Kalman Filter Assume that acyus ~ N (âcio, Polo) Let V = y - 9216-1 Then (x) | y: 6-1 ~ (| E[x, |y, 2, 2]) (Cov (x, |y, 6-1)) (Cov (x, |y, |y, 6)) (Cov (x, |y, |y, |z, |)) E[at |y1: t] = atto + From assumption E[Vely1:6-1]= E ye - gelo-1 | y1:6-1] = E[Zat + Et - Zatlo-1 y1:6-1] = Z E[d. 14,: -1] - Z2=16-1 = 0 Cov (a, 14...) = #[(a, -a, 16.) (a, -a, 16.) 14...] = Pele + From assumption = Z. E[(a_-a_1-1)(a_-a_1-a_1-1)]/1.5.] Z = ZPE16-Z (ov(de, ve (y.: +1) = [[(de-à bit-1) ve (y::e-] = [[de.(Zac+ E. - Zacto-)] | y::e-] = E | dt (dt-2+10-1) | y1: e-1) = Pt1t-12T This gives us Osing the conditional lemma we get that ably, y. ... Nather & Pelen ZT (Felt) Ve, Pelen ZT Felt, ZPelen) where as lygie = x | yie is The filter distribution.