## Finite Element Method for Heat Transfer

Rezgar Shakeri Leila Ghaffari

University of Colorado Boulder

Rezgar.Shakeri@colorado.edu Leila.Ghaffari@colorado.edu

December 7, 2020

## Outline

- Meat Equation
- 2 Finite Element Method (FEM)
- New Features
  - MATLAB to Python
  - Command line options
  - Modularity
  - Travis CI, Unit and Functional tests
  - Documentation, Comments, User Manual
  - First release v1.0

# Heat Equation

- Predicts the temperature of the body (domain) subjected to the heat source
- Derived from Fourier's law and the conservation of energy
- Of fundamental importance in diverse scientific fields

### Fourier's Law:

$$\mathbf{q} = -k\nabla u$$

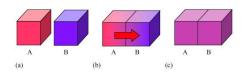


Figure: Heat conduction

# Heat Equation

$$\frac{\partial u}{\partial t} = \alpha \nabla^2 u = \alpha \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right), \tag{1}$$

$$u(x,y,z,t) = \text{Temperature}$$

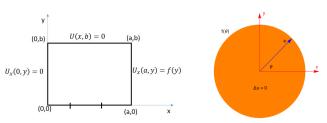
$$\alpha = \frac{k}{c_p \rho} = \text{Thermal Diffusivity} \quad c_p = \text{Specific Heat Capacity}$$

$$k = \text{Thermal conductivity} \quad \rho = \text{Mass density}$$

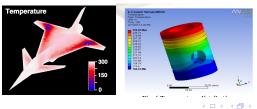


# Heat Equation

We can solve (1) analytically in **simple geometries** like rectangular (cubic in 3D) or circular by the **Separation of Variables** method.



But how about the complex region? Like aircraft, blade of the turbine?!



# Finite Element Method (FEM)

- Divide the domain to small pieces called Element
- Implement the weak form of Heat Equation for each element
- Expand the unknown variable (here temperature) using shape functions at each element
- Assemble the general form of the equation and find the solution

$$\frac{\partial^2 u}{\partial x^2} = f(x) \Longrightarrow \int_0^L w(x) \left[ \frac{\partial^2 u}{\partial x^2} - f(x) \right] dx = 0$$

$$\left( w \frac{\partial u}{\partial x} \right)_0^L - \int_0^L \frac{\partial w}{\partial x} \frac{\partial u}{\partial x} dx - \int_0^L w(x) f(x) dx = 0$$
(2)

Above equation is correct for each piece of the domain (element)

# Finite Element Method (FEM)

$$\begin{aligned} u^{h^e}(x) &= \sum_{a=1}^{n_{\text{en}}} N_a^e(x) d_a^e &= N_1^e(x) d_1^e + N_2^e(x) d_2^e \\ &= \begin{bmatrix} N_1^e & N_2^e \end{bmatrix} \begin{bmatrix} d_1^e \\ d_2^e \end{bmatrix} \\ &= N^e(x) \cdot d^e \end{aligned}$$

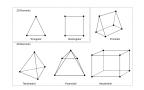




Figure: Different types of element and example of the Piston mesh

## New Features

- MATLAB to Python
- Command line options
- Modularity
- Travis CI, Unit and Functional tests
- Documentation, Comments, User Manual
- First release v1.0

# MATLAB to Python

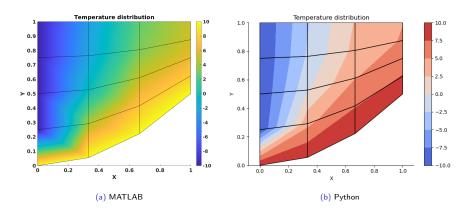


Figure: Temperature distribution, bottom and left edges are subjected to the 10 and -10 boundary conditions. Right and top edges are insulated.

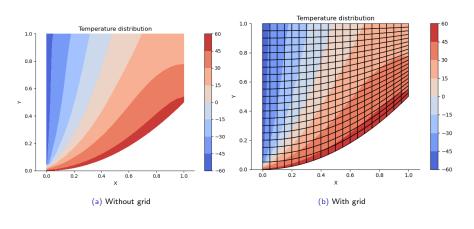
we found temperature by solving  $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$ 

4 1 1 4 1 1 4 2 1 4 2 1 4 2 1 4 2 1

Rezgar Shakeri Leila Ghaffari (CU Boulder)

# Command line options

python src/heat2d.py --num\_elm\_x 20 --num\_elm\_y 20
--T0\_bottom 50 --T0\_left -50 --heat\_source 400 --flux\_top
100 --grid



Sic tinx()

Dirichlet BCs (NeumannBCs)

connectivity() assembly()

heat2delem() phys\_coord()

setup() gauss()

## Travis CI, Unit and Functional tests

#### language: python before install: wget https://repo.anaconda.com/miniconda/Miniconda3-latest-Linux-x86 64.sh - bash Miniconda3-latest-Linux-x86 64.sh -b - . /home/travis/miniconda3/etc/profile.d/conda.sh - conda update --ves conda - conda config --add channels r - conda create --ves -n test - conda activate test - conda install --ves python=3.8 - conda install -y pycodestyle - conda install -v numpy - conda install -y matplotlib script: - python src/test FE subroutines.py - bash src/test heat2d.sh - pycodestyle src/test FE subroutines.py - pycodestyle src/heat2d.pv - pycodestyle src/FE subroutines.py - pycodestyle src/plot.py



## Documentation, Comments, User Manual

```
def phys coord(nelx, nely):
   """ This function returns the physical coordinates of the nodes.
   Input:
   nelx: integer
          number of elements in the x direction.
                                                                  # Get the setup properties
   nely: integer
                                                                  nel, lpx, lpy, nnp, ndof, nen, neq = setup(nelx, nely)
          number of elements in the v direction.
   Output:
                                                                  # Divide [0,1] by lpx (mesh in the x direction)
                                                                  x\theta = np.linspace(\theta, 1, lpx)
          float (1d array)
                                                                  v\theta = 0.5 * x0**2
                                                                                                    # the bottom geometry line
          the coordinate of the node in the x direction
          float (1d array)
          the coordinate of the node in the y direction
                                                                  y = np.zeros((nnp, 1))
                                                                  for i in range(0, lpx):
   The geometry we are working on is like the following.
                                                                       # Divide [0,1] by lpy (mesh in the y direction)
   (for nelx = 2, nelv = 2)
                                                                       v1 = np.linspace(v0[i], 1, lpv)
   6-----8
                                                                       for j in range(0, lpy):
      1 (3)
      (2) | ----5
                                                                           v[i + i*lpx] = v1[i] # collection of v
         ---4----/
                                                                   x = np.zeros((nnp, 1))
                                                                   for i in range(0, lpv):
                                                                       for i in range(0, lpx):
      ----/
                                                                           x[i + i*lpx] = x0[i] # collection of x
   There are 4 elements (numbering in parenthesis), and 9 nodes.
   Bottom edge (0 to 2) is y=0.5x^2. (see src/test subroutines.py)
                                                                  return x, y
   This function returns x,v as 9x2 array for the above mesh.
```

(a) Documentation

(b) Comments

## User Manual/README

### First release - v1.0



### Releases 1

v1.0 Latest
31 minutes ago

### Packages

No packages published Publish your first package

### Contributors 2



### rezgarshakeri

### Languages

Python 98.2%
 Shell 1.8%

# Question

