

# Lejun Jiang

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## EDUCATION

### University of Pennsylvania (Penn)

*Master of Science in Engineering, Robotics (projected)*

Philadelphia, PA

May 2022

**Coursework:** Optimization Theory & Analysis; Machine Learning; Computer Vision & Computational Photography

### Shanghai Jiao Tong University (SJTU), (Dual Degree program with UMich)

Shanghai, China

*Bachelor of Science in Engineering, Electrical and Computer Engineering (GPA: 3.8/4.0)*

Aug 2020

**Coursework:** Dynamics & Control of Connected Vehicles (Teaching Assistant); Solid Mechanics; Logic Design; Programming & Elementary Data Structures; Discrete Mathematics

### University of Michigan (UMich), (Dual Degree program with SJTU)

Ann Arbor, MI

*Bachelor of Science in Engineering, Mechanical Engineering (GPA: 4.0/4.0) w/ Minor in Electrical Engineering*

May 2020

**Coursework:** Linear Systems Theory; Control System Analysis & Design; Dynamic System Modeling, Analysis & Control; Engineering Acoustics; Fluid Mechanics; Design & Manufacturing; Data Structures & Algorithms; Probability & Statistics

## PUBLICATIONS

- L. Jiang, T. G. Molnar, G. Orosz. "On the Deployment of V2X Roadside Units for Traffic Prediction". Accepted by *Transportation Research Part C: Emerging Technologies*.
- S. Wong, L. Jiang, R. Walters, T. G. Molnar, G. Orosz, R. Yu. "Traffic Forecasting using Vehicle-to-Vehicle Communication". Proceedings of the 3rd Conference on Learning for Dynamics and Control, PMLR 144:917-929, 2021.
- Y. Kim, L. Jiang, L. Munoz, J. Luntz, D. Brei, P. Alexander, W. Kim. "Fiber-Reinforced Inflatable Torsional Actuator Design with Performance-Enhancing Axial Tension". Presentation at ASME 2019 Conference on Smart Materials, Adaptive Structures and Intelligent Systems, in preparation for submission to the ASME Journal of Mechanical Design.

## RESEARCH EXPERIENCE

### Waymo, LLC.

Philadelphia, PA (Remote)

*Intern, Behavior Planner, Prediction, & Controls - Robotist/SWE*

May 2021 - Present

- Developed software & algorithms for autonomous vehicles' onboard robust planning under uncertainty

### Learning Robust Output Control Barrier Functions in CARLA Simulator

Philadelphia, PA

*Group of Nikolai Matni*

Apr 2021 - Present

- Modelled vehicle dynamics and created PID feedback controller for lane keeping that serves as safe expert demonstrations
- Interfaced with CARLA simulator for verification of learned Robust Output Control Barrier Functions

### Multi-Vehicle Coordination for Overtaking Maneuvers of F1Tenth Autonomous Racing Cars

Philadelphia, PA

*Real-Time and Embedded Systems Lab, implemented with Python (ZeroMQ, CVXPY, F1Tenth Gym)*

Jan 2021 - May 2021

- Established scalable framework where central node generates coordinated overtaking maneuvers & communicates to each vehicle
- Combined RRT\* path planning algorithm and minimum jerk trajectory smoothing for individual vehicles in shared occupancy grid
- Designed Mixed Integer Linear Program for time-optimal velocity tuning, observing vehicles' relative priority and hybrid dynamics

### Traffic Prediction based on Vehicle-to-everything (V2X) Connectivity

Ann Arbor, MI

*Group of Gabor Orosz*

May 2019 - Aug 2020

- Developed Physics-Guided Deep Learning model for V2V traffic forecast with LSTM Recurrent Neural Network & Newell's model
- Established metrics to quantify amount of traffic prediction that roadside units (RSUs) can provide via V2I communication; developed optimal strategies for deploying RSUs along highways through evaluating proposed metrics numerically & analytically
- Modeled traffic flow with Markov Chain by establishing connection to continuum models; examined model through MATLAB simulations of single-lane traffic, attained robustness with 15% parameter variation tolerance

### Characterization & Design Methodology of Inflatable Torsional Actuators

Ann Arbor, MI

*Smart Materials and Structures Design Laboratory*

Jan 2019 - May 2019

- Enhanced actuator's operation performance by quantifying and exploiting effect of applied axial tension
- Modeled actuator's performance against its design and operating parameters; based on model developed unprecedented systematic design methodology for actuator, including design space visualization and step-by-step design process

## PROJECT EXPERIENCE

### Minimum-Snap Trajectory Generation and Control for Quadrotors

ESE 650: Learning in Robotics

Philadelphia, PA  
Apr 2021 – May 2021

- Planned trajectory of quadrotors in densely cluttered environments with  $A^*$  / Dijkstra's algorithm
- Formulated minimum snap trajectory smoothing algorithm with Quadratic Programming, and optimized travelling time for each segment of the trajectory by Constrained Gradient Descent
- Constructed dynamic model & developed Non-linear Geometric Controller for accurate control of quadrotors in Crazyflie simulator

### Machine Learning Algorithm Development with Python

Implemented with Python (Numpy, PyTorch, Scikit-learn)

Philadelphia, PA  
Sep 2020 – Dec 2020

- Implemented YOLO algorithm to realize fast real-time multi object detection and semantic label classification
- Developed a Convolutional Neural Network (CNN) for the Fashion MNIST dataset with PyTorch, achieved 91% overall accuracy
- Trained Random Forest, Kernel SVM, MLP & Adaboost classifiers on MNIST digits dataset with Scikit-learn, reached 99.3% accuracy

### Lane Detection for Autonomous Vehicles

Implemented with Python (Numpy, Cupy, OpenCV)

Philadelphia, PA  
Sep 2020 – Dec 2020

- Established Straight Lane Detection algorithm based on Canny Edge Detection and Hough Transform
- Improved accuracy by Curved Lane Detection algorithm based on Sobel Filtering, Perspective Warping & Sliding Window Search
- Adopted Vanishing Point Guided Network (VPGNet) to further enhance lane detection accuracy

### Creating Digital Twin Models for Tobacco Drying Processes

Capstone Design, Facilitator

Shanghai, China  
May 2020 – Aug 2020

- Developed 2D and 3D Finite Element Analysis (FEA) models for the tobacco drying process based on four physics modules in COMSOL Multiphysics; achieved 9.45% accuracy error with final model

### 2020 SAE Aero Design Competition

M-Fly SAE and AUVSI Aerospace Design Team, Aerodynamics Lead

Lakeland, FL  
Sep 2019 – May 2020

- Led aerodynamics design of high-lift plane through trade studies, which are based on evaluations & analysis of lift/drag performance and static/dynamic stability with XFOIL & AVL
- Reduced 30% of wingspan and 50% of takeoff distance by adopting bi-wing configuration

### Glovebox Pressure Control System for Redox Flow Battery

Capstone Design, Sponsor Contact, Team Leader

Ann Arbor, MI  
Jan 2020 - May 2020

- Created Gas Inflow/Outflow On/Off Control Algorithm, which achieved accuracy error within  $\pm 0.1$  mbar
- Analytically modelled the glovebox system and simulated its behavior by MATLAB to validate design

### Drone Delivery Simulation

Implemented with C++

Ann Arbor, MI  
Apr 2020

- Minimized cost of setting up beacons for fast drone by building Minimum Spanning Tree (MST) with Prim's algorithm
- Minimized total energy cost for regular drone to visit all desired locations and return back to original location by implementing Branch and Bound algorithm based on Traveling Salesperson Problem (TSP) insertion heuristics

### Query Language Database Implementation

Implemented with C++

Ann Arbor, MI  
Mar 2020

- Created relational database with object-oriented design to handle query language commands (insert, delete, generate index, join, etc) efficiently

### Stocks Market Implementation

Implemented with C++

Ann Arbor, MI  
Feb 2020

- Created implementation of stock market with object-oriented design and optimized its performance with priority queue
- Implemented priority queue with sorted array, binary heap and pairing heap; compared their performance against each other

### Automatic Ball Collection Robot

Course Project, Team Leader

Ann Arbor, MI  
Jan 2019 – May 2019

- Designed, modeled, simulated, and manufactured linkage system by SolidWorks and ADAMS
- Executed combined feedforward and PID feedback control algorithm using Arduino, achieved 97% accuracy for given task

### Robotic Arm with Soft Robotics

Course Project

Shanghai, China  
Feb 2018 – May 2018

- Designed and manufactured pneumatic silicone rubber gripper along with robotic arm based on Siemens NX that achieved high flexibility and efficiency for grabbing and transporting objects of different shapes and sizes
- Implemented remote control using PS2 wireless controller and Arduino microcontroller

### 9th SJTU Mechanical Innovation Competition for Freshmen

Runner-up

Shanghai, China  
Apr 2017

- Designed and built robot with high efficiency of holding and transporting objects of different shapes to desired areas

- Implemented remote control using PS2 wireless controller and Arduino microcontroller
- Controlled robot on behalf of team to contest with 47 opponent teams and won the 2nd prize

## TEACHING EXPERIENCE

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### **"Dynamics & Control of Connected Vehicles"**

Teaching Assistant

Shanghai, China  
May 2020 – Aug 2020

- Managed MATLAB simulation codes for project and homework, including simulations of Adaptive or Connected Cruise Control, energy consumption, etc.
- Held office hours; Assisted instructor in class; Created rubrics for homework problems and graded 10 students' submissions

### **"Heat Transfer"**

Grader

Ann Arbor, MI  
Jan 2020 – May 2020

### **"Introduction to Solid Mechanics"**

Grader

Ann Arbor, MI  
Sep 2019 – Dec 2019

### **"Academic Writing II"**

Teaching Assistant

Shanghai, China  
Feb 2018 – May 2018

- Polished students' essays during office hours, collected and answered common questions to enhance communication

### **UM-SJTU JI Volunteer Teaching Group**

Group leader

Eryuan, Yunnan, China  
Dec 2017 – Jan 2018

- Planned, organized, and held various courses (Math, Science, English, Art, etc) and activities with local government and teachers to help local students, involving 4 primary schools and 1 vocational high school
- Led group to win title of "Outstanding Team of Aid Education" out of 4 volunteer teaching groups

## AWARDS, SCHOLARSHIP & HONORS

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### **Shanghai Jiao Tong University Outstanding Graduates**

Overall outstanding performance in the undergraduate career

Shanghai Jiao Tong University  
2020

### **Robert. M. Caddell Memorial Scholarship**

Study in the area of materials and/or manufacturing and made significant contributions to relevant student activities

University of Michigan  
2020

### **James B. Angell Scholar**

Achieve an "A" record for two or more consecutive terms

University of Michigan  
2020

### **University Honors**

Earned a 3.5 GPA or higher during the term

University of Michigan  
FA18, WI19, FA19, WI20

### **Dean's List**

Achieved high scholastic standing for the term

University of Michigan  
FA18, WI19, FA19

### **Volunteer Spirit Scholarship**

Contribution to public welfare as a volunteer

Shanghai Jiao Tong University  
2018

### **Undergraduate Excellent Scholarship**

Overall outstanding performance during the year

Shanghai Jiao Tong University  
2017, 2018

### **Dean's List**

Achieved high scholastic standing for the term

Shanghai Jiao Tong University  
FA16, SU17, FA17, SU18

### **Honorable Mention**

Honorable performance in the contest

Mathematical Contest in Modeling / Interdisciplinary Contest in Modeling  
2017

## SKILLS

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**Programming Languages:** C++, C, Python, MATLAB, Arduino, Verilog, LaTeX.

**Development Tools & Software:** PyTorch, Scikit-learn, OpenCV, CVXPY, Protobuf, ROS, Github, Simulink, COMSOL, SolidWorks.