# Sistemas Distribuídos

### Group Communication

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# **Group Communication**

### Characterization



- Group Communication
  - All participating **processes are peers**, with **no special roles** or privileges.
  - ► This is known as communication among equals.
- Access to Shared Resources
  - Requires mechanisms to prevent race conditions.
    - Race conditions can cause inconsistent data if processes access shared resources unsafely.

### Characterization

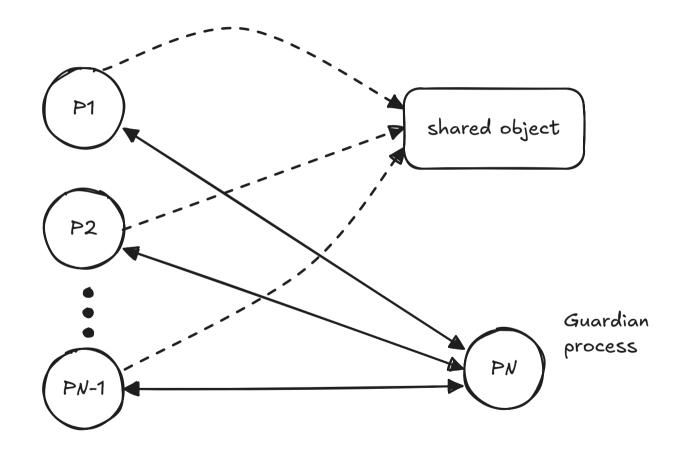


- No Shared Memory Space
  - Processes do not share an address space.
  - Synchronization must be achieved through message passing.
- Assumptions
  - Message transmission time is finite but has no upper bound.
  - ► **No message loss** is assumed during communication.



- Client-Server Adaptation
  - Represents an almost direct extension of the client-server model.
    - Includes request serialization to handle multiple access attempts in a controlled manner.
- Guardian Process or Coordinator
  - A dedicated process—the guardian process—manages access to a shared object.
  - It monitors all access attempts.
  - Grants access individually, based on incoming requests.





#### **Access Protocol Overview**





Applies to peer processes-  $p_i$ , where i=0,1,...,N-1, and a guardian process  $p_N$ .

### Requesting Access

- When a process  $p_i$  wants to access the shared object:
  - It sends a "request access"- message to the guardian proc.  $p_N$ .
  - Then it waits- for a "grant access" message in response.

### Guardian Response

- If no process is currently accessing- the shared object:
  - $p_N$  grants access immediately.
- ► If the object is **in use**:
  - $p_N$  queues the request- in a waiting list.



- Granting Access
  - When  $p_i$  receives the "grant access"- message:
    - It may **proceed to access** the shared object.
- Releasing Access
  - ullet Once finished,  $p_i$  sends a "release access"- message to  $p_N$ .
  - If there are pending requests:
    - $p_N$  removes the first request- from the queue.
    - It sends a "grant access"- message to the corresponding process.

# Group Communication

#### **Comments**

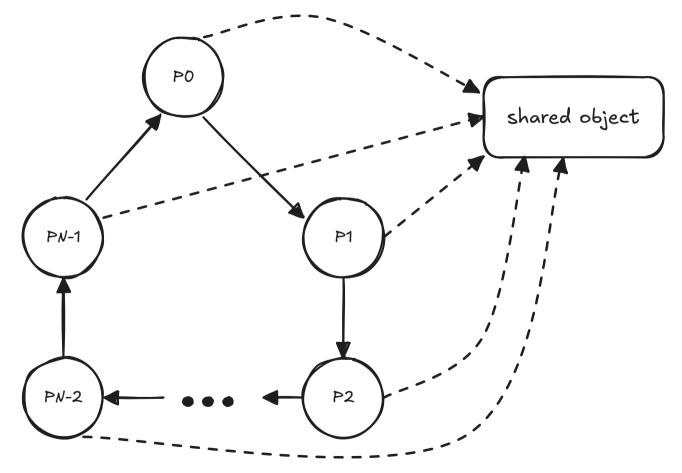
- Message Overhead
  - ► Each access to the shared object involves **three messages**:
    - request access, grant access and release access.
- Architectural Limitation
  - This is not a fully peer-to-peer solution.
    - It depends on a dedicated process—the guardian process—to control access.
- Single Point of Failure
  - The guardian process  $p_N$  is a **critical component**.
    - If  $p_N$  fails, the entire system halts, as no process can access the shared object.



- Logical Ring Topology
  - Processes are arranged in a closed communication loop.
- Communication Constraints
  - Each process  $p_i$ , where i = 0, 1, ..., N 1:
    - Receives messages- only from  $p_{(i-1) \bmod N}$ ,
    - **Sends messages** only to  $p_{(i+1) \mod N}$ .
- Token Passing Mechanism
  - ► A **token message circulates** continuously among the processes.
  - Access to the shared object- is restricted to the process holding the token.







# Group Communication

#### **Access Protocol Overview**

- Token-Based Access Protocol
  - Requesting Access
    - If a process  $p_i$  needs to access the shared object:
      - It waits to receive the token.
      - Once it holds the token, it proceeds to access the object.
      - After finishing, it **sends the token** to the **next process** in the ring.
  - No Access Needed
    - If a process  $p_i$  does not need access:
      - It **forwards the token immediately** to the **next process** in the ring upon receiving it.

# Group Communication

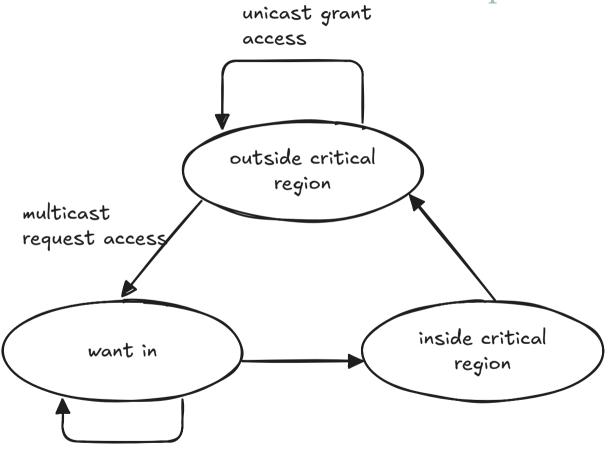
#### **Comments**

- Message Overhead
  - One message is always exchanged, whether or not the shared object is accessed.
- Efficiency in Small Groups
  - The protocol is highly efficient when the number of processes is small.
- Scalability Limitation
  - In large groups, a process may have to wait a long time to access the object.
    - This delay can occur even if no other process is currently using the object, due to the fixed token circulation order.



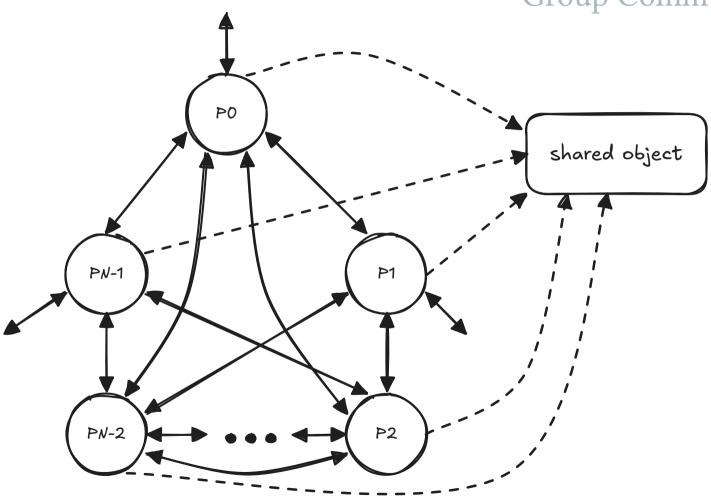
- Mutual Exclusion with Logical Clocks
  - Ricart and Agrawala (1981) proposed a method for ensuring mutual exclusion among N processes.
  - Access requests are totally ordered using Lamport logical clocks.
- Consensus on Access Order
  - All processes agree on the order of access requests to the shared object.
  - ▶ This results in an **overall consensus** for granting access.





wait for grant access from all / unicast grant access







### Timestamped Messages

- Messages include the timestamp of the sending event.
- Upon reception, a process adjusts its local logical clock according to Lamport's rules.
- Extended Timestamps for Total Order
  - ► Total ordering is achieved by associating each access request with an **extended timestamp**:
    - $(\operatorname{ts}(m), \operatorname{id}(m))$ , where:
      - ts(m) is the **logical timestamp**,
      - id(m) is the sender's process ID.
    - This ordered pair is used to break ties and totally order the events.

### **Total Ordering of Events (Algorithm)**



```
// initialization
state = outsideCR;
requestMessageReady = false;
// p i enters the critical region
state = wantIn;
numberOfRequestsGranted = 0;
myRequestMessage = multicast (requestAccess);
requestMessageReady = true;
wait until (numberOfRequestsGranted == N-1);
state = insideCR:
//pi exits the critical region
state = outsideCR:
requestMessageReady = false;
while (!empty (requestQueue)) {
  id = getId (queueOut (requestQueue));
  unicast (id, accessGranted);
```

### **Total Ordering of Events (Algorithm)**





```
//p i receives an access request message from p j
if (state == outsideCR) {
  id = getId (requestMessage));
 unicast (id, accessGranted);
} else if (state == insideCR) {
  queueIn (requestQueue, requestMessage);
} else {
 wait until (requestMessageReady);
  if (getExtTimeStamp (myRequestMessage) < getExtTimeStamp (requestMessage))</pre>
    queueIn (requestQueue, requestMessage);
 else { id = getId (requestMessage));
    unicast (id, accessGranted);
//p i processes access permissions
numberOfRequestsGranted += 1;
```

# **Total Ordering of Events (Algorithm)**

# Group Communication

#### **Comments**

- Message Overhead
  - ► Each access to the critical region requires **2(N-1) messages**:
    - (N-1) request messages sent by the requesting process.
    - (N−1) grant messages sent in response by other processes.
- Efficiency in Small Groups
  - The protocol is highly efficient when the number of processes is small.
- Scalability Limitation
  - For large process groups, the protocol becomes communication-intensive, resulting in the exchange of a large number of messages per access.



- Group-Based Permission Model
  - Maekawa (1985) proposed that mutual exclusion can be achieved without requiring permission from all processes.
  - Instead, each process is part of a **smaller subset (group)** of processes.
  - A process must obtain permission **only from all members of its group** to access the shared object.



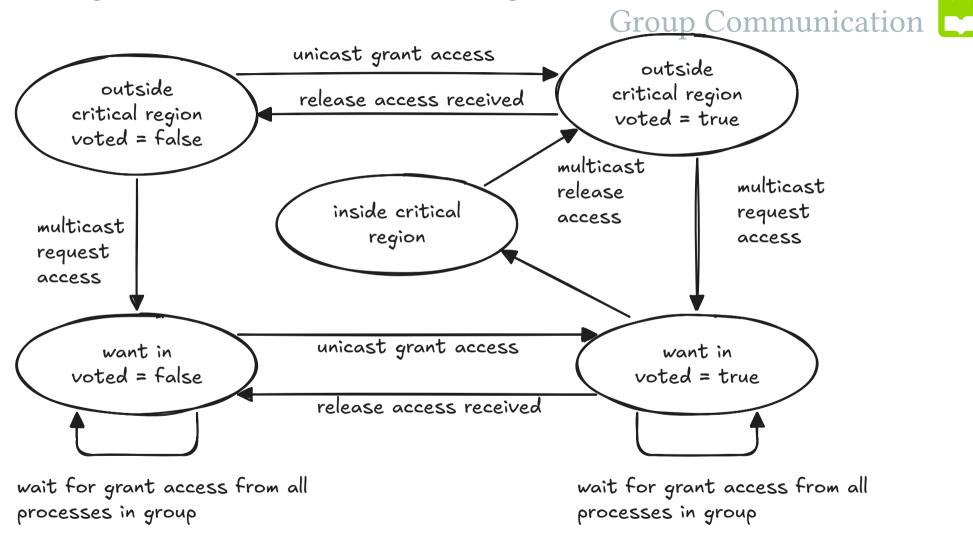
- Ensuring Mutual Exclusion
  - Groups must intersect—they are not mutually exclusive.
  - ► This intersection guarantees that **no two processes** can enter the critical region **simultaneously**.
- Permission by Voting
  - Access is granted through a voting mechanism:
    - A process can access the shared object if and only if it has received permission (votes) from all members of its group.



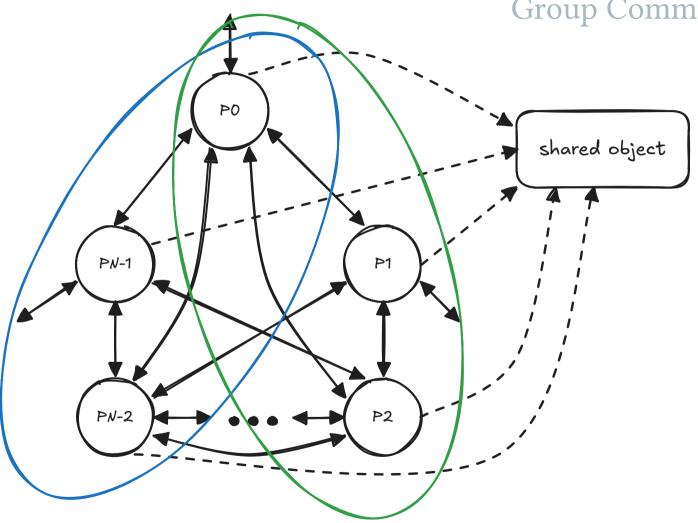


### Voting Group Structure

- Each process  $p_i$ , for i = 0, 1, ..., N 1, assign a **voting group**  $V_i$ .
- Group Definition Properties
  - $V_i \subseteq \{p_0, p_1, ..., p_{\{N-1\}}\}$ 
    - Each group is a **subset of all processes**.
  - $p_i \in V_i$ 
    - Every process is a member of its own voting group.
  - $V_i \cap V_i \neq \emptyset \quad \forall 0 \le i, j < N$ 
    - All voting groups must intersect—ensures mutual exclusion.
  - $\bullet$  # $(V_i) \approx \#(V_i) \quad \forall i, j$ 
    - All groups should be of **approximately equal size** to balance the load.
  - $\rightarrow \exists M \in \mathbb{N} \text{ such that } \forall i, p_i \text{ belongs to } M \text{ groups } V_*$ 
    - Each process is a member of exactly M voting groups.









### Voting Group Construction Complexity

- Determining the exact composition of each voting group  $V_i$ , for i = 0, 1, ..., N-1, is **non-trivial**.
- ▶ However, a **simple approximation** exists that satisfies:
  - $\#(V_i) \approx \#(V_i)$  (groups are of approximately equal size),
  - $M \approx \sqrt{N}$ , with group membership and size both in  $\mathcal{O}(\sqrt{N})$ .



### Approximate Voting Group Structure

- Processes are arranged in a  $\sqrt{N} \times \sqrt{N}$  matrix.
- Each voting group consists of:
  - All processes in a **specific row**,
  - All processes in a **specific column**.
- ► This ensures:
  - Every group intersects with every other,
  - Each process belongs to exactly 2 voting groups (1 row + 1 column),
  - Total message complexity becomes  $\mathcal{O}(\sqrt{N})$  per access.





- Example Structure for Group  $V_1$ 
  - $V_1 = \{0, 1, ..., K-1, K+1, ..., (R-1)K+1\}$
  - ▶ This includes all processes in **row 1** and **column 1**, skipping the diagonal overlap to avoid duplication.

0	1	• • •	K-2	K-1
K	K+1	•••	2K-2	2K-1
•••	•••	•••	•••	•••
(R-1)K	(R-1)K + 1	•••	RK-2	0

# Group Communication

### Algorithm

```
//initialization
state = outsideCR;
voted = false;
//p i enters the critical region
state = wantIn;
numberOfRequestsGranted = 0;
multicast (requestAccess) to all processes in V i;
wait until (numberOfRequestsGranted == #(V i));
state = insideCR;
//p i exits the critical region
state = outsideCR;
multicast (releaseAccess)to all processes in V i;
```



```
//p_i receives an access request message from p Communicatio
if ((state != insideCR) && !voted) {
  id = getId (requestMessage));
  unicast (id, accessGranted);
  voted = true;
} else queueIn (requestQueue, requestMessage);
//pi receives a release access message from pj
if (!empty (requestQueue)){
  id = getId (queueOut (requestQueue));
  unicast (id, accessGranted);
  voted = true;
} else voted = false;
//p i processes access permissions
numberOfRequestsGranted += 1;
```



#### **Comments**

- Message Complexity
  - Each access to the shared object involves  $\approx 3 \times \mathcal{O}(\sqrt{N})$  messages:
    - Request, grant, and release messages are exchanged within each process's voting group.
- Scalability and Efficiency
  - The protocol is highly efficient for large process groups.
    - By reducing the number of participants per access, it significantly lowers the communication overhead compared to full peer-topeer solutions.



#### **Correctness Issue: Potential Deadlock**

• Although **Maekawa's algorithm** reduces message complexity, it is **not deadlock-free**.



### • Example scenario:

- Voting groups:
  - $-V_0 = \{0,1\}$
  - $-V_1 = \{1, 2\}$
  - $-V_2 = \{2, 0\}$
- If processes  $p_0, p_1, p_2$  request access simultaneously, the following can occur:
  - $p_0$  receives a vote from  $p_1$ ,
  - $p_1$  receives a vote from  $p_2$ ,
  - $p_2$  receives a vote from  $p_0$ .
- Each has **one vote**, but **no one receives all votes required** to enter the critical region.
- ▶ The system reaches a **deadlock**: no process can proceed or release its vote.

### Group Communication



- Solution to Prevent Deadlock
  - ▶ Introduce a **total ordering of requests** to break circular wait conditions:
    - Use Lamport timestamps or logical clocks to assign a global order to each access request.
    - Each voter grants its vote only to the request with the earliest timestamp.
  - Implement a **priority queue** in each process to manage incoming requests by timestamp.
    - When a process finishes its critical section, it releases its vote to the next lowest-timestamped request in its queue.
  - Alternatively, enforce a centralized or token-based fallback mechanism:
    - Use a **coordinator** or **token circulation** in high-contention scenarios to guarantee progress.

### **Election Procedure**



- Leader Election in Symmetric Process Groups Communication
  - In some situations, a **single process must be selected** from a group to perform a **specific task at a specific time**.
  - All processes are conceptually identical (i.e., peers), so any process may be selected in principle.
- Key Requirements for the Election Procedure
  - Termination:
    - The election must complete in a finite number of steps.
  - Unambiguity:
    - The outcome must be **unique**—**only one process** is selected.
  - Consensus:
    - All involved processes must agree on the elected process.

# **Election Procedure (Assumptions)**



### **System Assumptions for Election Protocols**

- Fixed Process Group
  - The number of processes is fixed and known in advance.
- Process States
  - Each process is either:
    - In execution, or
    - In catastrophic failure (i.e., completely non-responsive or crashed).

#### **Election Procedure (Assumptions)**



- Message Transmission Timing
  - Message delivery has a finite upper bound.
    - Therefore, timeouts can be defined and used to detect failures or non-responsiveness.
- Reliability of Communication
  - Messages may be lost, requiring fault-tolerant mechanisms such as retransmission or acknowledgments.



- Election Initialization
  - Initially, no election is in progress.
    - All processes are in the **no participant** state.
  - Election Trigger
    - Any process may initiate the election.
      - It sets its state to participant.
      - Sends a **start election** message to the **next process** in the ring.
      - The message contains its own **process ID**.

#### • Handling start election Messages





- ▶ When a proc. receives a start election msg, it compares the msg ID with its own ID:
  - Case 1:
    - If the message ID is **less than its own**:
      - Forwards the message to the next process.
      - ▶ **Becomes a participant** (if not already).
  - Case 2:
    - If the message ID is **greater than its own** and the process is **not a participant**:
      - Replaces the message ID with its own ID.
      - Forwards the updated message to the next process.
      - Changes its state to participant.
    - If it is already a participant, it discards the message to reduce unnecessary traffic.
  - Case 3:
    - If the message ID equals its own ID:
      - ▶ The election is **complete**.
      - The process has been **elected leader**.



- Leader Announcement
  - Once a process is elected as leader, it sends an elected message containing its own ID to the next process in the ring.
- Handling elected Messages
  - ▶ Upon receiving an elected message, a proc. does the following:
    - Reset Participation State
      - Sets its state to **no participant**.
    - Case 1: Leader ID ≠ Own ID
      - Records the leader's ID.
      - Forwards the elected message to the next process.
    - Case 2: Leader ID = Own ID
      - Discards the message, marking the end of the election process.



- Chang and Roberts Algorithm Failure-Free Assumption cation
  - ► The original algorithm (1979) assumes:
    - A static ring,
    - No process failures,
    - No message loss.



- Failure Detection
  - Implement **timeouts**: if a process doesn't receive a response from the next in the ring within a bounded time, assume **catastrophic failure**.
- Bypassing Failed Processes
  - Upon detecting a failed neighbor:
    - Skip over it and forward the message to the next reachable alive process in the ring.
    - Maintain a locally updated view of the ring or rely on a failure detector service.



- Rejoining After Recovery
  - When a previously failed process recovers:
    - It must **register** or **announce its re-entry** to the group.
    - The ring structure must be **reconstructed** to include the process again.
    - This may require **suspending the current election** and restarting it with the **updated ring topology**.



- Reliable Communication Layer
  - Introduce an **acknowledgment (ACK)** system for every election-related message.
  - ▶ If an ACK is not received within the timeout window:
    - **Resend the message** (with a retry limit to avoid infinite loops).



- Election Timeout and Restart
  - ► If a process suspects message loss or stalling:
    - It can restart the election after a timeout using a higher ID to avoid conflicts.
    - Care must be taken to avoid concurrent elections leading to inconsistencies.



- Election Initialization
  - Initially, no election is in progress, and all processes are in the no participant state.
  - Election Trigger
    - **Any process** may initiate the election:
      - Sets its state to participant.
      - Sends a **start election** message (with its own ID) to **all processes with lower IDs**.



- Handling start election Messages
  - ▶ When a process receives a start election message:
    - Replies with an acknowledge message to the sender.
    - If its state is **no participant**:
      - Sets its state to participant.
      - Sends a start election message (with its own ID) to all processes with lower IDs.
- Handling acknowledge Messages
  - ► Upon receiving an acknowledge message:
    - The sender **waits for an elected message** to learn the identity of the leader.



- Timeout and Leadership Assumption
  - ► If a participant process does not receive any acknowledge messages within a predefined timeout:
    - It assumes it is the lowest-ID process still alive.
    - It declares itself the leader.
    - Sends an **elected message** (with its own ID) to **all processes** to announce the result.



Garcia-Molina's Election Algorithm

The original algorithm (1982)- assumes:

- A failure-free environment during the election,
- A known set of processes,
- Reliable communication.

To extend it to handle **dynamic reconfiguration**, the algorithm must be enhanced as follows:



#### Process Failure (Catastrophic Crash)

- Failure Detection:
  - Use **timeouts** and **heartbeat mechanisms** to detect non-responsive processes.
  - ► If a coordinator (leader) fails:
    - A new election is triggered by the highest-ID process that detects the failure.
    - Peers with higher IDs are contacted; if none respond, the detecting process elects itself.
- Failure Propagation:
  - On detecting a failure, processes broadcast the updated membership to maintain group consistency.



#### **Process Recovery**

- A recovered process must:
  - Announce its return to the group.
  - Query for the current leader (e.g., by sending a "who is leader?" message).
  - If the recovered process has a **higher ID than the current leader**, it may **initiate a new election** (if allowed by policy).

## Group Communication

#### **Handling Message Loss**

- Acknowledgment & Retransmission:
  - ► Use **ACKs** for all critical messages (start election, acknowledge, elected).
  - If an ACK is **not received within a timeout**, **retransmit** the original message.
- Election Recovery:
  - ► If a process waits too long for an elected message (after sending start election) without success:
    - It retries the election.
    - To avoid repeated elections, include a round number or election ID to track and avoid duplication.



#### Additional Enhancements for Robustness

- Membership Service:
  - Use a distributed or centralized membership protocol to track active nodes.
  - Keeps all processes informed about the current system configuration.
- Persistent State:
  - ► Processes may store election state (e.g., participant status, known leader) in **persistent storage** to recover consistently after crashes.

## **Suggested Reading**

- M. van Steen and A.S. Tanenbaum, Distributed Systems, 4th ed., distributed-systems.net, 2023.
- Distributed Systems: Concepts and Design, 4th Edition, Coulouris, Dollimore,

Kindberg, Addison-Wesley