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Exam 3

89.5
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1) a) $\begin{bmatrix} 6 & 7 \\ -3 & -5 \end{bmatrix}$ $\det = -30 - (-21) = -30 + 21 = -9 \neq 0$
Thus, the matrix is invertible. ✓

b) The matrix is not invertible because there is a column of 0's, meaning there cannot be 3 pivots, and therefore all the statements of IMT are false. ✓

c) $\begin{bmatrix} 1 & -5 & -4 \\ 0 & 3 & 4 \\ -3 & 6 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -5 & -4 \\ 0 & 3 & 4 \\ 0 & -9 & -12 \end{bmatrix} \sim \begin{bmatrix} 1 & -5 & -4 \\ 0 & 3 & 4 \\ 0 & 0 & 0 \end{bmatrix}$

The matrix is not invertible because there are not 3 pivots, so all the statements of IMT are false. ✓

d) There are 4 pivots, so the matrix is invertible since all the statements of IMT are true.

2) $A = \begin{bmatrix} 4 & 2 & 0 & 0 \\ 0 & -3 & 1 & 0 \\ 0 & 2 & 0 & 4 \\ -3 & 0 & 5 & 1 \end{bmatrix}$ ✓

$$\det(A) = a_{11}(-1)^{1+1}A_{11} + a_{12}(-1)^{1+2}A_{12} + a_{13}(-1)^{1+3}A_{13} + a_{14}(-1)^{1+4}A_{14}$$

$$\det(A) = 4 \det \begin{bmatrix} -3 & 1 & 0 \\ 2 & 0 & 4 \\ 0 & 5 & 1 \end{bmatrix} - 2 \det \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 4 \\ -3 & 5 & 1 \end{bmatrix} + 0 A_{13} - 0 A_{14}$$

$$\det(A) = 4(-3 \det \begin{bmatrix} 0 & 4 \\ 5 & 1 \end{bmatrix} - 1 \det \begin{bmatrix} 2 & 4 \\ 0 & 1 \end{bmatrix}) - 2(-1 \det \begin{bmatrix} 0 & 4 \\ -3 & 1 \end{bmatrix})$$

$$\det(A) = 4(-3(0-20) - (2-0)) + 2(0-12)$$

$$\det(A) = 4(-3(-20) - 2) - 24$$

$$= 4(58) - 24$$

$$= 208$$

256

$$\begin{array}{r} 38 \\ \times 4 \\ \hline 232 \\ + 24 \\ \hline 208 \end{array}$$

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3) $\begin{bmatrix} a+2c \\ 2a+b+3c \\ 3b-3c \\ a+4b-2c \end{bmatrix}$ subspace of \mathbb{R}^4 and find a basis

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Subspace:

When $a=0$, $b=0$, and $c=0$, the vector = $\vec{0}$, so the $\vec{0}$ is in H . ✓

$$\begin{bmatrix} a+2c \\ 2a+b+3c \\ 3b-3c \\ a+4b-2c \end{bmatrix} + \begin{bmatrix} d+2f \\ 2d+e+3f \\ 3e-3f \\ d+4e-2f \end{bmatrix} = \begin{bmatrix} (a+d)+2(c+f) \\ 2(a+d)+(b+e)+3(c+f) \\ 3(b+e)-3(c+f) \\ (a+d)+4(b+e)-2(c+f) \end{bmatrix}$$

10 pt.

$$k \begin{bmatrix} a+2c \\ 2a+b+3c \\ 3b-3c \\ a+4b-2c \end{bmatrix} = \begin{bmatrix} k(a+2c) \\ k(2a+b+3c) \\ k(3b-3c) \\ k(a+4b-2c) \end{bmatrix}$$

basis $(H) = \left\{ \begin{bmatrix} 0 \\ 1 \\ 3 \\ 4 \end{bmatrix} \right\}$ by the Spanning Set Theorem

$$H = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ -3 \\ -2 \end{bmatrix} \right\}$$

4) basis $(\text{Col } A) = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -3 \\ 1 \\ -2 \end{bmatrix} \right\}$ ✓

$\dim(\text{Col } A) = 3$ ✓

$$\begin{bmatrix} 1 & 0 & 2 \\ 2 & 1 & 3 \\ 0 & 3 & -3 \\ 1 & 4 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 1 & 0 & 1 \\ 0 & 1 & 2 & -1 & 0 \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 1 & 0 & 1 \\ 0 & 1 & 2 & 0 & 2 \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -3 & 0 & -3 \\ 0 & 1 & 2 & 0 & 2 \\ 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Basis $\left\{ \begin{bmatrix} 1 \\ 2 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 3 \\ 4 \end{bmatrix} \right\}$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 3x_3 + 3x_5 \\ -2x_3 - 2x_5 \\ x_3 \\ -2x_5 \\ x_5 \end{bmatrix} = x_3 \begin{bmatrix} 3 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} 3 \\ -2 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

basis $(\text{Nul}(A)) = \left\{ \begin{bmatrix} 3 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ -2 \\ 0 \\ -2 \\ 1 \end{bmatrix} \right\}$ ✓

$\dim(\text{Nul } A) = 2$ ✓

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5) $T(A) = T\left(\begin{bmatrix} 1 & -8 \\ 6 & -1 \end{bmatrix}\right) = \begin{bmatrix} 1+(-8) & \\ & 6 \\ -1+1 & \end{bmatrix} = \begin{bmatrix} -7 & \\ 6 & \\ 0 & \end{bmatrix}$ ✓ 5 pt.

$\ker(T) \equiv T(\vec{v}) = \vec{0}$

$T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = \begin{bmatrix} a+b & \\ c & \\ d+1 & \end{bmatrix} = \begin{bmatrix} 0 & \\ 0 & \\ 0 & \end{bmatrix}$

$\ker(T)$ = the set of all vectors such that $a+b=0$, $c=0$, and $d=-1$.

$K(T) = \left\{ \begin{bmatrix} a & -a \\ 0 & -1 \end{bmatrix} \mid a \in \mathbb{R} \right\} \Rightarrow b = -a$ 8 pt.

6) a) \mathbb{R}^{12} is an example because for \mathbb{R}^h , $\dim(\mathbb{R}^h) = h$. ✓

b) \mathbb{P} , the set $\{1, x, x^2, x^3, x^4, \dots\}$ is infinite dimensional since the set is not constrained by some number n . ✓

7) If a matrix is 6×8 , the smallest possible number is 2 since 2 columns will be nonpivot columns no matter what since there are only 6 rows. ✓

8) a) FALSE

b) FALSE

c) FALSE

d) TRUE

$A^{-1} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \frac{1}{-2} \begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix}$

$A^T = \begin{bmatrix} 1 & 3 \\ 2 & 4 \end{bmatrix} \Rightarrow (A^T)^{-1} = \frac{1}{-2} \begin{bmatrix} 4 & -3 \\ -2 & 1 \end{bmatrix} = \begin{bmatrix} -2 & \frac{3}{2} \\ 1 & -\frac{1}{2} \end{bmatrix}$

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