

# Time Series and Sequence Learning

## Temporal Convolutional Networks

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# Limitations of AR models

Auto-regressive model,  $AR(p)$ :

$$y_t = a_1 y_{t-1} + \dots + a_p y_{t-p} + \varepsilon_t, \quad \varepsilon_t \sim \mathcal{N}(0, \sigma_\varepsilon^2).$$

The AR model is linear in the parameters:

- ▲ Learning of parameters easy  $\Leftrightarrow$  linear regression
- ▼ Flexibility/ability to model complex temporal dependencies is limited
- ▼ Receptive field is just  $p$  time steps

# From NAR to TCN

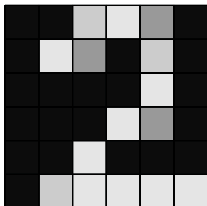
So far: Nonlinear AR = AR + MLP

- ▲ Flexibility increased.
- ▼ Receptive field is *still* just  $p$  steps

**Alternative view:** We can address this issue by using a **convolutional network architecture!**

# Convolutional Neural Network

Image



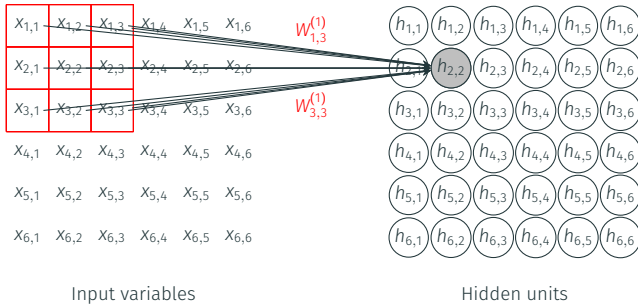
Data representation

0.0	0.0	0.8	0.9	0.6	0.0
0.0	0.9	0.6	0.0	0.8	0.0
0.0	0.0	0.0	0.0	0.9	0.0
0.0	0.0	0.0	0.9	0.6	0.0
0.0	0.0	0.9	0.0	0.0	0.0
0.0	0.8	0.9	0.9	0.9	0.9

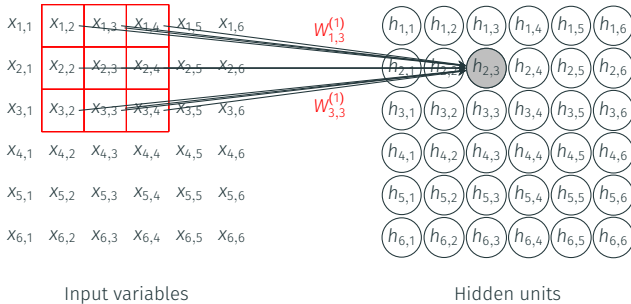
Input variables

$X_{1,1}$	$X_{1,2}$	$X_{1,3}$	$X_{1,4}$	$X_{1,5}$	$X_{1,6}$
$X_{2,1}$	$X_{2,2}$	$X_{2,3}$	$X_{2,4}$	$X_{2,5}$	$X_{2,6}$
$X_{3,1}$	$X_{3,2}$	$X_{3,3}$	$X_{3,4}$	$X_{3,5}$	$X_{3,6}$
$X_{4,1}$	$X_{4,2}$	$X_{4,3}$	$X_{4,4}$	$X_{4,5}$	$X_{4,6}$
$X_{5,1}$	$X_{5,2}$	$X_{5,3}$	$X_{5,4}$	$X_{5,5}$	$X_{5,6}$
$X_{6,1}$	$X_{6,2}$	$X_{6,3}$	$X_{6,4}$	$X_{6,5}$	$X_{6,6}$

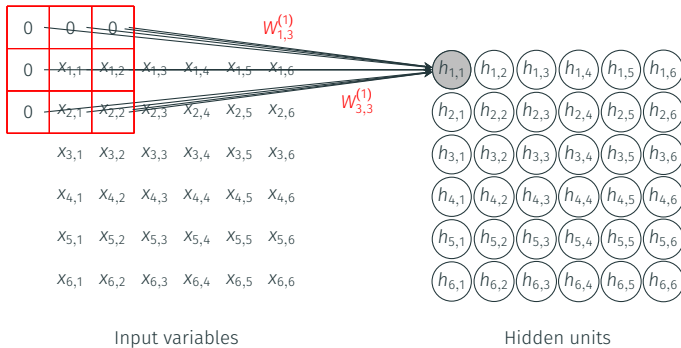
# Convolutional Neural Network



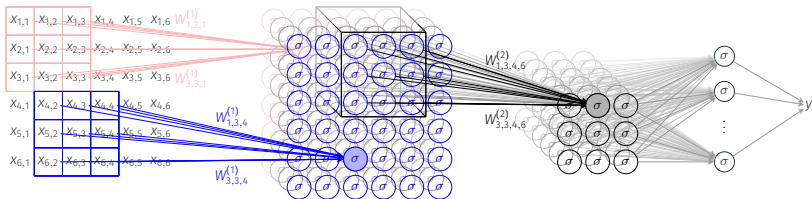
# Convolutional Neural Network



# Convolutional Neural Network

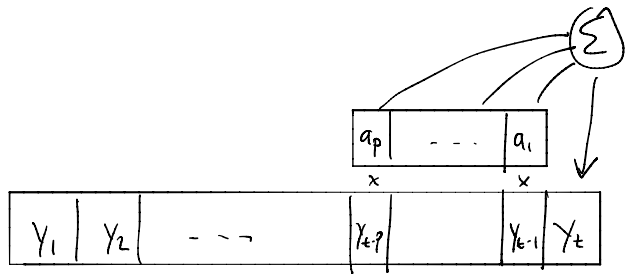


# Convolutional Neural Network





# AR as convolution



$$y_t = \sum_{j=1}^p a_j y_{t-j} + \varepsilon_t$$

# AR as convolution

This is a **causal convolution** between the process  $y_{1:n}$  and the convolutional filter,

$$W = \begin{bmatrix} a_p & \dots & a_2 & a_1 \end{bmatrix}. \quad \theta = (a_1 \dots a_p)^\top$$

Formally, we can write this as  $y_t = \hat{y}_t + \varepsilon_t$  where:

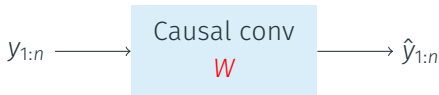
$$\hat{y}_t = W H_{t-1}$$

$$\hat{y}_t = \theta^\top \varphi_t$$

$$H_{t-1} := \begin{bmatrix} y_{t-p} & \dots & y_{t-2} & y_{t-1} \end{bmatrix}^\top$$

$$\varphi_t = \begin{bmatrix} y_{t-1} & \dots & y_{t-p} \end{bmatrix}^\top$$

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# Temporal Convolutional Network

We can augment the AR model with a **second (hidden) convolutional layer**.

Let  $h_t^{(0)} := y_t$  and introduce the "hidden signal"

$$h_t^{(1)} := \sigma \left( \underbrace{W^{(1)} H_t^{(0)}}_{\text{linear AR}} + \underbrace{b^{(1)}}_{\text{"bias term"}} \right)$$

*nonlinear activation*

$$H_t^{(0)} := [h_{t-p-1}^{(0)} \quad \dots \quad h_t^{(0)}]$$

Next, the output is given by

$$\hat{y}_{t+1} = W^{(2)} H_t^{(1)} + b^{(2)}$$

$$H_t^{(1)} = [h_{t-p-1}^{(1)} \quad \dots \quad h_t^{(1)}]$$

# Temporal Convolutional Network

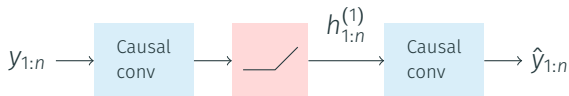
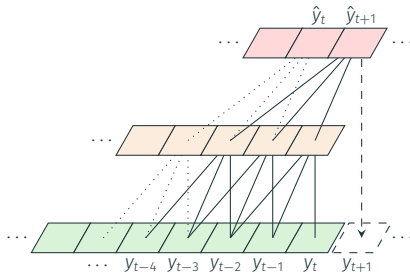
## 2-layer TCN:

$$h_t^{(0)} = y_t,$$

$$h_t^{(1)} = \sigma(W^{(1)}H_t^{(0)} + b^{(1)}),$$

$$y_{t+1} = W^{(2)}H_t^{(1)} + b^{(2)} + \varepsilon_{t+1},$$

with  $\varepsilon_{t+1} \sim N(0, \sigma_\varepsilon^2)$ .



# Temporal Convolutional Network

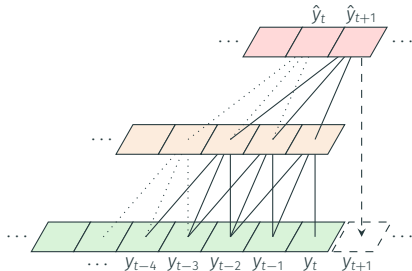
## 2-layer TCN:

$$h_t^{(0)} = y_t,$$

$$h_t^{(1)} = \sigma(W_t^{(1)} H_t^{(0)} + b^{(1)}),$$

$$y_{t+1} = W_t^{(2)} H_t^{(1)} + b^{(2)} + \varepsilon_{t+1},$$

with  $\varepsilon_{t+1} \sim N(0, \sigma_\varepsilon^2)$ .



Can extend to multiple layers of hidden signals,  $h_t^{(2)}$ ,  $h_t^{(3)}$ , ...

- ▲ Multiple layers  $\Rightarrow$  very flexible models
- ▲ Receptive field increases with depth...
- ▼ ...but only linearly