

Time Series and Sequence Learning

Validation, Order selection

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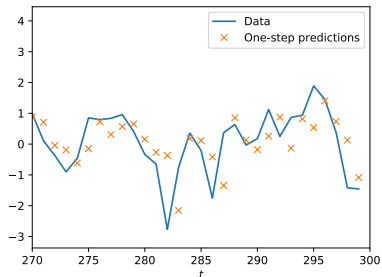
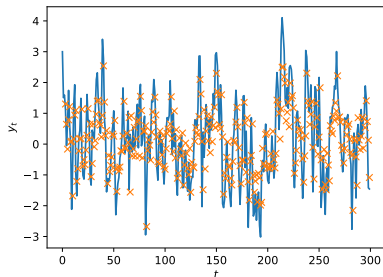
ex) Toy model

We simulate an AR(3) model for $n = 300$ time steps,

$$y_t = 0.9y_{t-1} - 0.4y_{t-2} + 0.2y_{t-3} + \varepsilon_t, \quad \varepsilon_t \sim \mathcal{N}(0, 1)$$

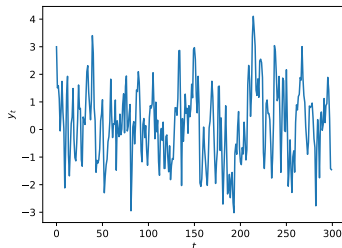
Estimating the model parameters with OLS gives:

$$\hat{\theta} = (0.84, -0.33, 0.16) \text{ and } \hat{\sigma}_\varepsilon^2 = 0.95.$$



Order selection

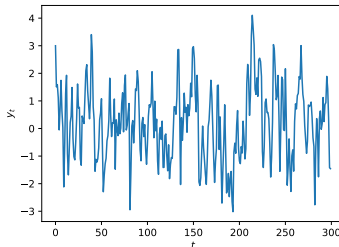
In practice we only observe the data.



How do we know which model order p to pick?!

Order selection

In practice we only observe the data.



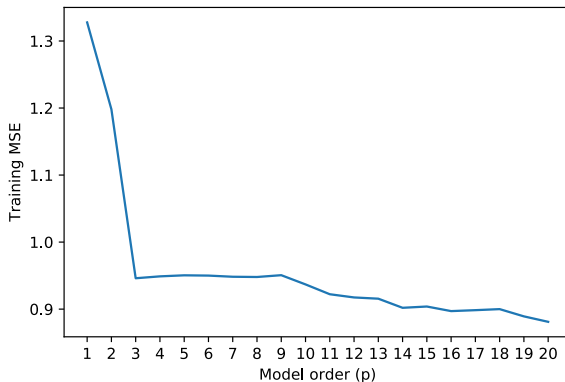
How do we know which model order p to pick?!

Two approaches:

1. Try to figure it out *before* fitting the model (“exploratory data analysis”)
2. Estimate **multiple models of different orders** and perform model selection by **validation**!

ex) Toy model, cont'd

1. Look for the “bend” in training error plot



Residual analysis

2. Look at the residuals!

The **model assumption** is

$$y_t = \theta^\top \phi_t + \varepsilon_t,$$

$$\varepsilon_t \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \sigma_\varepsilon^2).$$

Residual analysis

2. Look at the residuals!


The **model assumption** is

$$y_t = \theta^T \phi_t + \varepsilon_t, \quad \varepsilon_t \stackrel{\text{iid}}{\sim} \mathcal{N}(0, \sigma_\varepsilon^2).$$

Hence, if the model is accurate, we expect

$$y_t - \hat{\theta}^T \phi_t \approx \varepsilon_t.$$

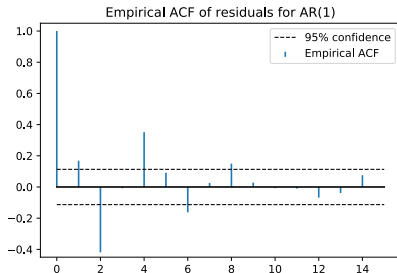
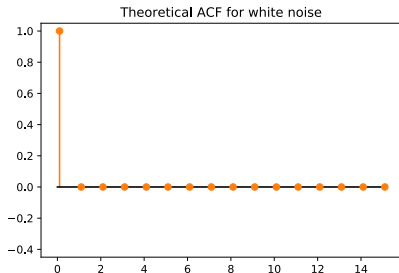
The residuals should be **white Gaussian noise**!

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1. Auto-correlation
 2. QQ-plots for marginal Gaussianity
 3. ...

ex) Toy model, cont'd

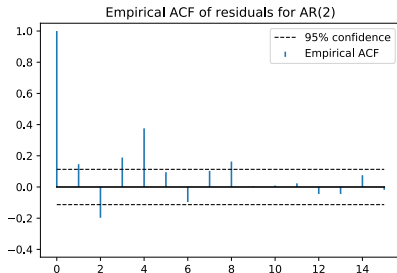
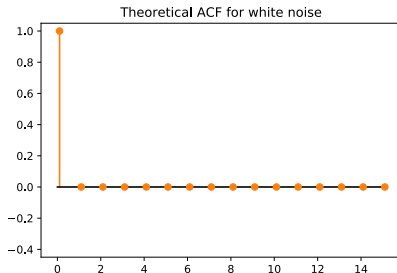
$$\hat{\beta}(h) \sim \mathcal{N}\left(0, \frac{1}{\sqrt{n}}\right) \quad h > 0, \quad n \text{ large}$$

Estimated model: AR(1)



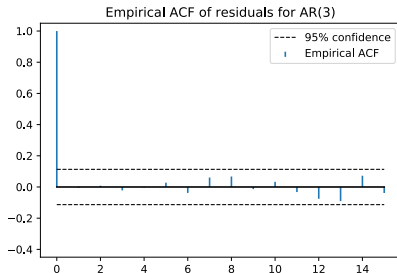
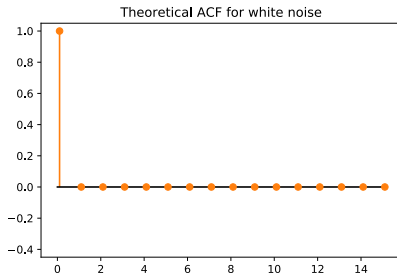
ex) Toy model, cont'd

Estimated model: AR(2)



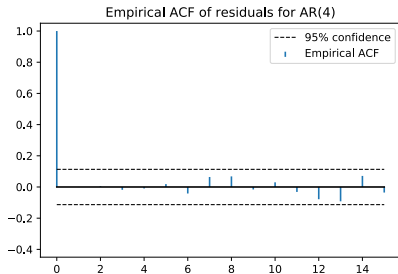
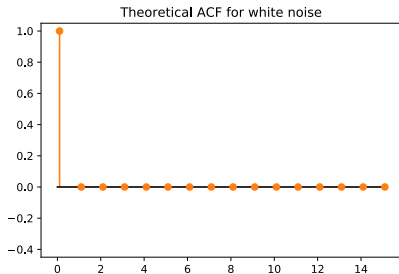
ex) Toy model, cont'd

Estimated model: AR(3)



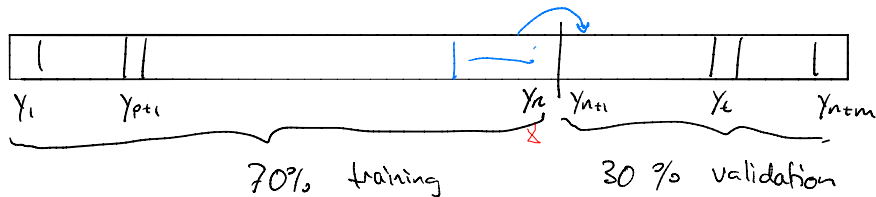
ex) Toy model, cont'd

Estimated model: AR(4)



Prediction error validation

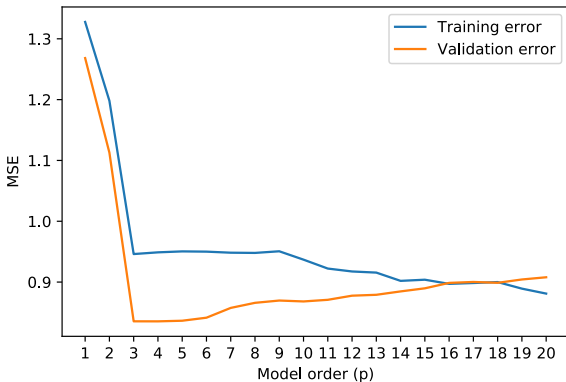
3. Evaluate on held-out validation data!



Validation mean-squared error, using one-step-ahead predictions:

$$\text{Val-MSE}(\hat{\theta}) = \frac{1}{m} \sum_{t=n+1}^{n+m} (y_t - \hat{\theta}^T \phi_t)^2$$

ex) Toy model, cont'd



Testing the model

