

Interactive Visual Analysis with Dimensionality Reduction

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Visualization

Present

- “*Everything*” known about the data,
- ➡ Visualization used for **Communication** of results

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 - ➡ Visualization used **Verification** or **Falsification**

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- *Nothing* is known
 - ➡ Visualization used for data **Exploration**

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- “Ever”

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Visual Analytics

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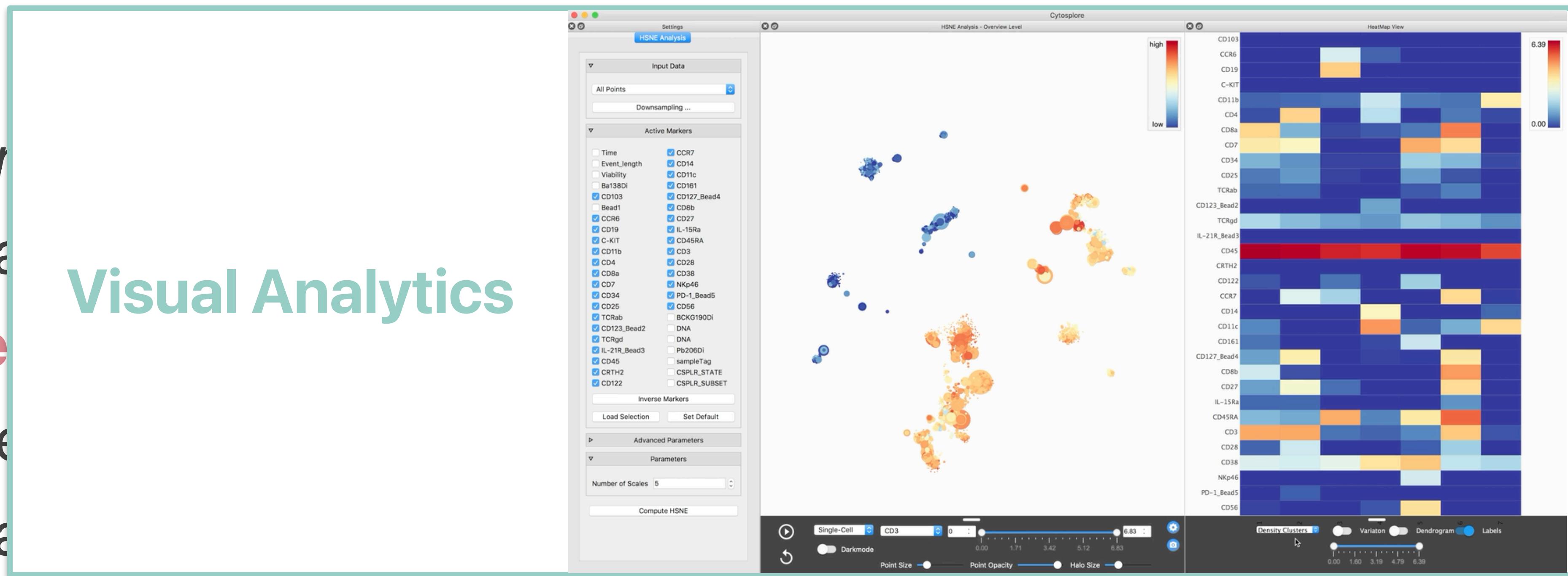
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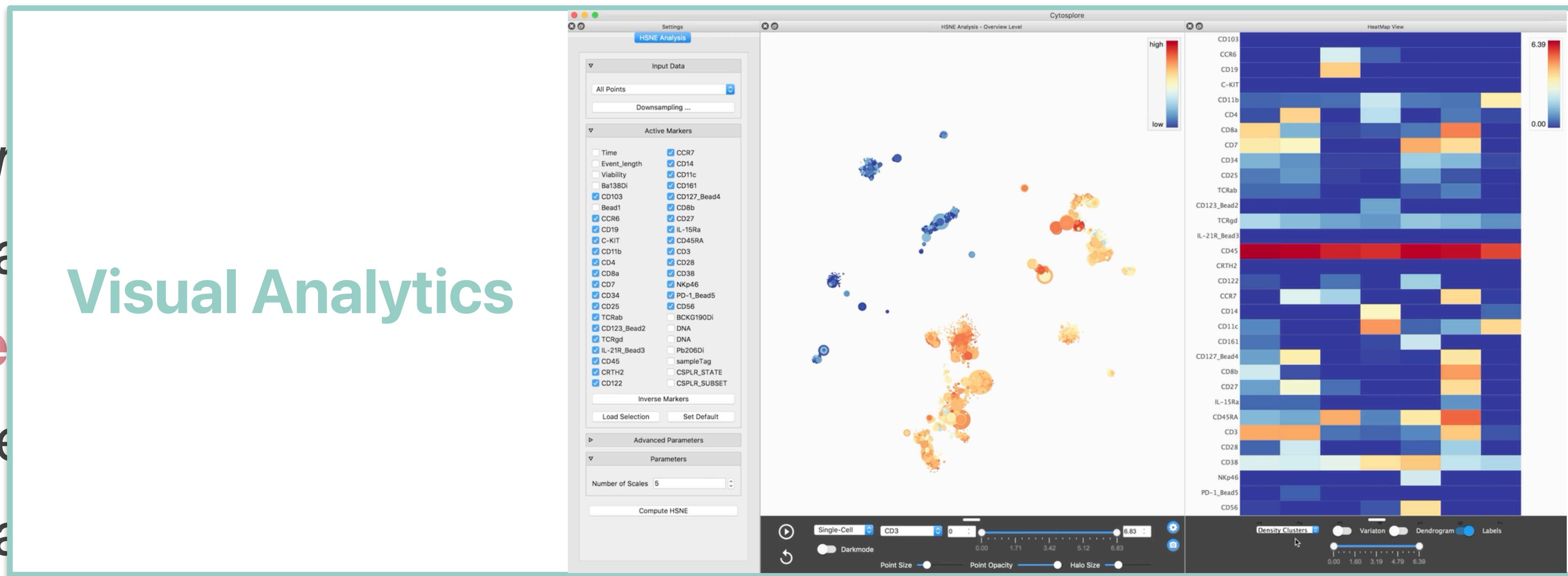
- There

➡ Visual

Explore

- *Nothing* is known

➡ Visualization used for data Exploration



The case for interactive visual analysis

Numbers do not tell the whole story...

A		B		C		D	
x	y	x	y	x	y	x	y
10.0	8.04	10.0	9.14	10.0	7.46	8.0	6.58
8.0	6.95	8.0	8.14	8.0	6.77	8.0	5.76
13.0	7.58	13.0	8.74	13.0	12.74	8.0	7.71
9.0	8.81	9.0	8.77	9.0	7.11	8.0	8.84
11.0	8.33	11.0	9.26	11.0	7.81	8.0	8.47
14.0	9.96	14.0	8.10	14.0	8.84	8.0	7.04
6.0	7.24	6.0	6.13	6.0	6.08	8.0	5.25
4.0	4.26	4.0	3.10	4.0	5.39	19.0	12.50
12.0	10.84	12.0	9.13	12.0	8.15	8.0	5.56
7.0	4.82	7.0	7.26	7.0	6.42	8.0	7.91
5.0	5.68	5.0	4.74	5.0	5.73	8.0	6.89

Statistics:

Mean(x):

Variance(x):

Mean(y):

Variance(y):

Correlation(x,y):

Anscombe's Quartet

Numbers do not tell the whole story...

A		B		C		D	
x	y	x	y	x	y	x	y
10.0	8.04	10.0	9.14	10.0	7.46	8.0	6.58
8.0	6.95	8.0	8.14	8.0	6.77	8.0	5.76
13.0	7.58	13.0	8.74	13.0	12.74	8.0	7.71
9.0	8.81	9.0	8.77	9.0	7.11	8.0	8.84
11.0	8.33	11.0	9.26	11.0	7.81	8.0	8.47
14.0	9.96	14.0	8.10	14.0	8.84	8.0	7.04
6.0	7.24	6.0	6.13	6.0	6.08	8.0	5.25
4.0	4.26	4.0	3.10	4.0	5.39	19.0	12.50
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Statistics:

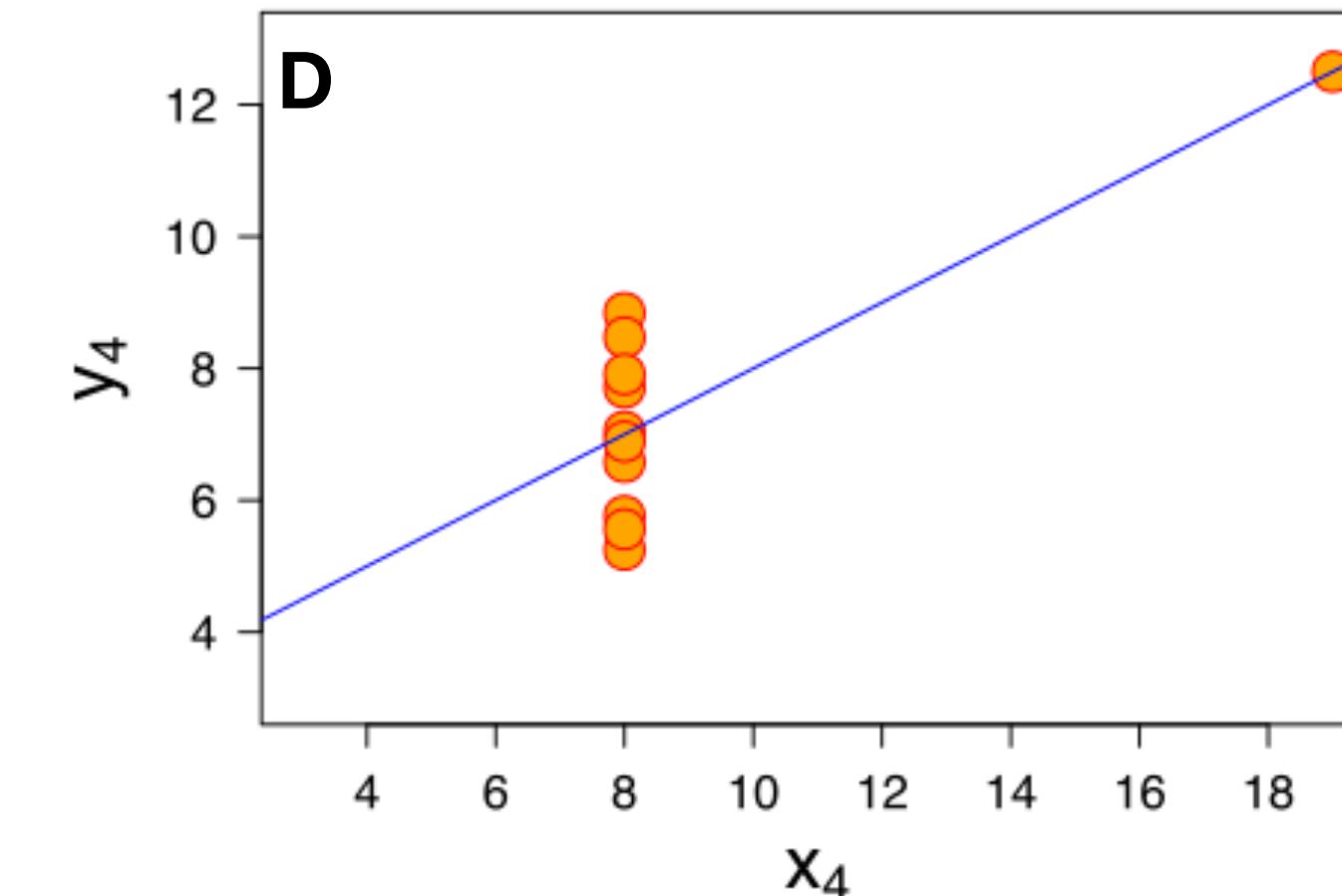
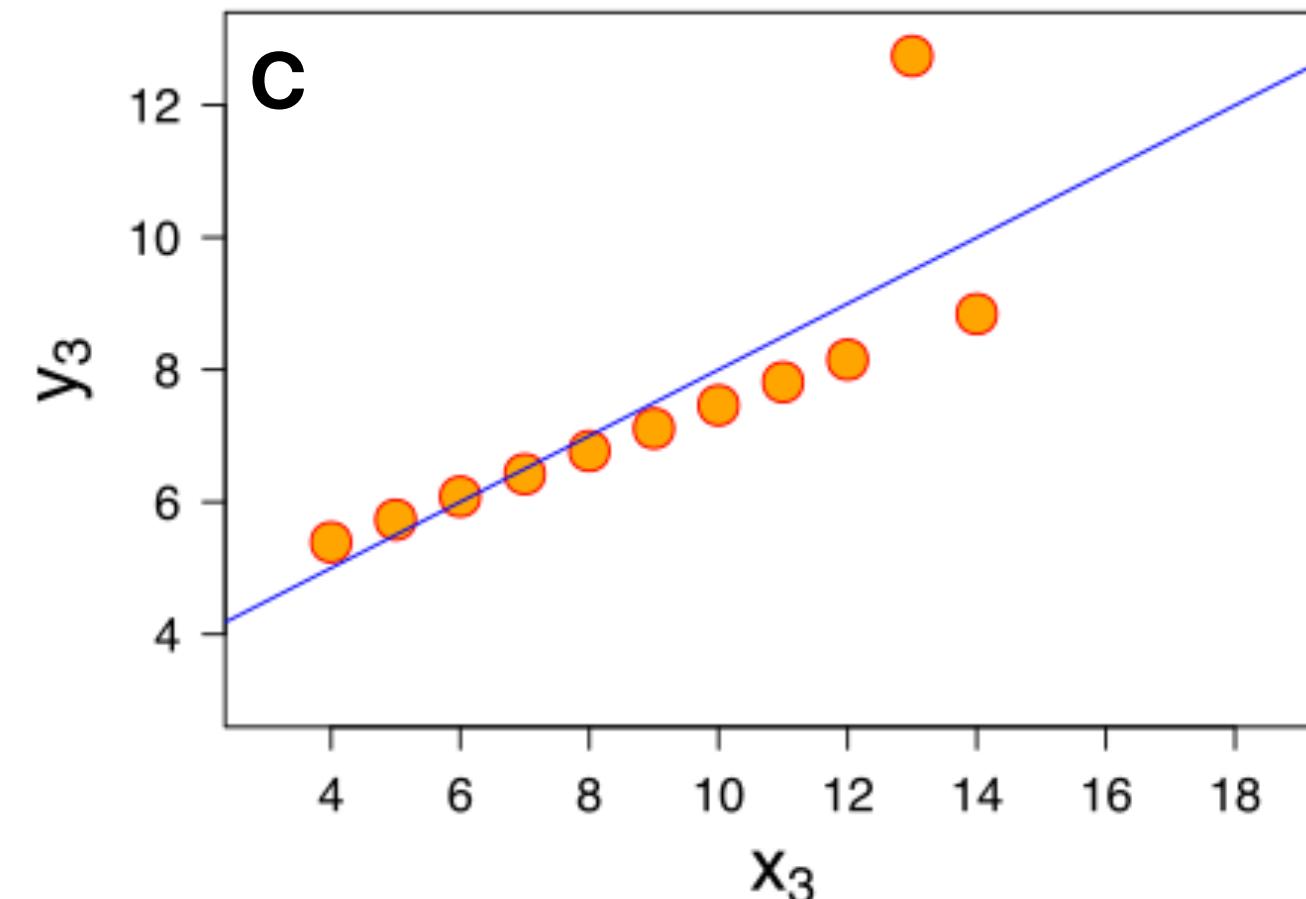
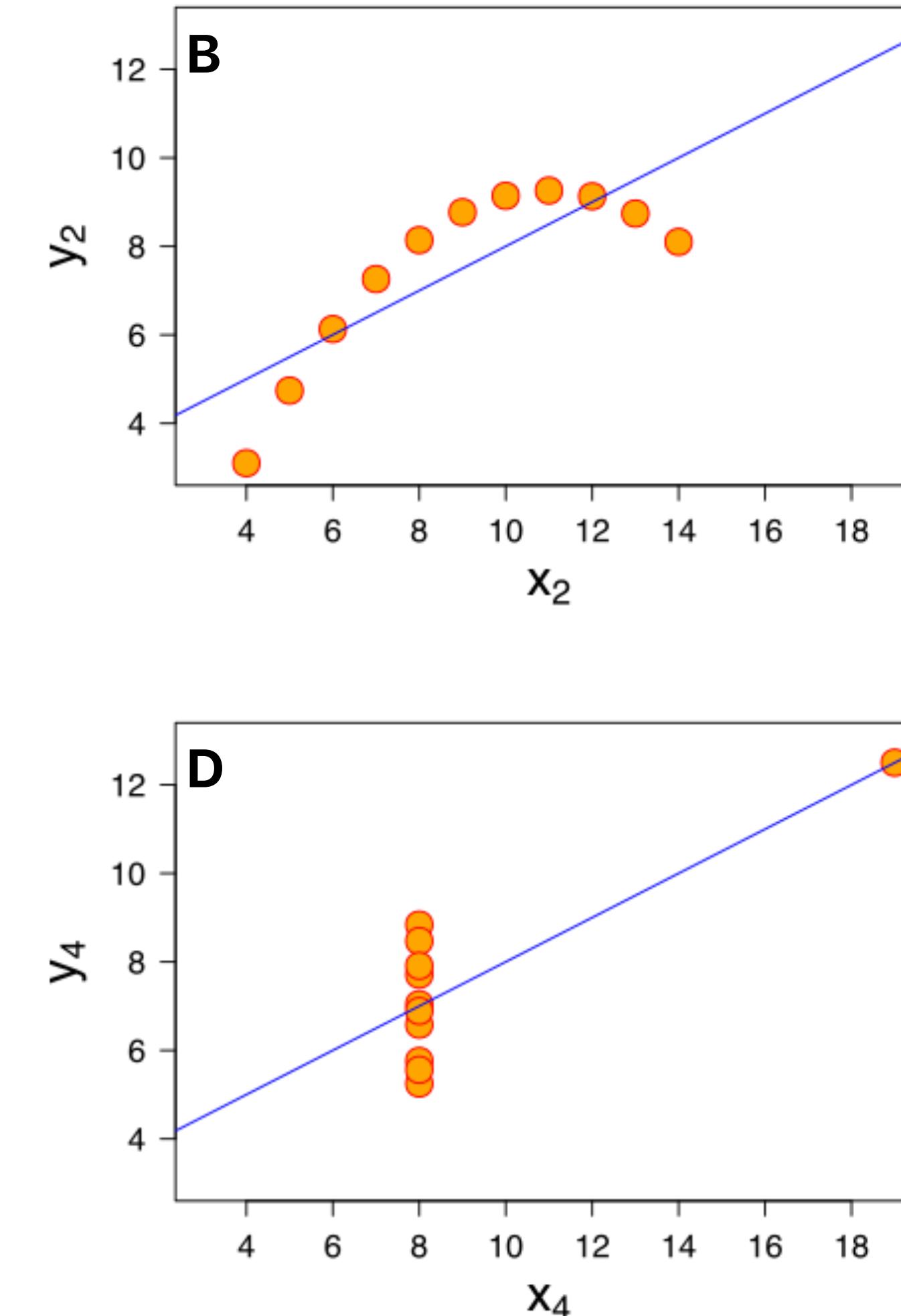
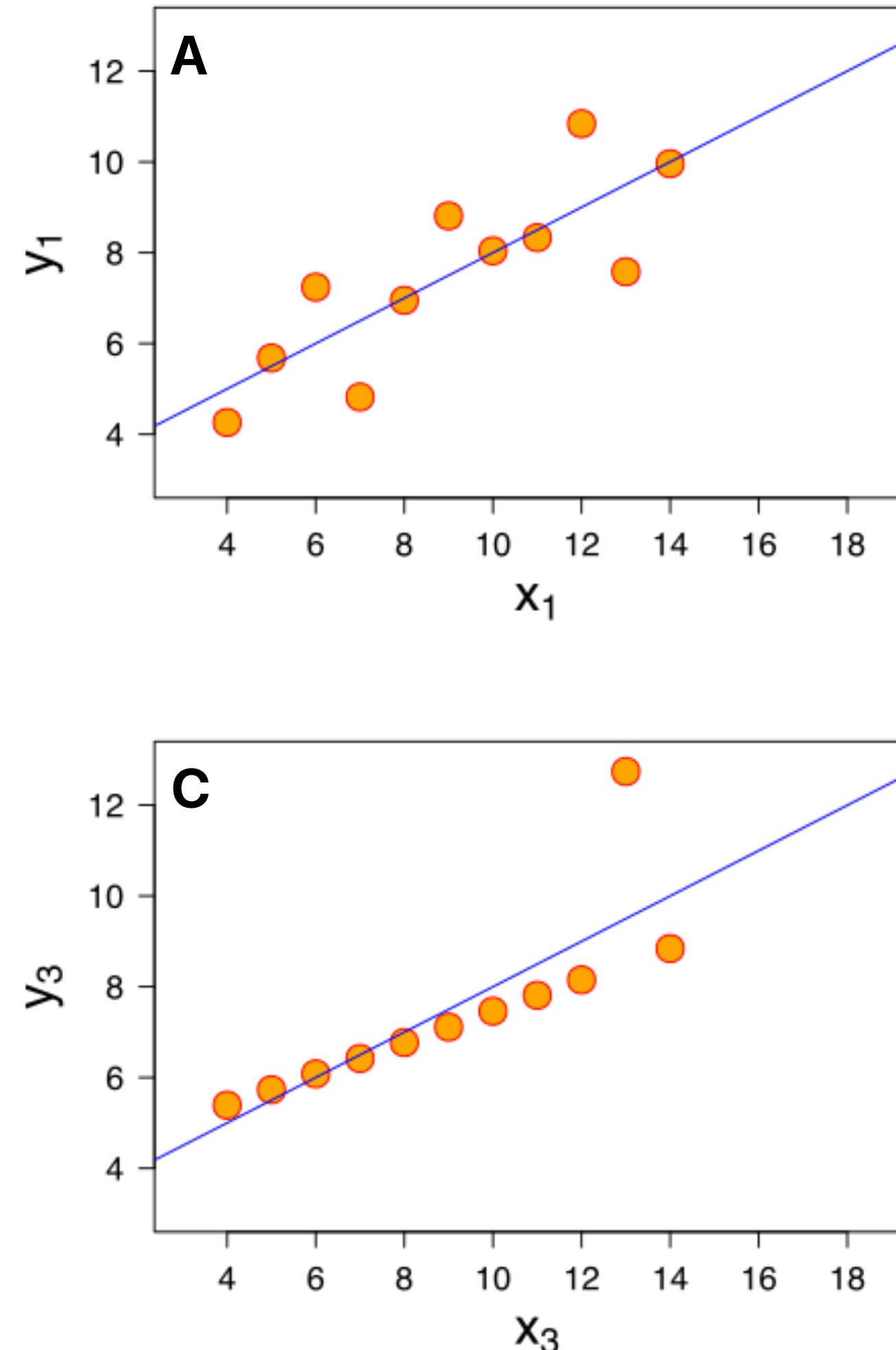
- Mean(x): $A=B=C=D=9$ exact
- Variance(x): $A=B=C=D=11$ exact
- Mean(y): $A=B=C=D=7.50$ (2 decimals)
- Variance(y): $A=B=C=D=4.125$ (+/- 0.003)
- Correlation(x,y): $A=B=C=D=816$ (3 decimals)

Anscombe's Quartet

Numbers do not tell the whole story...

A		B		C		D	
x	y	x	y	x	y	x	y
10.0	8.04	10.0	9.14	10.0	7.46	8.0	6.58
8.0	6.95	8.0	8.14	8.0	6.77	8.0	5.76
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11.0	8.33	11.0	9.26	11.0	7.81	8.0	8.47
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Anscombe's Quartet



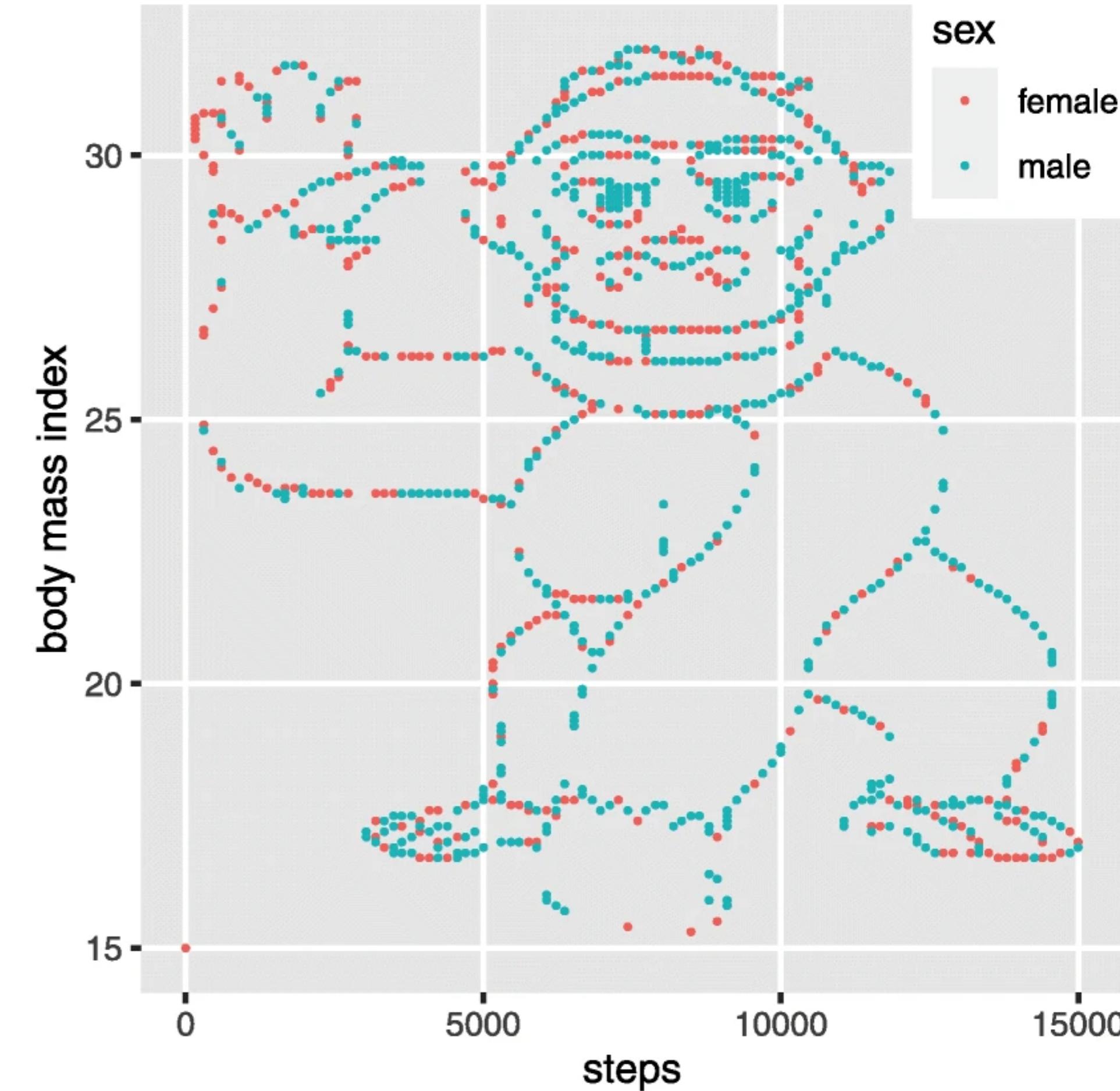
Do we look for the whole story?

ID	steps	bmi
3	15000	17.0
4	14861	17.2
5		
9		
ID	steps	bmi
1	15000	16.9
2	15000	16.9
6	14861	16.8
7	14861	16.8
8	14699	17.3
10	14560	20.5
11	14560	20.6
13	14560	20.5
17	14560	20.4
18	14560	20.4
19	14560	19.8
20	14560	19.7
22	14560	19.7
24	14560	19.6
25	14560	19.6
27	14560	19.6
29	14560	17.4
30	14560	17.4
32	14398	20.9
37	14398	17.5
40	14398	17.1
42	14259	21.1
43	14259	21.1
44	14259	21.1

Do we look for the whole story?

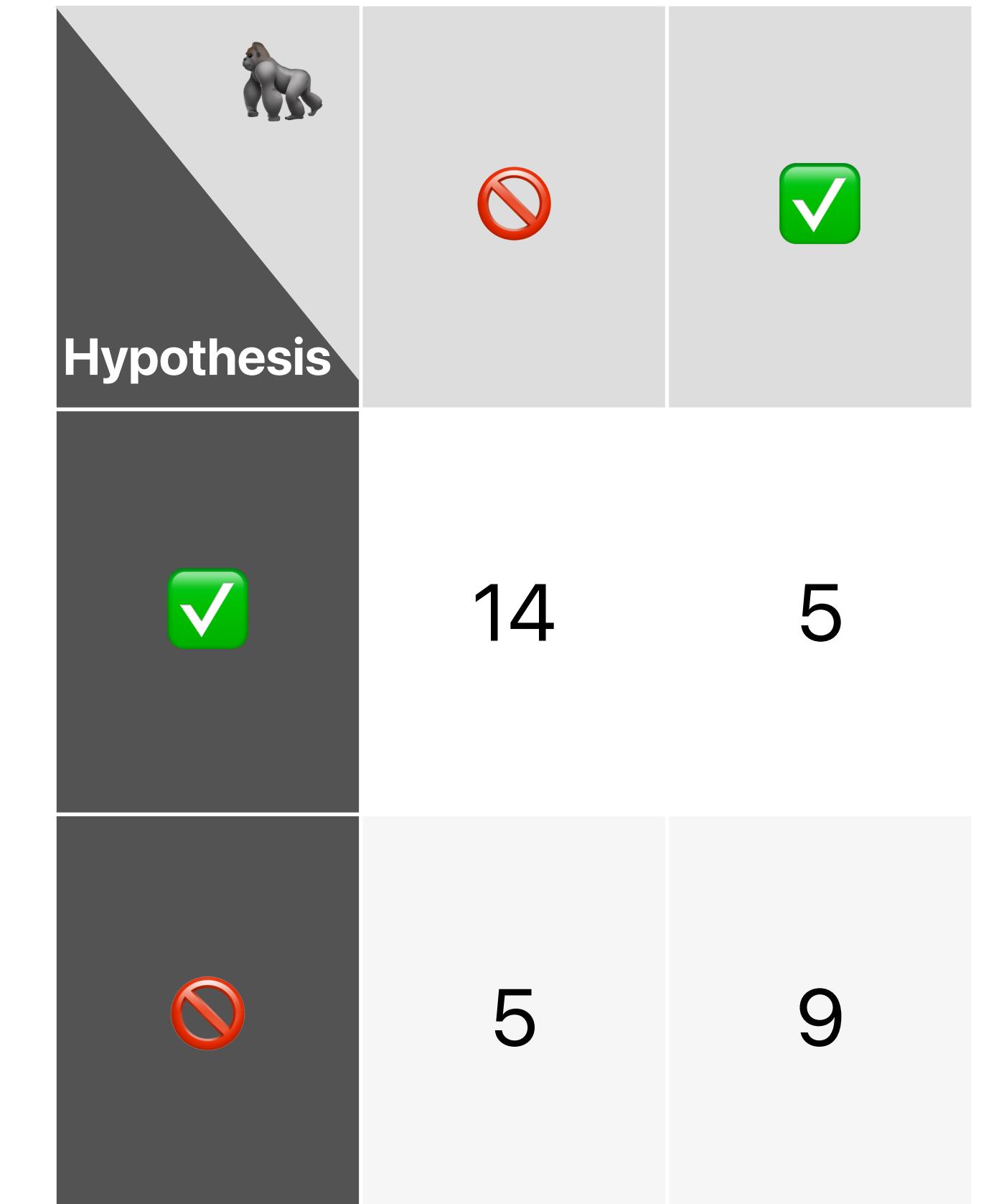
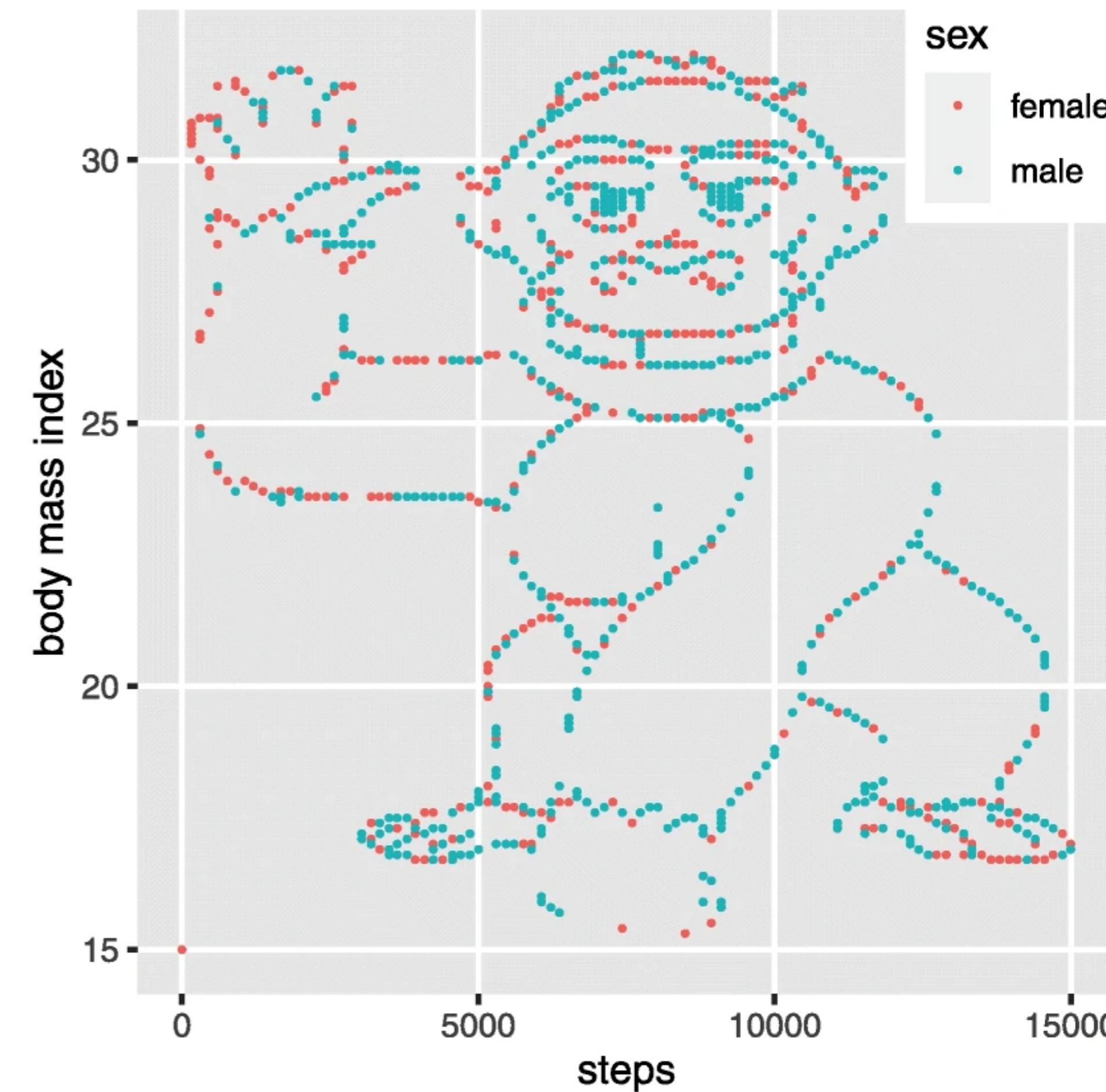
ID	steps	bmi
3	15000	17.0
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ID	steps	bmi
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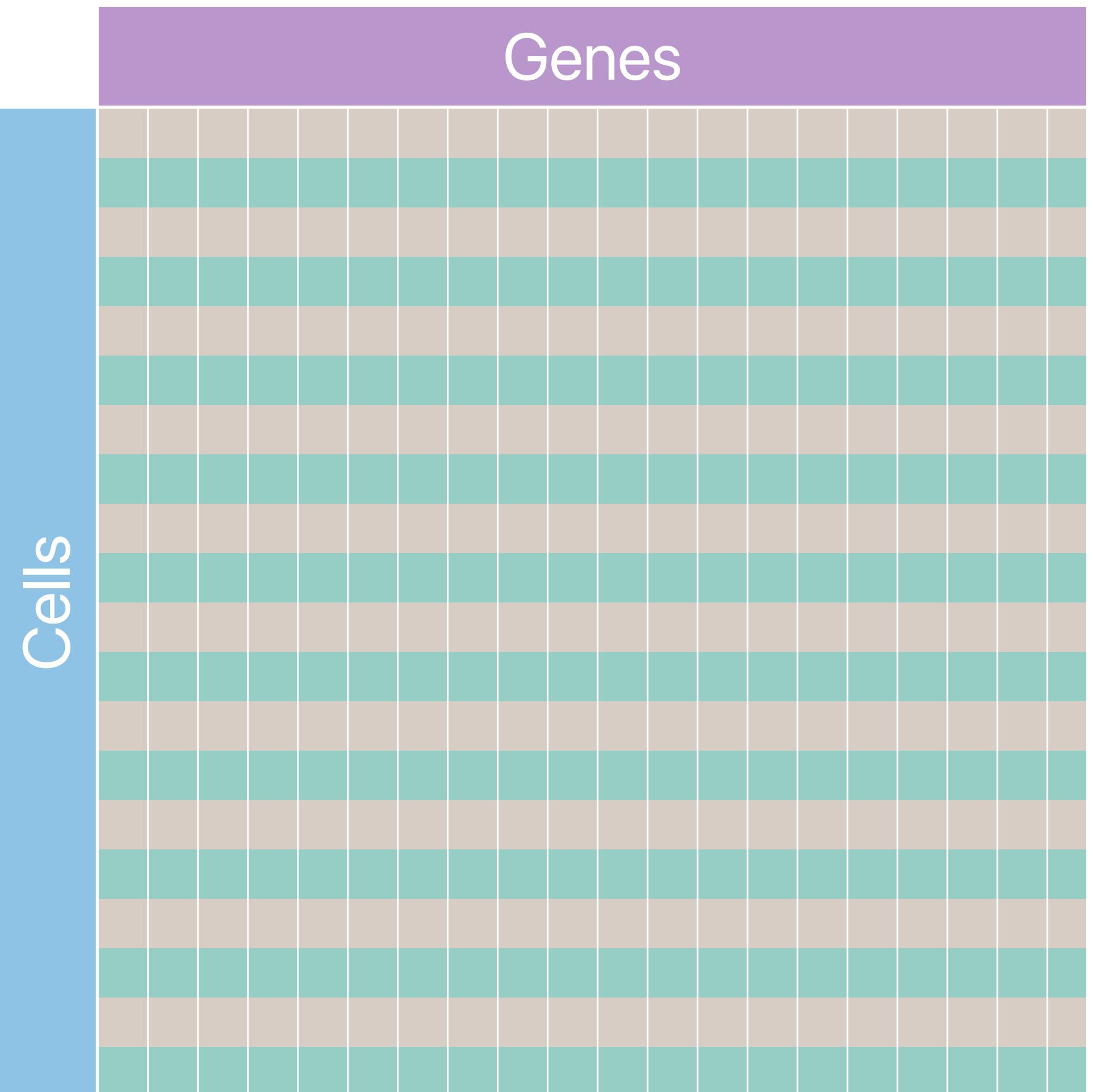
ID	steps	bmi	
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4	14861	17.2	
5			
9			
12			
14			
15	1	15000	16.9
16	2	15000	16.9
21	6	14861	16.8
23	7	14861	16.8
26	8	14699	17.3
28	10	14560	20.5
31	11	14560	20.6
33	13	14560	20.5
34	17	14560	20.4
35	18	14560	20.4
36	19	14560	19.8
38	20	14560	19.7
39	22	14560	19.7
41	24	14560	19.6
44	25	14560	19.6
45	27	14560	19.6
<	29	14560	17.4
30	30	14560	17.4
32	32	14398	20.9
37	37	14398	17.5
40	40	14398	17.1
42	42	14259	21.1
43	43	14259	21.1
>	44	14259	19.0



Single-Cell Visualization

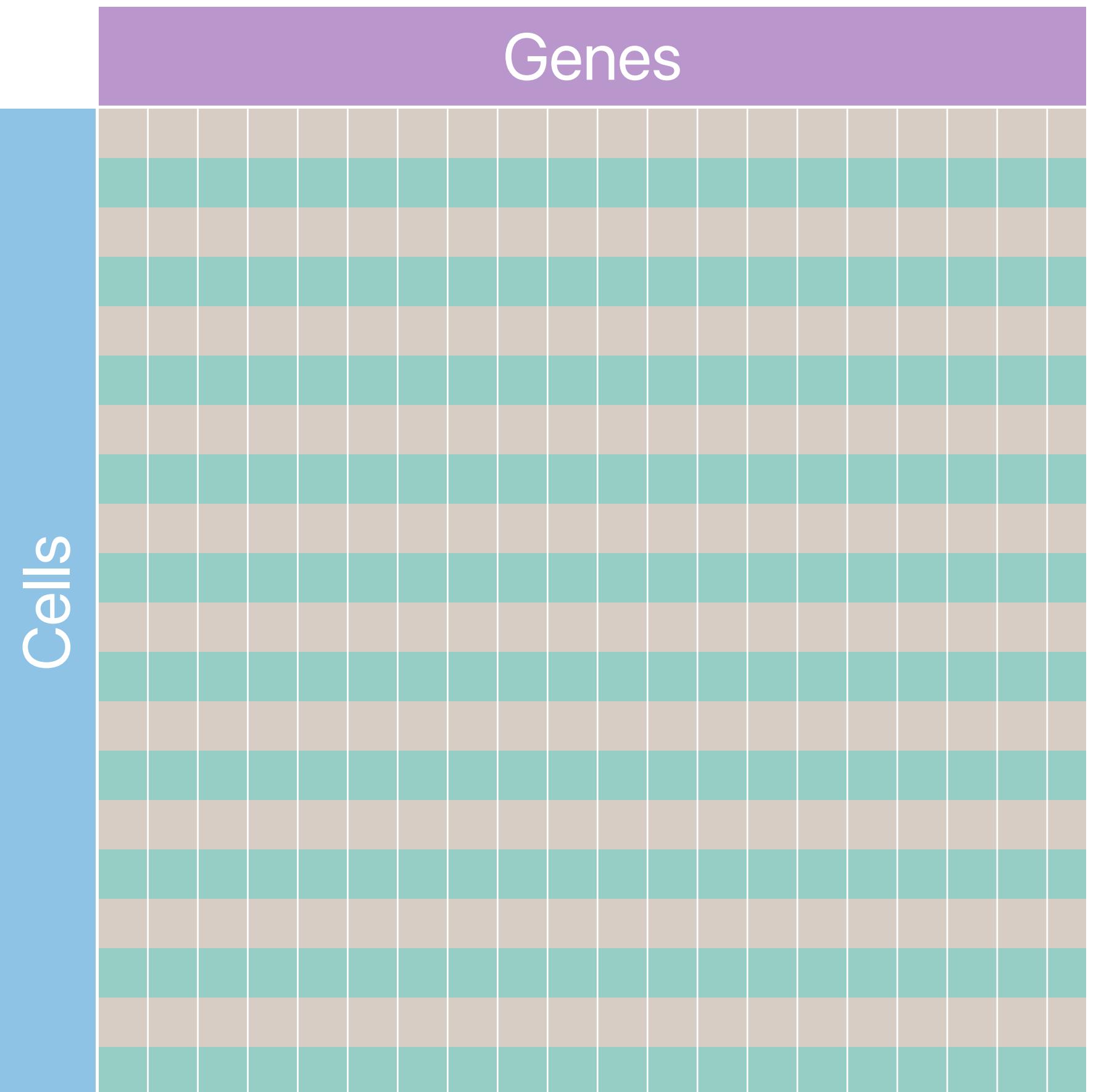
Dimensionality Reduction?

- We have huge amounts of complex data
(many cells x many genes)
- We want to reduce complexity for analysis
 - Clustering
 - Dimensionality Reduction



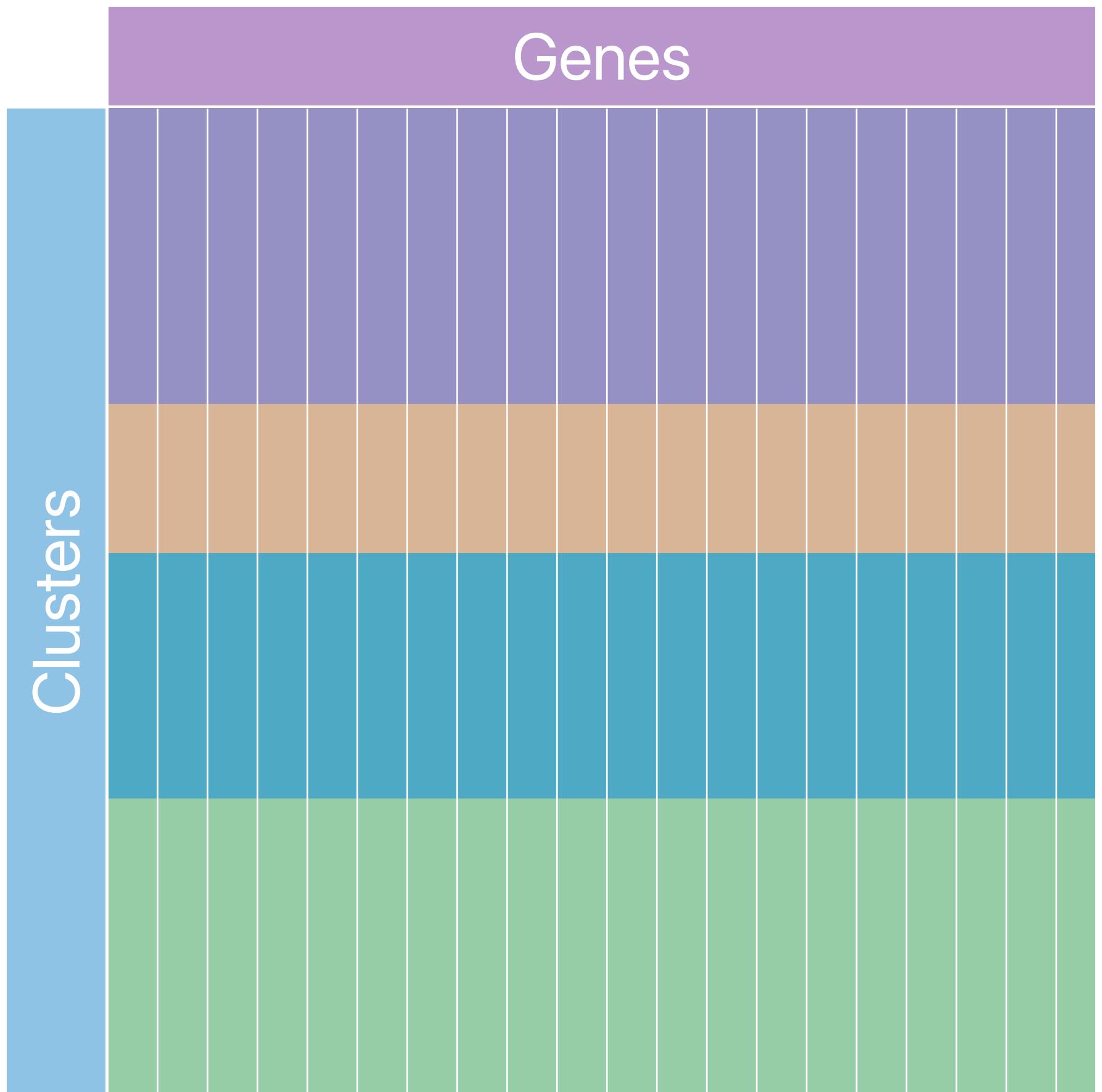
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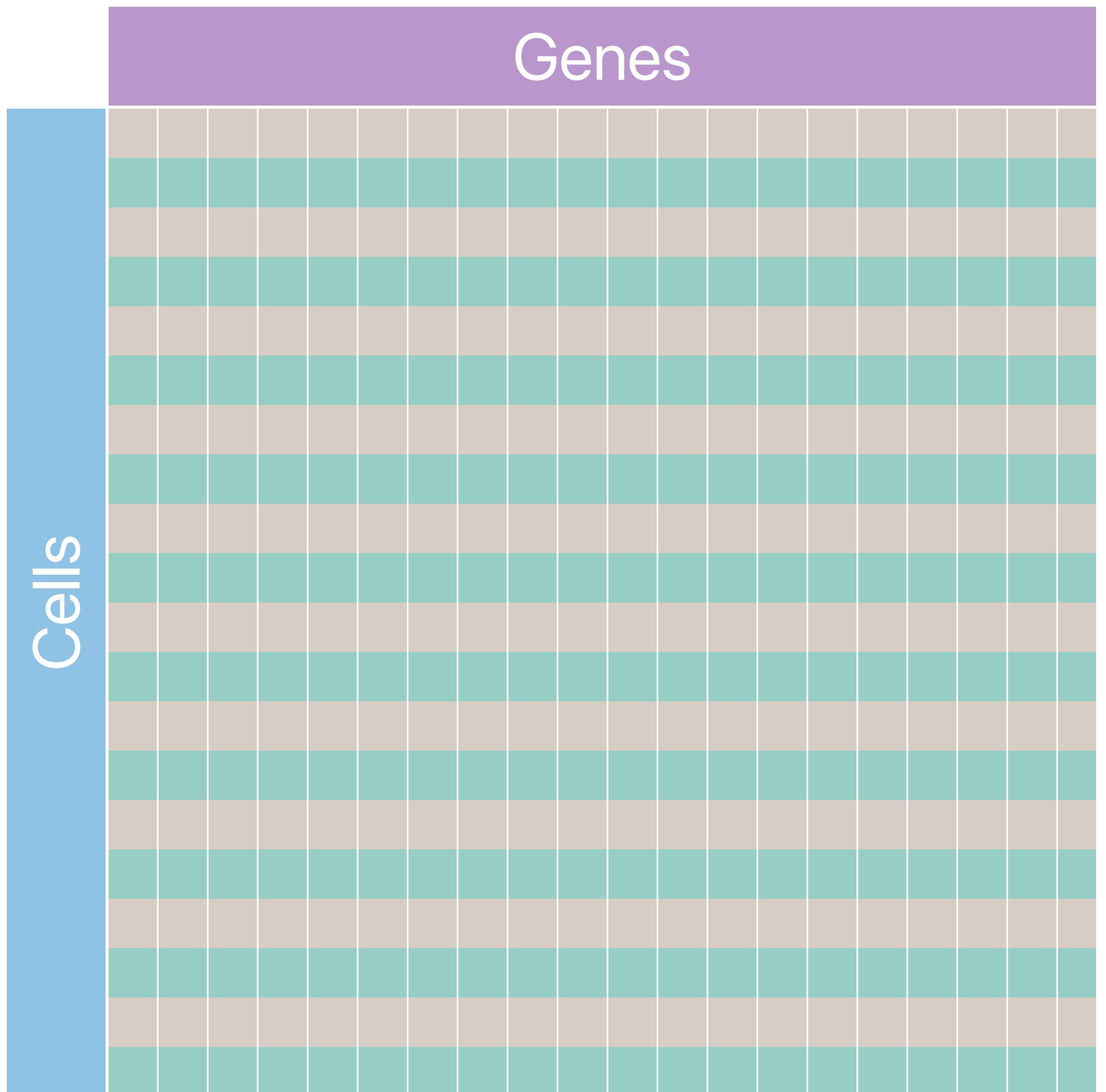
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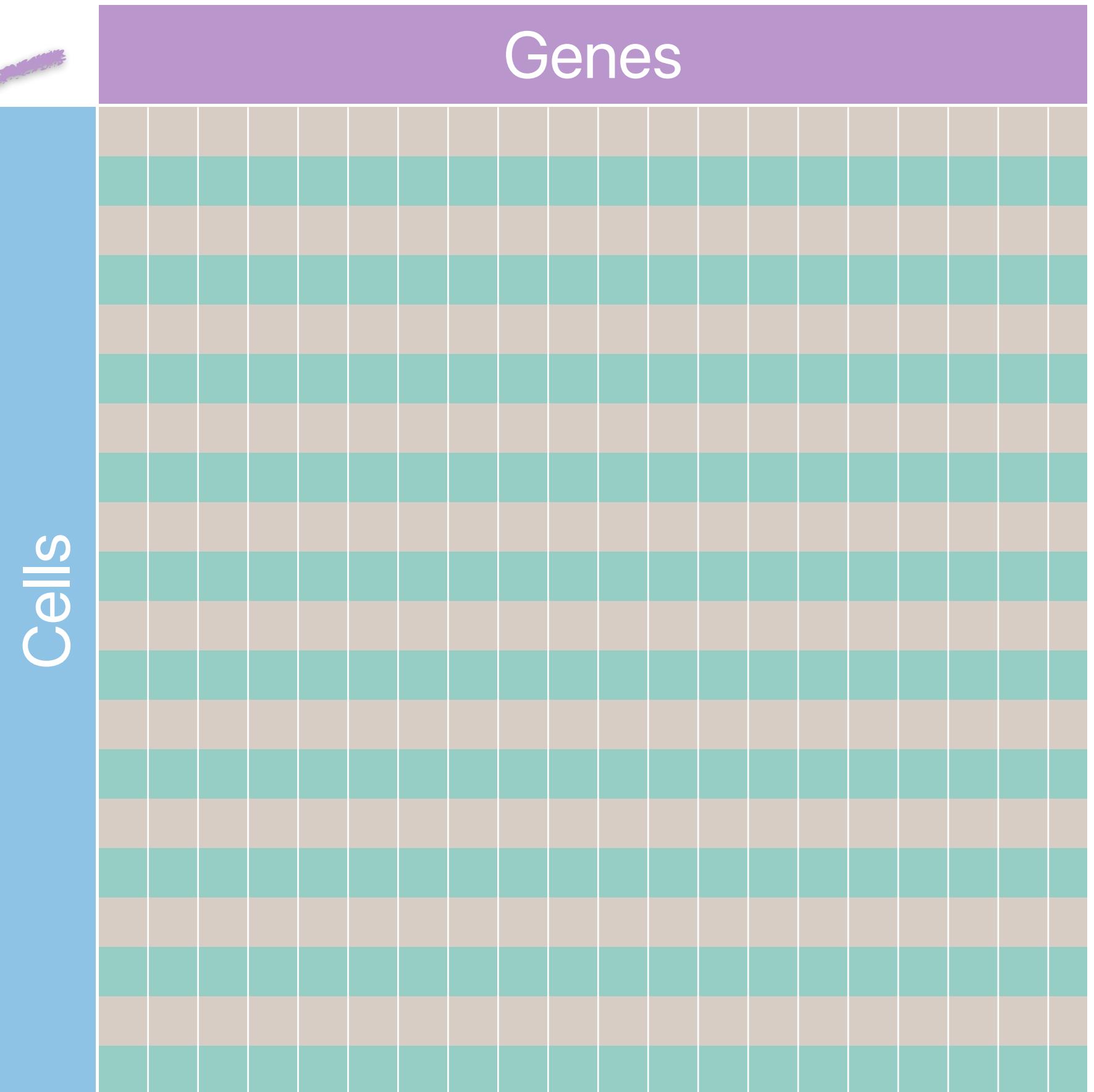
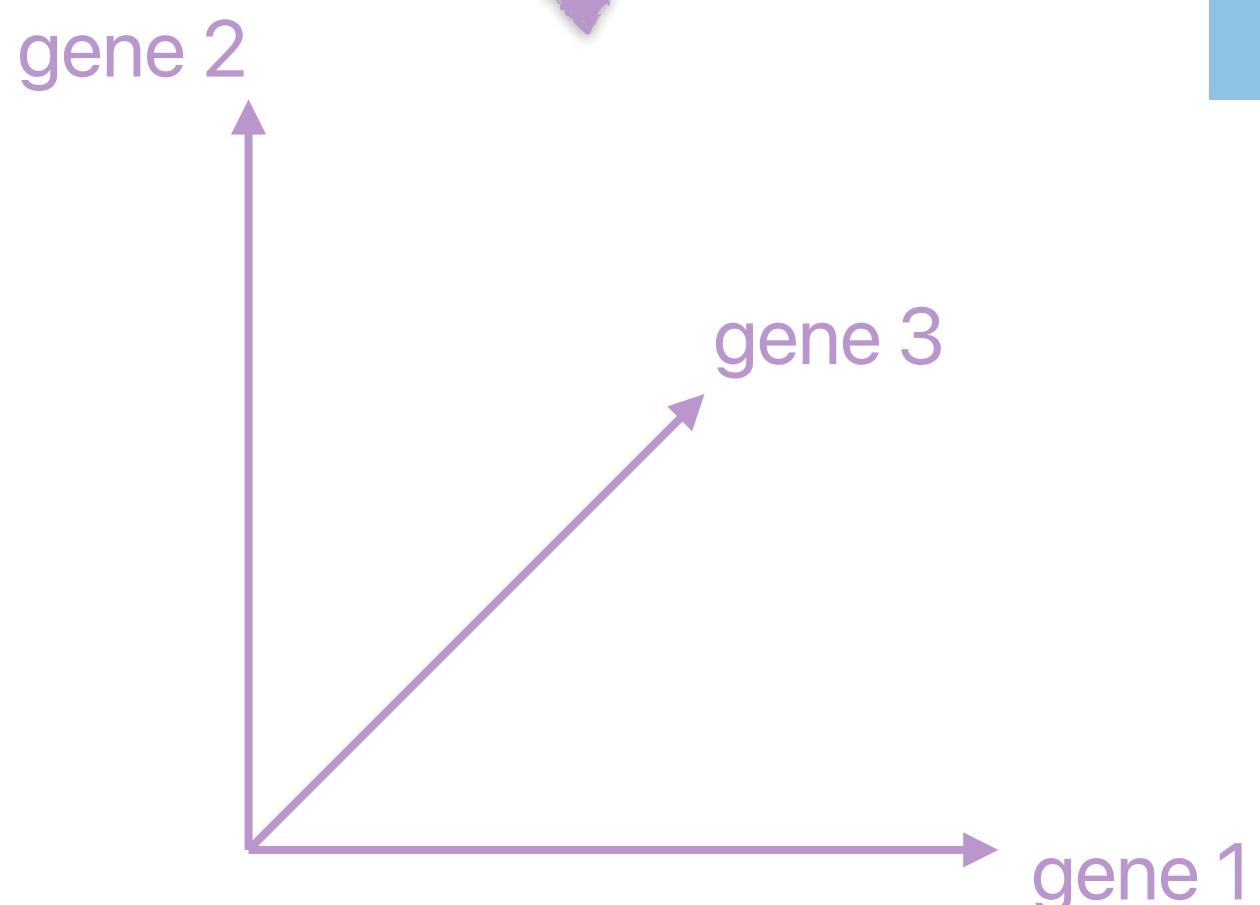
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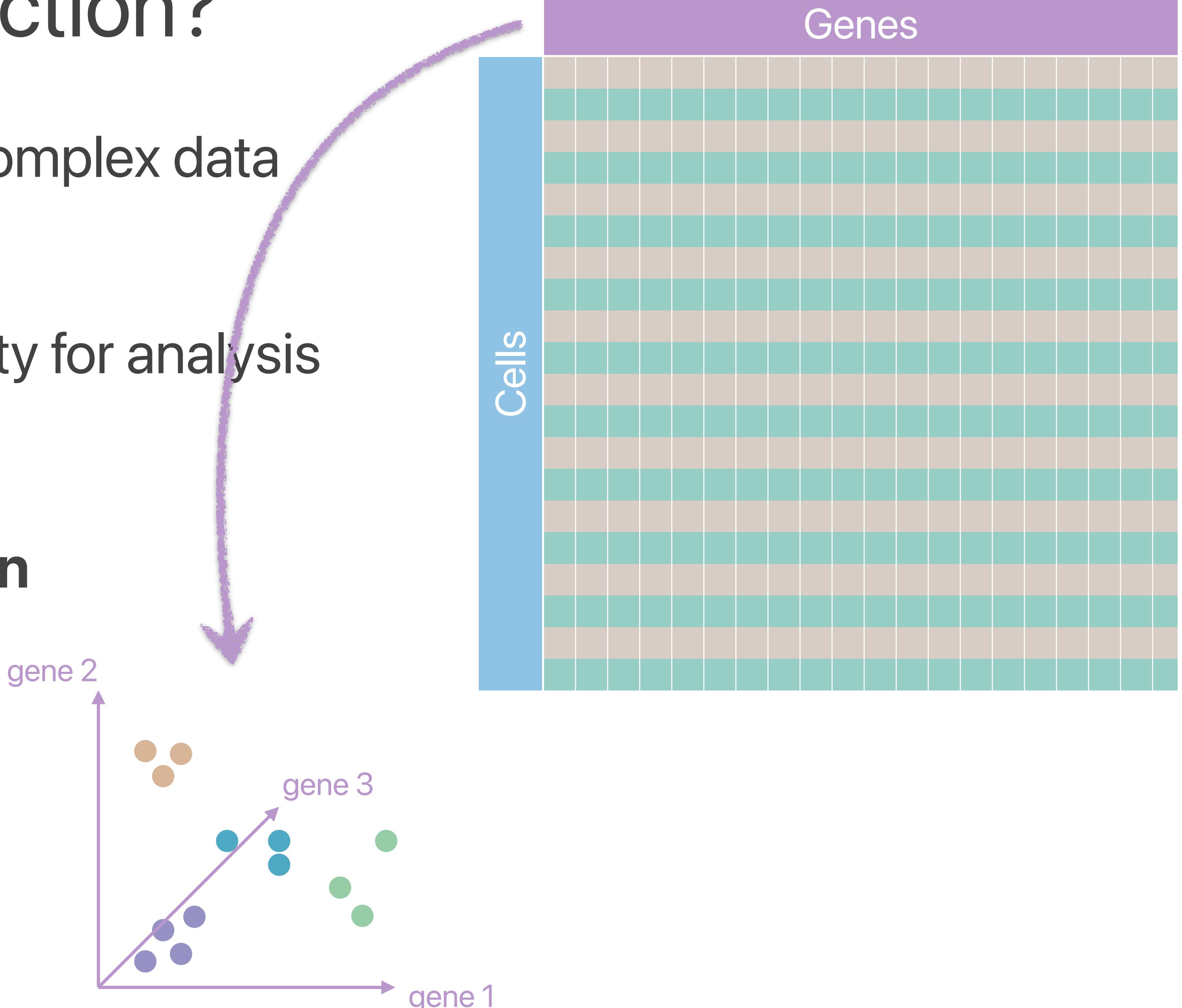
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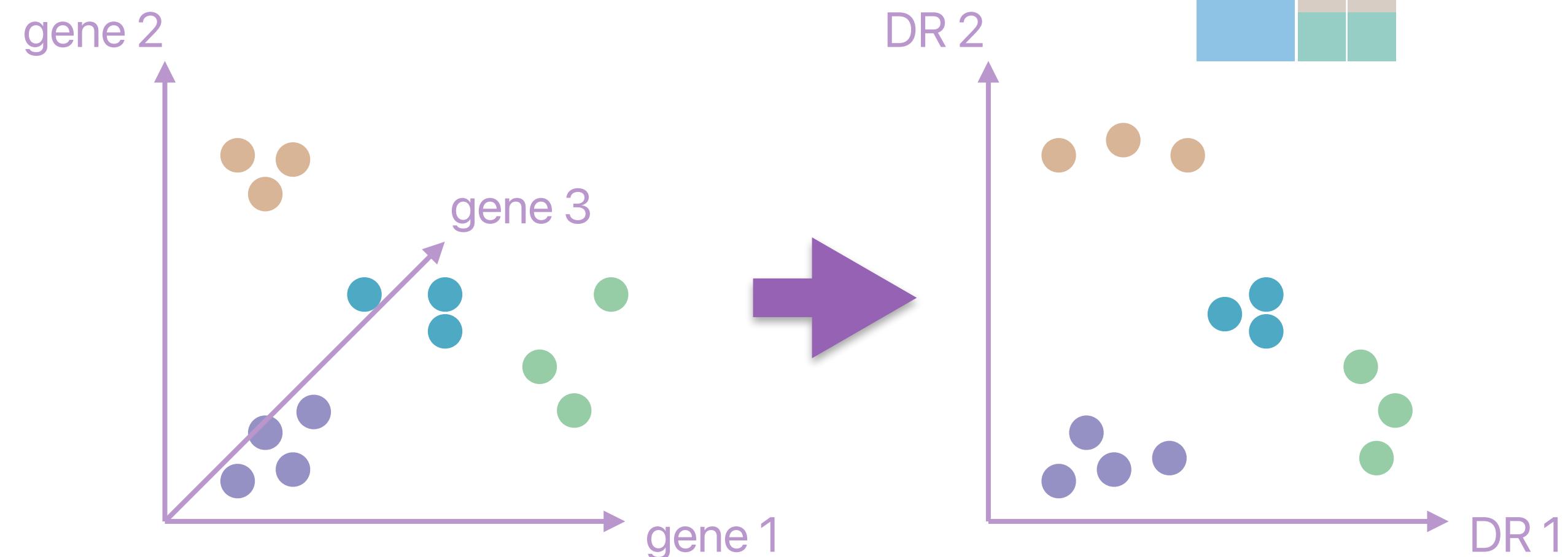
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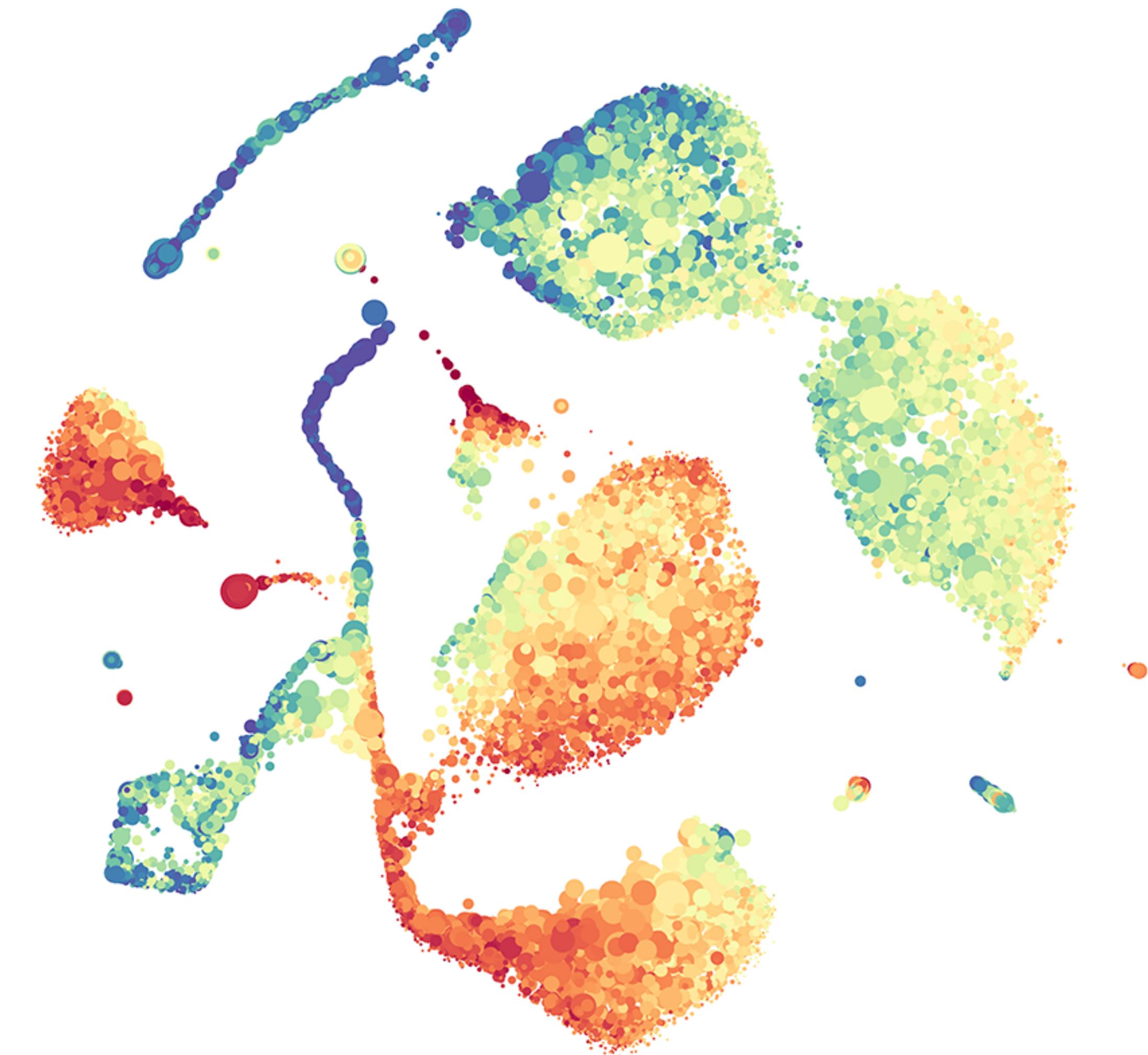
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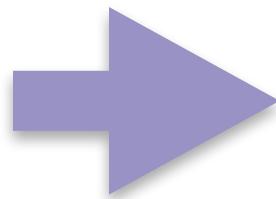


Why Visualization for Data Exploration?

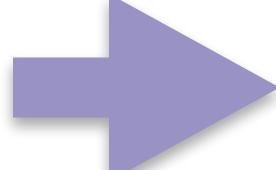
- Can't machines do (learn) that?
- Machine learning is great for
 - Well defined problems
 - Verifying Hypothesis
- ML not so great for
 - Finding the unknown
 - Fuzzy problems
 - Hypothesis generation



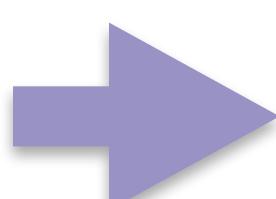
Algorithms



PCA	linear	Matrix Factorization	
ICA	linear	Matrix Factorization	
MDS	non-linear	Matrix Factorization	
cPCA	non-linear	Matrix Factorization	https://doi.org/10.1038/s41467-018-04608-8
ZIFA	non-linear	Matrix Factorization	https://doi.org/10.1186/s13059-015-0805-z
ZINB-WaVE	non-linear	Matrix Factorization	https://doi.org/10.1038/s41467-017-02554-5



Diffusion maps	non-linear	Graph-based	https://doi.org/10.1073/pnas.0500334102
Isomap	non-linear	Graph-based	https://doi.org/10.1126/science.290.5500.2319
t-SNE	non-linear	Graph-based	https://lvdmaaten.github.io/publications/papers/JMLR_2008.pdf
HSNE	non-linear	Graph, hierarchical	https://dx.doi.org/10.1038/s41467-017-01689-9
LargeVis	non-linear	Graph-based	arXiv:1602.00370



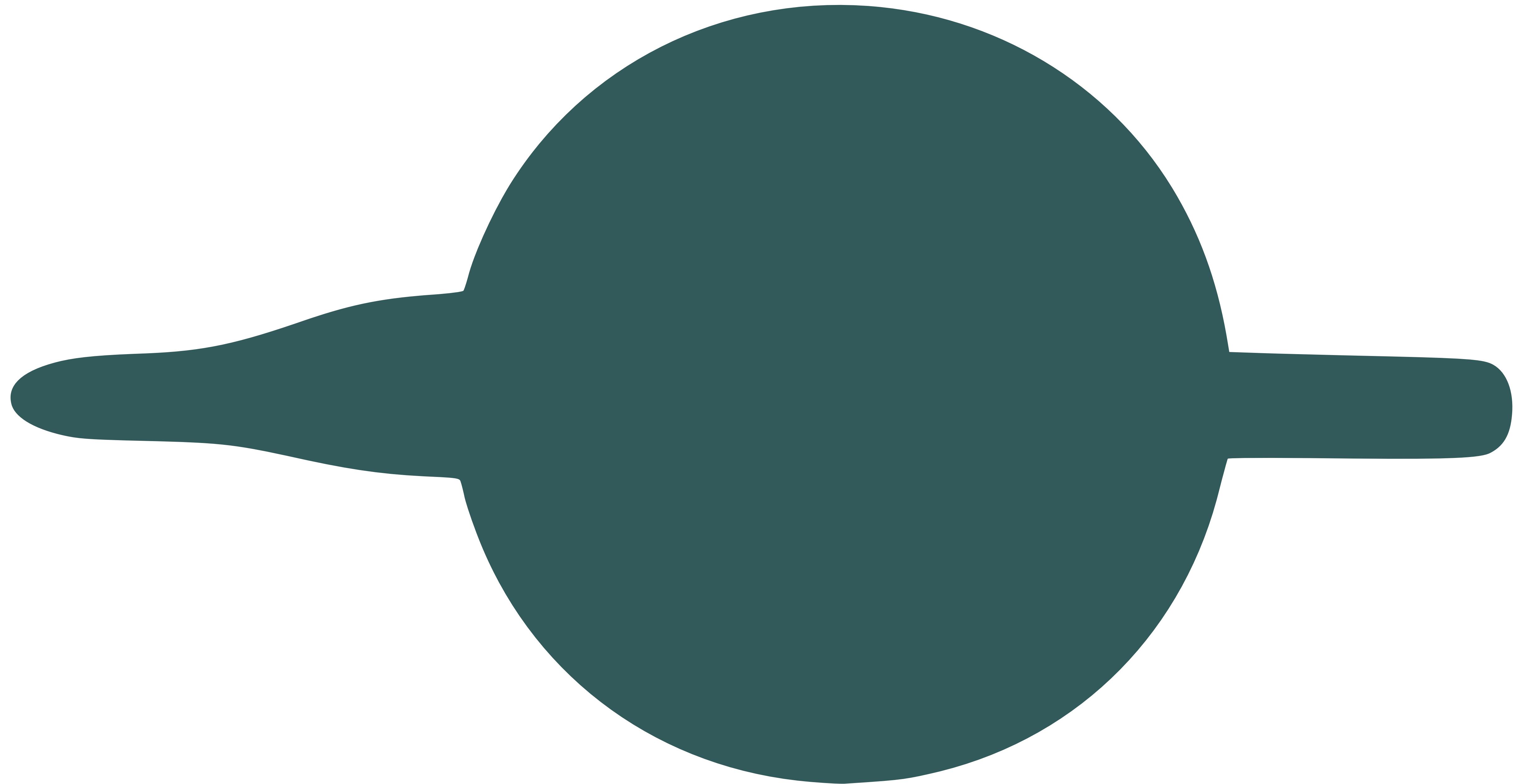
UMAP	non-linear	Graph-based	arXiv:1802.03426
PHATE	non-linear	Graph-based	https://doi.org/10.1101/120378

scvis	non-linear	Autoencoder	https://doi.org/10.1038/s41467-018-04368-5
VASC	non-linear	Autoencoder	https://doi.org/10.1016/j.gpb.2018.08.003

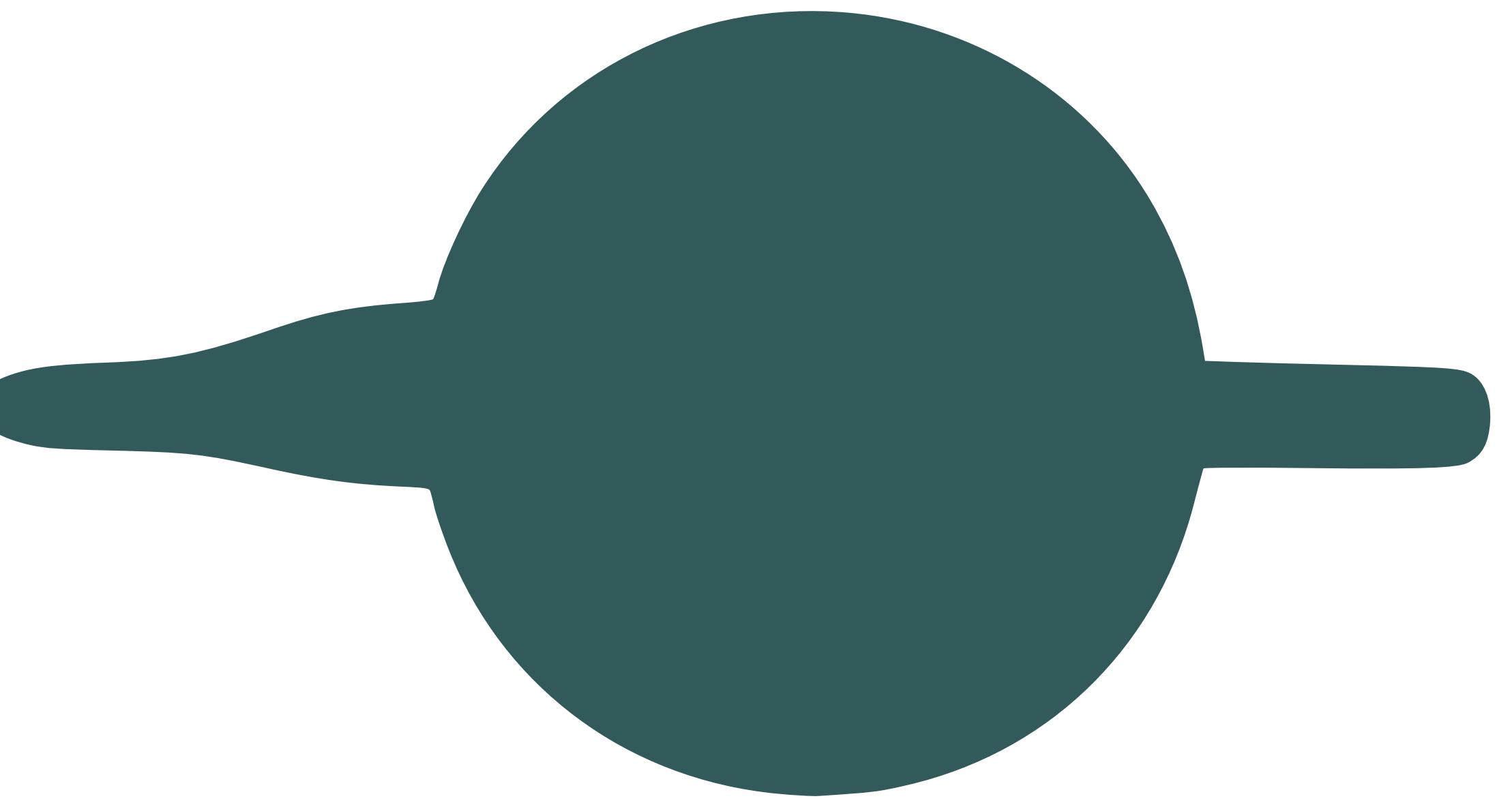
PCA

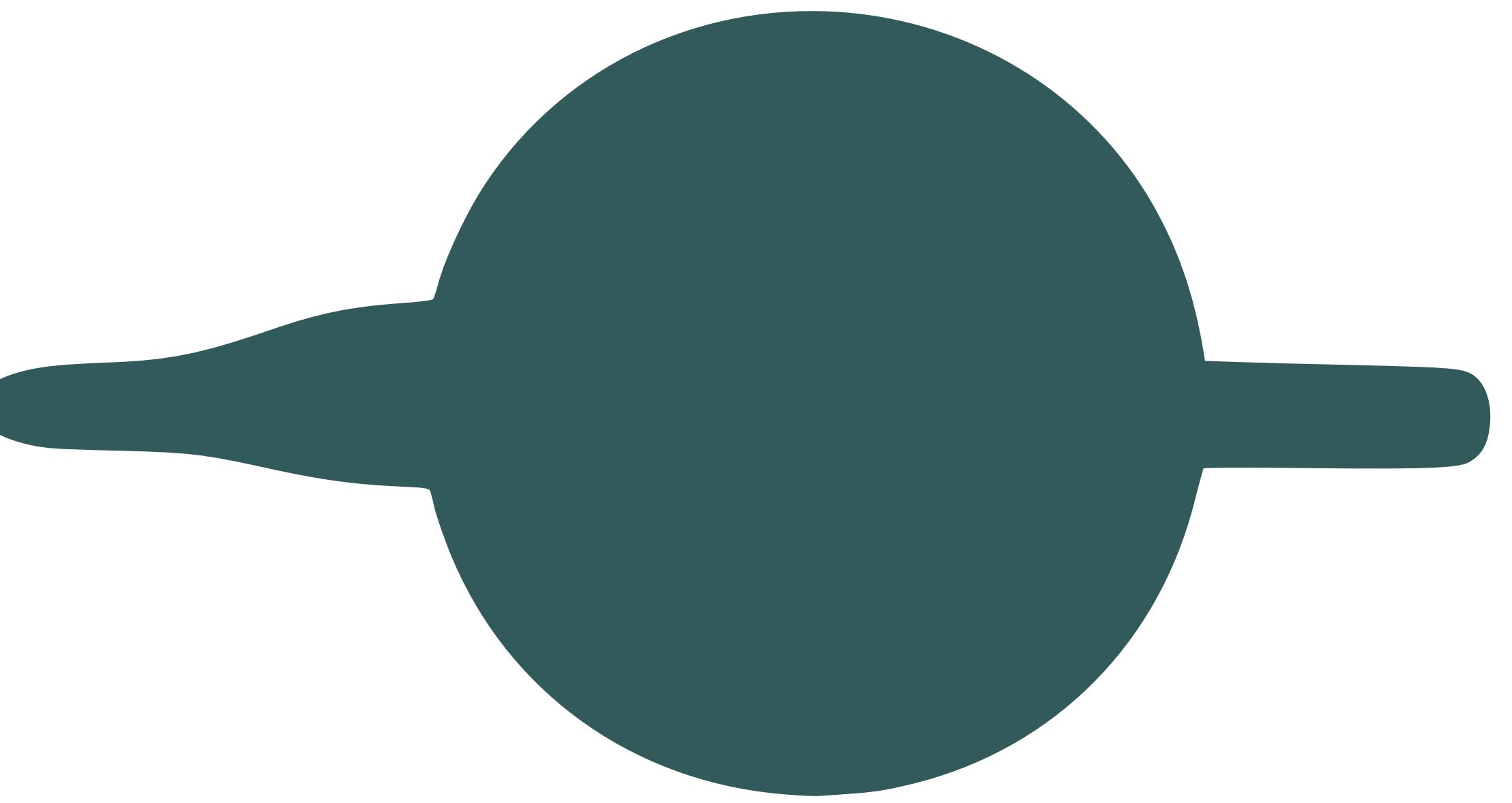
Principal Component Analysis











PCA - Intuition

- Given a dataset, compute/measure a number of features
- These features represent an N-dimensional problem
- PCA finds a new coordinate system obtained from the previous one by translation and rotation only
change the point of view
- Moves the center of the coordinate system with center of the data
- Moves the x-axis into the principal axis of variation
- Orders axes by amount of variation (importance)

PCA in Brief

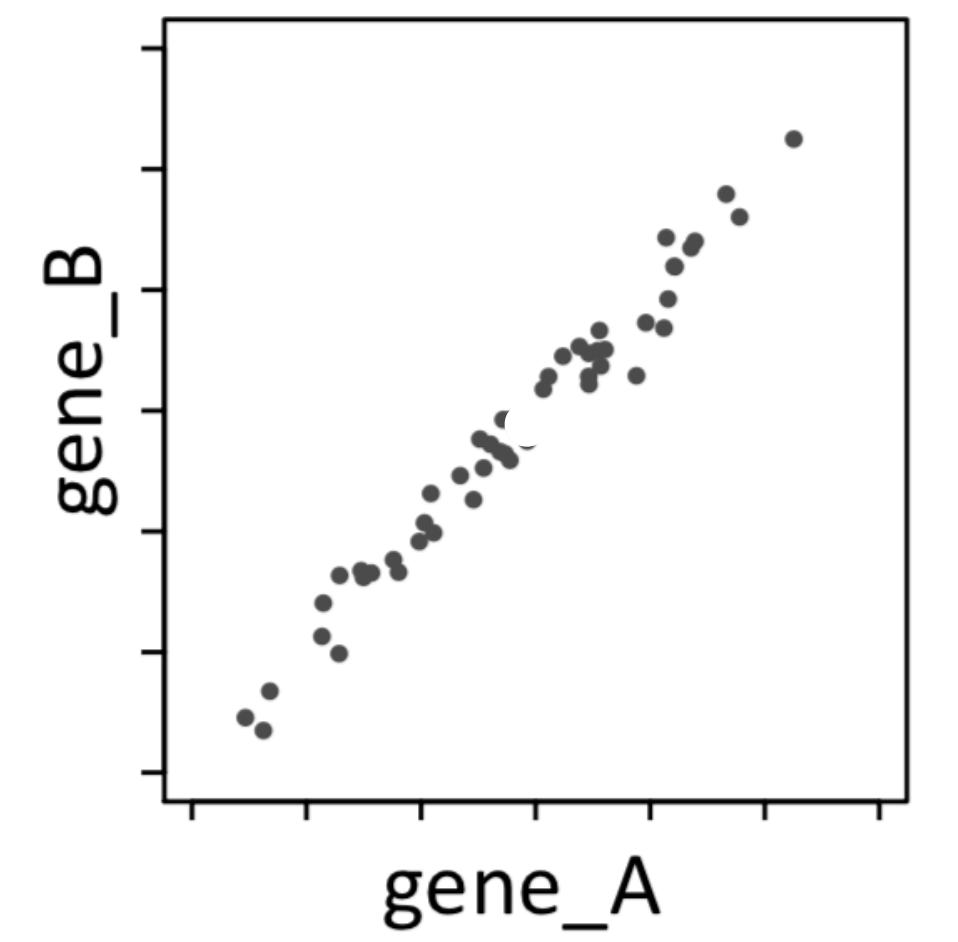
$$\mathbf{M} = \mathbf{U} \Sigma \mathbf{V}^*$$

Original data Center Rotation Scaling Planar rotation

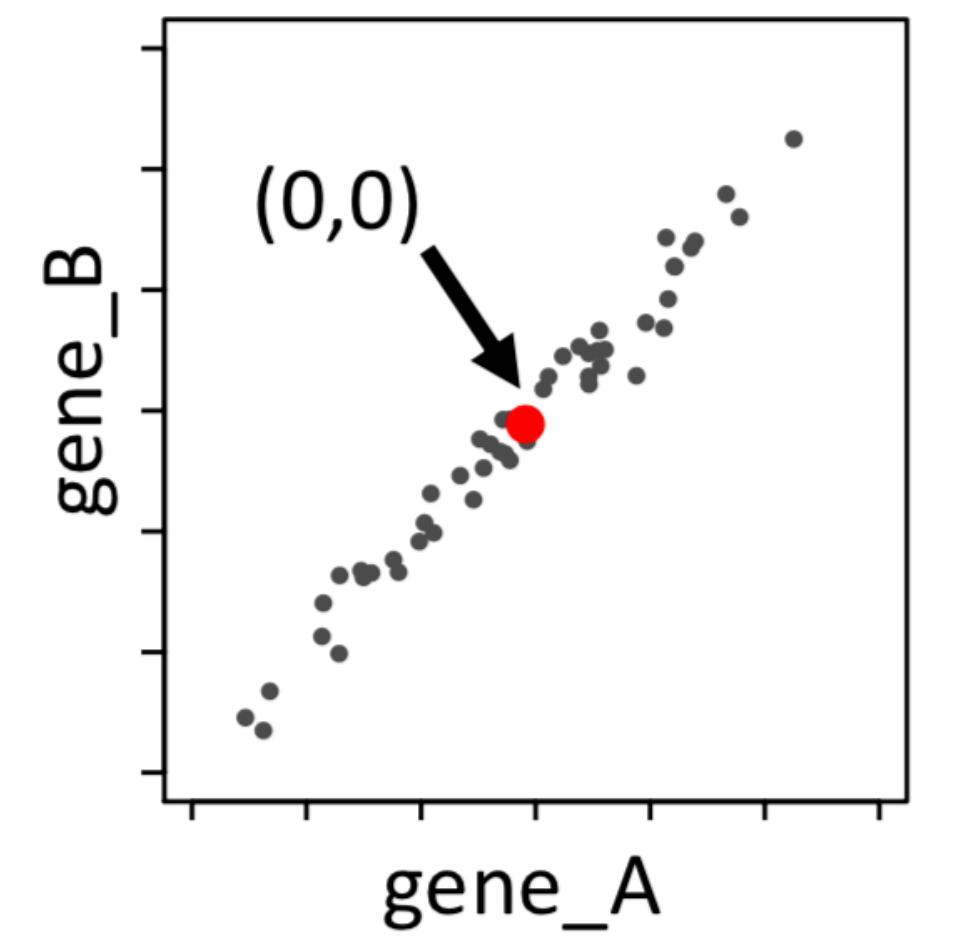
genes cells genes cells genes cells PCs

The diagram illustrates the Singular Value Decomposition (SVD) of a matrix M. It shows four matrices arranged horizontally: 1) Original data M (m×n), represented by a grey grid; 2) Center Rotation U (m×m), represented by a grid with colored vertical stripes; 3) Scaling Σ (m×n), represented by a grid with yellow cells containing numerical values; 4) Planar rotation V* (n×n), represented by a grid with colored horizontal stripes. The labels 'genes' and 'cells' are placed above the first and third matrices respectively, while 'genes' and 'cells' are placed to the left of the second and fourth matrices.

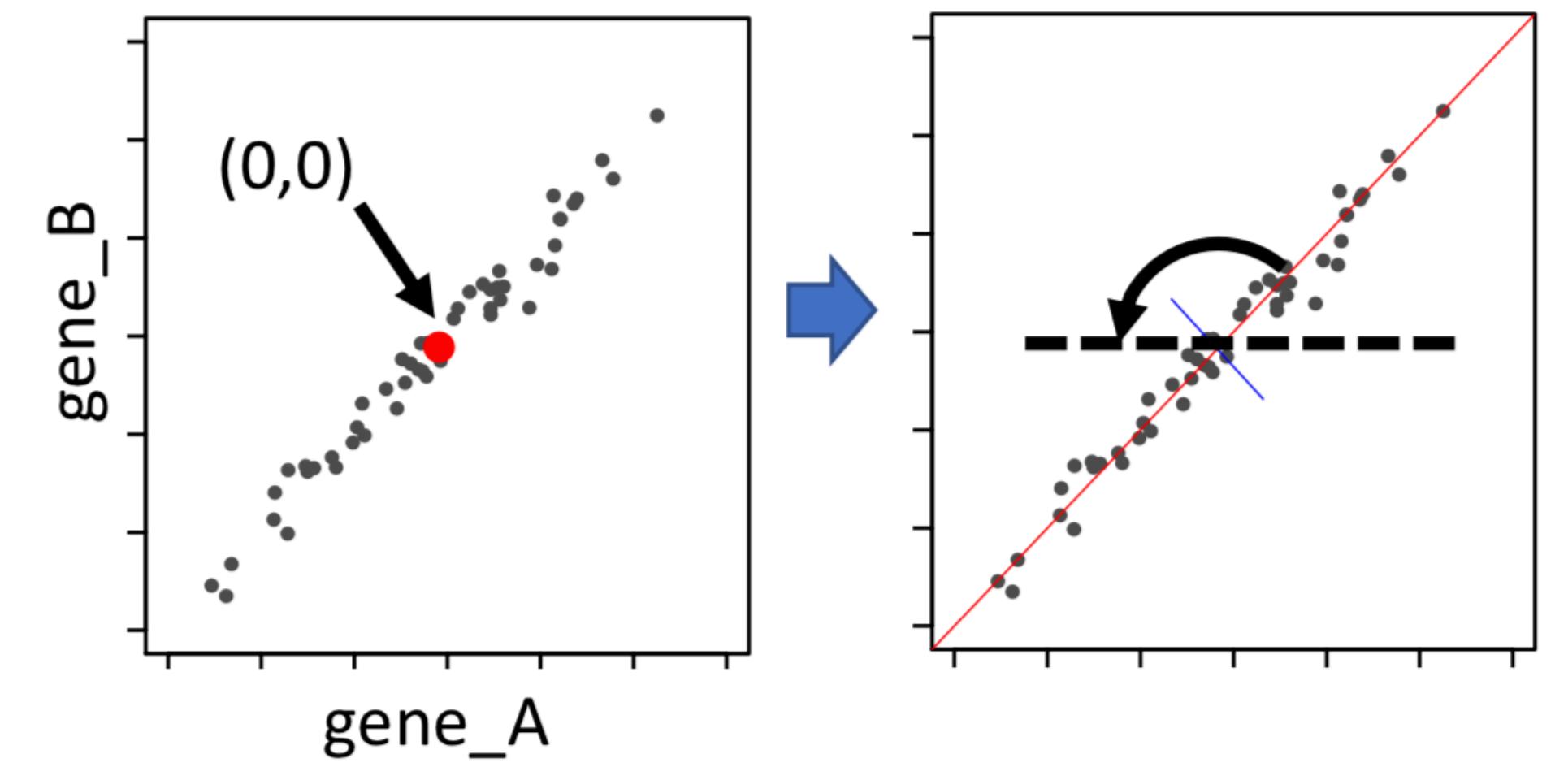
PCA in Brief



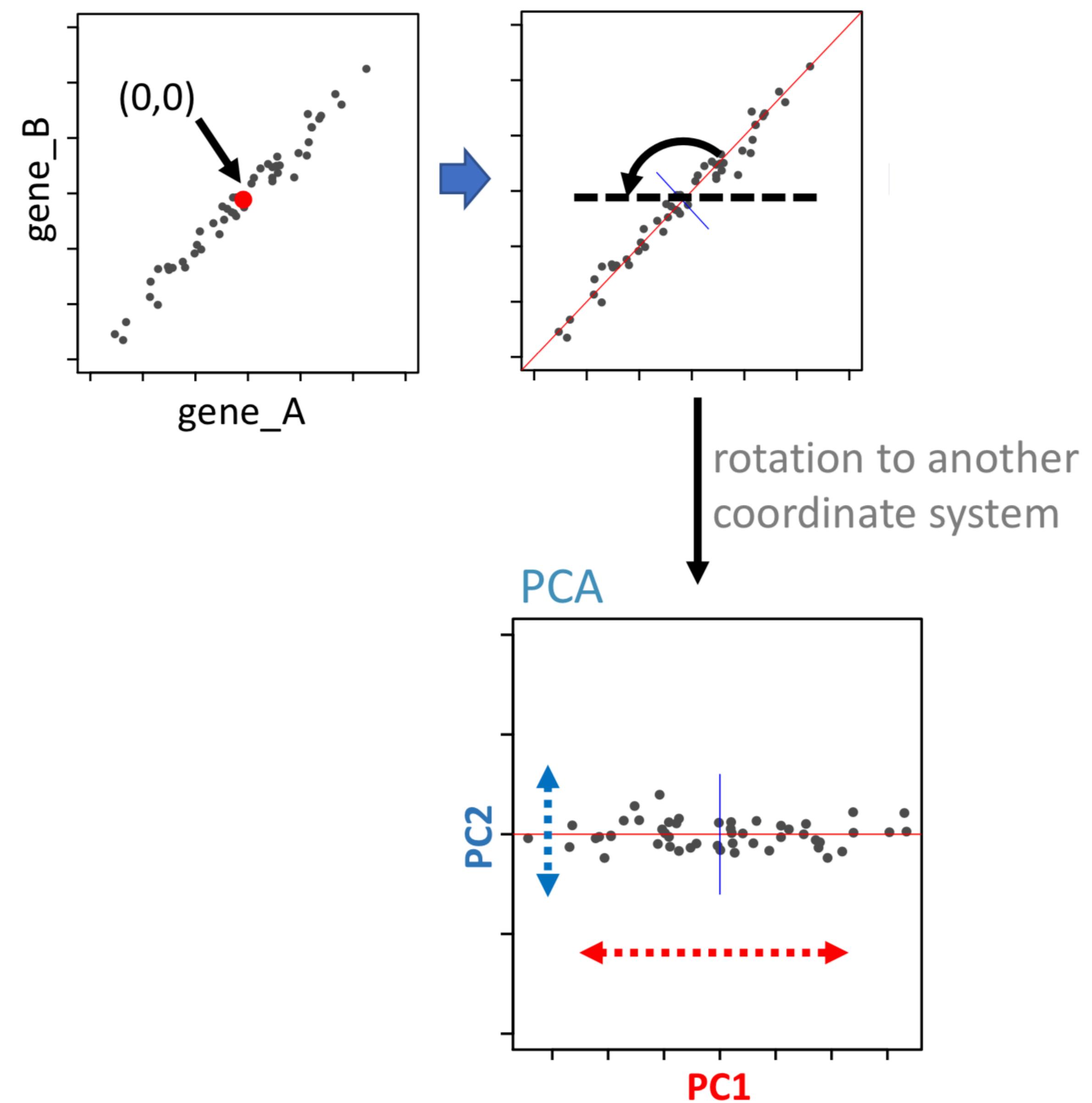
PCA in Brief



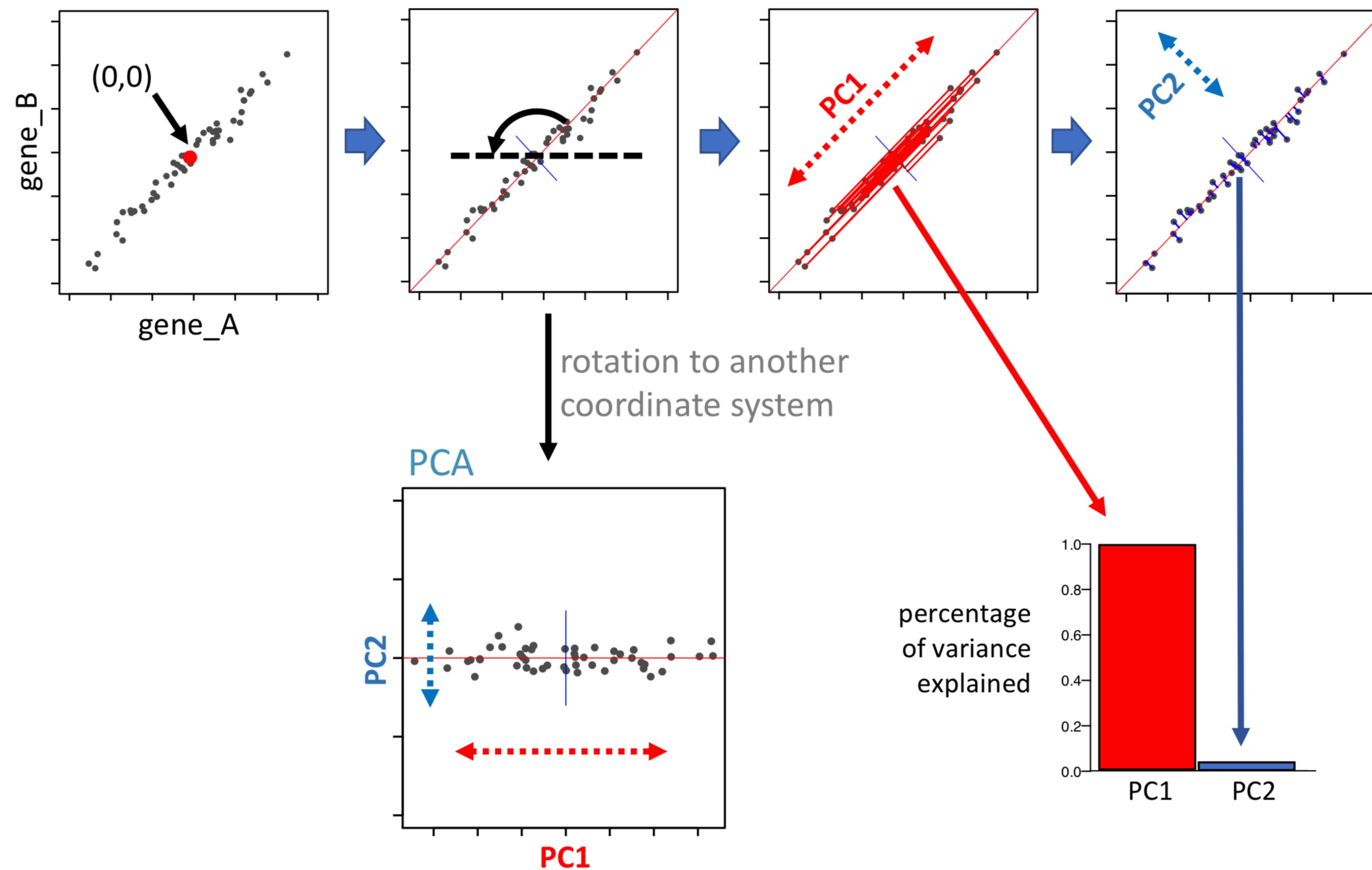
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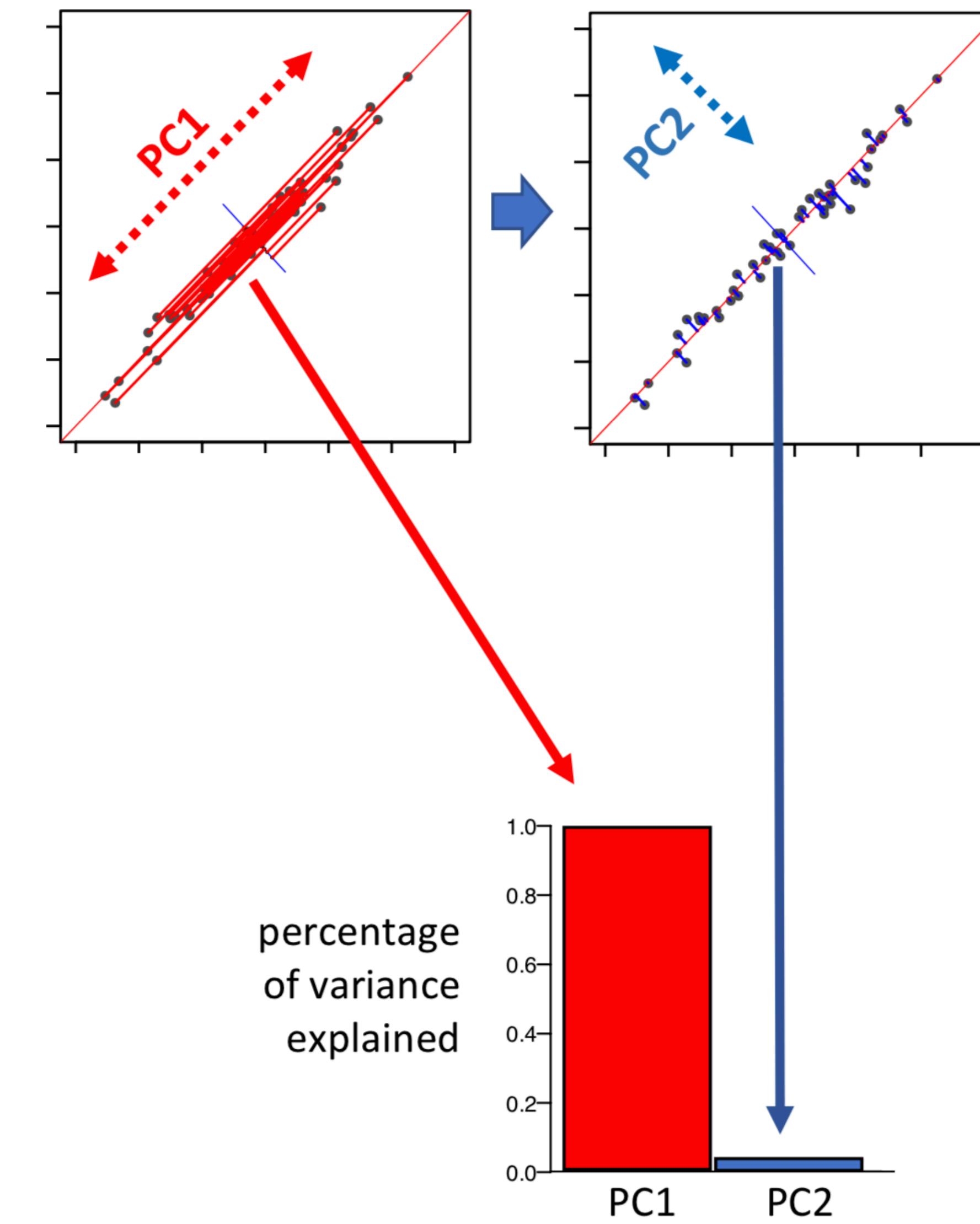


PCA in Brief

PC1 explains >98% of the variance

1 PC thus represents 2 genes very well
"Removing" redundancy

PC2 is nearly insignificant in this example
Could be disregarded

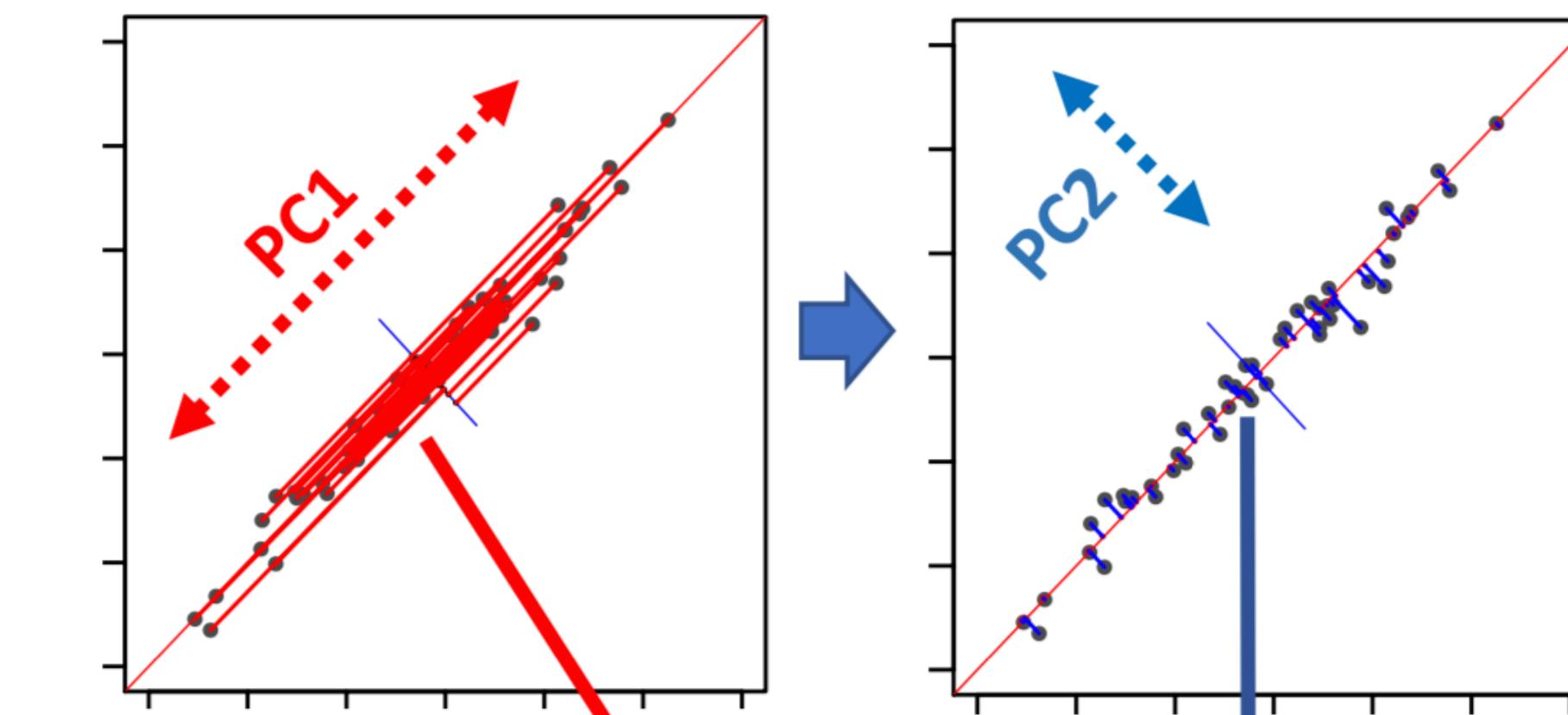


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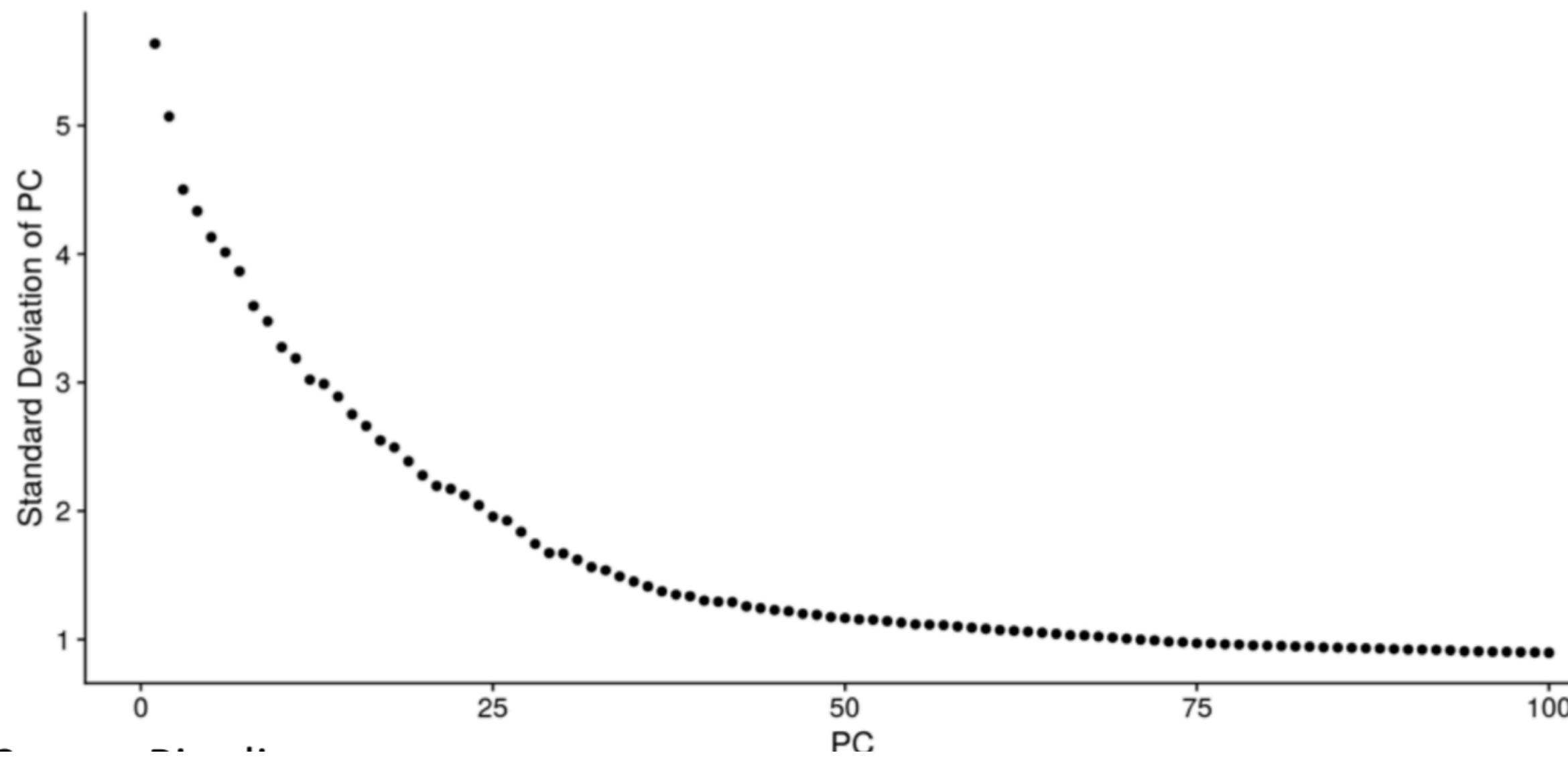
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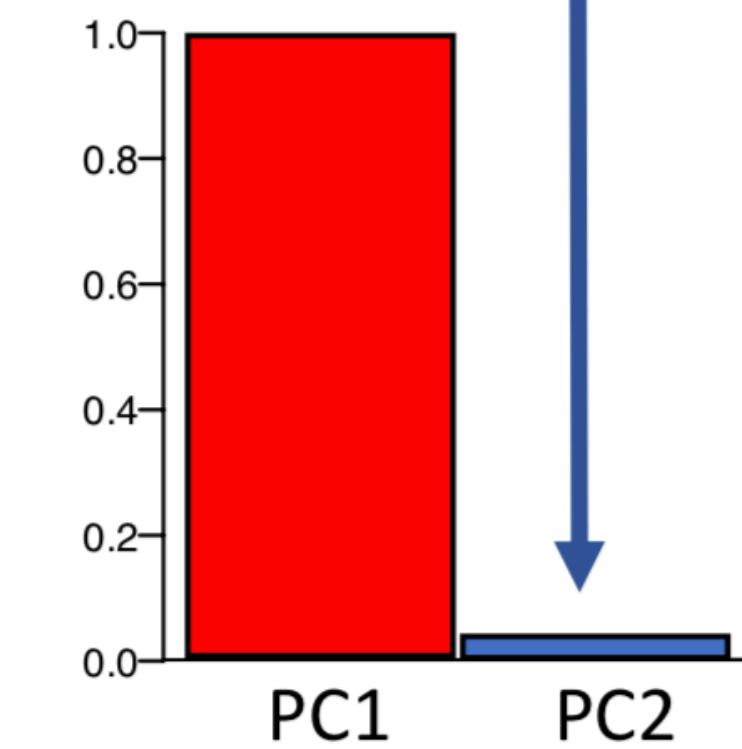
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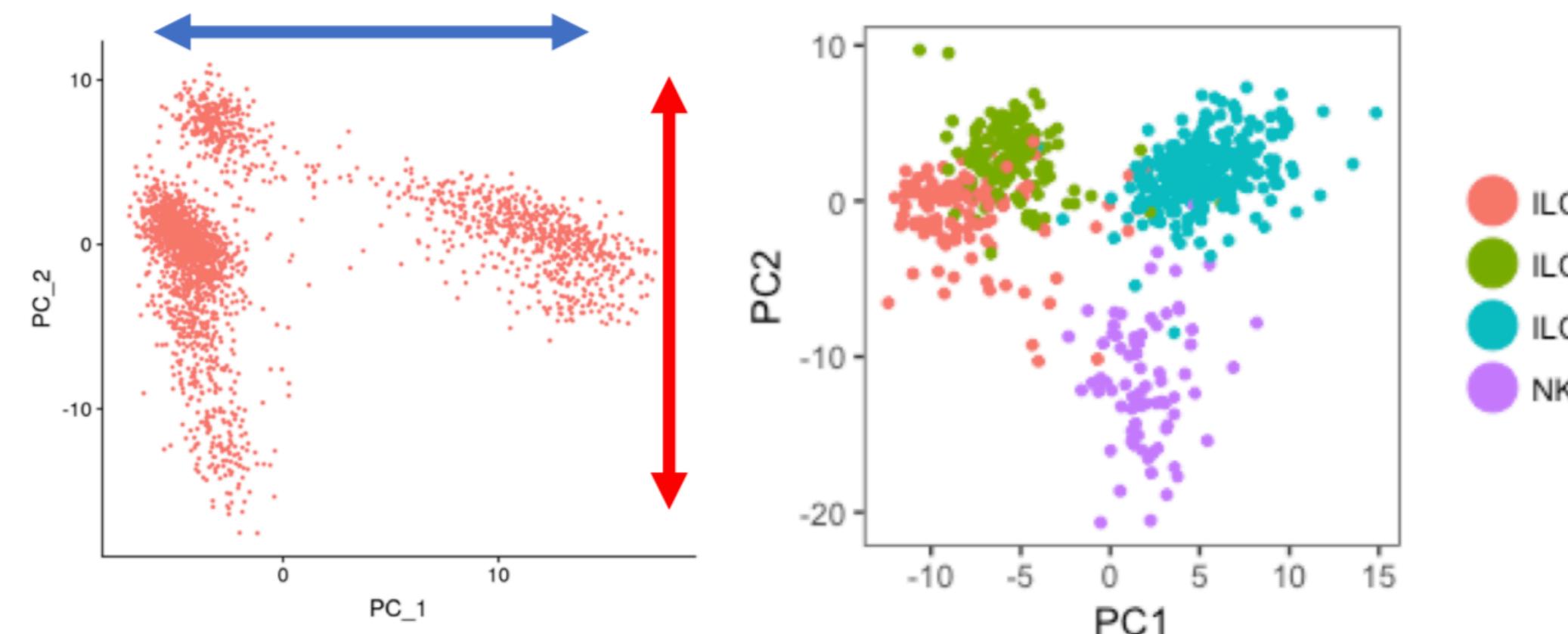
In real life ...



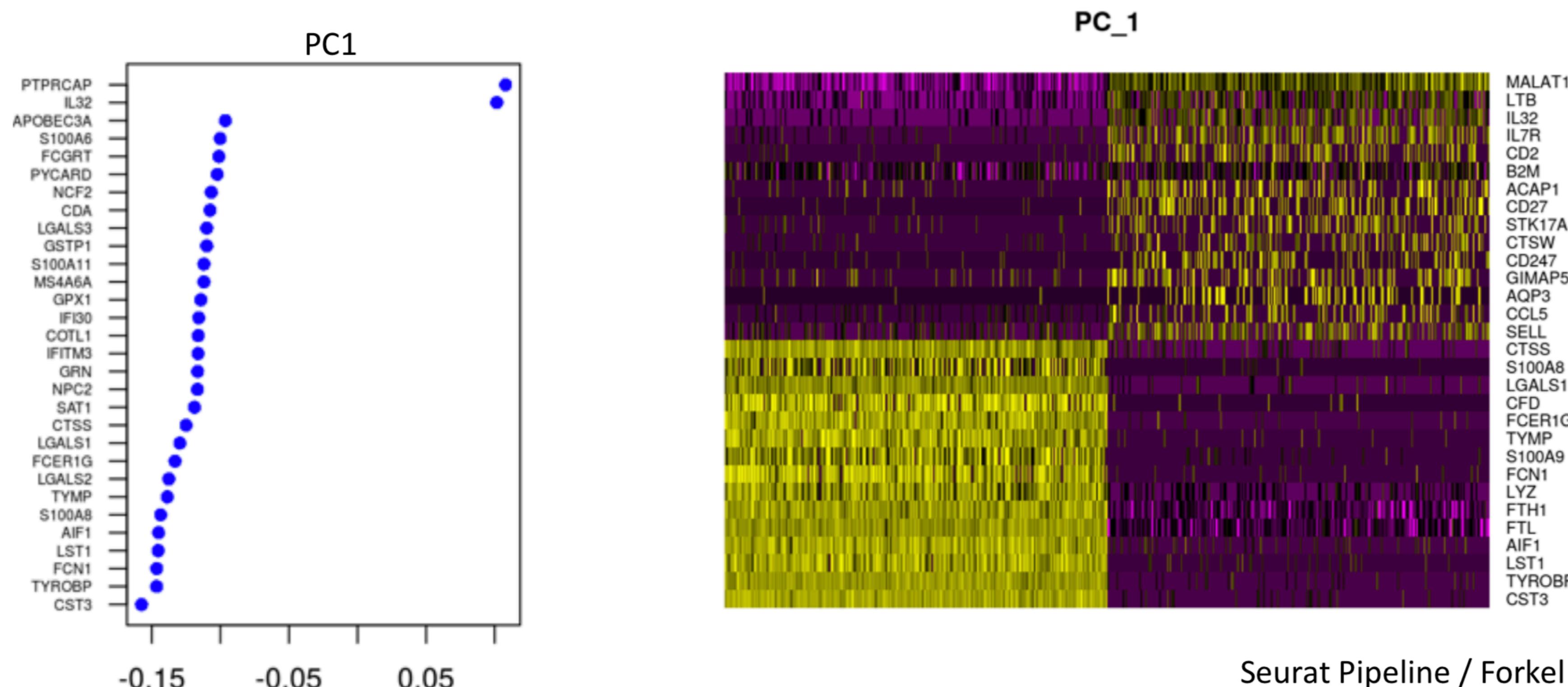
percentage
of variance
explained



PCA in Brief



PC1 and PC2 are commonly correlated to sequencing depth and cell heterogeneity/complexity
(but not always ...)



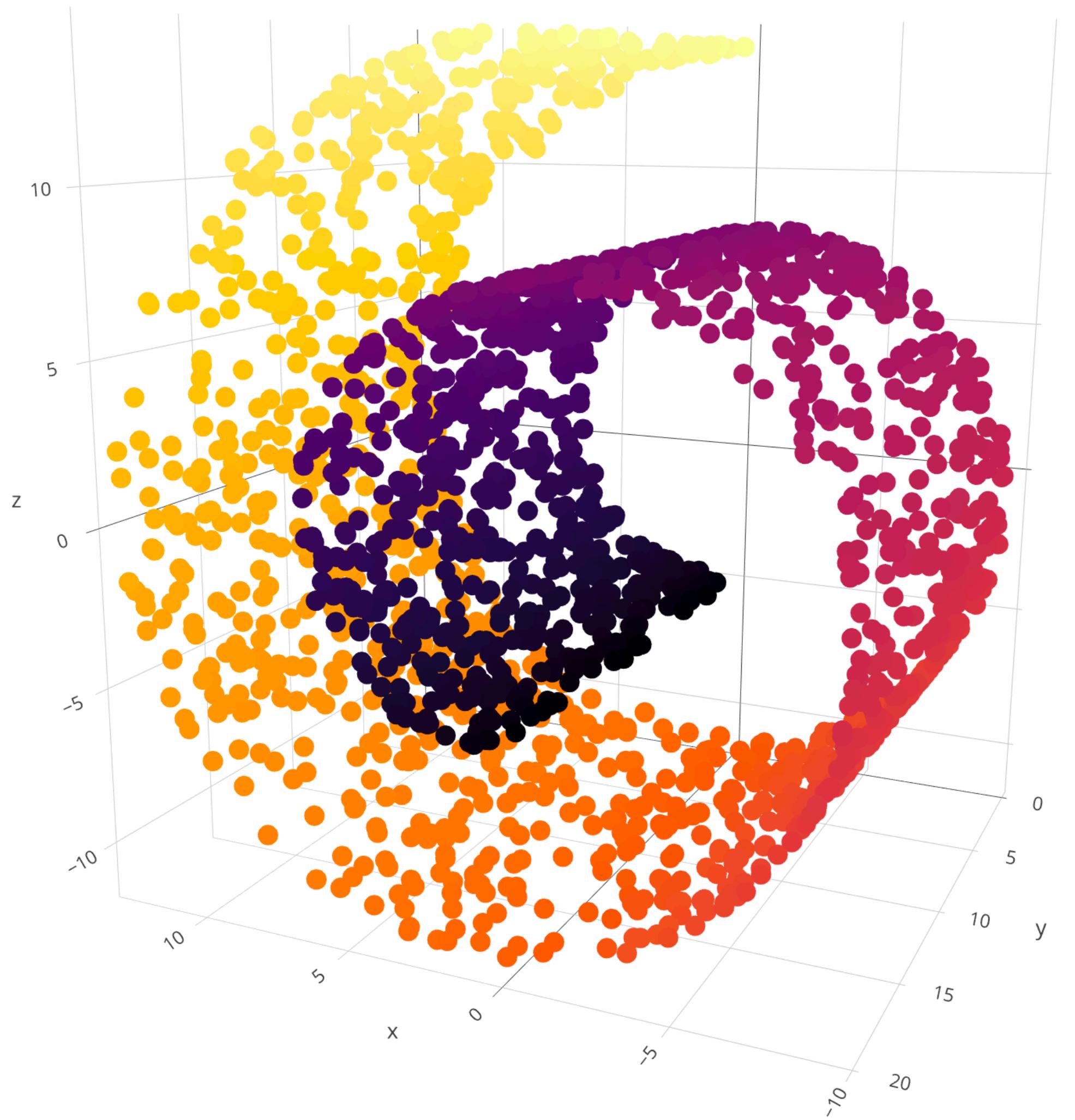
Summary: PCA

- LINEAR method of dimensionality reduction
- The TOP principal components contain higher variance from the data
- Can be used as FILTERING, by selecting only the top significant PCs
- *It is an interpretable/parametric dimensionality reduction*
- **Problems:**
 - It performs poorly to separate cells in 0-inflated data types
 - Cell sizes and sequencing depth are usually captured in the top PCs

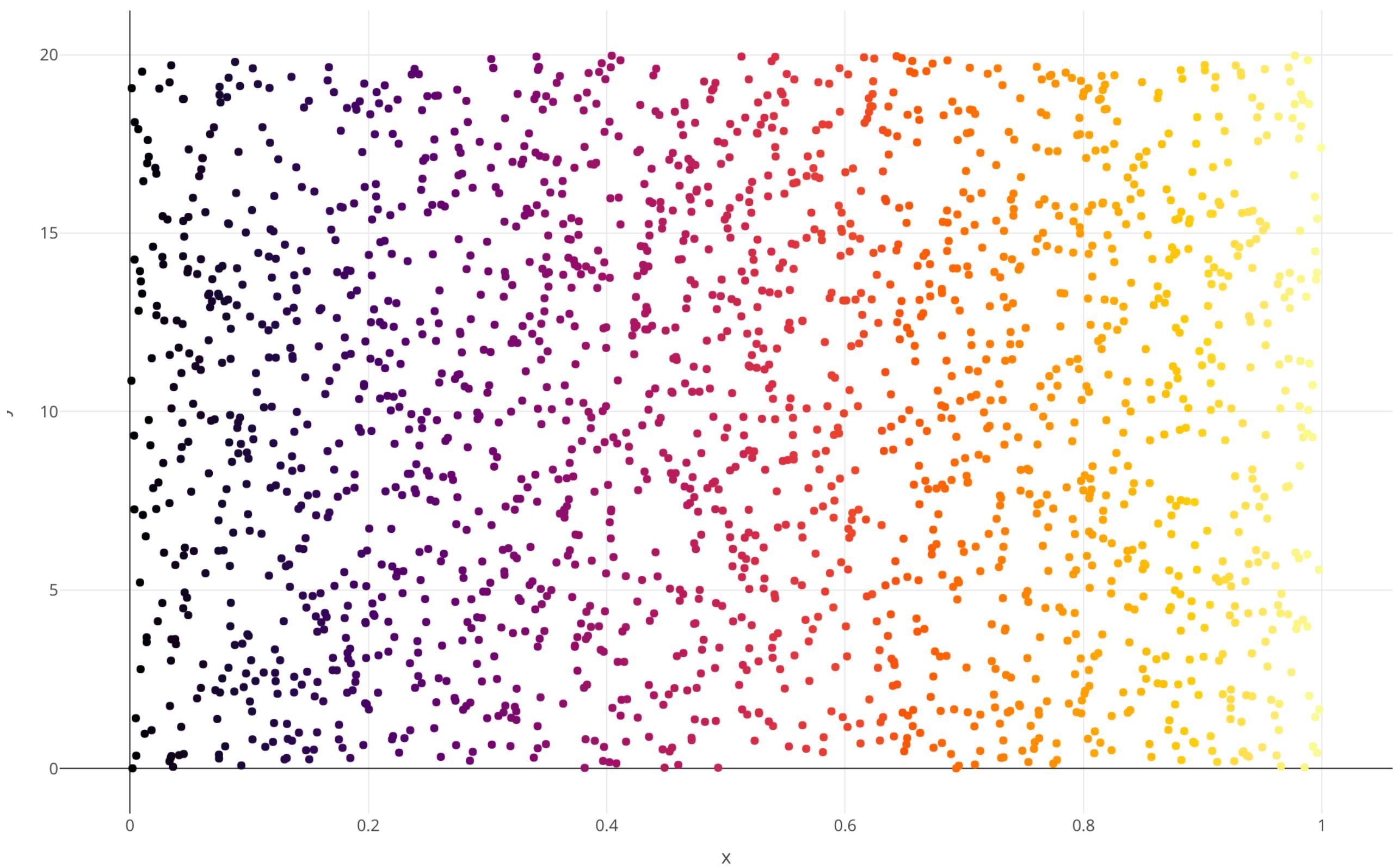
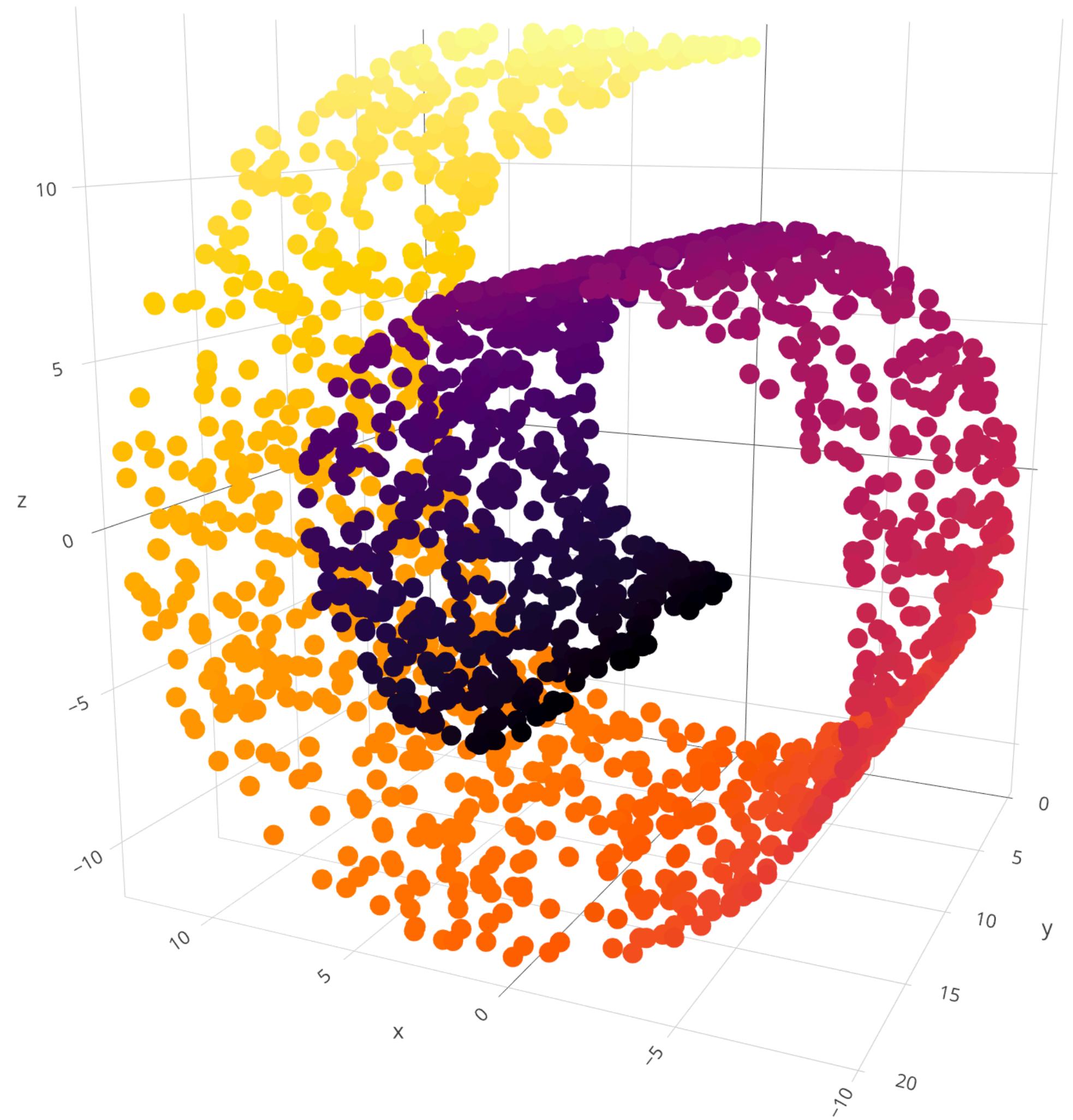
t-SNE

t-distributed Stochastic Neighborhood Embedding

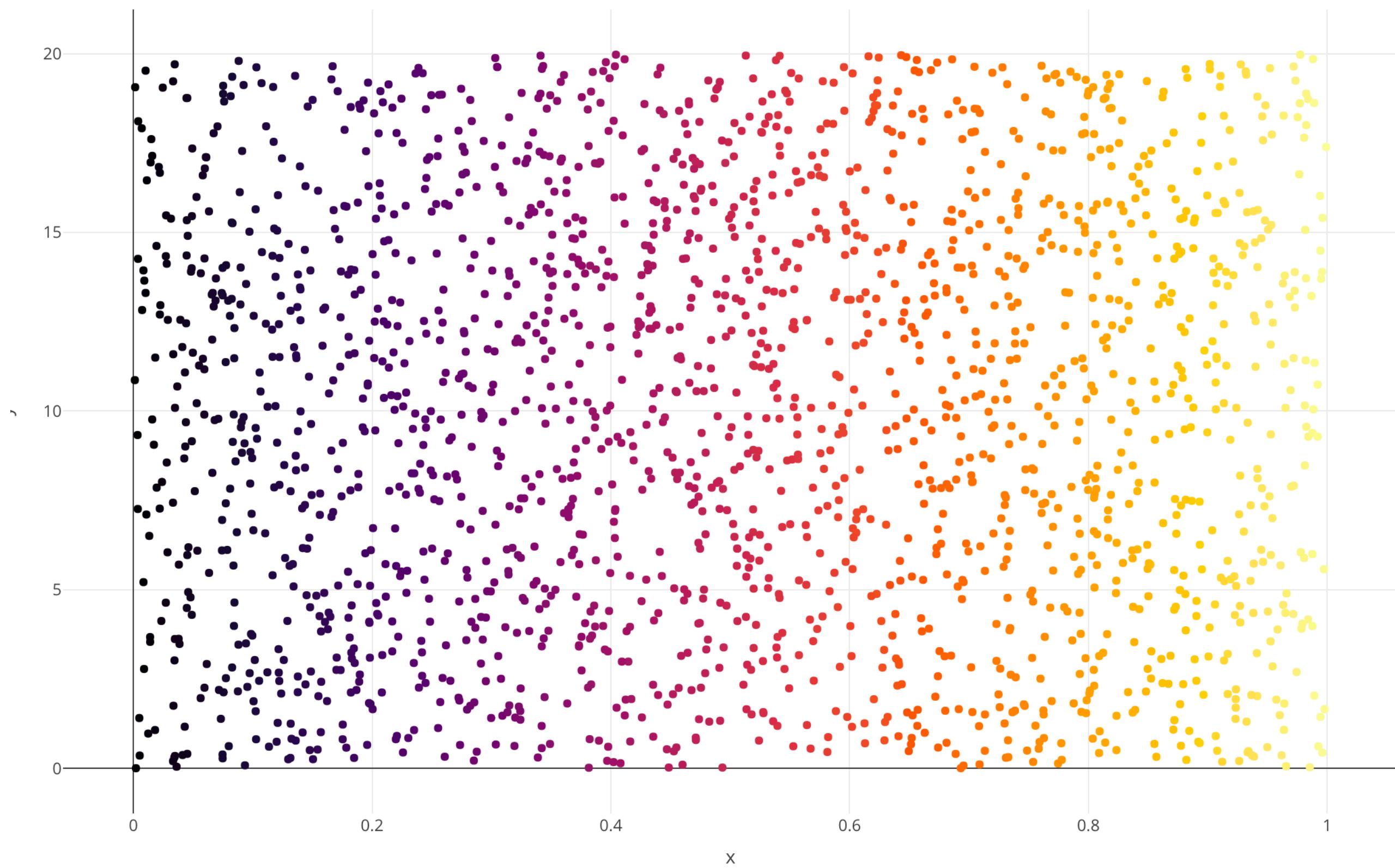
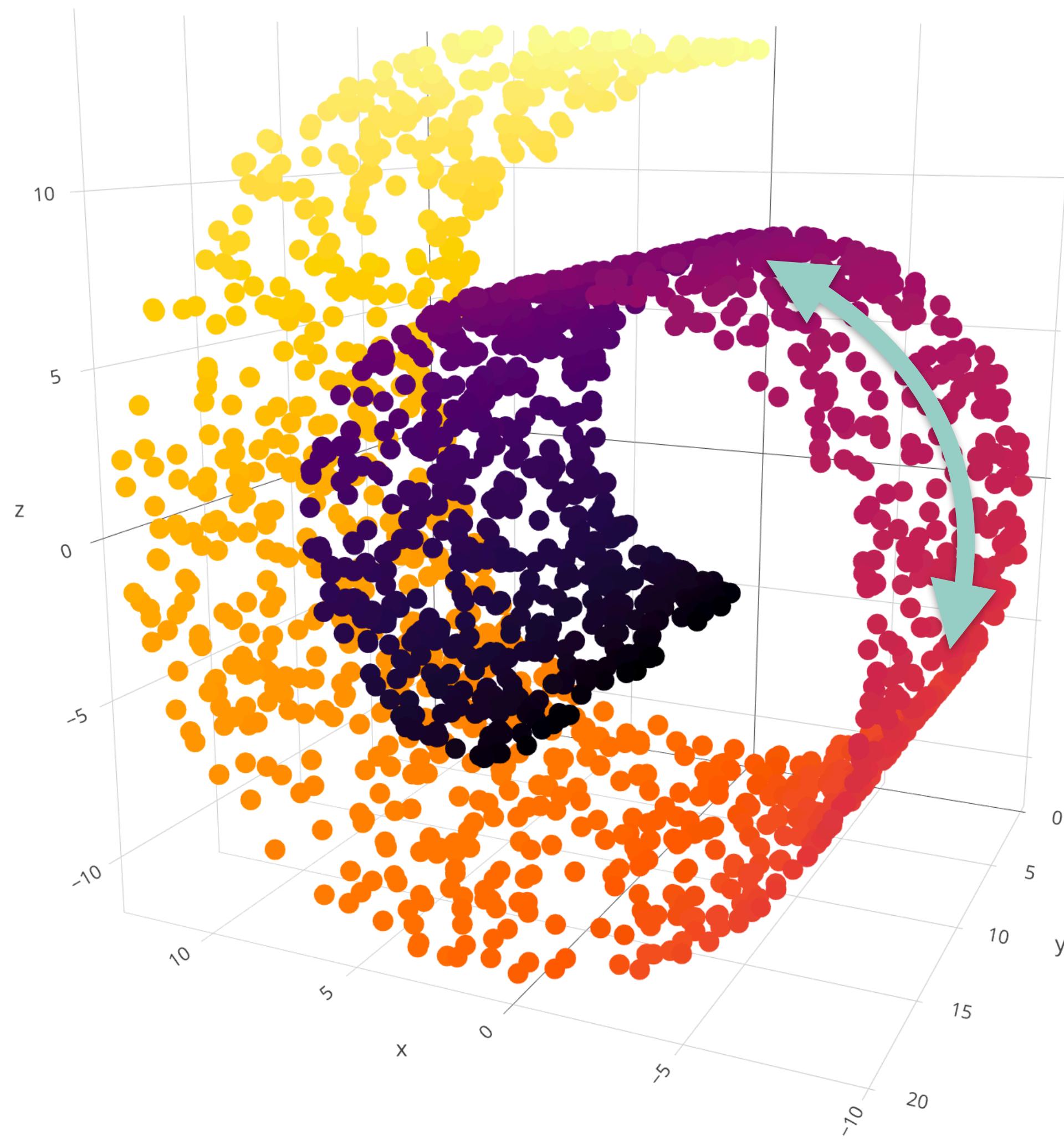
Manifold Learning



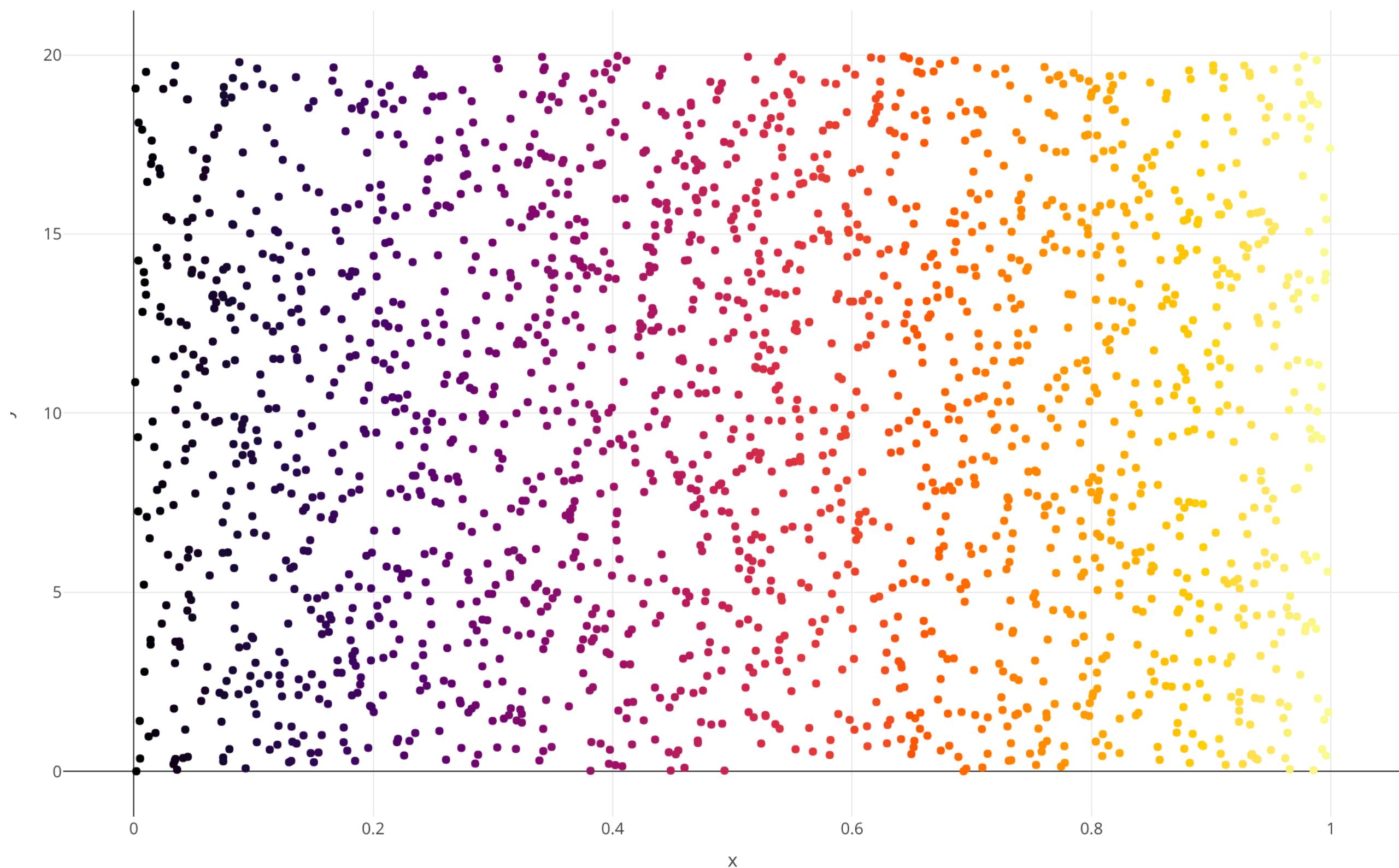
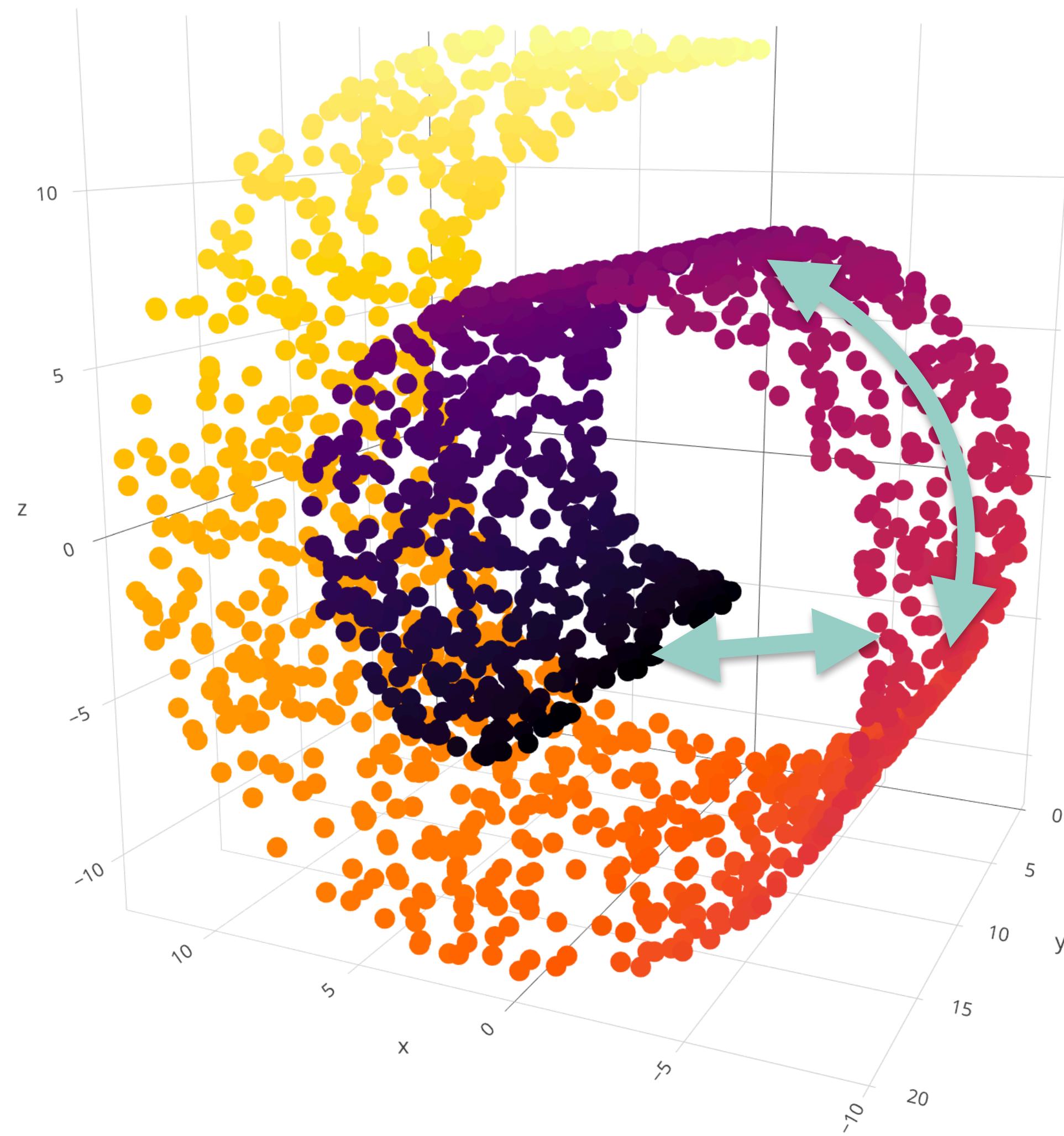
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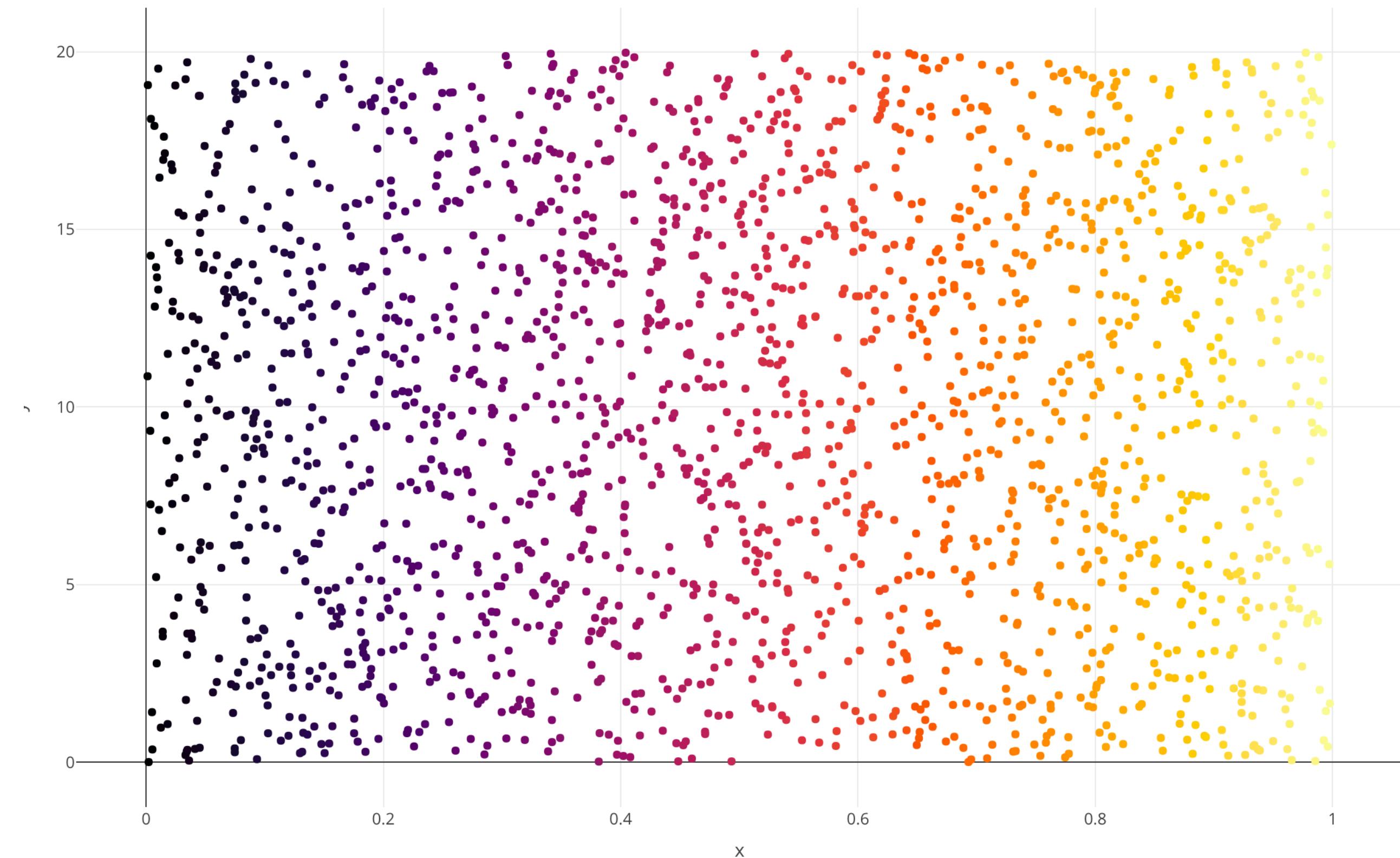
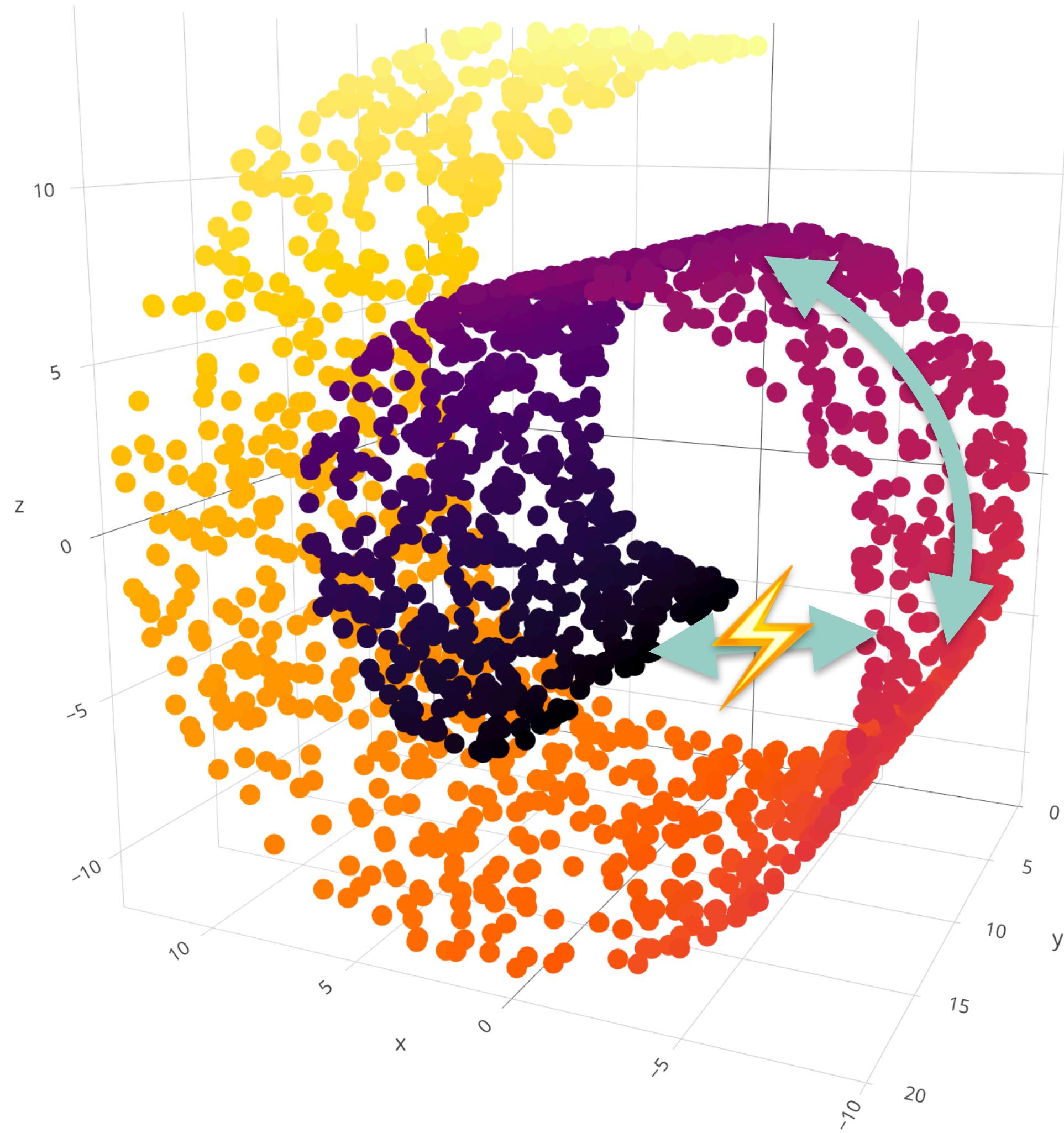
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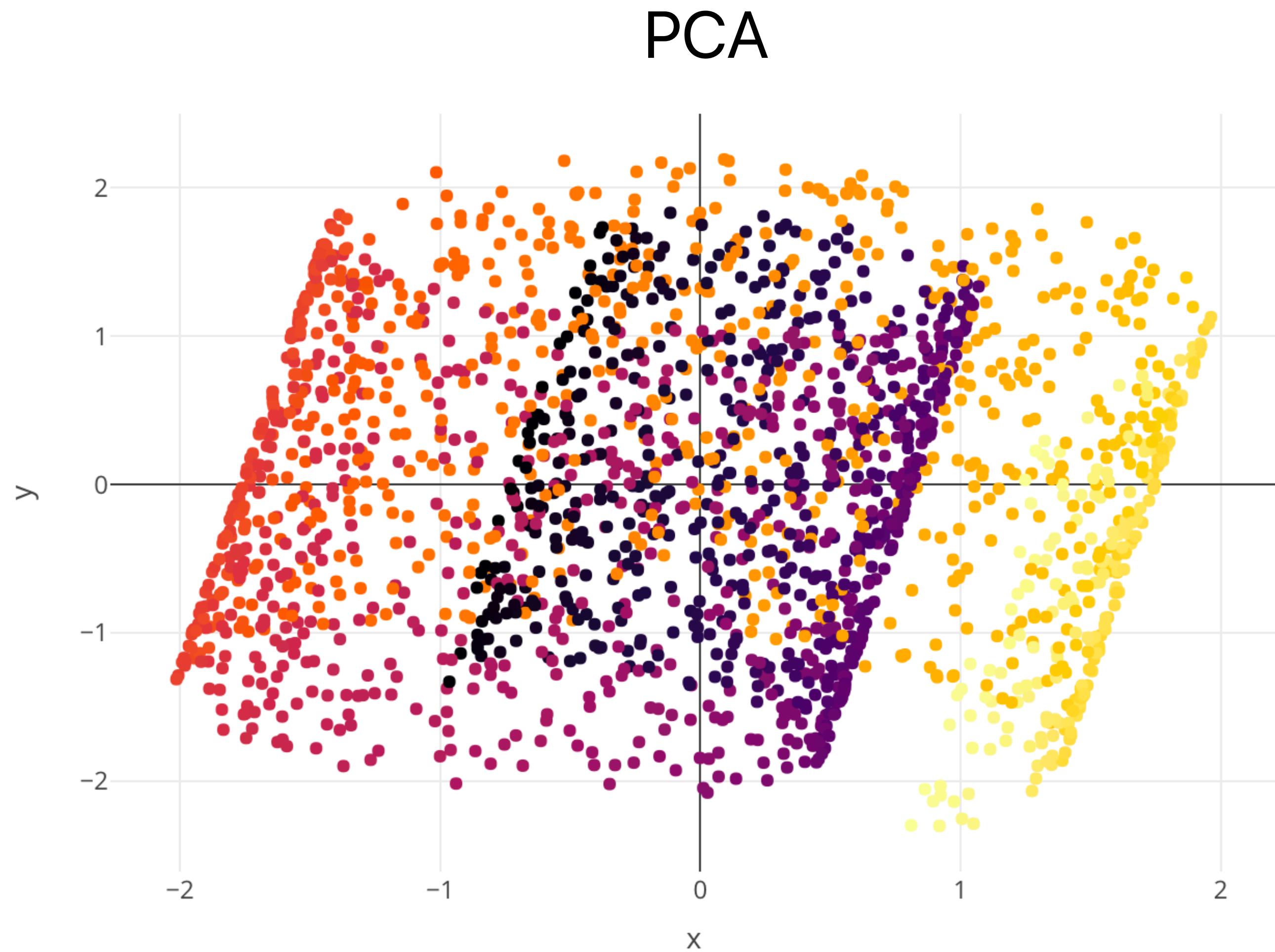
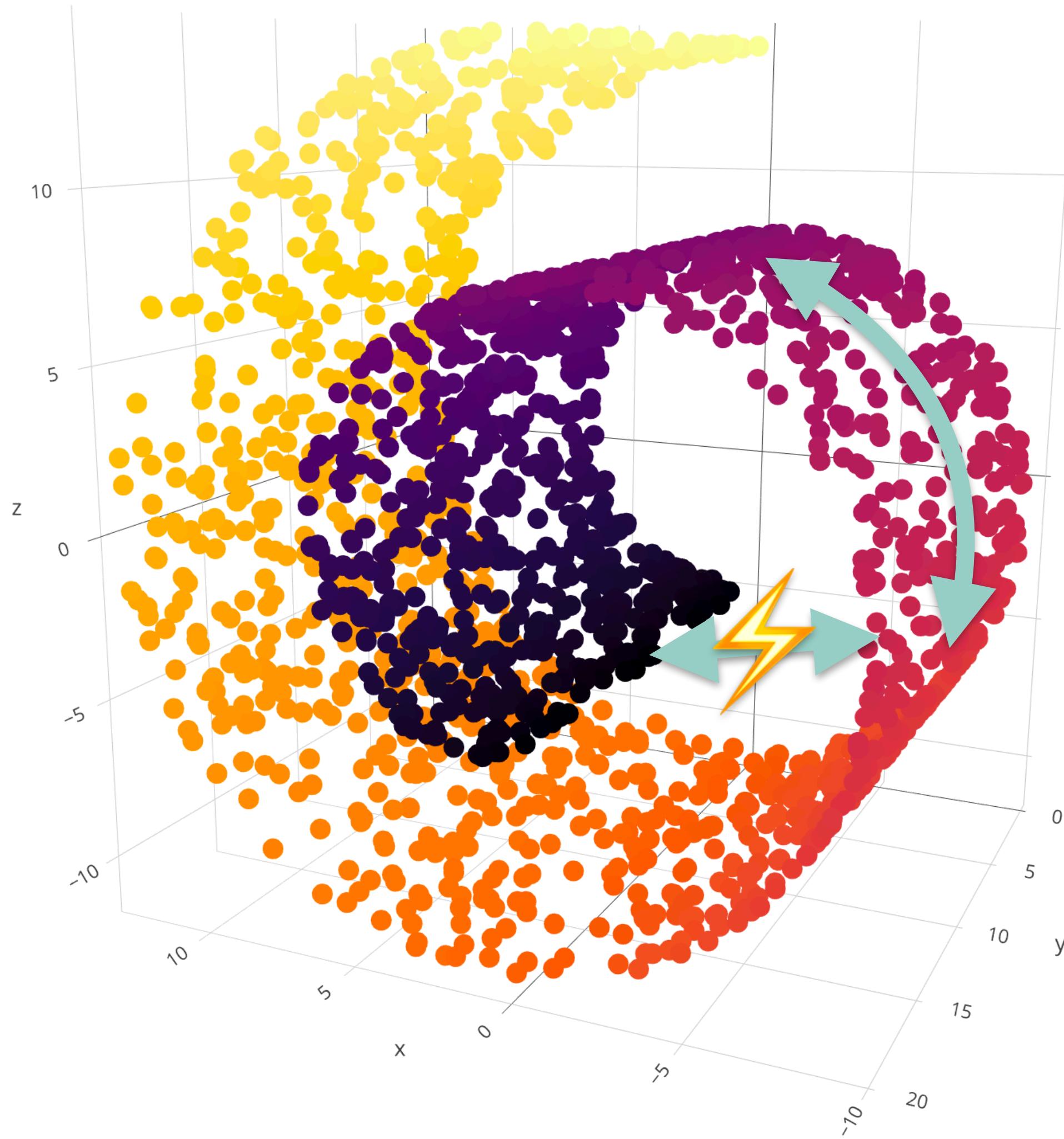
Manifold Learning



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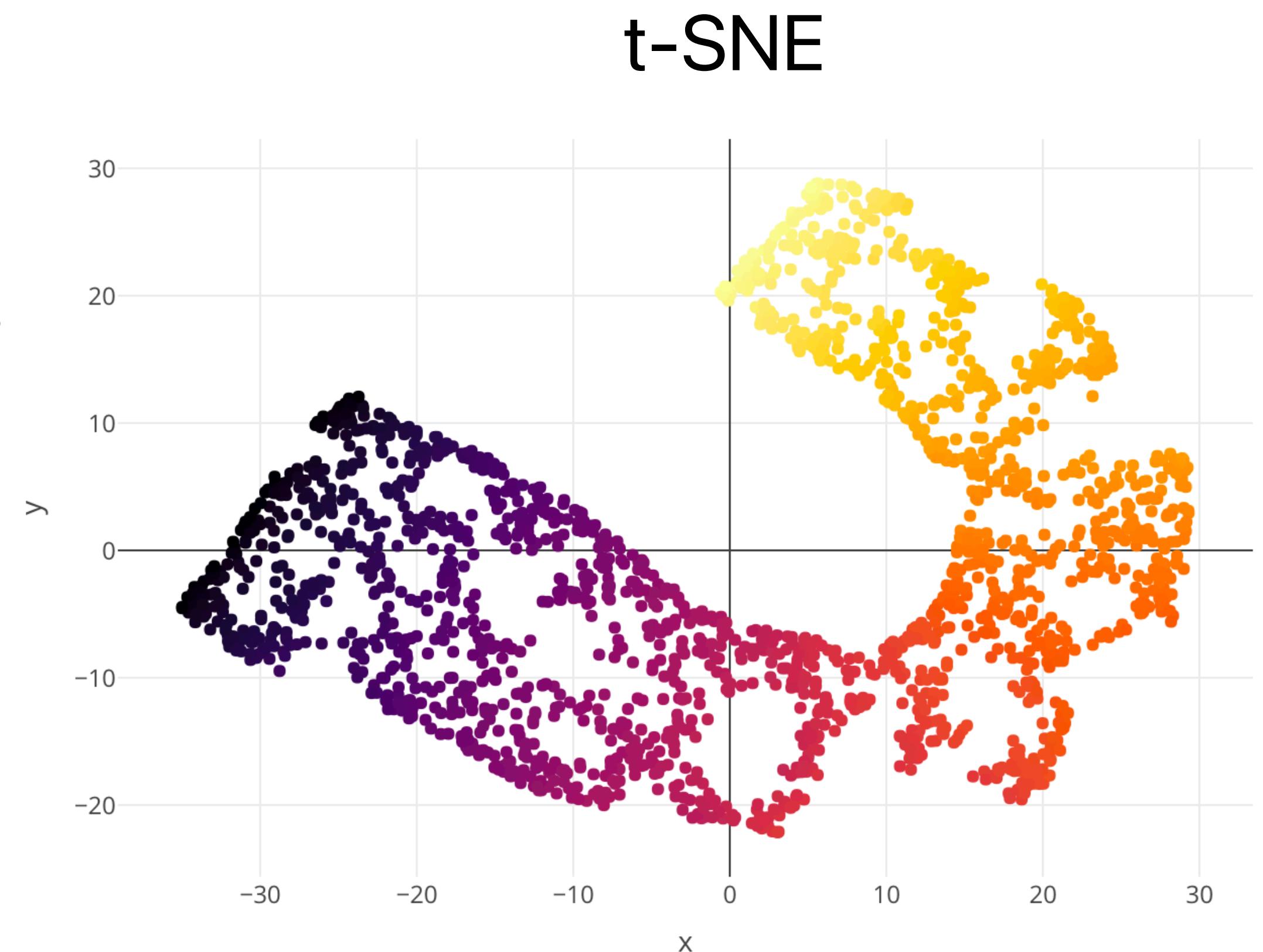


t-SNE Intuition

- Non-linear dimensionality reduction
 - Compute neighborhoods in hi-D
 - Model low-D to preserve neighborhoods
 - Preserves local neighborhoods
- ➡ Preserves high-D clusters!

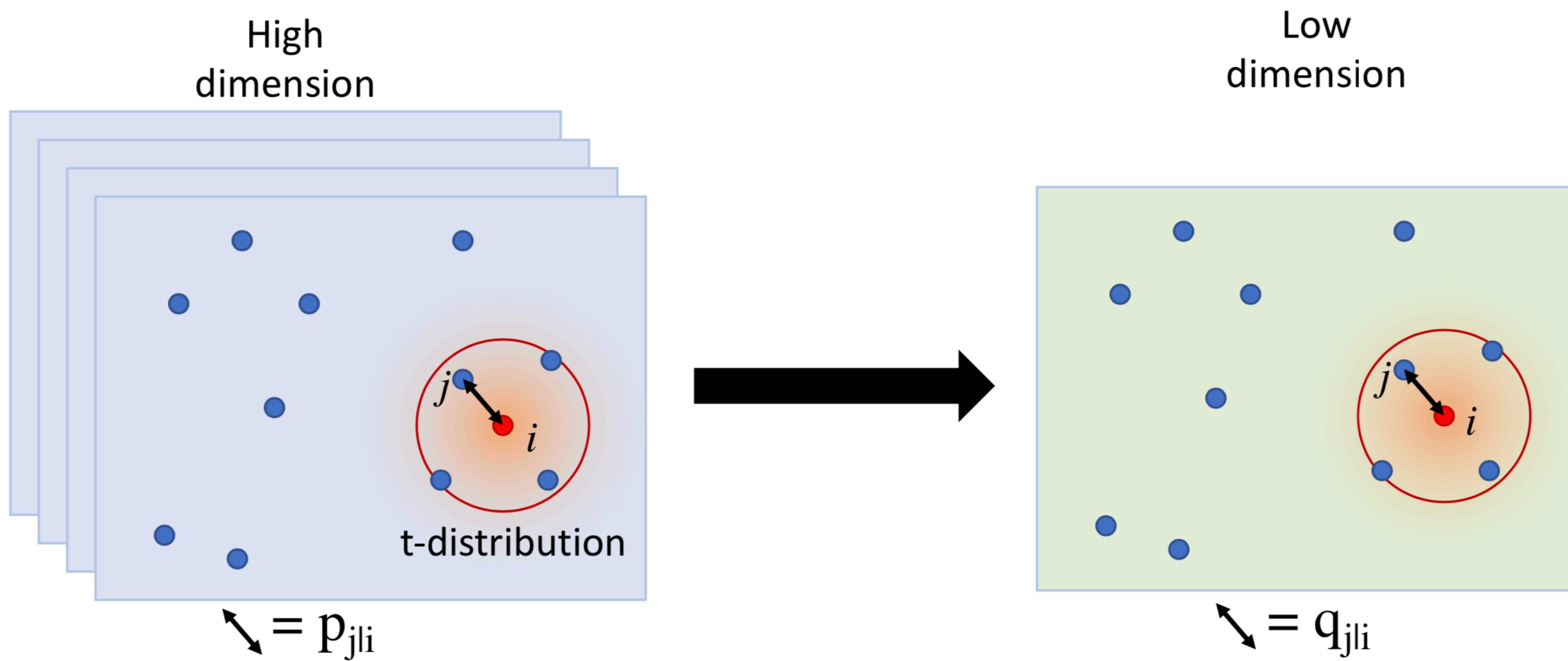
t-SNE Intuition

- Non-linear dimensionality reduction
 - Compute neighborhoods in hi-D
 - Model low-D to preserve neighborhoods
- Preserves local neighborhoods
- ➡ Preserves high-D clusters!

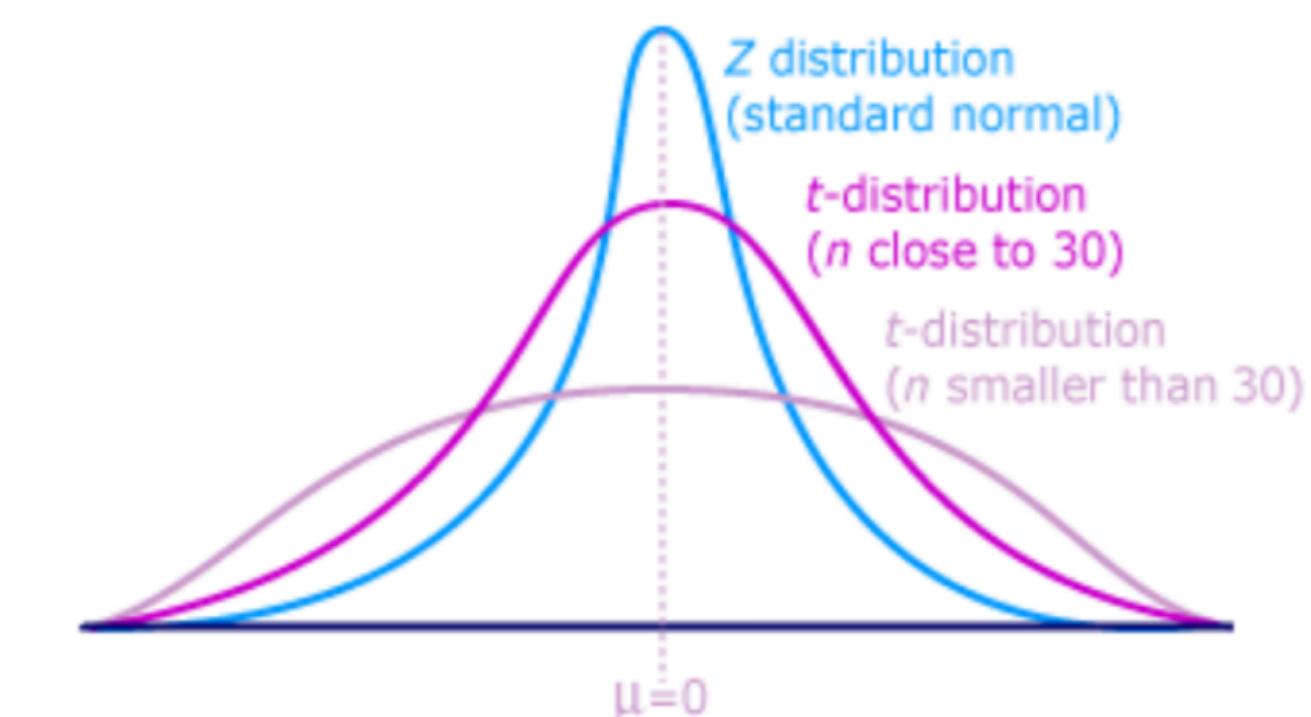


*actually also not great with Swiss Roll

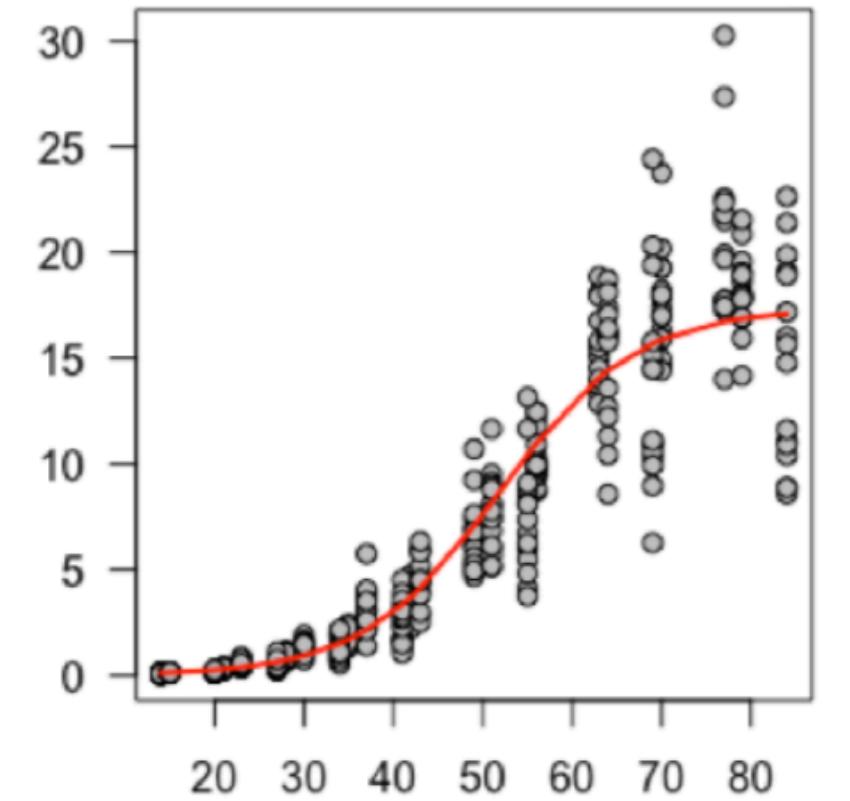
t-SNE in Brief



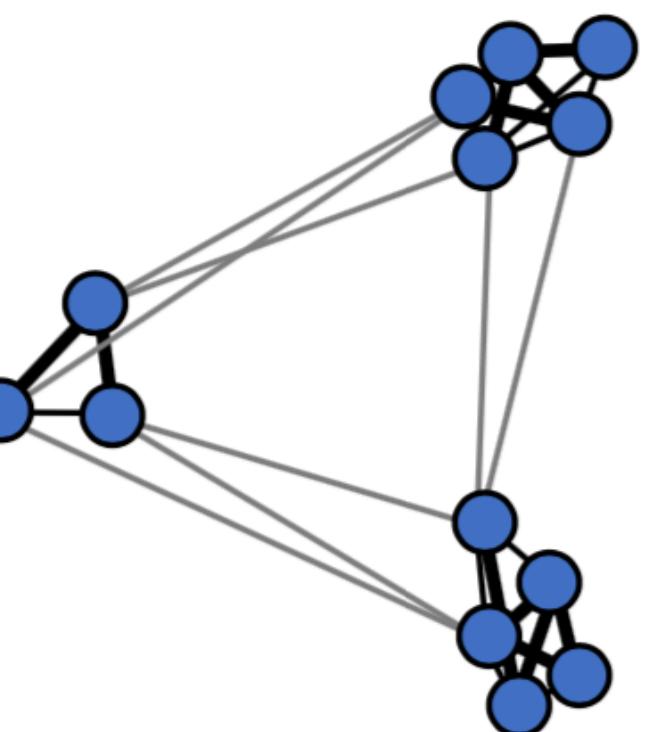
$p_{j|i}$ and $q_{j|i}$ measure the conditional probability that a point i would pick point j as its nearest neighbor, in high (p) and low (q) dimensional space respectively.



Sidestep: Graphs

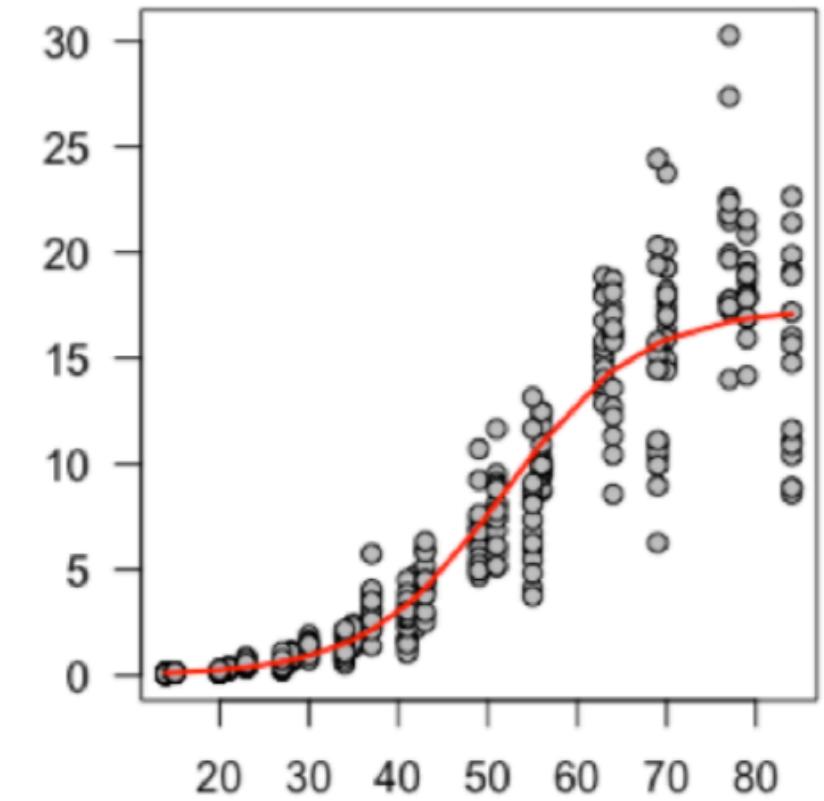


This is a PLOT

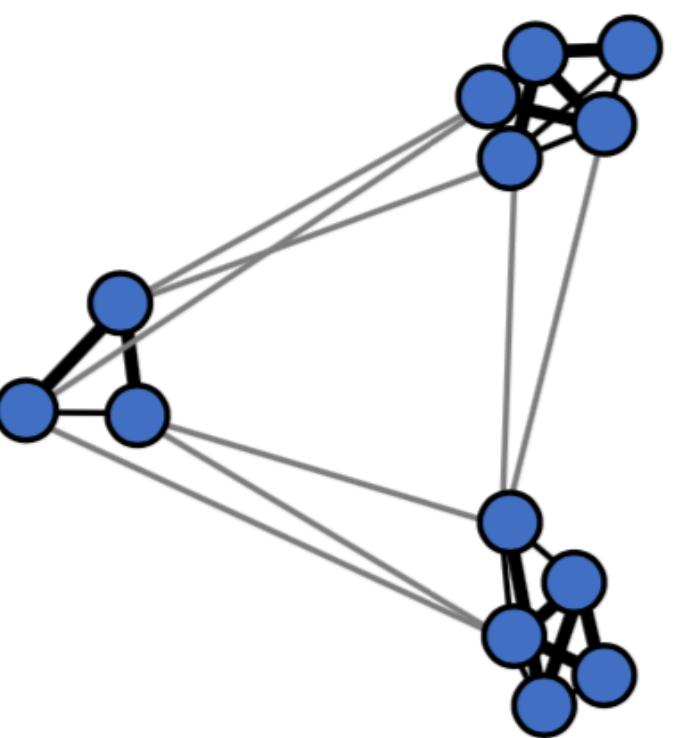


This is GRAPH
(a.k.a. network)

Sidestep: Graphs



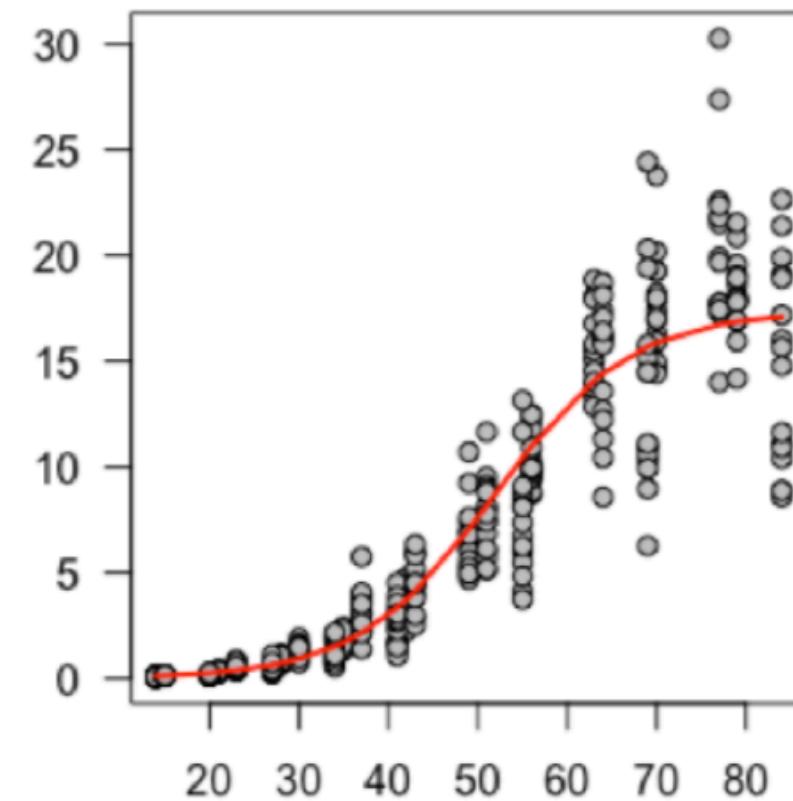
This is a PLOT



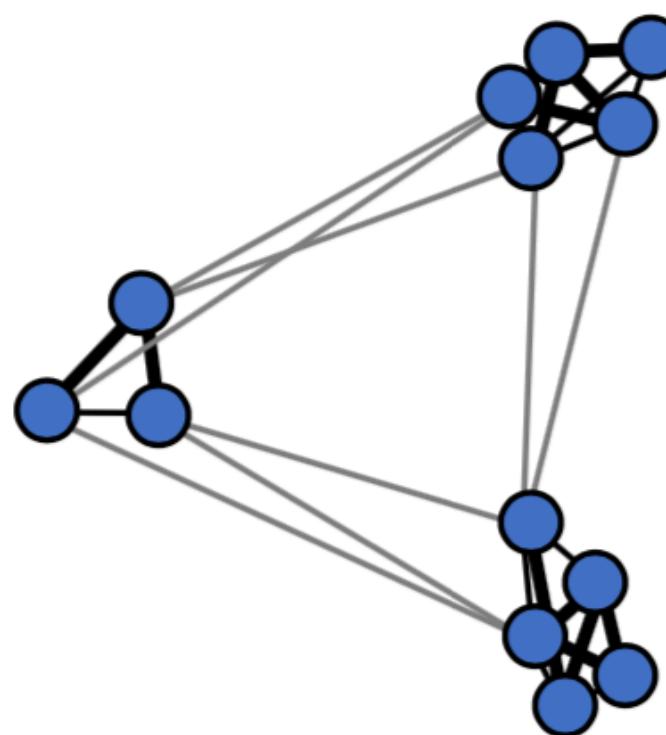
This is GRAPH
(a.k.a. network)

- Each dot is a cell (or a gene)
- Each line represents a connection between 2 cells
- Each connection can be weighted as a proximity between cells
 - Correlation (high and positive)
 - Euclidean distance (low)
 - etc.

Sidestep: Graphs



This is a PLOT



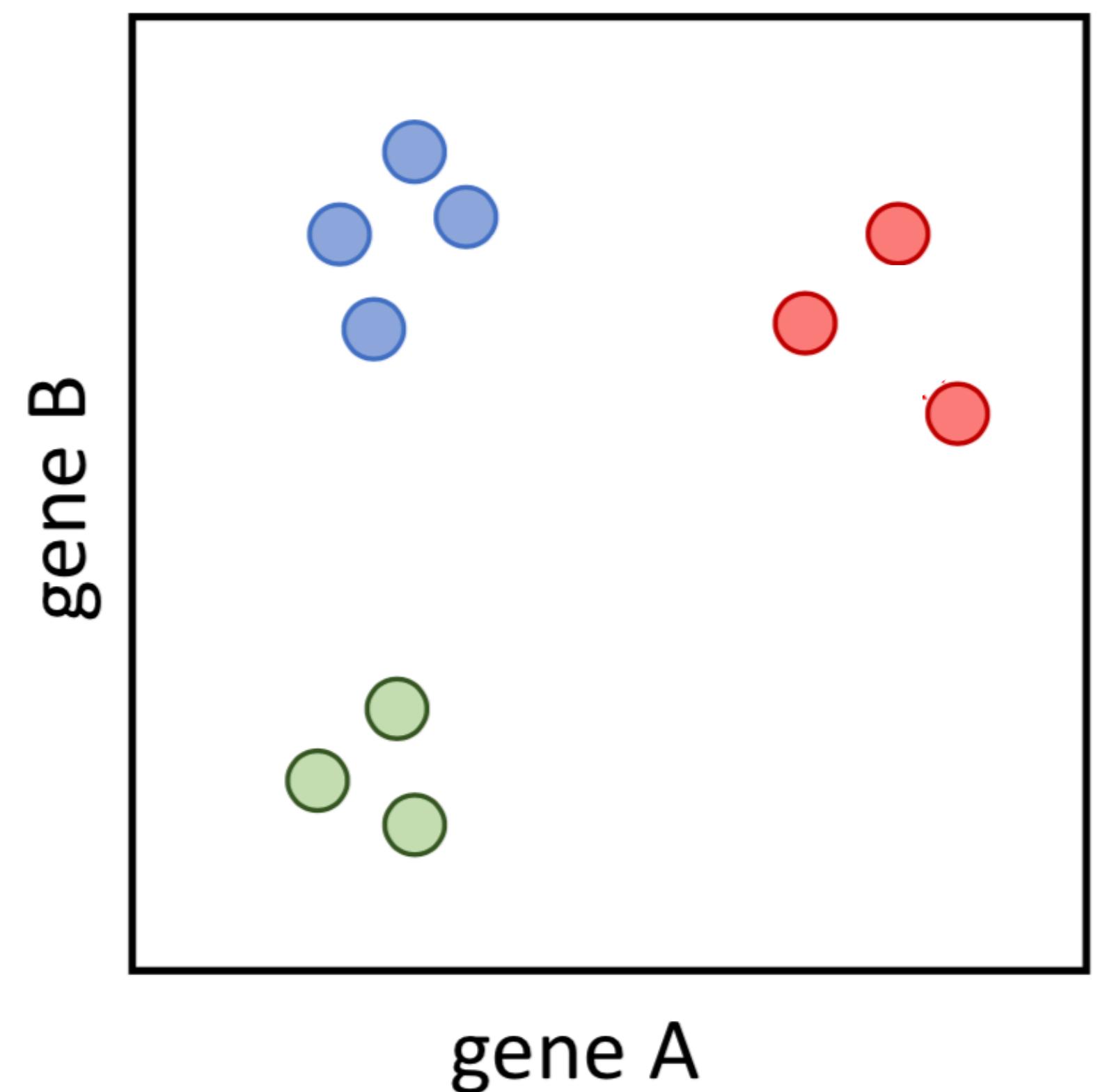
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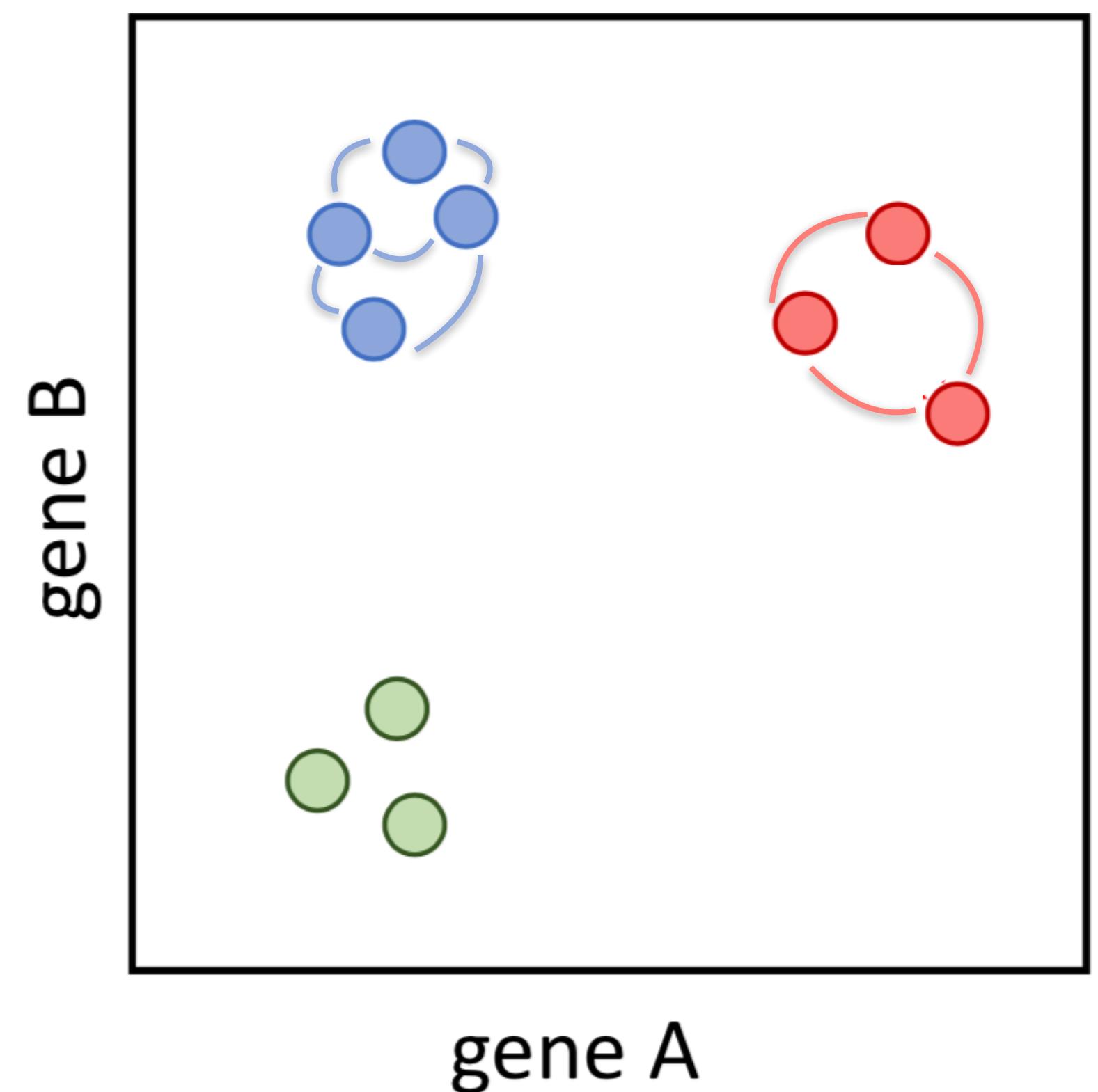
Graph-based dimensionality reduction algorithms can be divided into 2 main steps:

1. Construct a weighted graph based on the top k connections
(a.k.a. k -nearest neighbors, KNN)
2. The low dimensional layout of the graph is computed and optimized

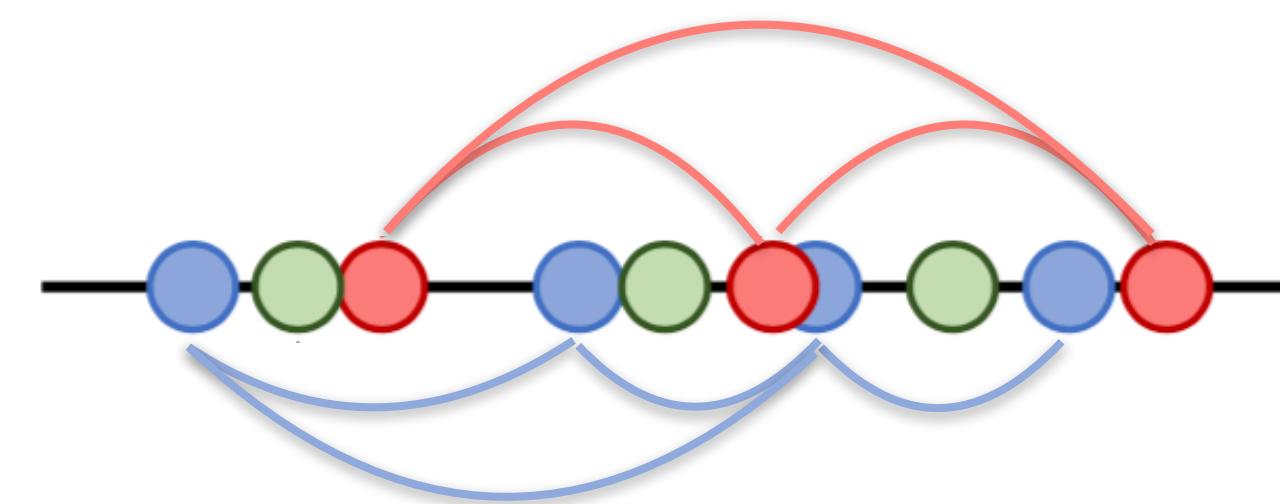
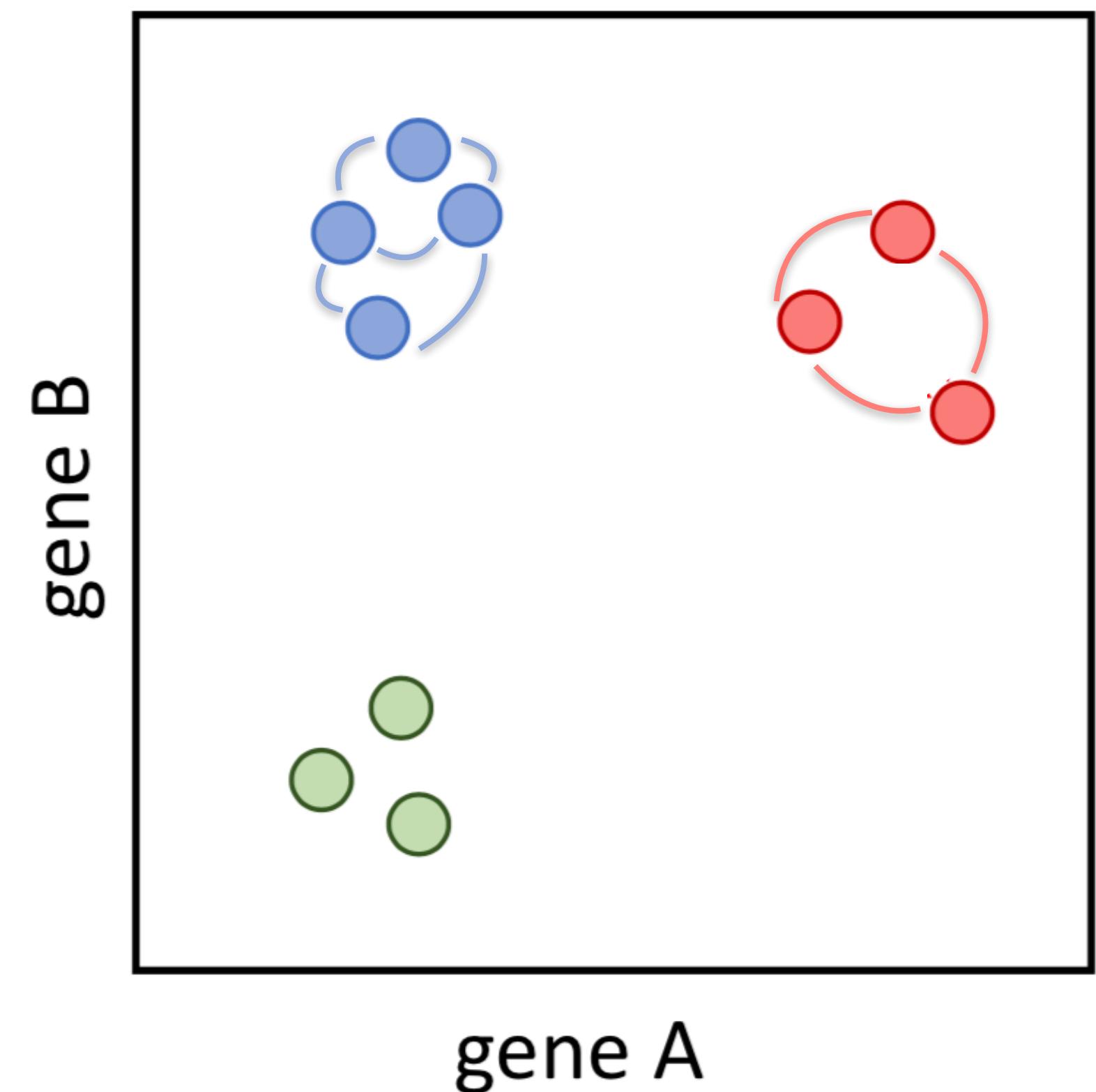
t-SNE in Brief



t-SNE in Brief

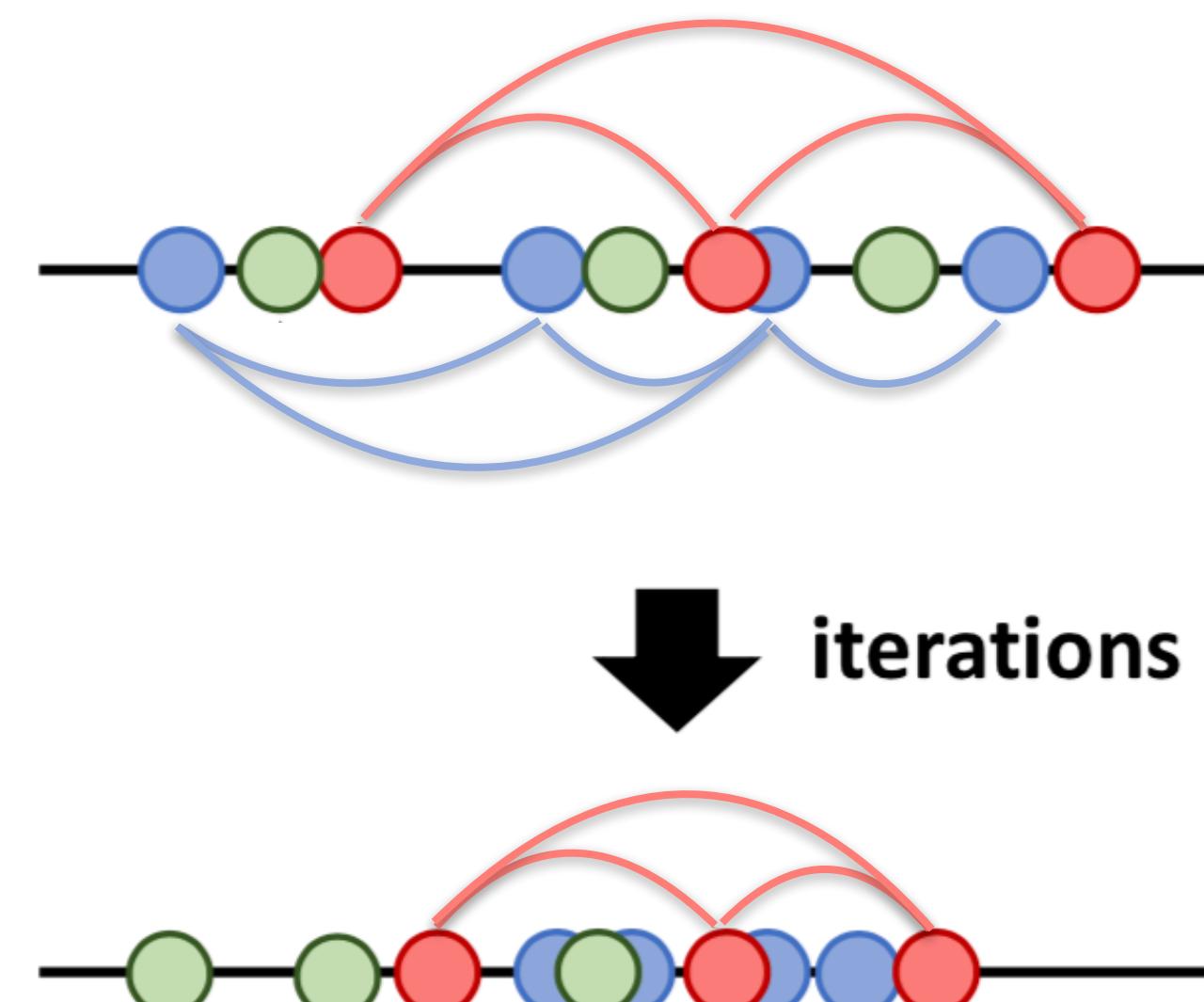
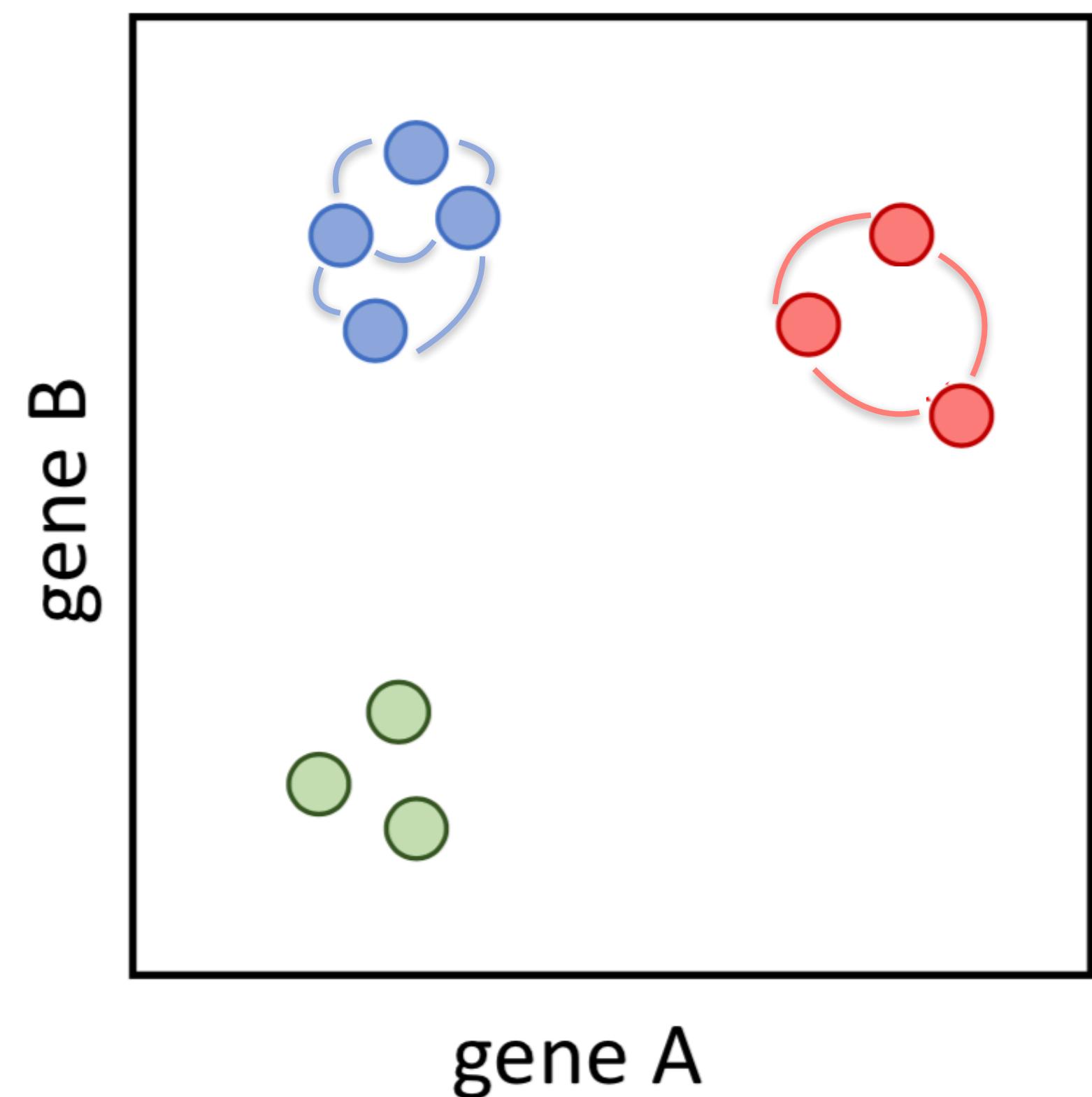


t-SNE in Brief



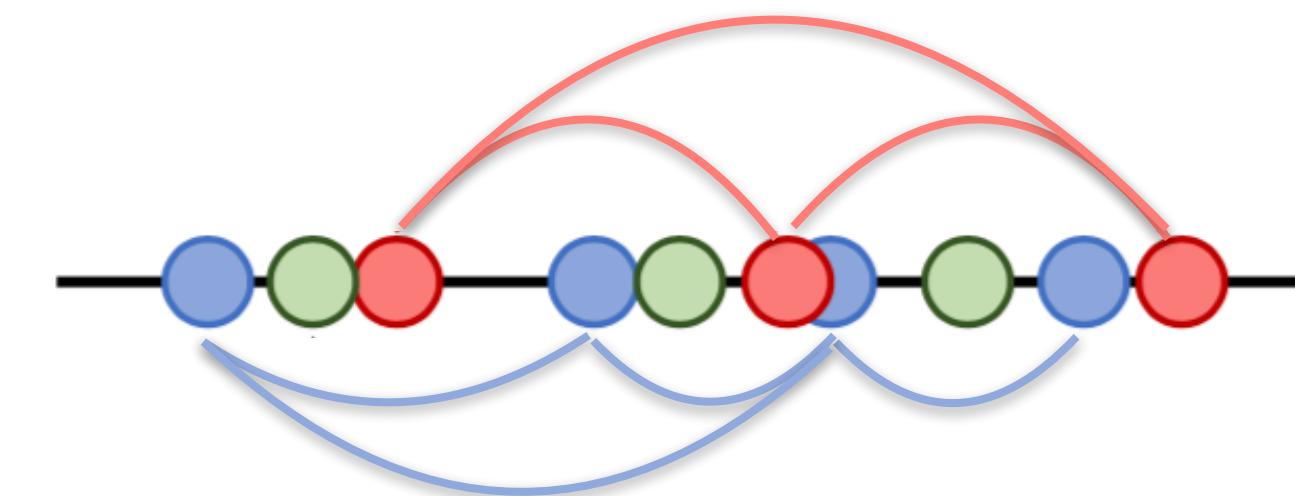
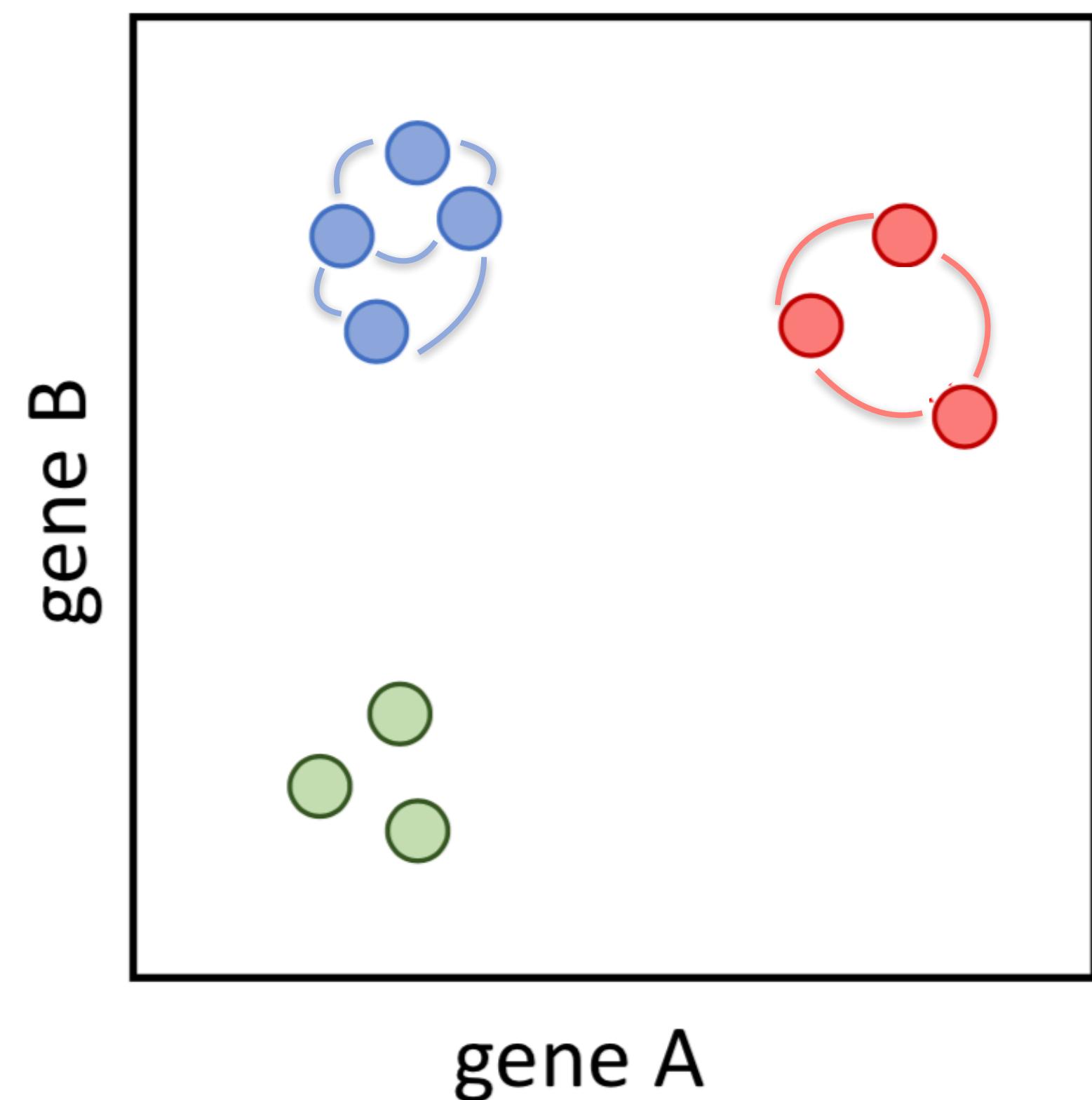
Higher KL divergence
(cost / error)

t-SNE in Brief



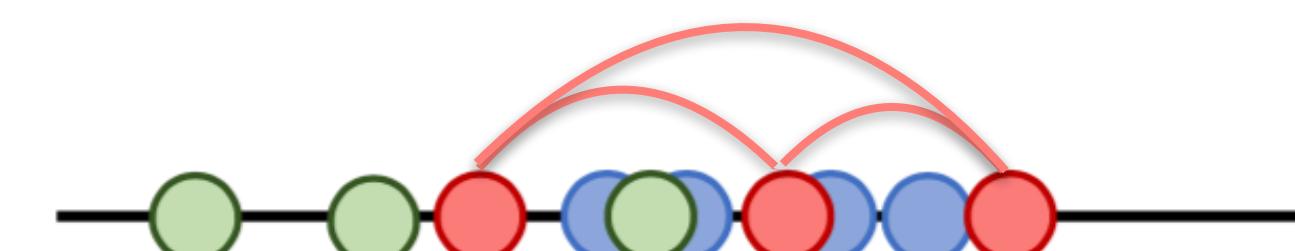
Higher KL divergence
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t-SNE in Brief

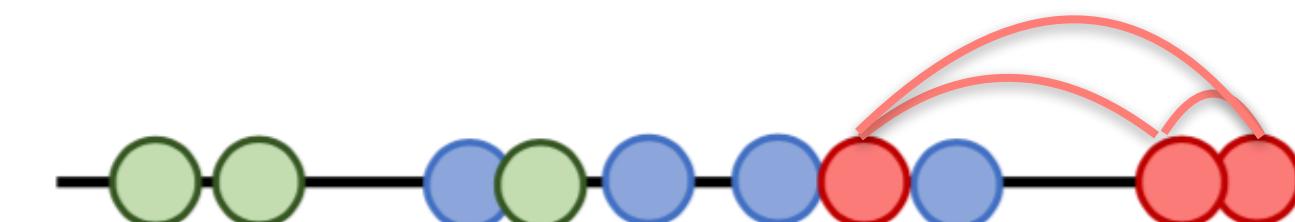


Higher KL divergence
(cost / error)

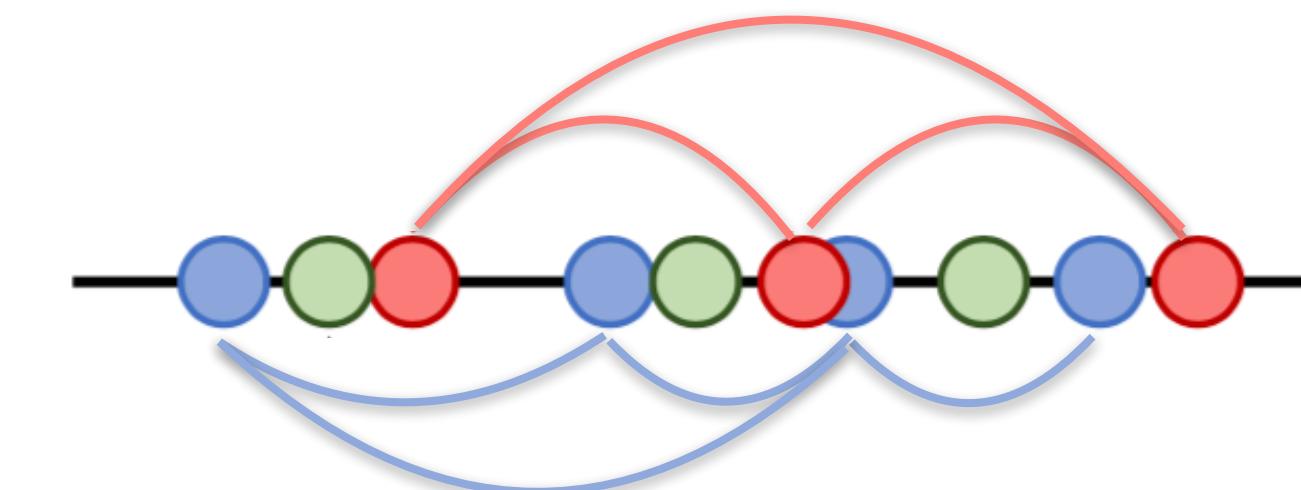
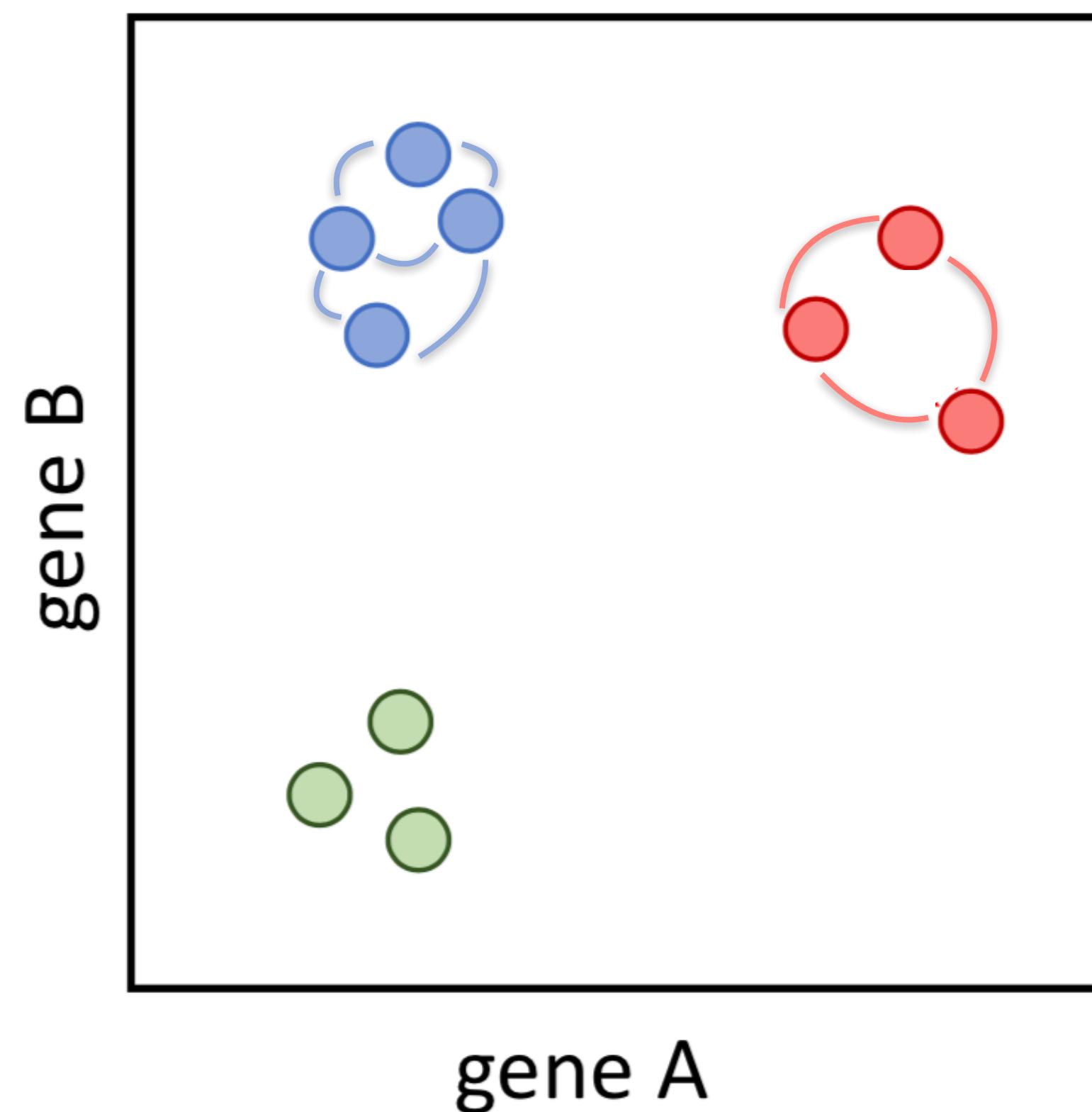
iterations



iterations

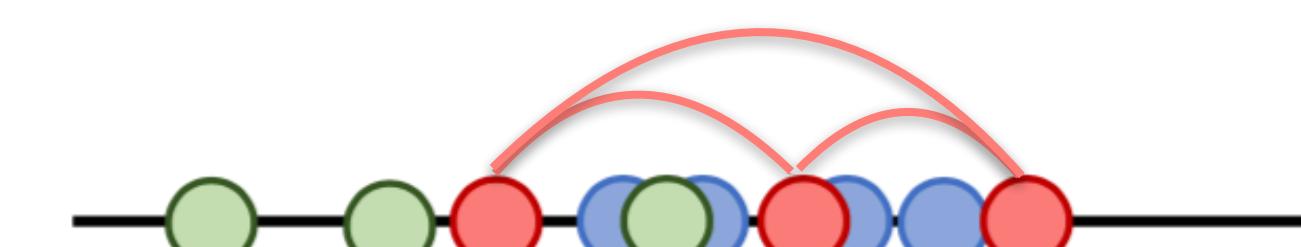


t-SNE in Brief



Higher KL divergence
(cost / error)

iterations



iterations



iterations



Lower KL divergence
(cost / error)

t-SNE in Brief

- 2 major computation parts in tSNE
 - compute high dimensional neighborhoods
 - optimize low dimensional neighborhoods
- Computationally intensive
 - Barnes-Hut implementation improves this
- Several parameters
 - Some can severely impact results

<https://distill.pub/2016/misread-tsne/>



t-SNE in Brief

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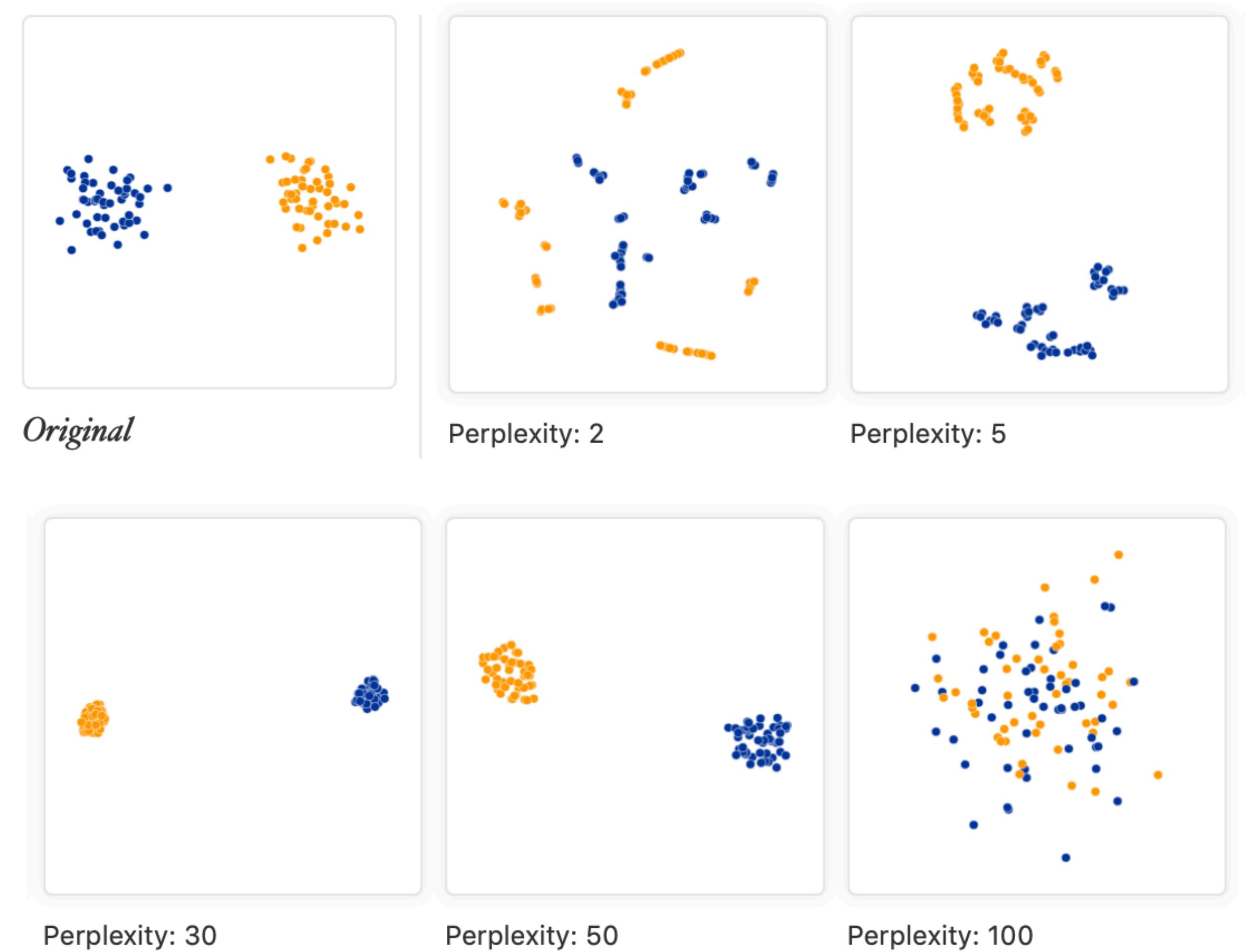
<https://distill.pub/2016/misread-tsne/>



t-SNE Parameters

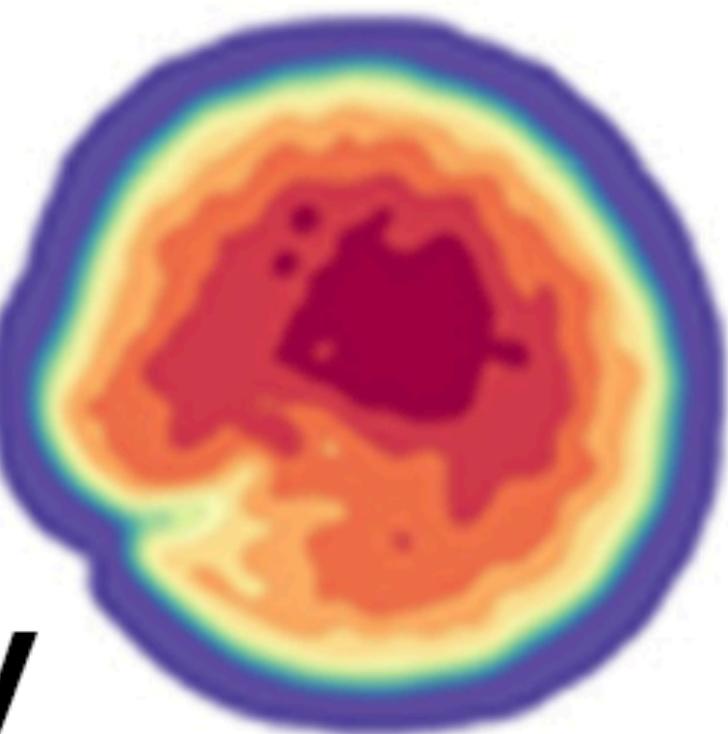
- Perplexity
- Number of iterations
- Learning rate
- Theta (for BH t-SNE)

...



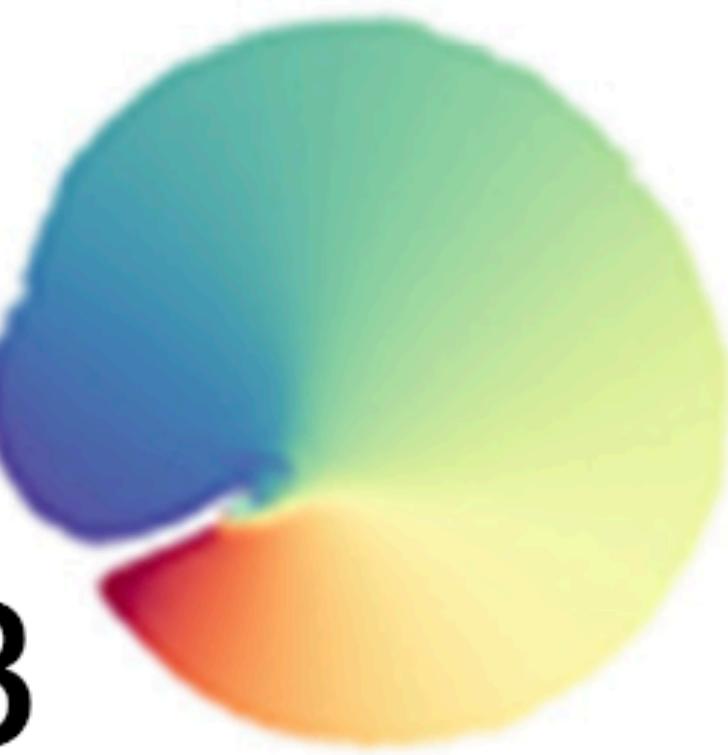
t-SNE Parameters

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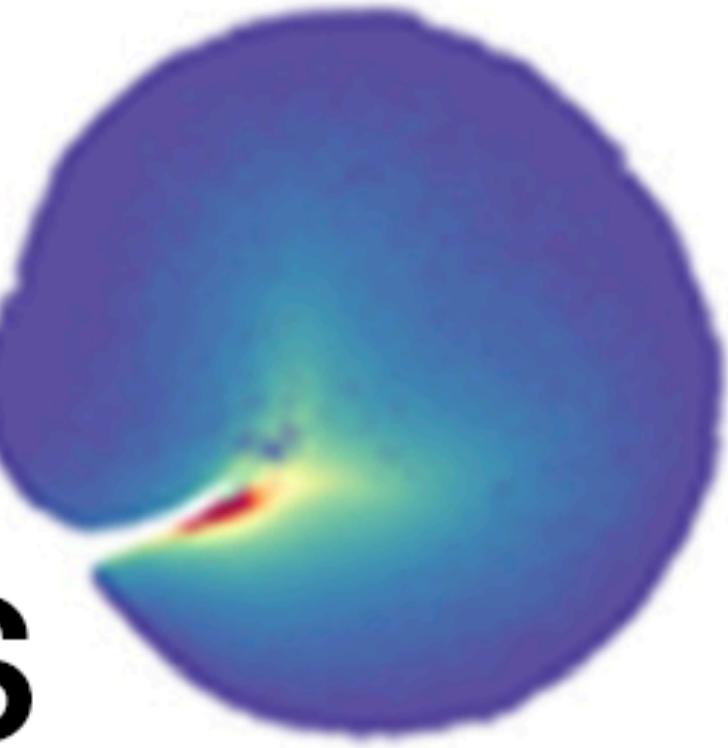
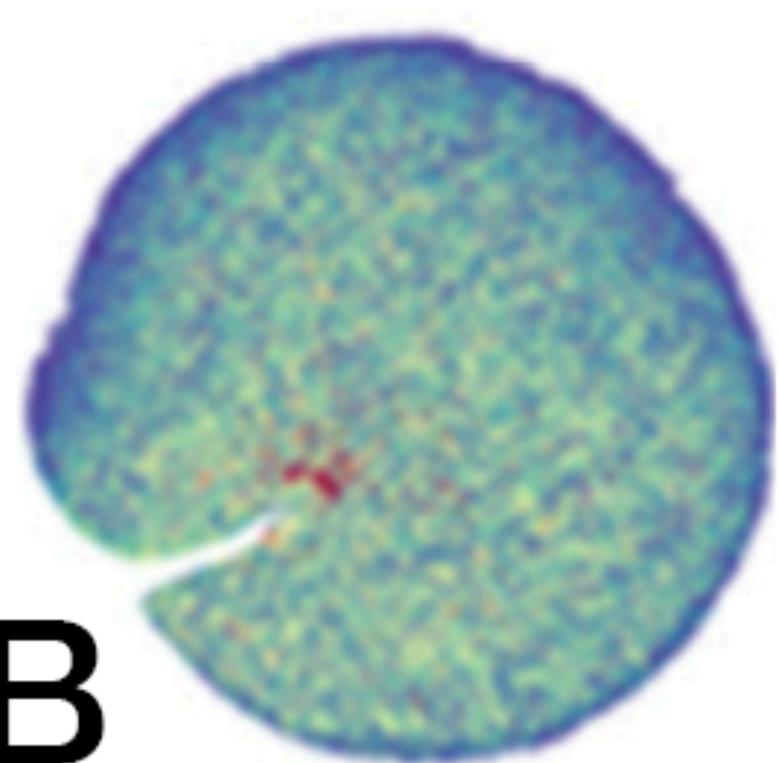
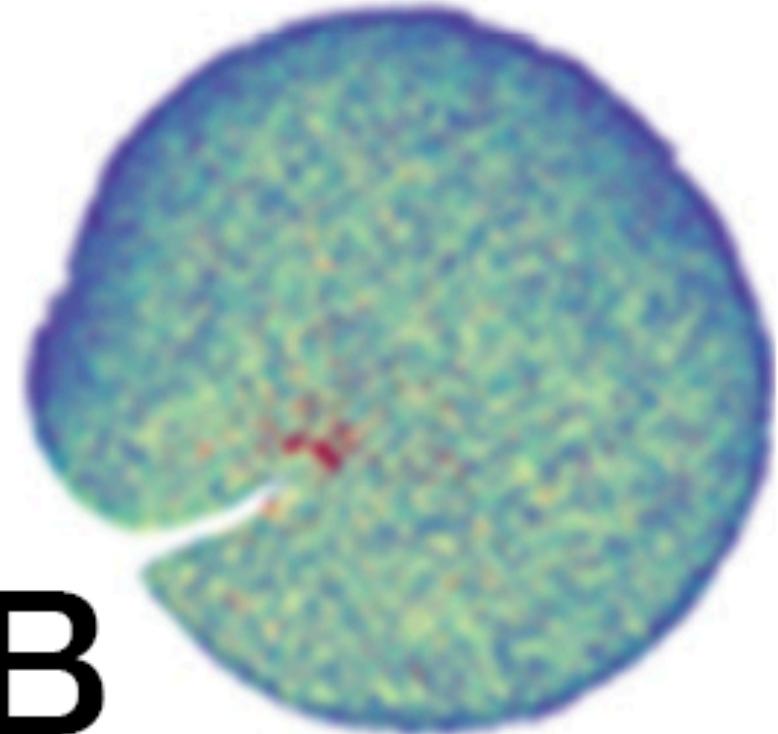


density

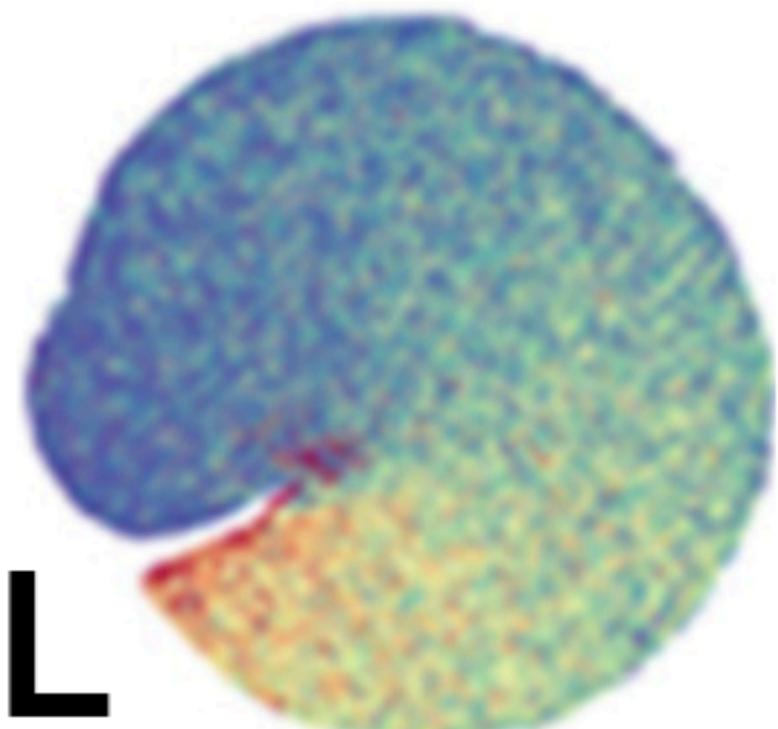
4-11BB



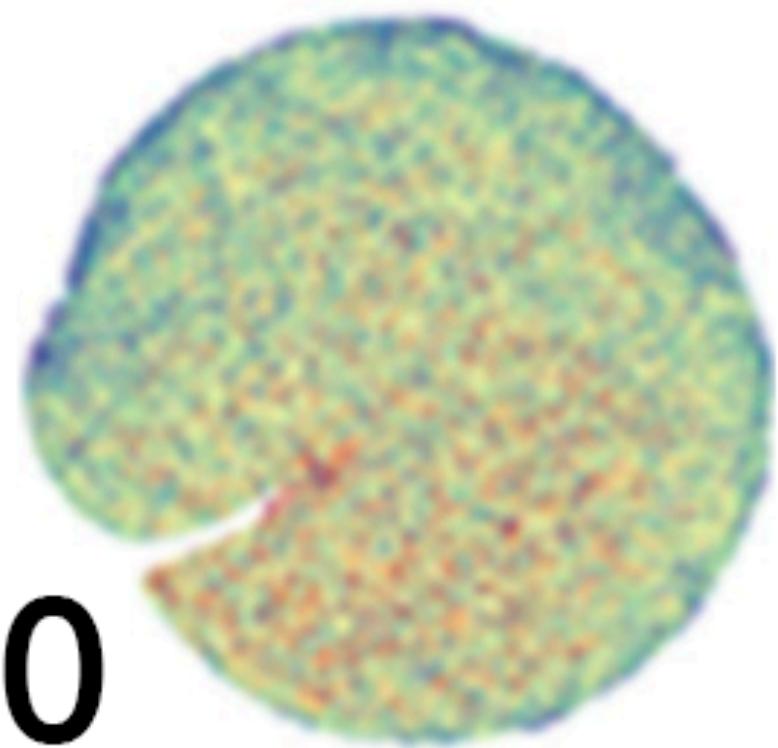
CD28



ICOS



CD40L



OX40

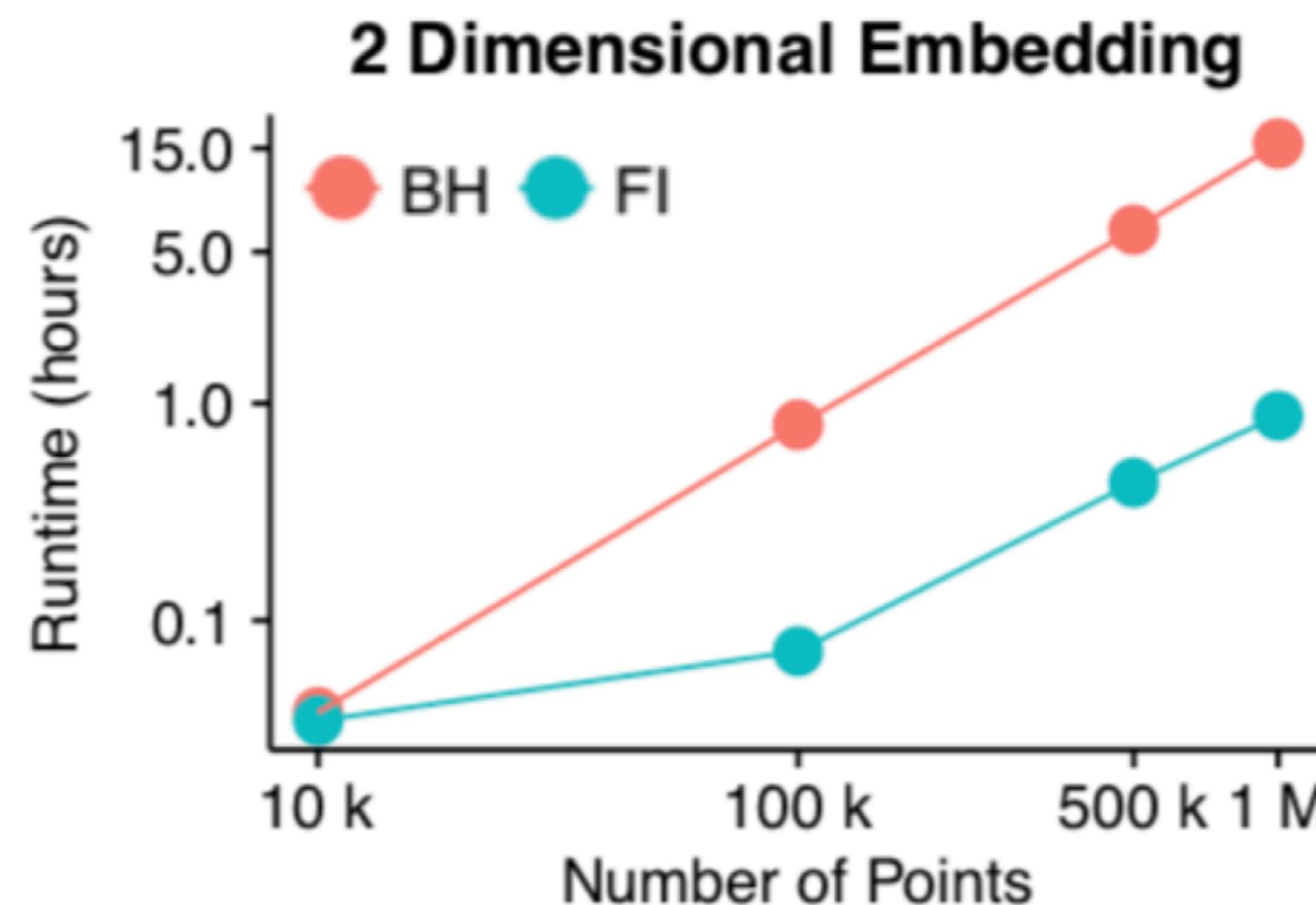
Important Notes

- Typically, the optimization is initialized randomly
Multiple runs will produce different results
- The cost function never reaches the minimum
- t-SNE optimizes the distance between close points (local embedding)
Distances within a group are slightly meaningful, but not between groups!
- To add more samples, you need to re-run the algorithm from start.

t-SNE Implementations

- Many Implementations available
- Fast Fourier Transform-accelerated

<https://www.nature.com/articles/s41592-018-0308-4>



Implementations

Below, implementations of t-SNE in various languages are available for download. Some of these implementations were developed by me, and some by other contributors. For the standard t-SNE method, implementations in Matlab, C++, CUDA, Python, Torch, R, Julia, and JavaScript are available. In addition, we provide a Matlab implementation of parametric t-SNE (described [here](#)). Finally, we provide a Barnes-Hut implementation of t-SNE (described [here](#)), which is the fastest t-SNE implementation to date, and which scales much better to big data sets.

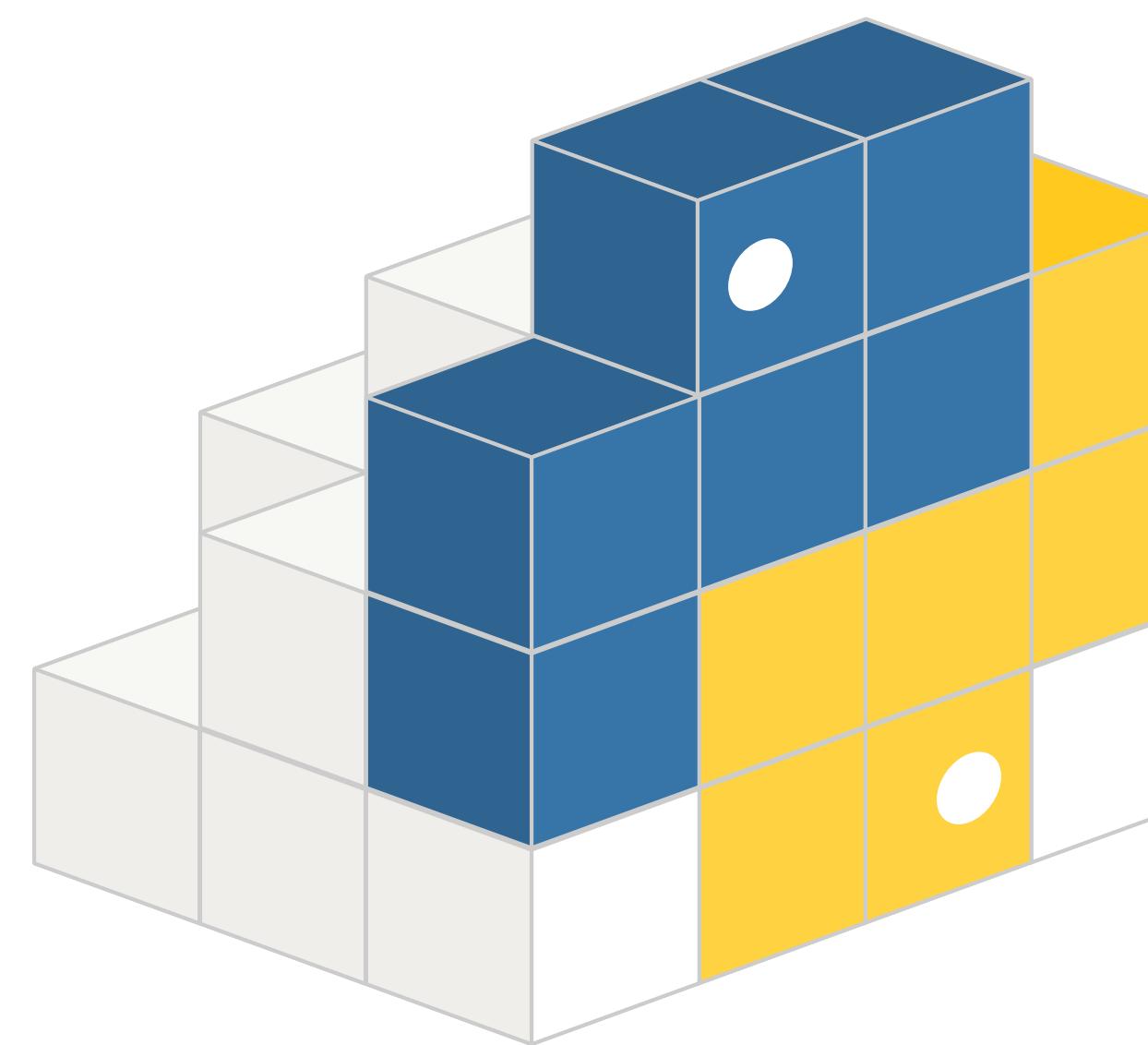
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NOTE: t-SNE is now built-in functionality in [Matlab](#) and in [SPSS](#)!

Matlab implementation (user guide)	All platforms
CUDA implementation (by David, Roshan, and Forrest ; see paper)	All platforms
Python implementation	All platforms
Go implementation (by Daniel Salvadori)	All platforms
Torch implementation	All platforms
Julia implementation (by Leif Jonsson)	All platforms
Java implementation (by Leif Jonsson)	All platforms
R implementation (by Justin)	All platforms
JavaScript implementation (by Andrej; online demonstration)	All platforms
Parametric t-SNE (outdated; see here)	All platforms
Barnes-Hut t-SNE (C++, Matlab, Python, Torch , and R wrappers; see here)	All platforms / Github
MNIST Dataset	Matlab file

<https://lvdmaaten.github.io/tsne/>

GPU t-SNE



PyPI

pip install nptsne

<https://pypi.org/project/nptsne/>

<https://www.github.com/biovault/>

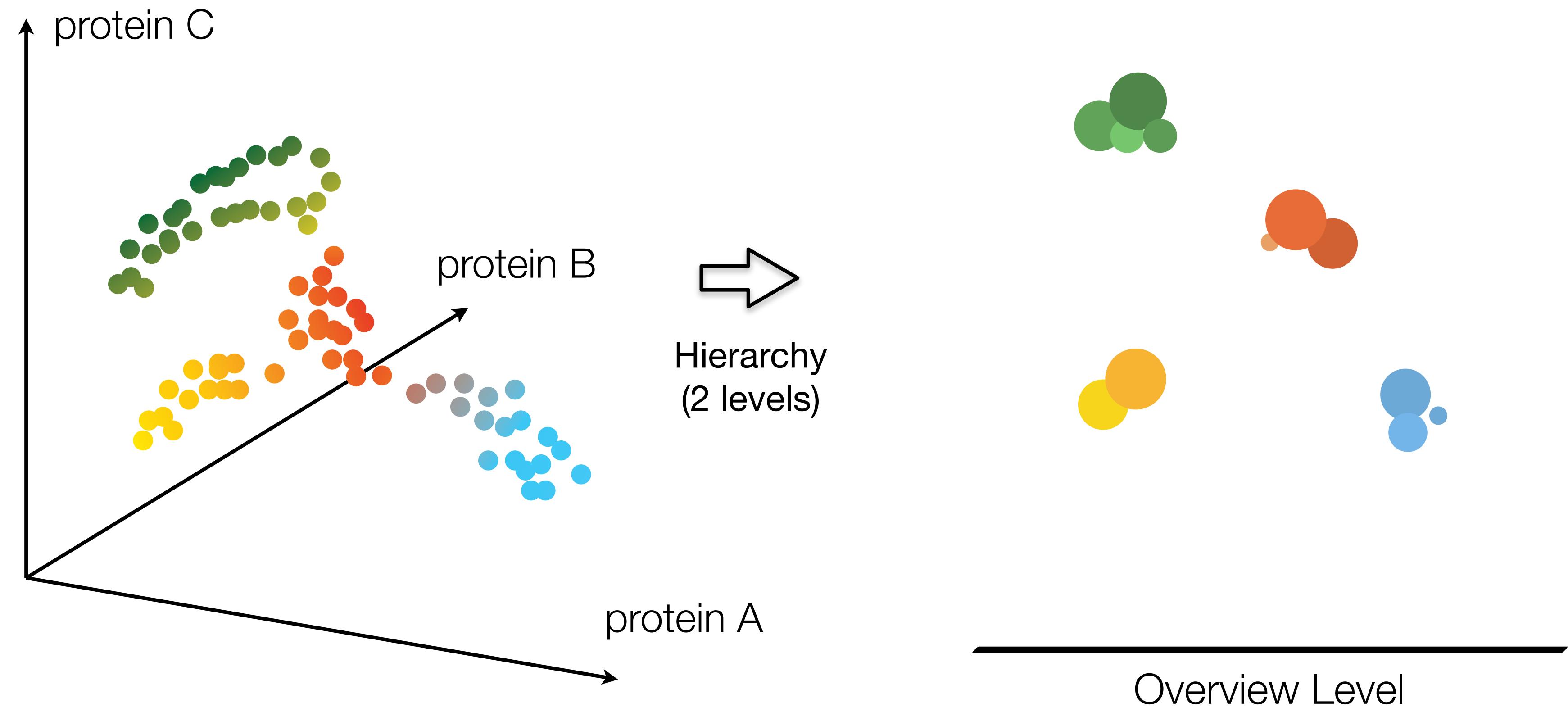
Summary: t-SNE

- NON-LINEAR method of dimensionality reduction
- It is the current GOLD-STANDARD method in single cell data (including scRNA-seq)
- Can be run from the top PCs (e.g.: PC1 to PC10)

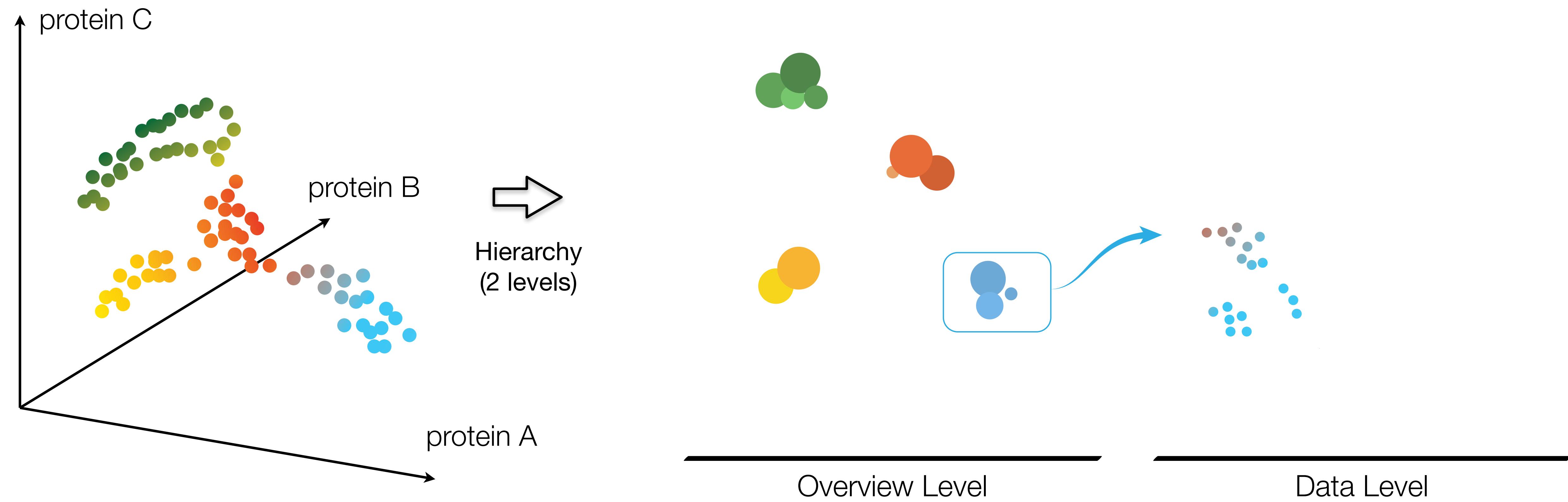
Problems:

- It does not learn an explicit function to map new points
- Its cost function is not convex – This means that the optimal t-SNE cannot be computed
- Many hyper-parameters need to be defined empirically (dataset-specific)
- It does not preserve global structure (in practice)

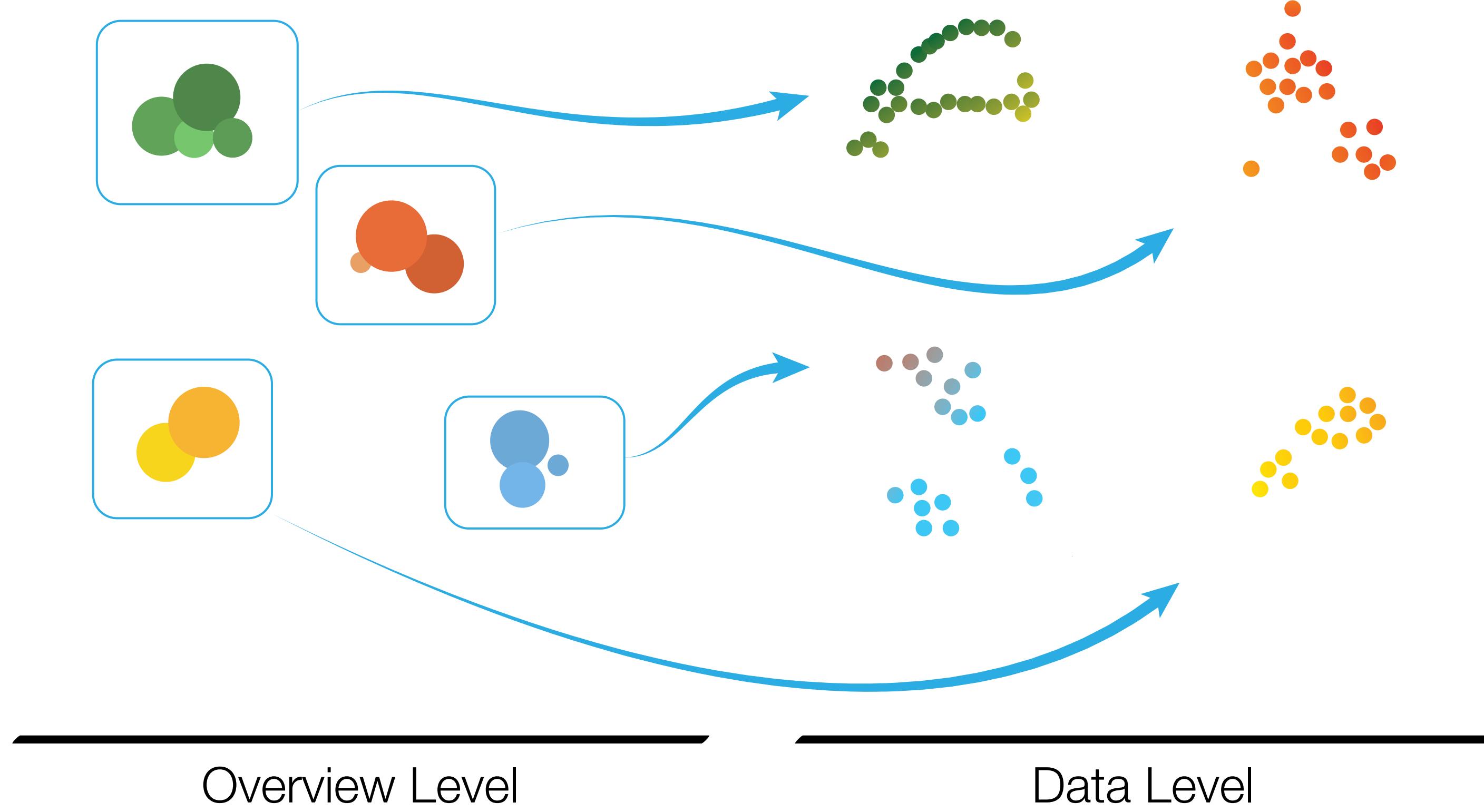
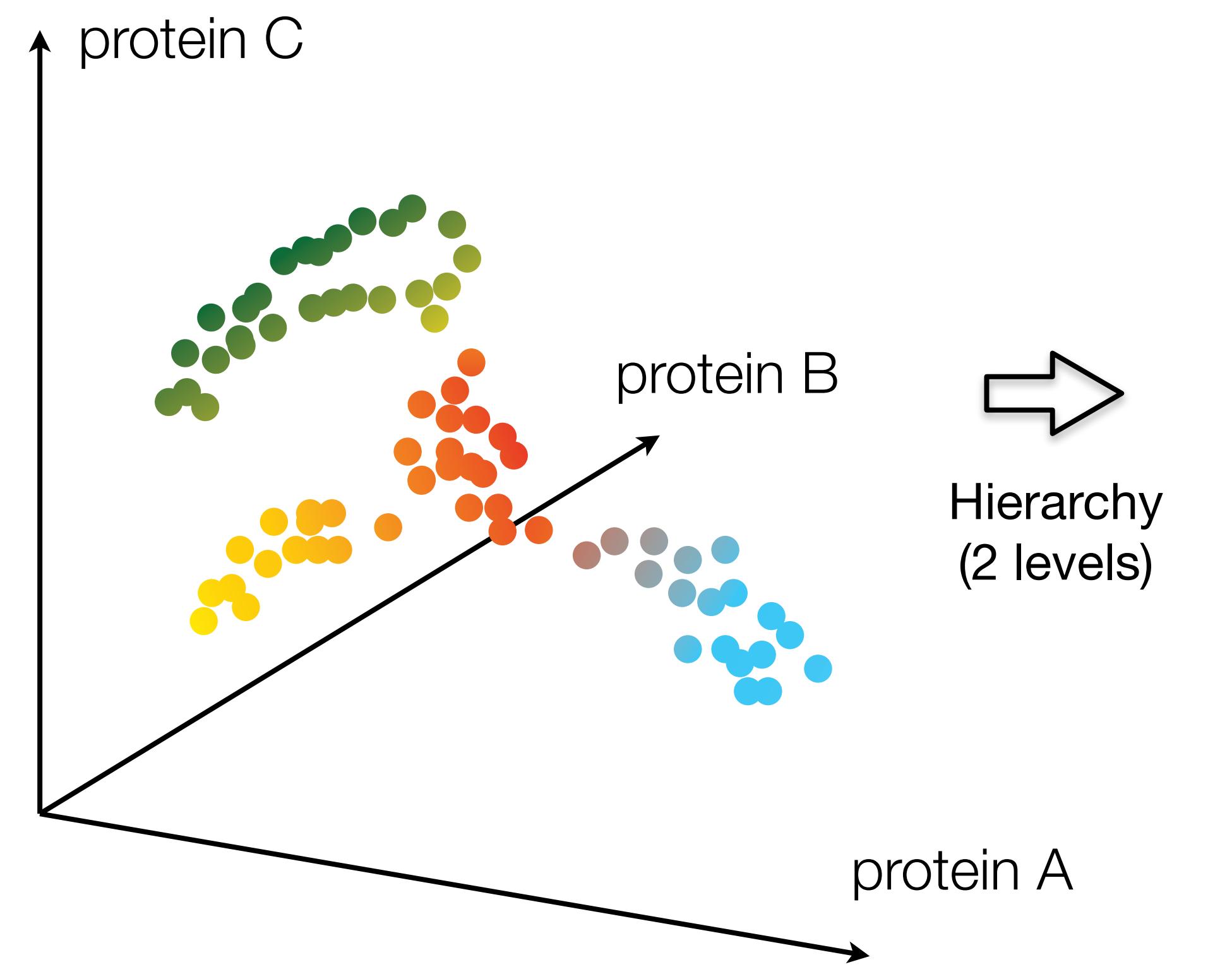
Hierarchical SNE

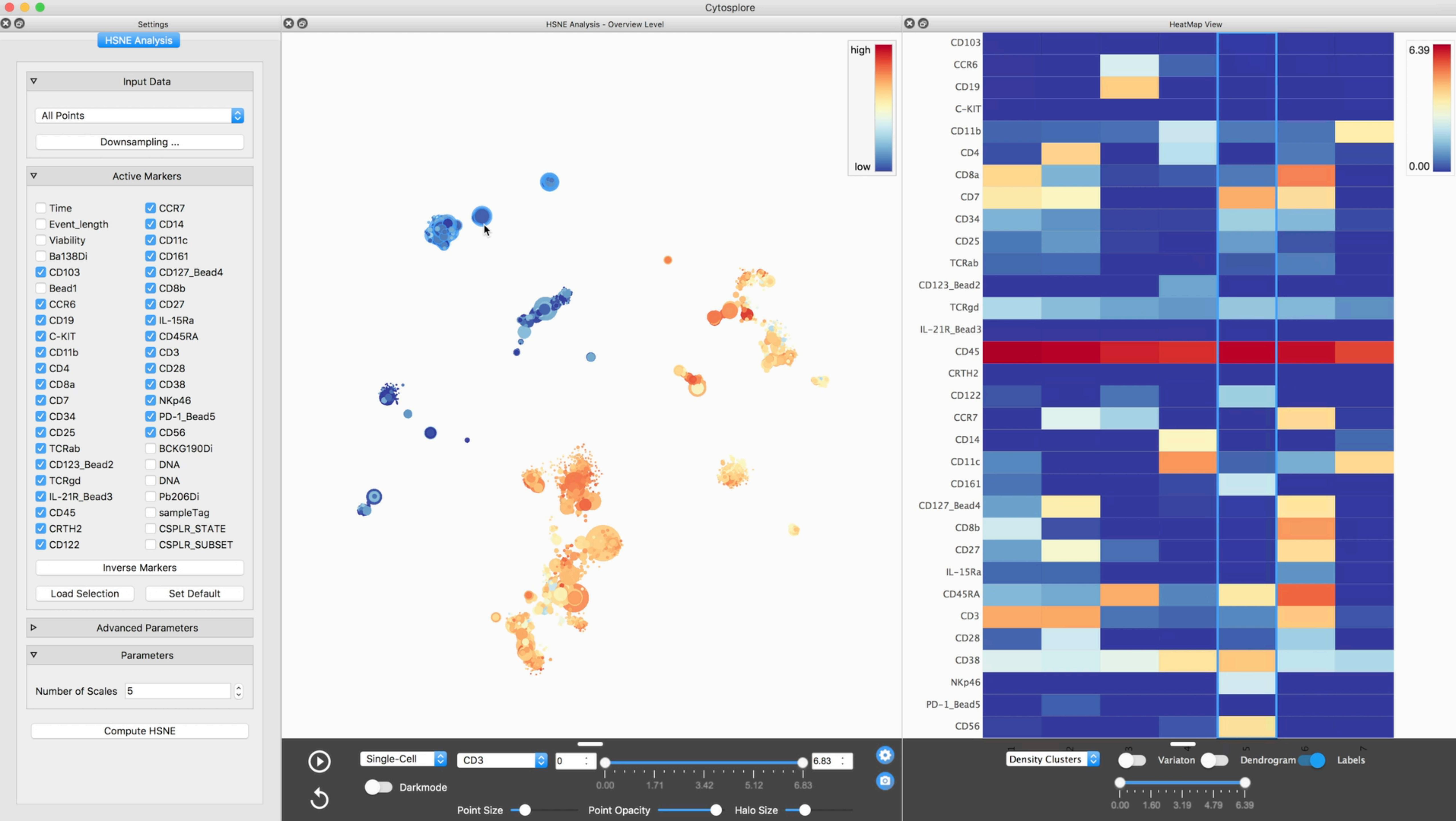


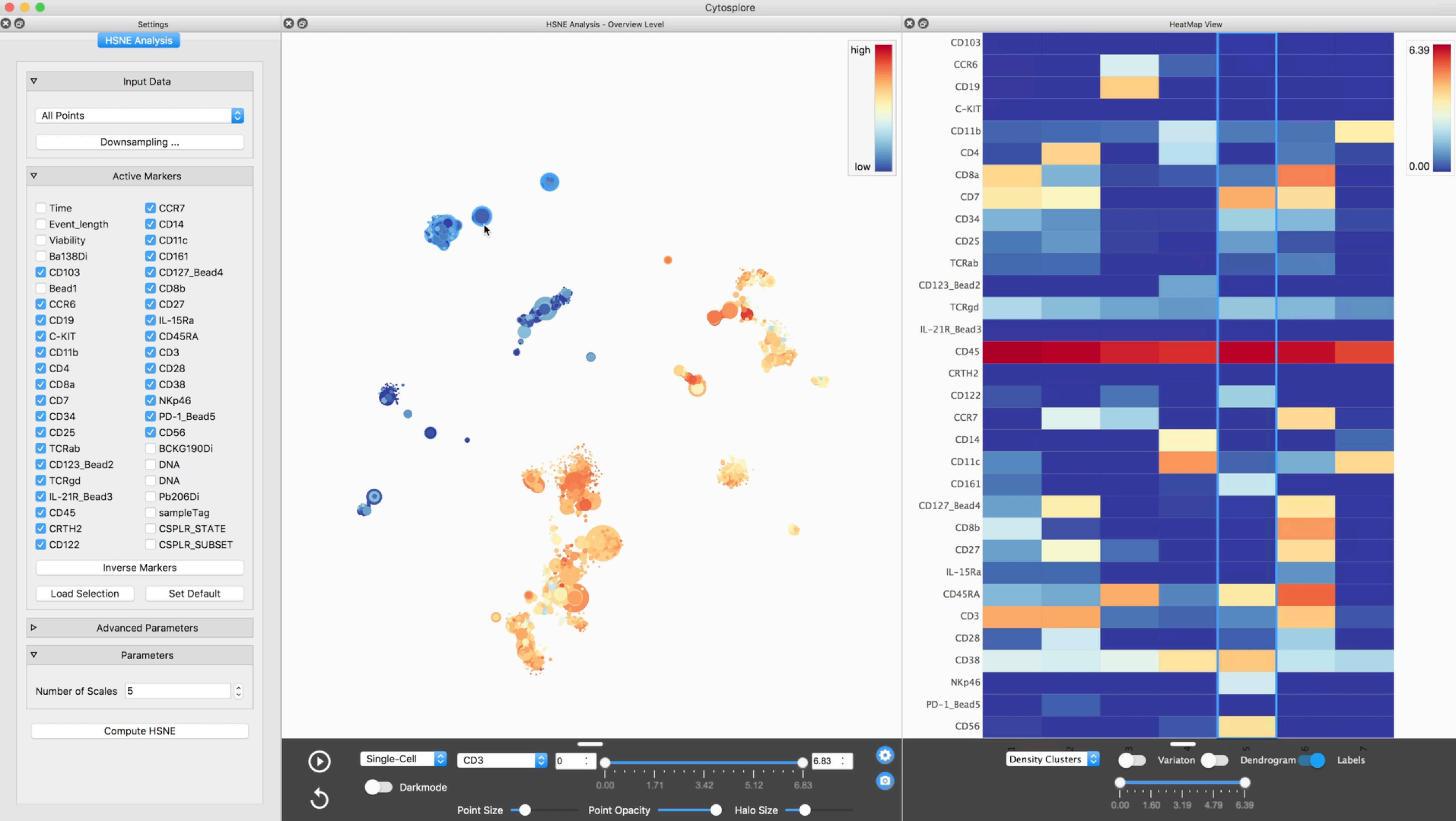
Hierarchical SNE



Hierarchical SNE





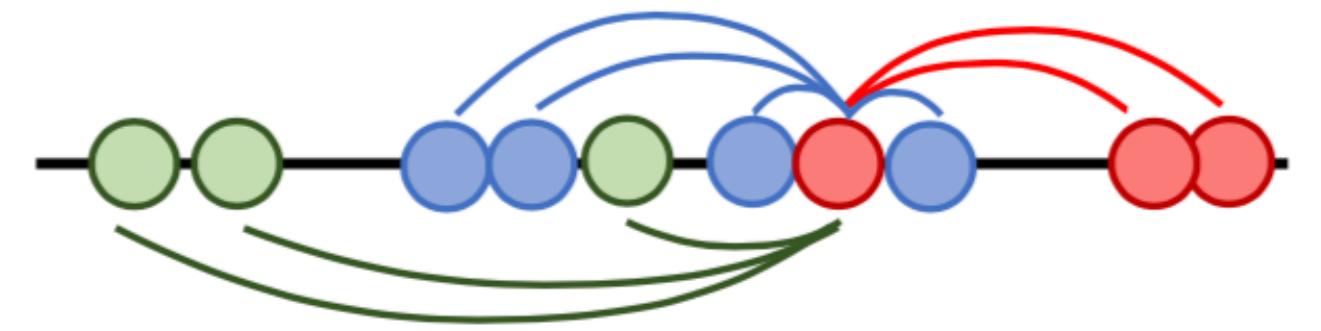
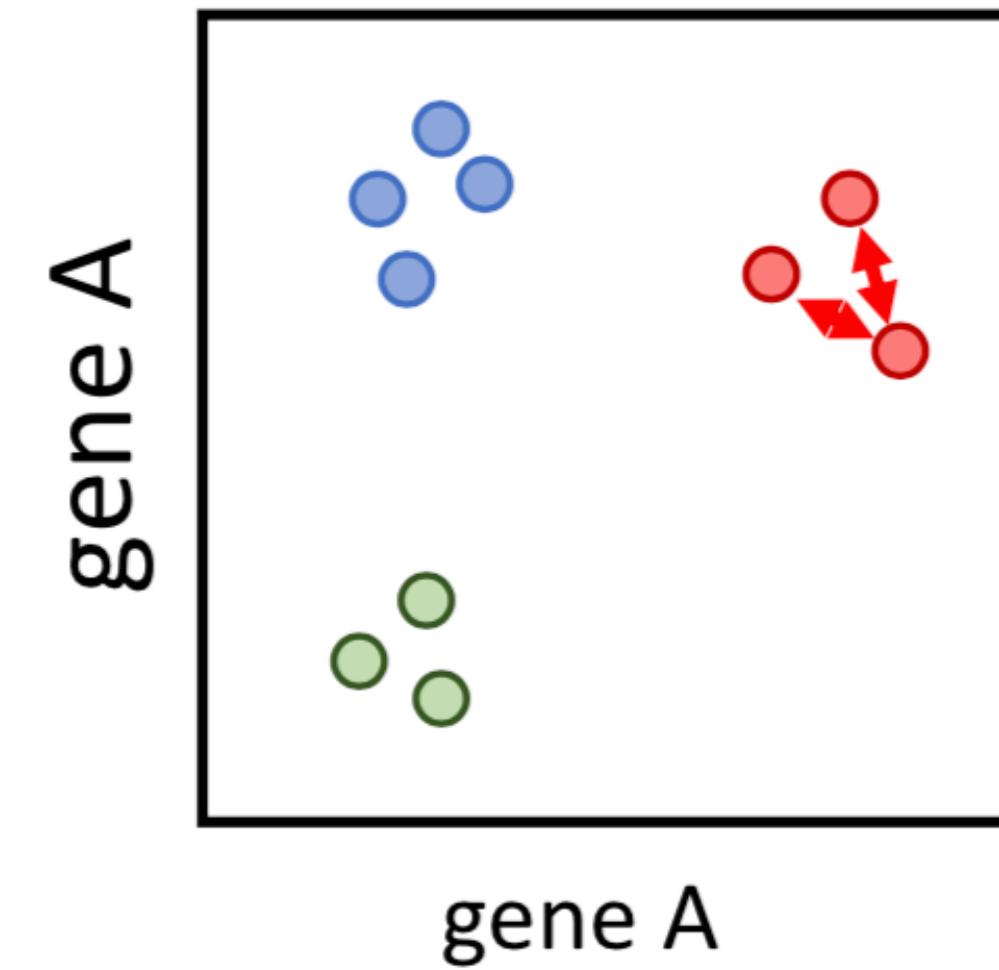


UMAP

Uniform Manifold Approximation and Projection

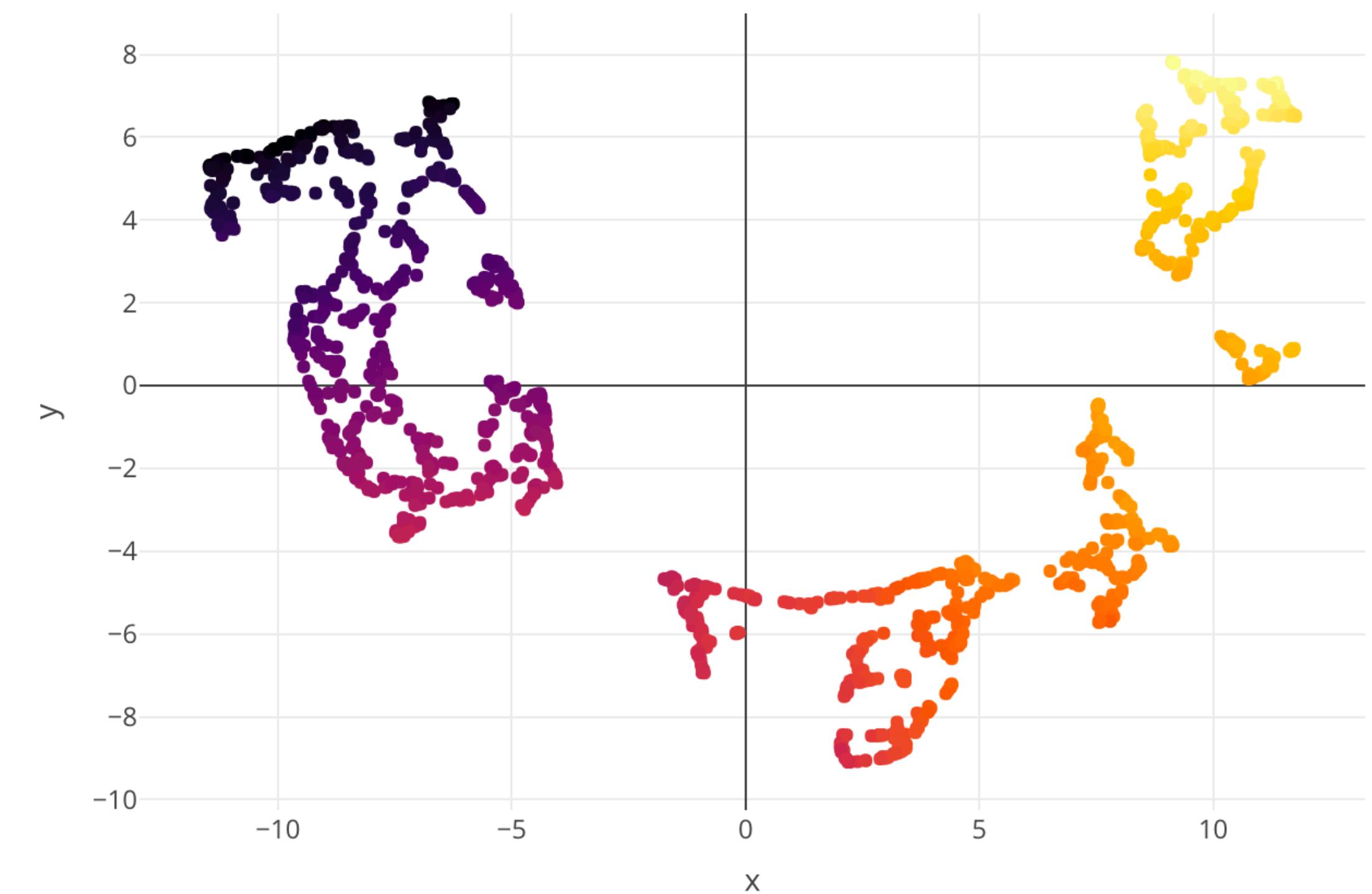
UMAP Intuition

- Similar principle as t-SNE
- Initializes with a non-heuristic “guess”
 - Same result every time
- Resolves global structure somewhat better (due to initialization)

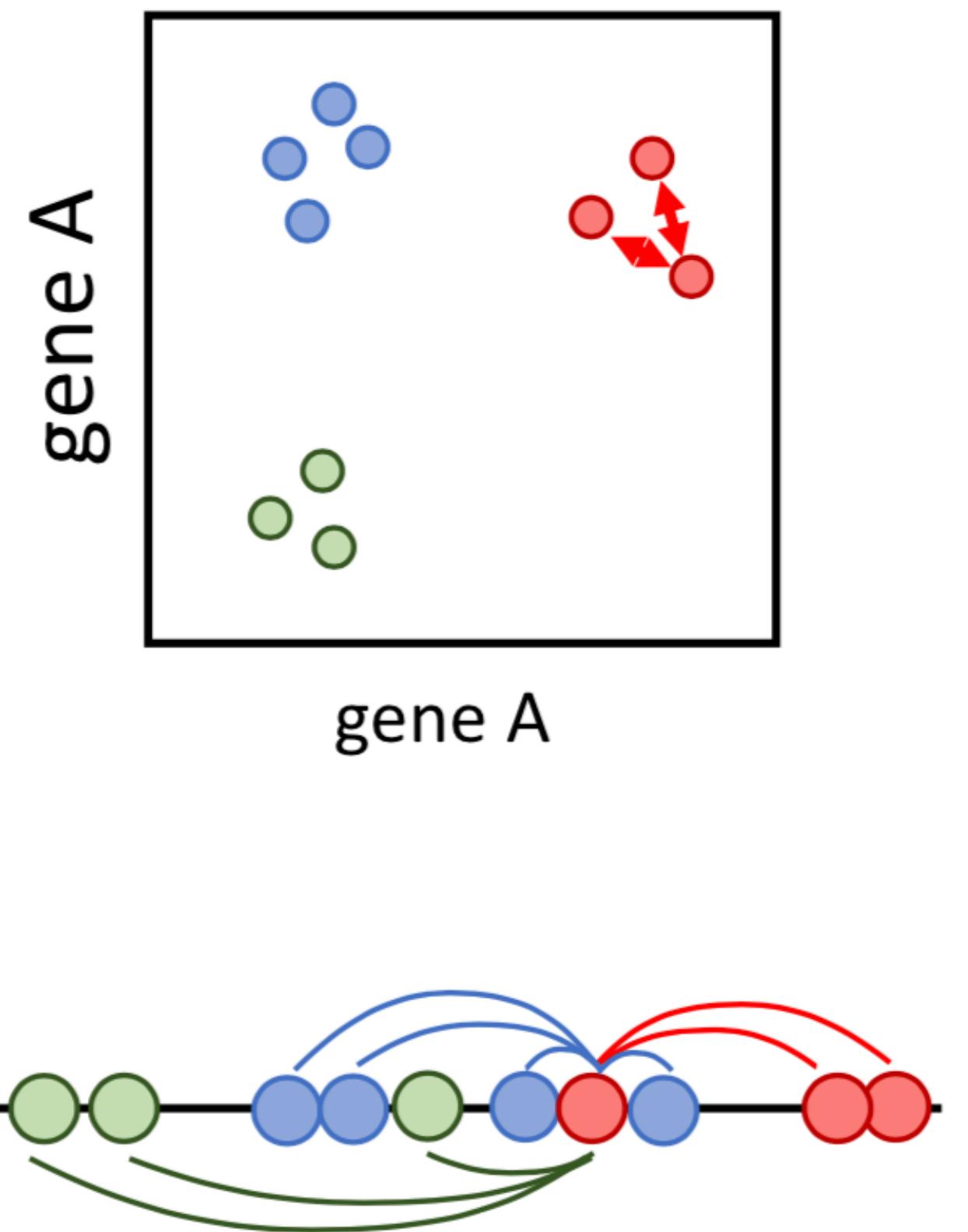


UMAP Intuition

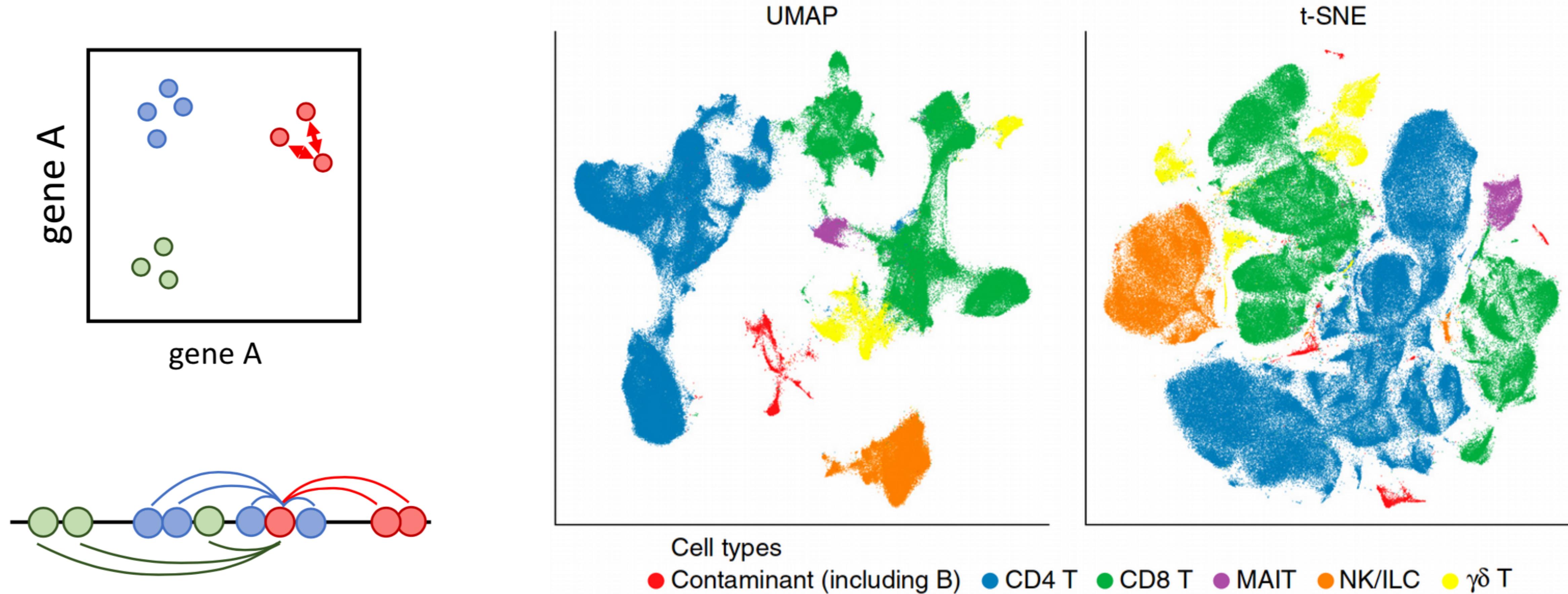
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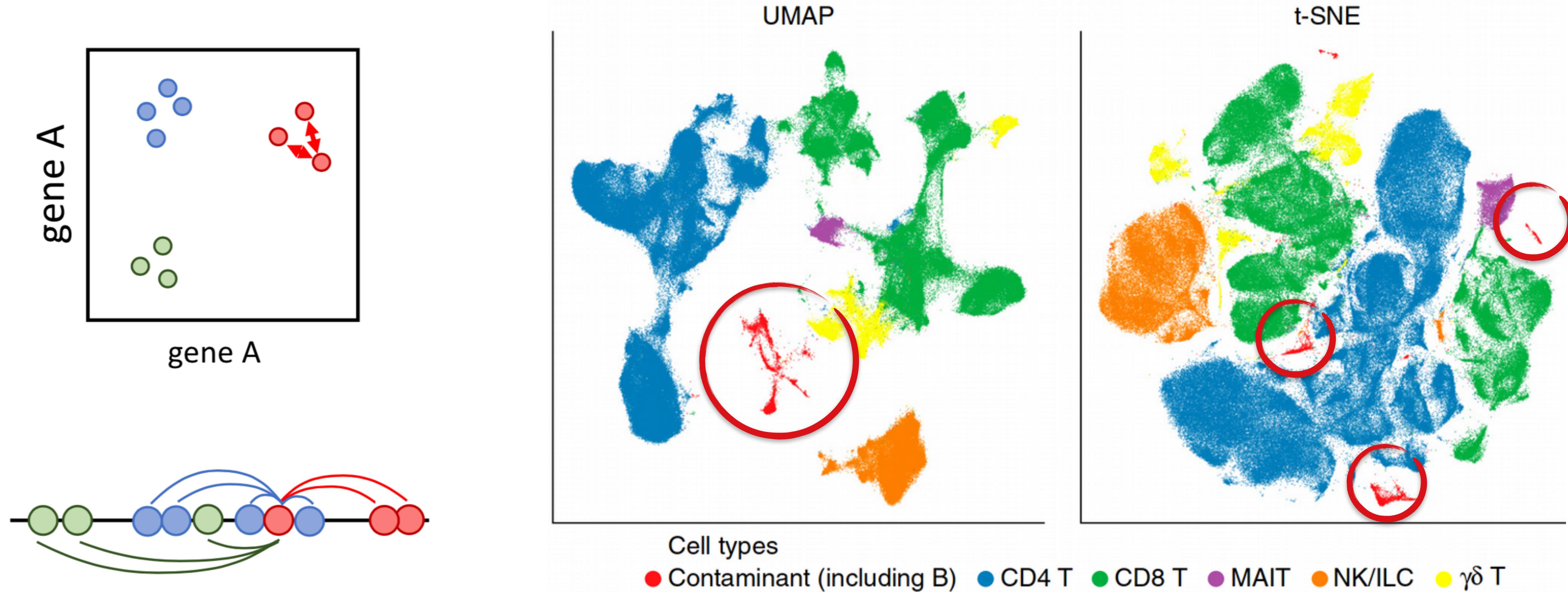
UMAP in Brief



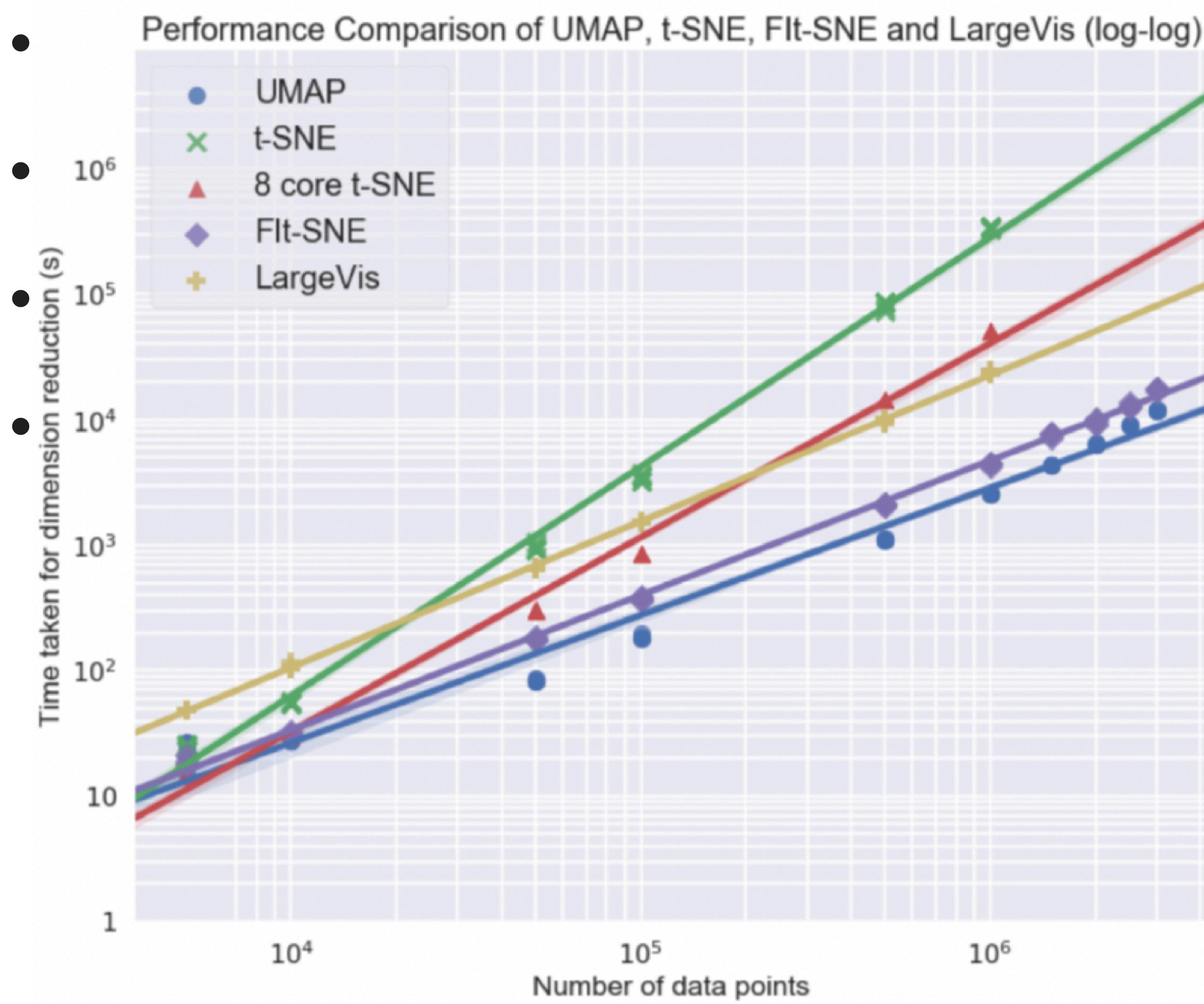
UMAP in Brief



UMAP in Brief



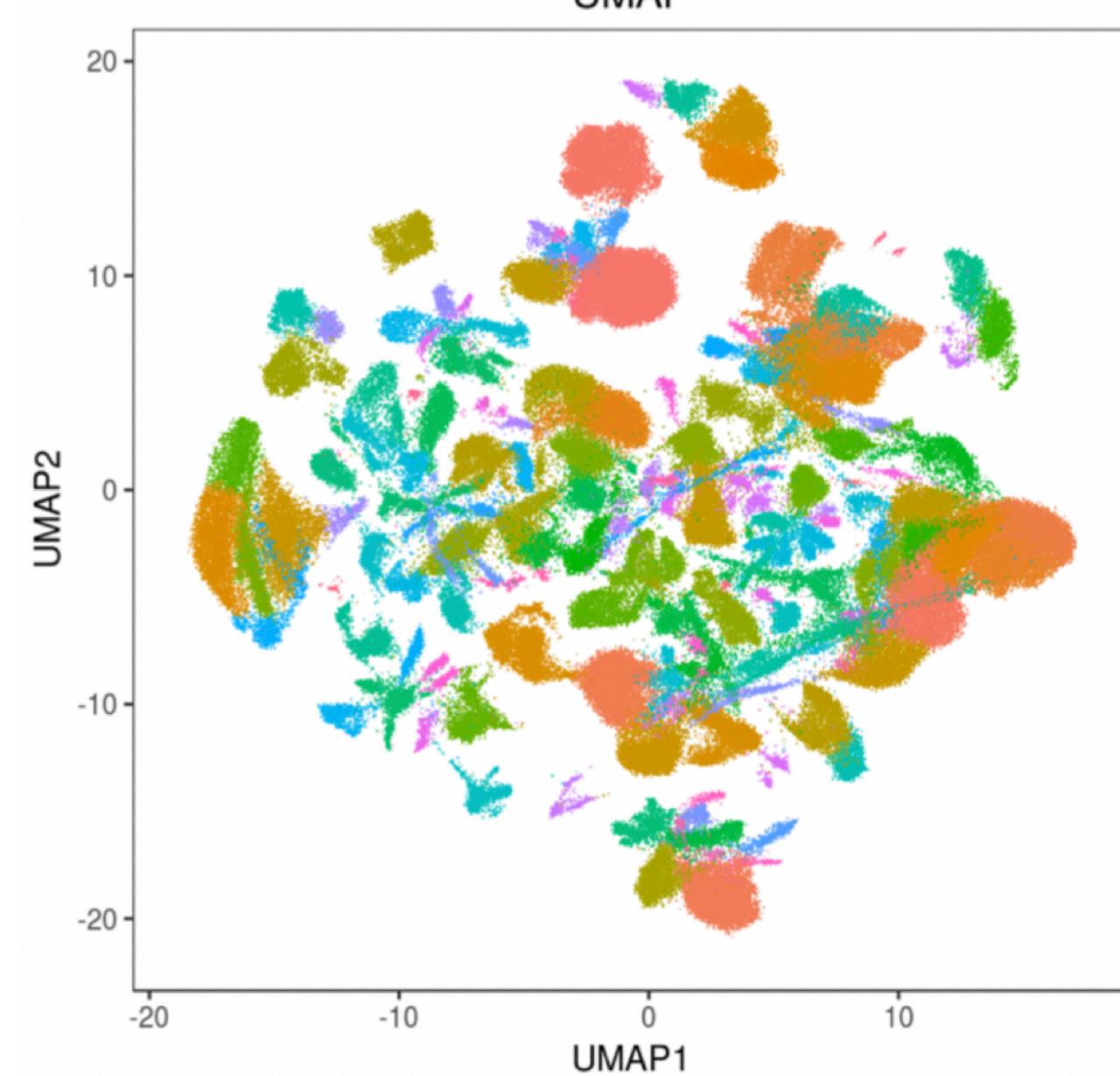
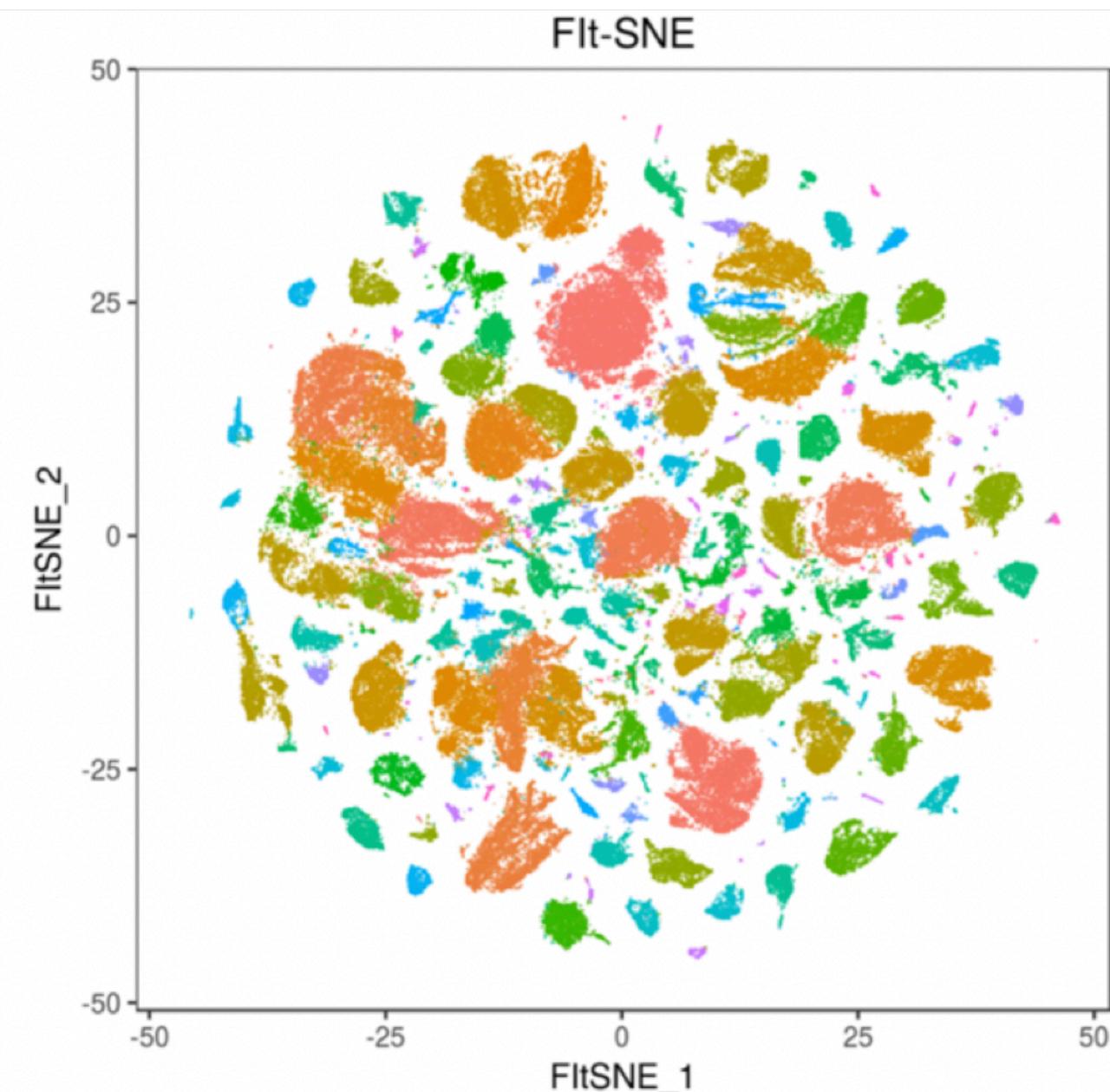
UMAP Parameters



250k cells

Flt-SNE
1 hour

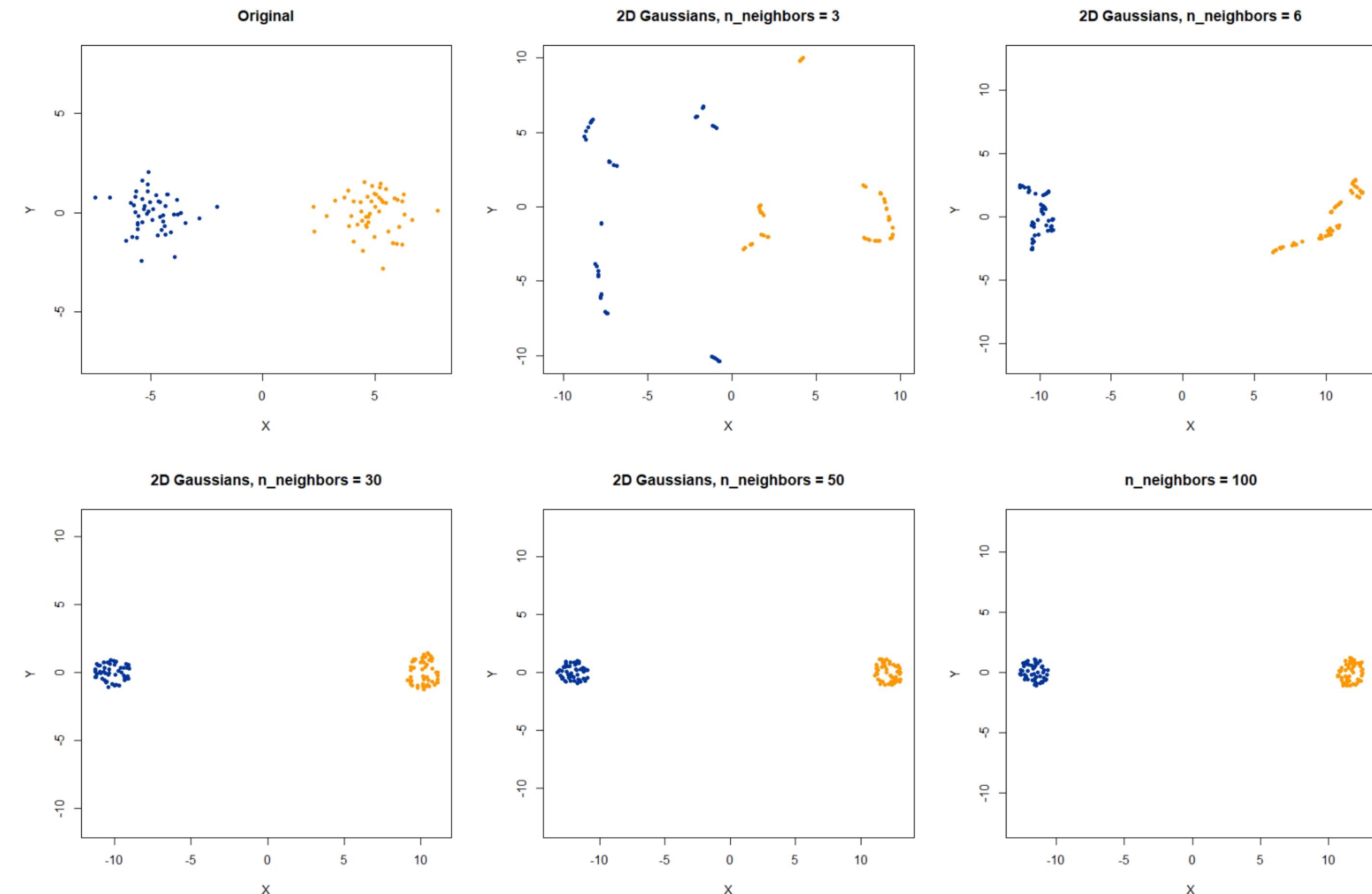
UMAP
7 minutes



UMAP Parameters

- Number of neighbors
- Number of iterations
- Minimum Distance (low-D)
- Metrics

...



Summary: UMAP

- NON-LINEAR method of dimensionality reduction
- Very efficient to compute
- Can be run from the top PCs (e.g.: PC1 to PC10)
- Is not randomly initialized and allows
- It should preserve global structure

Problems:

- It is designed to group cells stronger than t-SNE to show meaningful larger distances
- Similar number of hyper-parameters as t-SNE

www.cytosplore.org
graphics.tudelft.nl
 **@thomashollt**

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STW / NWO Grant 12720 VAnPIRe
LKEB, IHB, LCBC @ LUMC
CGV @ TU Delft