

PROJECT NAME:	OBD-II Based Predictive Maintenance System		
STUDENT NAME:	Dang Khoa Le		
STUDENT ID:	103844421	WEEK # (& dates covered):	#9

TASKS	STATUS	TIME SPENT	ACTION ITEM/NOTE
Task	Status	Time Spent	Action Item/Note
Successfully collected physical OBD-II data using the ELM327 adapter across 4 driving trials.	Completed	0.5 hours	Dale drove his car, and I collect it.
Loaded, explored, and analyzed the collected data in Google Colab.	Completed	1 hours	Break down the shape, feature and insights from the 4 trials in CSV files.
Merged datasets based on common columns only, resulting in a consolidated dataset.	Completed	1 hour	Enlarge the dataset.
Implemented a comprehensive data cleaning pipeline	Completed	3 hours	Duplicate row & column removal. Constant-value and empty-column detection. Placeholder error filtering (255, -40, -22). Row-wise missing threshold filtering. Timestamp parsing and missing detection. Outlier capping (RPM outside [100, 6000]). MinMax normalization.
Designed and applied basic feature engineering	Completed	2 hours	Average engine load (AVG_ENGINE_LOAD). Aggregated temperature (TEMP_MEAN). Derived metric for air efficiency (AIRFLOW_PER_RPM).
Generated visual insights	Completed	1 hours	Correlation heatmap. Time-series trends for key signals (RPM, Load, Temp). Missing timestamp detection through time delta plotting.
Improved the OBD-II Python Raspberry Pi logging script	Completed	0.5 hour	Split polling of high- and low-frequency PIDs. Robust WiFi and serial failover handling. Dynamic CSV logging with initial full PID snapshot.
Delivered a well-structured 9-slide presentation to demonstrate physical data logging, cleaning pipeline, and Python logger implementation	Completed	2 hour	
TOTAL WEEKLY TIME SPENT		11 hours	

TASKS PLANNED FOR NEXT WEEK	EXPECTED COMPLETION
Conduct longer data logging sessions over multiple driving scenarios.	Week 10
Implement timestamp-based resampling for fixed-Hz ML model preparation.	Week 10
Begin state labeling strategy based on speed/RPM thresholds.	Week 10
Draft anomaly detection prototypes using early models (XGBoost, Autoencoder).	Week 10-11
Group/remove high correlated features	Week 10-11
Do Research Report	Week 10

Summary/weekly reflection for Week 9:

- **Key Tasks Done:**

- ◊ Successfully collected physical OBD-II data using the ELM327 adapter across 3 real-world driving trials.
- ◊ Loaded, explored, and analyzed the collected data (test1.csv, test2.csv, test3.csv) in Google Colab.
- ◊ Merged datasets based on common columns only, resulting in a consolidated dataset.
- ◊ Implemented a comprehensive data cleaning pipeline, including:
 - Duplicate row & column removal.
 - Constant-value and empty-column detection.
 - Placeholder error filtering (e.g., 255, -40, -22).
 - Row-wise missing threshold filtering.
 - Timestamp parsing and missing detection.
 - Outlier capping (e.g., for RPM outside [100, 6000]).
 - MinMax normalization.
- ◊ Designed and applied basic feature engineering, including:
 - Average engine load (AVG_ENGINE_LOAD).
 - Aggregated temperature (TEMP_MEAN).
 - Derived metric for air efficiency (AIRFLOW_PER_RPM).
- ◊ Generated visual insights:
 - Correlation heatmap.
 - Time-series trends for key signals (RPM, Load, Temp).
 - Missing timestamp detection through time delta plotting.
- ◊ Improved the OBD-II Python Raspberry Pi logging script, allowing:
 - Split polling of high- and low-frequency PIDs.
 - Robust WiFi and serial failover handling.
 - Dynamic CSV logging with initial full PID snapshot.
- ◊ Delivered a well-structured 8-slide presentation to demonstrate physical data logging, cleaning pipeline, and Python logger implementation.

- **Key Learning:**

- ◊ Cleaning real-world OBD-II data is drastically different from public datasets due to:
 - Inconsistent sensor availability.
 - Connection delays and packet loss.
 - Sensor saturation and encoding quirks.
- ◊ Preventing data leakage and bias starts at cleaning — filling all missing values with median may distort actual driving behavior if done blindly.
- ◊ Logger script enhancements (e.g., PID grouping, fallback polling) are crucial for efficiency.
- ◊ Insightful visualizations allow us to uncover sensor drift, inactivity, or logging issues early on.
- ◊ Future work will focus on labeling driving states (idle, low speed, high speed) for predictive modeling and supervised training opportunities.

- **Literature/Resources Reviewed:**

Understanding and Knowledge taken from last few weeks research works.

- **Issues Faced:**

- ◊ Low sampling rate (~0.07 Hz) due to sequential PID queries (~200 ms per PID).
- ◊ Logging resulted in large gaps between readings, requiring post-processing strategies.
- ◊ Some trials recorded only timestamps and missing sensor values due to temporary loss of connection or data lockout during startup phase.
- ◊ Removing near-empty rows and duplicated placeholders required conditional logic.
- ◊ Timestamp axis in plots introduced unwanted gaps – addressed by switching to uniform integer-based indexing for clearer visualization.