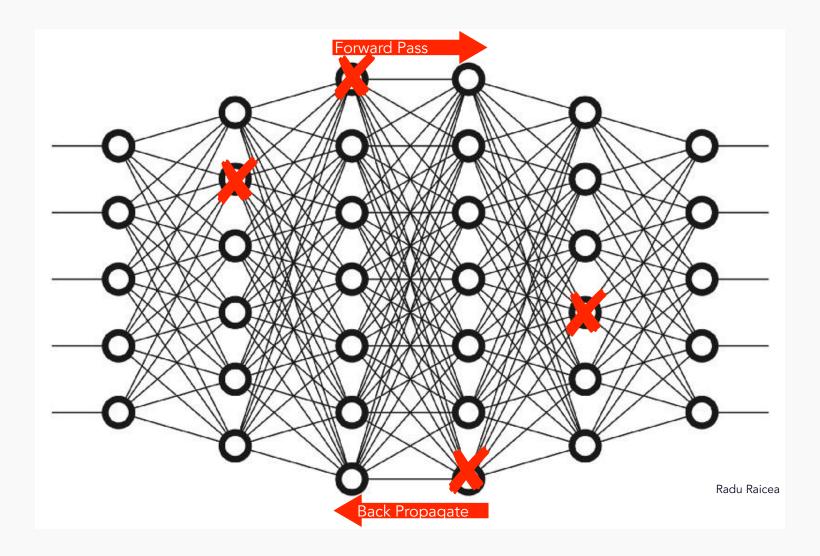




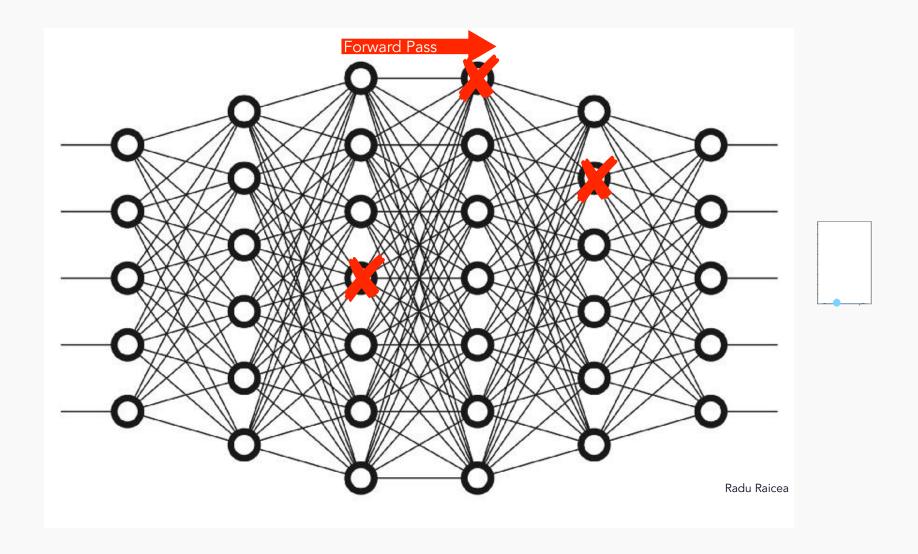




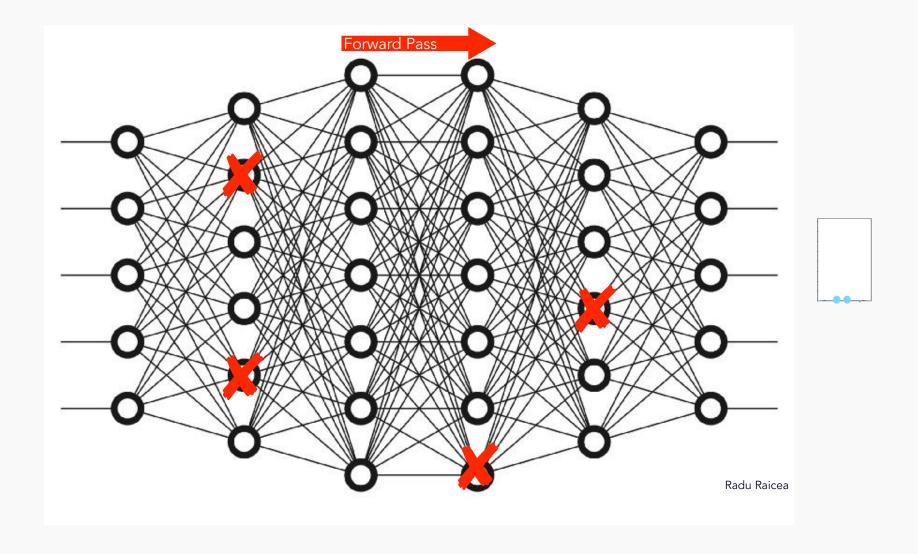




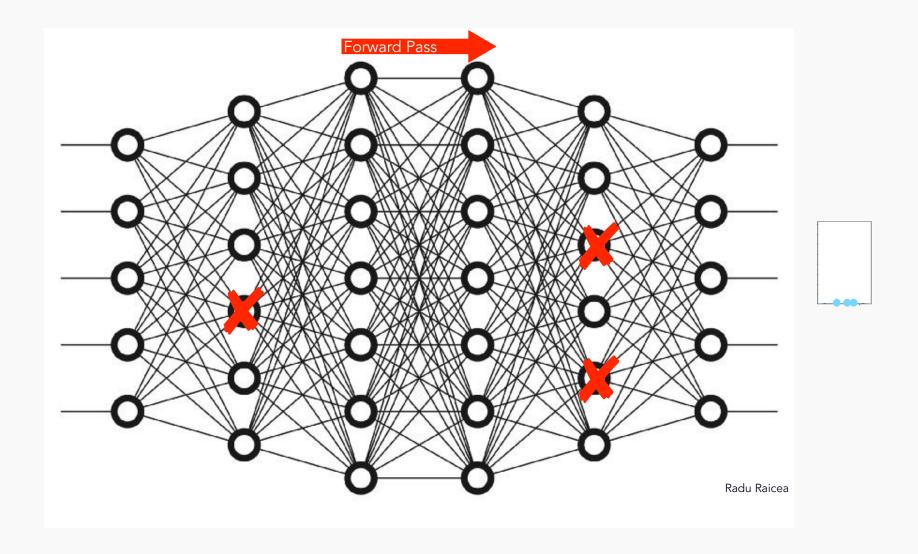




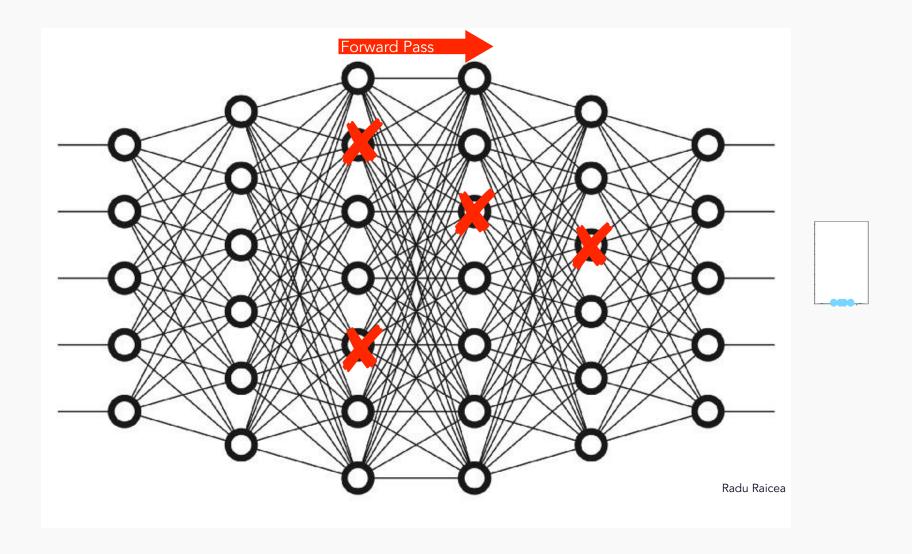




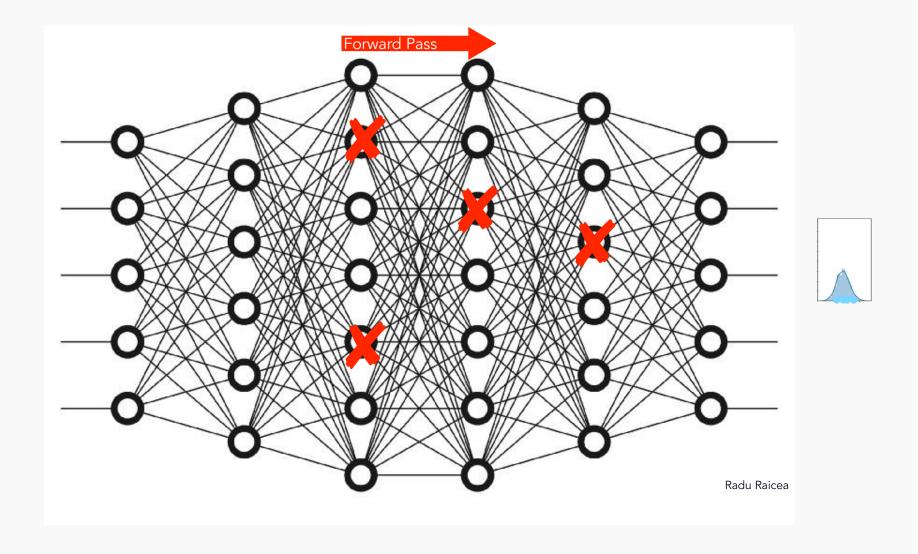




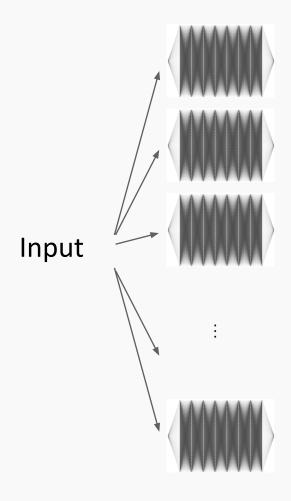




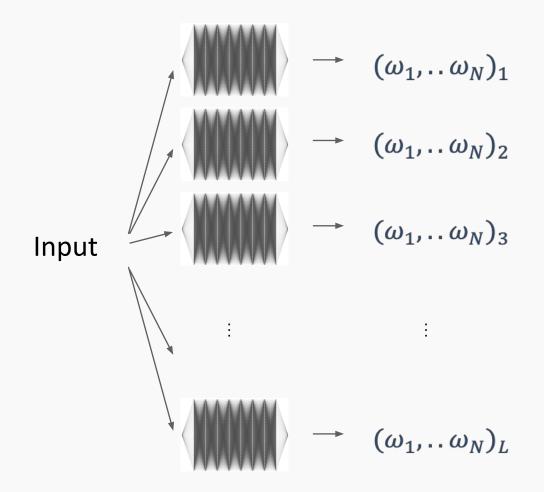




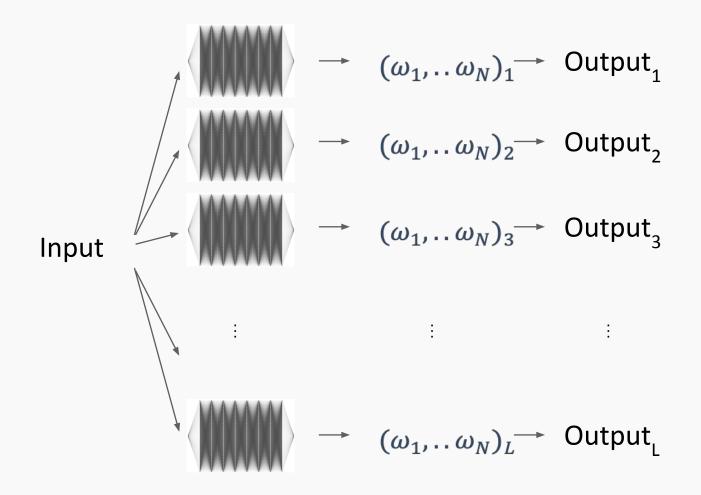




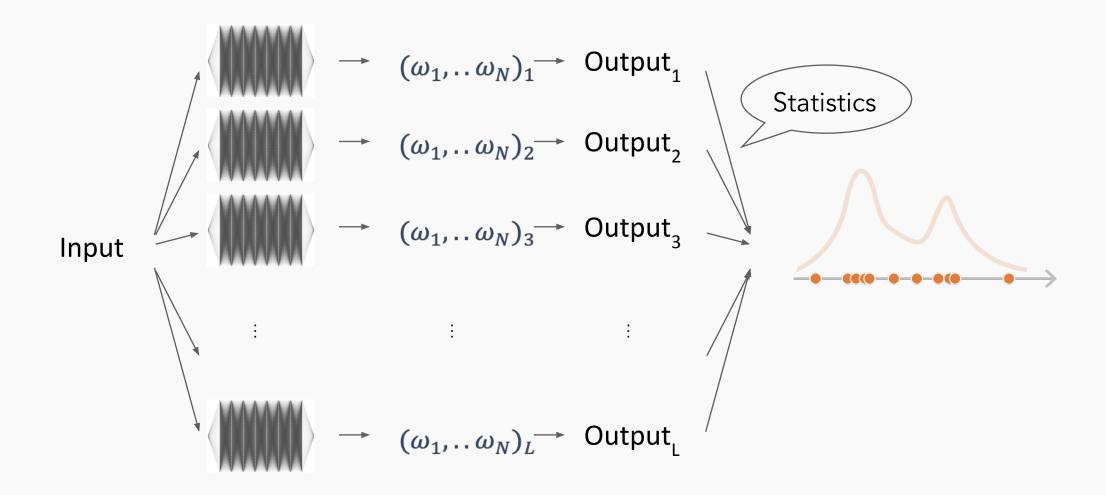




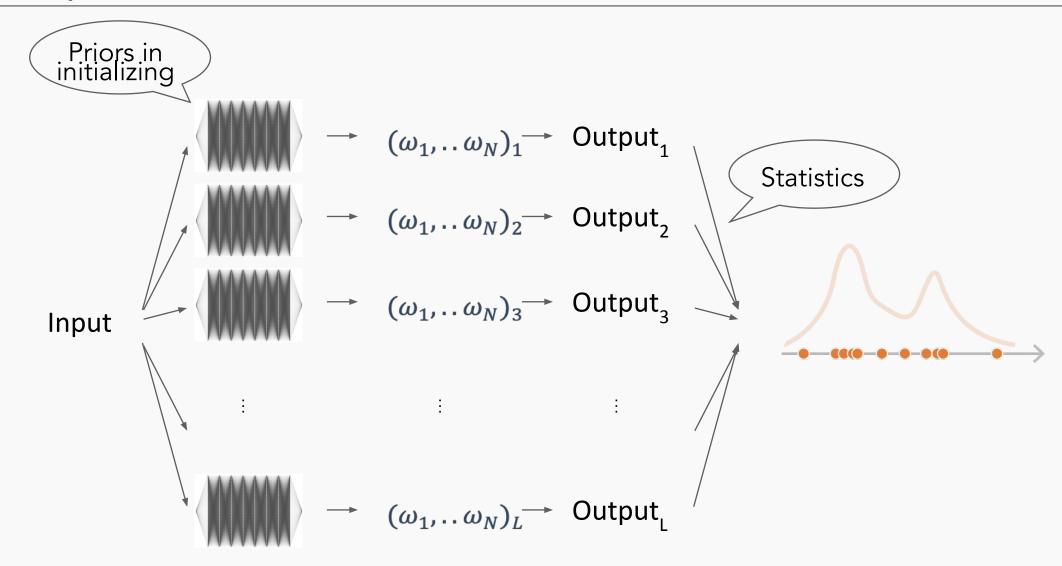






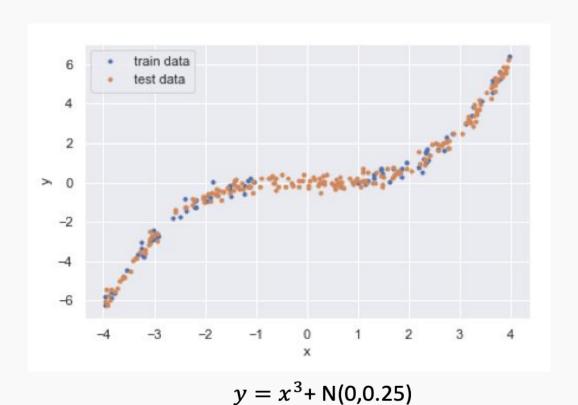






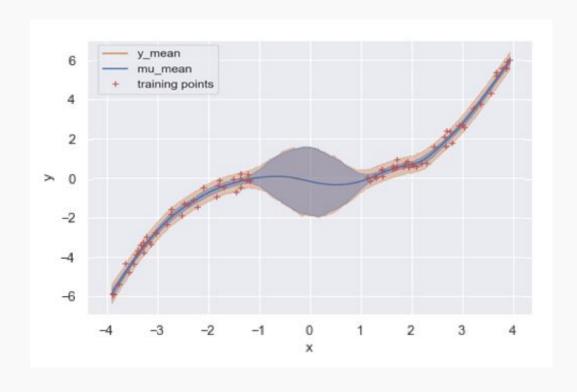


# Variational Bayesian Inference The problem



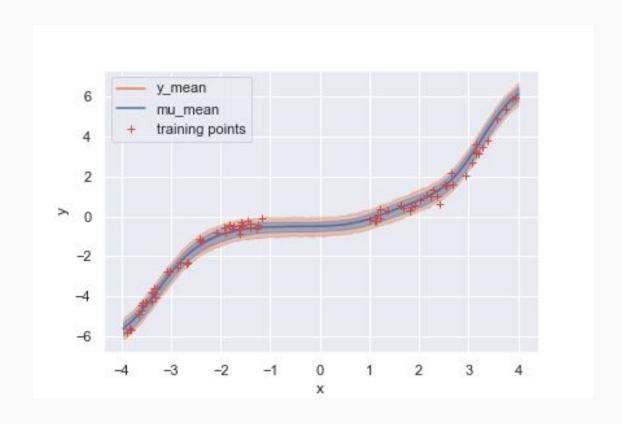


Variational Bayesian Inference The right solution (MCMC)





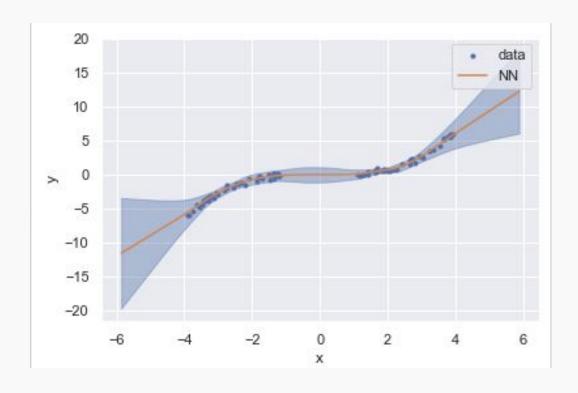
# Variational Bayesian Inference SVI





#### Variational Bayesian Inference Bootstrap

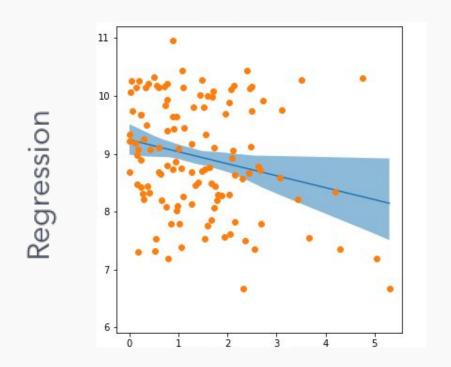
Model Mean 95% models

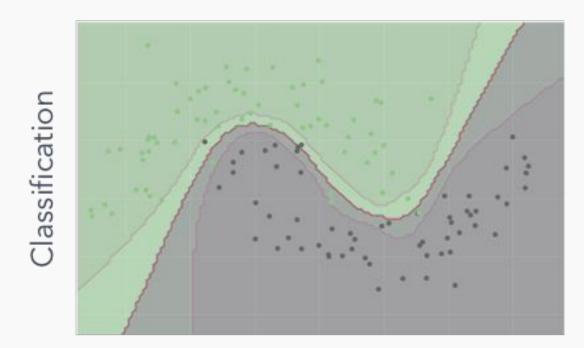




#### Variational Bayesian Inference Bootstrap

Model Mean 95% models



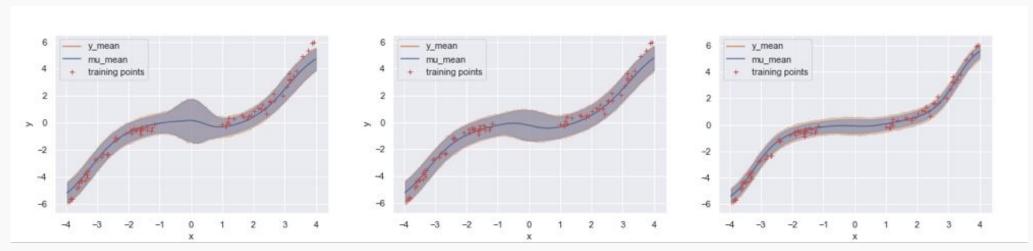


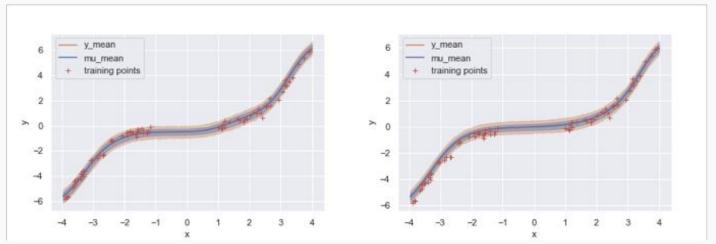


### Extra



# Variational Bayesian Inference SVI







### DONE

