

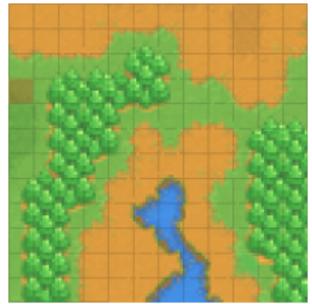


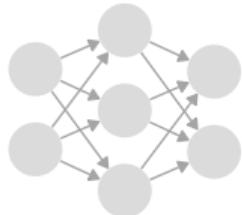
Artificial
Intelligence
Vlaanderen/Flanders



EXPLAIN, AGREE, LEARN: Scaling Learning for Neural Probabilistic Logic

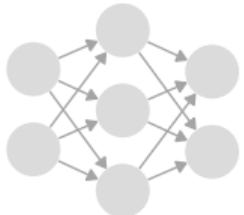
Victor Verreet, **Lennert De Smet**, Luc De Raedt and Emanuele Sansone





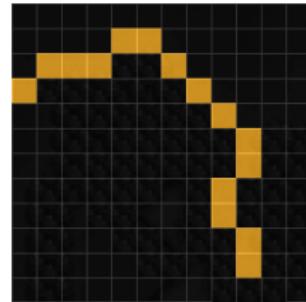
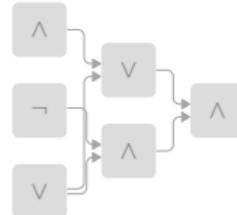
$x \in \{$
grass,
sand,
water,
tree,
mountain
 $\}^{12 \times 12}$

$$p_{\Lambda}(x)$$



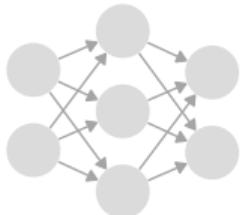
$x \in \{$
grass,
sand,
water,
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mountain
 $\}^{12 \times 12}$

$$p_{\wedge}(x)$$

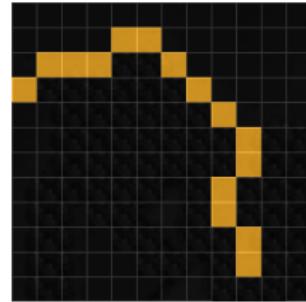
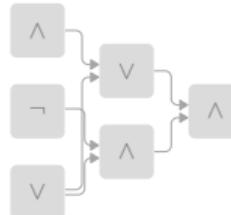


$\varphi \leftrightarrow \text{dijkstra}(x)$ is shortest

$\text{WMC}(\varphi) = \mathbb{P}(\varphi)$ (intractable!)



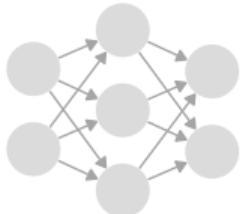
$x_{0,0}$ = grass
 $x_{0,1}$ = sand
...
 $x_{11,10}$ = tree
 $x_{11,11}$ = mountain



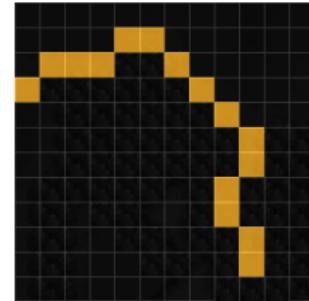
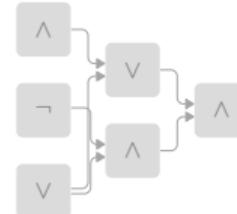
sample $\mathbf{x} \models \varphi \leftarrow$ EXPLAIN $\varphi \leftrightarrow \text{dijkstra}(\mathbf{x})$ is shortest

EXPLAIN

Sample **some** explanations for φ



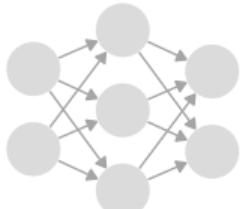
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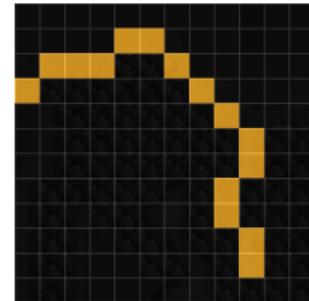
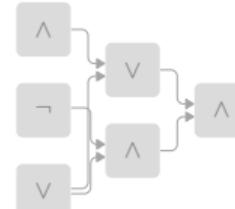
sample $\mathbf{x} \models \varphi$ ← EXPLAIN $\varphi \leftrightarrow \text{dijkstra}(\mathbf{x})$ is shortest
AGREE

EXPLAIN Sample **some** explanations for φ

AGREE Align samples with neural predictions



$x_{0,0} = \text{grass}$
 $x_{0,1} = \text{sand}$
...
 $x_{11,10} = \text{tree}$
 $x_{11,11} = \text{mountain}$



EXPLAIN Sample **some** explanations for φ

AGREE Align samples with neural predictions

LEARN Learn from the aligned samples via variational objective

Learning through all logical solutions does not scale
but is also not necessary

Setting

Neurosymbolic AI informs neural networks
by supervising with logical solutions

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Problem Getting all logical solutions is #P-hard
and bottlenecks neurosymbolic learning

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Setting

Neurosymbolic AI informs neural networks
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Problem

Getting all logical solutions is #P-hard
and bottlenecks neurosymbolic learning

Our solution

Sampled logical solutions form a variational objective
as a surrogate that scales better and provides guarantees

- 1 Explanations induce a variational surrogate objective
- 2 A generic algorithm to sample explanations with bounds
- 3 Verification of bounds and improved scaling

A variational objective supported on explanations

$$\log \mathbb{P}(\varphi) =$$

A variational objective supported on explanations

$$\log \mathbb{P}(\varphi) = \log \sum_{x \models \varphi} p_A(x)$$

A variational objective supported on explanations

$$\log \mathbb{P}(\varphi) = \log \sum_{x \models \varphi} p_A(x) = \log \sum_{x \models \varphi} \frac{q(x)p_A(x)}{q(x)}$$

A variational objective supported on explanations

$$\begin{aligned}\log \mathbb{P}(\varphi) &= \log \sum_{\mathbf{x} \models \varphi} p_\Lambda(\mathbf{x}) = \log \sum_{\mathbf{x} \models \varphi} \frac{q(\mathbf{x}) p_\Lambda(\mathbf{x})}{q(\mathbf{x})} \\ &\geq \sum_{\mathbf{x} \models \varphi} q(\mathbf{x}) \log \frac{p_\Lambda(\mathbf{x})}{q(\mathbf{x})}\end{aligned}$$

A variational objective supported on explanations

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Upshot Any proposal distribution q over **some solutions** of φ yields a valid lower bound on $\log \mathbb{P}(\varphi)$

The optimal proposal agrees with the neural network

The optimal proposal q on explanations \mathcal{E}_φ chooses

$$q(e) = \frac{p_\Lambda(e)}{\sum_{e' \in \mathcal{E}_\varphi} p_\Lambda(e')}$$

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The optimal proposal q on explanations \mathcal{E}_φ chooses

$$q(e) = \frac{p_\Lambda(e)}{\sum_{e' \in \mathcal{E}_\varphi} p_\Lambda(e')}$$

Upshot The best q weighs explanations like the **neural network**

Learning from a set of explanations instead of all solutions

EXPLAIN Get a set \mathcal{E}_φ of explanations for φ

Learning from a set of explanations instead of all solutions

EXPLAIN Get a set \mathcal{E}_φ of explanations for φ

AGREE Proposal distribution q is mixture of explanations

$$q(x) = \frac{\mathbb{1}_{x \in \mathcal{E}_\varphi} p_\Lambda(x)}{\sum_{e \in \mathcal{E}_\varphi} p_\Lambda(e)}$$

Learning from a set of explanations instead of all solutions

EXPLAIN Get a set \mathcal{E}_φ of explanations for φ

AGREE Proposal distribution q is mixture of explanations

$$q(x) = \frac{\mathbb{1}_{x \in \mathcal{E}_\varphi} p_\Lambda(x)}{\sum_{e \in \mathcal{E}_\varphi} p_\Lambda(e)}$$

LEARN Maximize the variational lower bound

$$\log \sum_{e \in \mathcal{E}_\varphi} p_\Lambda(e)$$

- 1 Explanations induce a variational surrogate objective
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DPLL as a generic explanation sampler

Sample next assignment \mathbf{x}'
instead of all assignments

```
1: Input: formula  $\varphi$ , assignment  $\mathbf{x}$ , sampling strategy  $s$ 
2: Output: explanation for  $\varphi$ 
3:
4:  $\mathbf{x} \leftarrow \text{propagate}(\varphi, \mathbf{x})$                                 ▷ trivial assignments
5: if  $\mathbf{x}$  is an explanation for  $\varphi$  then
6:     return  $\mathbf{x}$                                               ▷ explanation found
7: else if  $\mathbf{x}$  cannot satisfy  $\varphi$  then
8:     return EXPLAIN( $\varphi, \mathbf{x}_?, s$ )                                ▷ conflict restart
9: end if
10:  $\mathbf{x}' \leftarrow \text{sample from } s(\mathbf{x})$                                ▷ new assignment
11: return EXPLAIN( $\varphi, \mathbf{x}', s$ )                                     ▷ recurse
```

DPLL as a generic explanation sampler

Sample next assignment \mathbf{x}'
instead of all assignments

Sampling strategy s is free
and can be parametrised

- 1: **Input:** formula φ , assignment \mathbf{x} , sampling strategy s
- 2: **Output:** explanation for φ
- 3:
- 4: $\mathbf{x} \leftarrow \text{propagate}(\varphi, \mathbf{x})$ ▷ trivial assignments
- 5: **if** \mathbf{x} is an explanation for φ **then**
- 6: **return** \mathbf{x} ▷ explanation found
- 7: **else if** \mathbf{x} cannot satisfy φ **then**
- 8: **return** EXPLAIN($\varphi, \mathbf{x}_?, s$) ▷ conflict restart
- 9: **end if**
- 10: $\mathbf{x}' \leftarrow \text{sample from } s(\mathbf{x})$ ▷ new assignment
- 11: **return** EXPLAIN(φ, \mathbf{x}', s) ▷ recurse

Every set of explanations provides an upper and lower bound
and diversity improves bounds

Summing probabilities of \mathcal{E}_φ
lower bounds the WMC

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Summing probabilities of \mathcal{E}_φ
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$$\tilde{\mathbb{P}}(\varphi) = \sum_{e \in \mathcal{E}_\varphi} p_\wedge(e)$$

Every set of explanations provides an upper and lower bound
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Summing probabilities of \mathcal{E}_φ
lower bounds the WMC

$$\tilde{\mathbb{P}}(\varphi) = \sum_{e \in \mathcal{E}_\varphi} p_\Lambda(e) \leq \sum_{x \models \varphi} p_\Lambda(x)$$

Every set of explanations provides an upper and lower bound
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Summing probabilities of \mathcal{E}_φ
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$$\tilde{\mathbb{P}}(\varphi) = \sum_{e \in \mathcal{E}_\varphi} p_\Lambda(e) \leq \sum_{x \models \varphi} p_\Lambda(x) = \mathbb{P}(\varphi) = \text{WMC}(\varphi)$$

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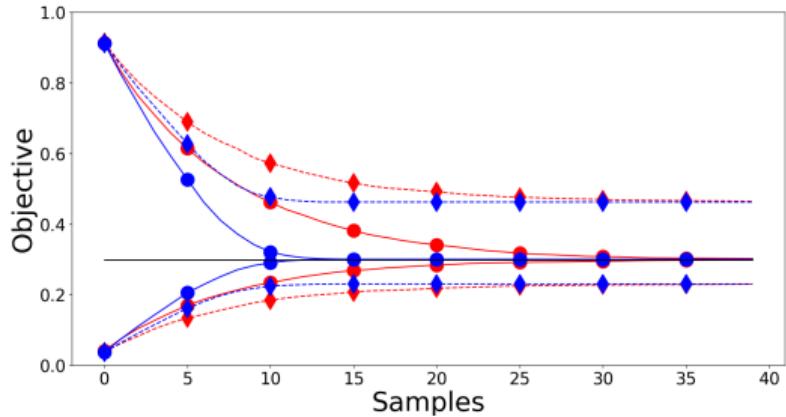
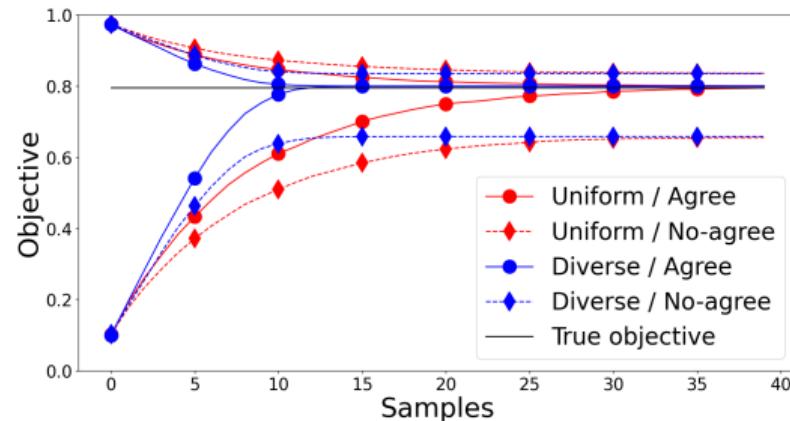
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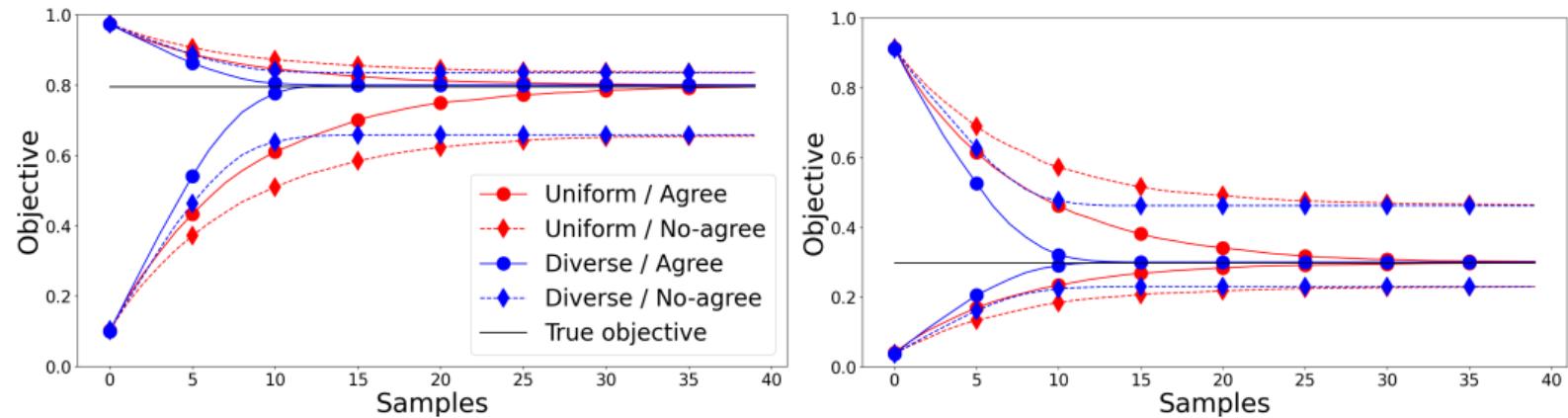
Implication A sampler with a **diverse** sampling strategy
will provide a better lower bound through a larger \mathcal{E}_φ

- 1 Explanations induce a variational surrogate objective
- 2 A generic algorithm to sample explanations and bounds
- 3 **Verification of bounds and improved scaling**

Diversity and AGREE step improve bounds



Diversity and AGREE step improve bounds



Upshot

The AGREE step is crucial to get closer to the true WMC and diverse samples improves sample efficiency

Learning to classify sums of digits

$$\begin{array}{r} 7 \boxed{3} \boxed{2} \boxed{1} 9 \\ + \quad 0 \boxed{8} \boxed{5} \boxed{4} 6 \\ = \quad 8 \; 1 \; 7 \; 6 \; 5 \end{array}$$

Method	$N = 2$	$N = 4$	$N = 15$
Reference	96.06	92.27	73.97
DeepStochLog	96.40 ± 0.10	92.70 ± 0.60	T/O
Embed2Sym	93.81 ± 1.37	91.65 ± 0.57	60.46 ± 20.4
A-NeSI	95.96 ± 0.38	92.56 ± 0.79	75.90 ± 2.21
EXAL	95.82 ± 0.36	91.77 ± 0.83	73.27 ± 2.05
A-NeSI (time)	81.7	198.2	1979.9
EXAL (time)	51.4 ± 2.3	74.8 ± 7.2	198.6 ± 15.7

Learning to classify sums of digits

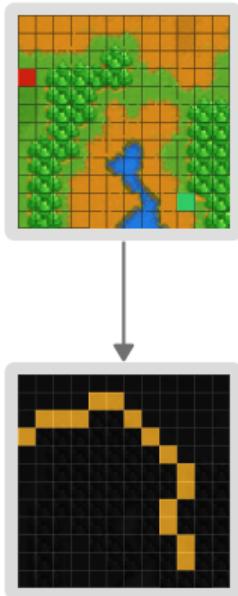
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Upshot

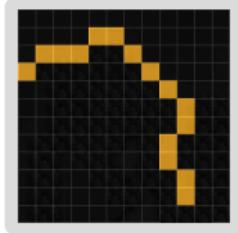
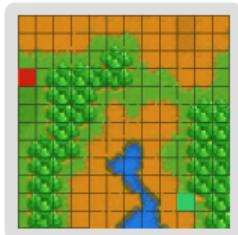
EXAL learns as well as other methods
and is up to **10x faster**

Learning to predict shortest paths



Method	12×12	30×30
RLOO	43.75 ± 12.35	12.59 ± 16.38
A-NeSI	94.57 ± 2.27	17.13 ± 16.32
A-NeSI + RLOO	98.96 ± 1.33	67.57 ± 36.76
EXAL	94.19 ± 1.74	80.85 ± 3.83
A-NeSI (time)	1380	2640
EXAL (time)	11.1 ± 0.1	84.3 ± 0.7

Learning to predict shortest paths



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EXAL	94.19 ± 1.74	80.85 ± 3.83
A-NeSI (time)	1380	2640
EXAL (time)	11.1 ± 0.1	84.3 ± 0.7

Upshot

EXAL learns as well or better as other methods and is up to **30x faster**

EXAL learns faster than other methods
and provides guarantees

Faster learning EXAL with diverse explanations outperforms SOTA
by always providing a satisfying signal

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Provable guarantees EXAL provides bounds on the true WMC that other methods do not have

EXAL learns faster than other methods and provides guarantees

Faster learning

EXAL with diverse explanations outperforms SOTA by always providing a satisfying signal

Provable guarantees

EXAL provides bounds on the true WMC that other methods do not have

Generic and flexible

EXAL is a generic algorithm and agnostic to the sampler but we provide a universal DPLL-based sampler



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