

Version_: 0.11

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This is a simple read me file for the app.

Aim: Solves the real-world problems of auto-driving

Achieved:

1. Fuzzy decision making
2. Kalman filter: Noise reduction of Lidar data
3. Predicted movement
4. Simulate computer vision

Working Principle/Flow:

Operation / Movement defined:

TurnLeft
TurnRight
Halt
MoveForward
Multi – type Break

Future Updates:

- * Reinforcement learning (Q-learning)
- * More data control
- * More data visualization
- * Step Recording / file system

Github link: Github repository