

1b)
$$W = \vec{f} \cdot \vec{s}$$
 [1]

 $\vec{S} = \vec{V} \cdot \delta t = 1 \frac{m}{s} \cdot 600 s = 600 m$ [1]

 $\vec{f} = m \cdot g \cdot sind = -20 lag \cdot 10 \frac{m}{s^2} \cdot 0.5 = -100 N$
 $W = \vec{f} \cdot \vec{s} = 6 \cdot 10^4 \text{ J}$ [1]

 $h = s \cdot sind = 300 m$ [1]

1c) $W_{pot} = m \cdot g \cdot h$
 $W_{kin} (h = 0) = W_{pot} (h = 100)$
 $W_{kin} = \frac{1}{2} m \sigma^2$ [3]

 $mgh = \frac{1}{2} m \sigma^2$

$$mgh = \frac{1}{2}m\sigma^{2}$$

$$v = \sqrt{\frac{2gh}{s^{2}}} \cdot 300m = \sqrt{6000} \cdot \frac{1000}{s} \approx 75 \cdot \frac{100}{s}$$

mit Ersatewert

J=√2000 m × 45 m

Musker lossing

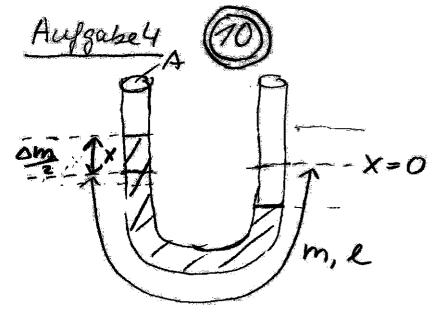
Aufgabe 2 (7)

a)

$$uv^2 = G \frac{uM}{v^2}$$
 $uv = \frac{1}{2} uv = \frac{1}{$

(Sonde fall des Virralsaties)

Anfgabe 3 (3) $\Delta t' = \frac{\Delta c}{\sqrt{1 - \left(\frac{c}{c}\right)^2}}$ [2] v = 990 / at = 14 $\Delta t' = \frac{-1h}{\sqrt{1-99^2}}$ Nt' = 14 1-0,81 at = 14 Vo,19 et. Regale => $\Delta t' = 2,3h$ [1]



Rinchtrebende Wraft
$$F_R = \Delta m \cdot g$$
 [1]
$$\Delta m = \Delta V \cdot S = A \cdot 2x \cdot g$$

$$=) F_R = A \cdot 2x \cdot g \cdot g$$

Bevegungsgleichung: m x=-AZXG.g

=) Beschleumigunger Auslankung
und dieser entgegengerichtet

=) Schwingung harmonisch

(oder Fer X =) "

[] [A]

$$\int \omega^2 = \frac{A \cdot 2 \times \cdot 9}{m \cdot x} \quad \boxed{1} \quad m = A \cdot \ell \cdot 9$$

$$\int \omega^2 = \frac{29}{\ell} \quad \omega = \sqrt{\frac{29}{\ell}} \quad \boxed{1}$$

$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{e}{2s}} = \frac{10^9 \text{ mm}^2}{50 \text{ mm}^2} = \frac{200 \text{ mm}^2}{50 \text{ mm}^2$$

Aufgabe S (S)

a)
$$p = t_1 k_2$$
 (oder $p = \frac{h}{\lambda}$)

2) $m U = \frac{h}{2\pi} \cdot \frac{2\pi}{\lambda}$
 $U = \frac{h}{m \lambda}$ [1]

 $U = \frac{h}{m \lambda}$ [2]

 $U = \frac{h}{m \lambda}$ [3]

 $U = \frac{66 \times 70^{-34} \text{ Js}}{77 \times 70^{-27} \text{ kg}} \cdot 0.3 \times 10^{-9} \text{ m}$
 $U \approx \frac{66}{77 \times 3} \times 20^2 \frac{\text{kg}}{5^2} \cdot \frac{5}{5^2}$
 $U \approx \frac{22}{77} \times 70^2 \frac{\text{kg}}{5}$
 $U \approx \frac{1300 \frac{\text{kg}}{5}}{5^2} \cdot \frac{1}{3} \cdot \frac{1}{7 \times 70^{-27} \text{ kg}}$
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T = 77 / 1

Anfgale 6 (7)
a)
$$pV = nRT$$

(3) => $T = \frac{pV}{nR}$
 $T_1 = \frac{10^5 Px \cdot 16.8 \cdot 10^{-3} m^3 K}{m^2 8.4 J} = 200 K$

(4)
$$T_2 = 400 K (da V_2 = 2 V_1)$$
(5) Weg 1-2: isobar

b) Weg 1-2: isobar $M_{2} = -p(V_{2}-V_{1}) = -10^{5} Pa \cdot 16.8 \cdot 10^{3} m^{3} = 1.68 \cdot 10^{3}$ $1Q_{2} = nCp(T_{2}-T_{1})[1]$ $C_{p} = R + C_{V}; C_{V} = \frac{3}{2}R \left(\frac{1}{9} \text{ adoming is ideals} \right)$ $C_{p} = \frac{5}{2}R [1]$ $1Q_{2} = \frac{5}{2}; 8.4 \frac{1}{2} \cdot 1 \text{ mol} \cdot 200 \text{ K}$

= 4,2.10³] [2] $\Delta U = 16.2 \cdot 10^3$] +4.2.10] = 2.52.10³] (alternatio: $\Delta U = n C_V \Delta T = 2.52 \cdot 10^3$]

Fox first Law suly 1 points is below no more points for income

$$2W_3 = 0$$
 $\sqrt{2}$
 $2W_3 = h C_V (T_3 - T_2) = -\frac{3}{2} R \cdot 200 \text{ K·mol}$
 $= -2.52 \cdot 10^3 \text{ Te}$

Weg 3-1: isokrem
$$\frac{W_0}{3W_1} = \left(-\int_{V_2}^{1} p dV = -nRT \int_{V_2}^{1} dV = -nRT \ln \frac{V_1}{V_2}\right)$$

$$= nRT \ln \frac{V_2}{V_1} \left[-1 \right]$$

$$= 8.4 \cdot 200 \cdot 0.7 J = 1200 J M_2$$

$$\Delta U = (n C V D T) = 0 J$$

$$3Q_1 = \Delta U - 3W_1 = -1200 J M_2$$

KreisprozeB

$$\oint dU = 2.52 \cdot 10^{3} J - 2.52 \cdot 10^{3} J = 0$$

$$= -0.48 \cdot 10^{3} J + 1.2 \cdot 10^{3} J$$

$$= -0.48 \cdot 10^{3} J - 7.52 \cdot 10^{3} J - 1.210^{3} J$$

$$= +0.48 \cdot 10^{3} J - 7.52 \cdot 10^{3} J - 1.210^{3} J$$

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f≈0,14m [1]*

$$T_2 = T(x_1)$$

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Annahme: Ta L Ti,
für Ti Ta Würmefeurs
in entgegengesetzter Richtung

$$\boxed{1} \frac{dq}{dt} = \lambda \frac{dT}{dx} \left(oder \frac{dQ}{dt} = \lambda A \frac{dT}{dx} \right)$$
mit A: Fenskerfleide

Weg 1: $|\overline{I}| \dot{q}_1 = \lambda_1 \left(\frac{T_1 - T_1}{n_1} \right)$ $|\overline{I}_2| \dot{q}_2 = \lambda_2 \left(\frac{T_2 - T_2}{n_2} \right)$ $|\overline{I}_2| \dot{q}_3 = \lambda_1 \left(\frac{T_2 - T_2}{n_2} \right)$

unter stat. Bedingungen gilt: $\dot{q}_{\lambda} = \dot{q}_{2} = \dot{q}_{3}$

Weg 2: $\vec{Q} = \frac{T \vec{u} - T \vec{a}}{R_G}$

1 Ro = 2Rn + Rz

1/2 R, = h

12 R2 = 1/2,