

Unreal Engine 5 - Lesson 6 - Physics

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Physics engine

- Let's start by speaking about **physics engine**
- Unreal Engine being a **game engine**, it needs to **rely** on a **physics system** in order to make **physics computation, collision detection, etc...**
- There is a chronology in physics engine usage for the engine
 - On **UE2**, Havok was used and then drops because of **lack of functionalities, slower** and a **high licensing cost**
 - On **UE3**, **software character movement** was made **in-engine**, while **PhysX** was used for **physics objects and vehicles**.
 - The transition from **Havok** to **PhysX** can be explained by many things like **NVIDIA GPU hardware acceleration, sponsoring, faster, etc...**
 - On **U4**, **character movement** was **reimplemented** on top of physics (PhysX by default). It does **simplified interaction** between **character and physics objects**.
 - With this change UE4 **require** PhysX in order to run.
 - In later stage of development of **UE4**, they start working on **animation physics engine** for cheaper **cloth / chains / hair**, used for Paragon & Fortnite. This leads to the **creation** of **Chaos Physics**, given more **control** and **optimization** scope.
 - On **U5**, **PhysX** was dropped to use **Chaos Physics** instead
 - Technically speaking, PhysX is still available to be compiled from source but needs to be ported to UE5



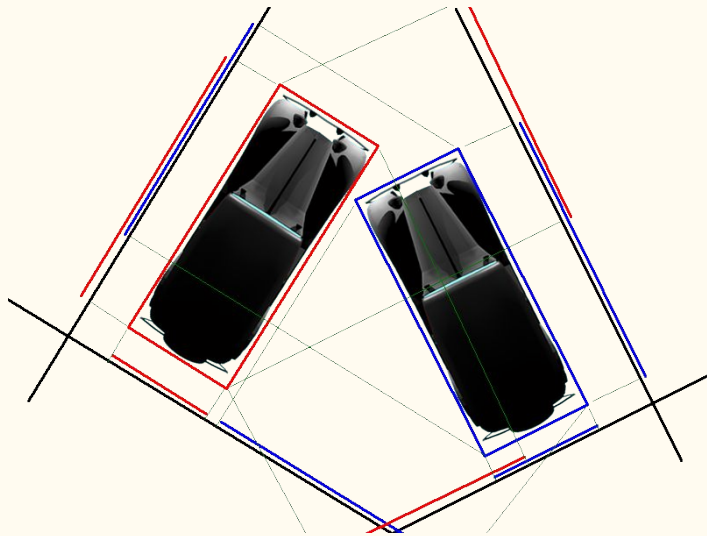
Chaos Engine

- **Chaos Engine** is now the **default** physics engine
- Physics is a really **difficult subject** with a lot of **point** that would require **entire lesson** to be simply **highlighted**
- In this lecture, we'll go through the **basics of physics** on which all **complex system** are **built on**. However, in order to offer the **possibility** to check by **yourself**, here are some **complex topics** that we may want to check out
 - Chaos destruction
 - Cloth Simulation
 - Fluid simulation
 - Hair Physics
 - Physics Fields
 - Etc...



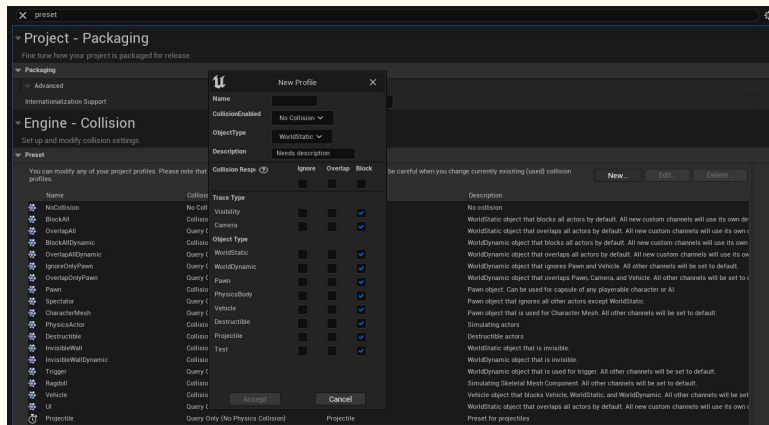
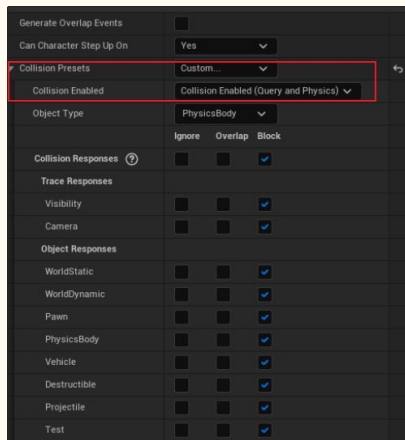
Collision overview

- When we are thinking about **physics**, we are thinking about **two** mains **topics** in most cases
 - **Collisions**
 - **Raycasting**
- Every object that needs to **generate** some sort of **geometry** to be **rendered** or use as a **collision data** inherit from **UPrimitiveComponent**
 - Inside them **ShapeComponents** are **collision component** which generated **geometry** only used for **collision detection**
 - **StaticMesh** & **SkeletalMesh** components contain **pre-built geometry** that is **rendered** but that can also be **used** for **collision detection**



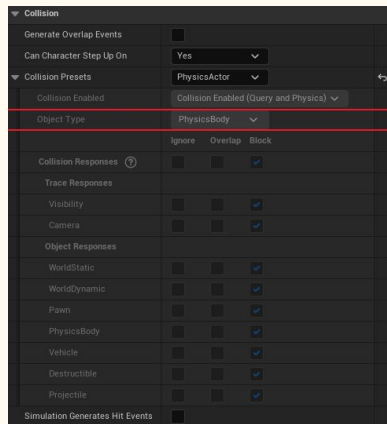
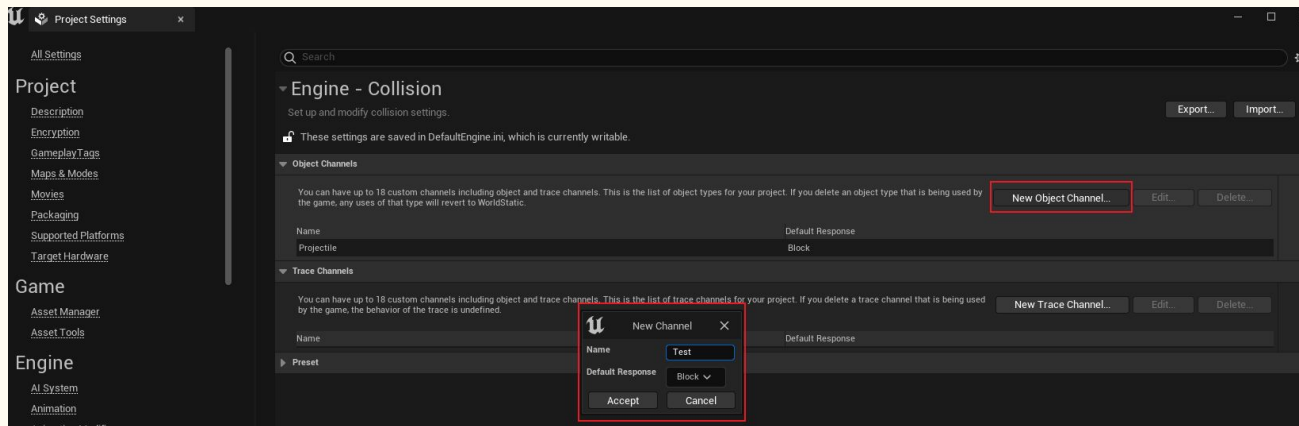
Collision Presets & Collision Enabled

- Collision Presets allows to have a **predefined collision matrix** setup based on the **preset**. But using a preset **doesn't allow to modify** how it should behave. In order to do so, you need to select **“Custom”** in the **Collision Presets**
 - It is possible to **create** new preset through the **Project Settings** tab
- Collision Enabled has 4 different values :
 - **NoCollision** : **No representation** in the physics engine.
 - **QueryOnly** : Only for **spatial queries** (raycast, sweeps, etc...). It is useful for character movement and object that do not need physical simulation.
 - **Physics Only** : Only for **physics simulation** (rigid body, etc...). This is useful for simulated secondary motion character not needing per bone detection
 - **Collision Enabled** : For **both, spatial queries** (raycast, sweeps, etc...) and **simulation** (rigid body, constraints, etc...)



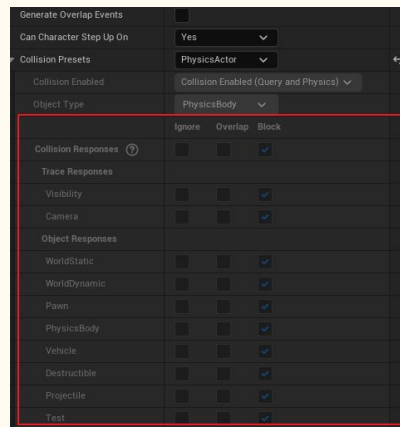
Object Type

- Each collider get an **Object Type**
- **Object Type** are essential in **collision detection** and **interaction** has there are the type **used in object responses** when you are defining how an object **should interact** with the world
- By going into **Edit>Project Settings>Collision**, you'll be able to **create new object channel** that will be usable as **object type** in the collision
- As you can see during creation, **Object Type** has a **default response** that can be changed from this **panel** also



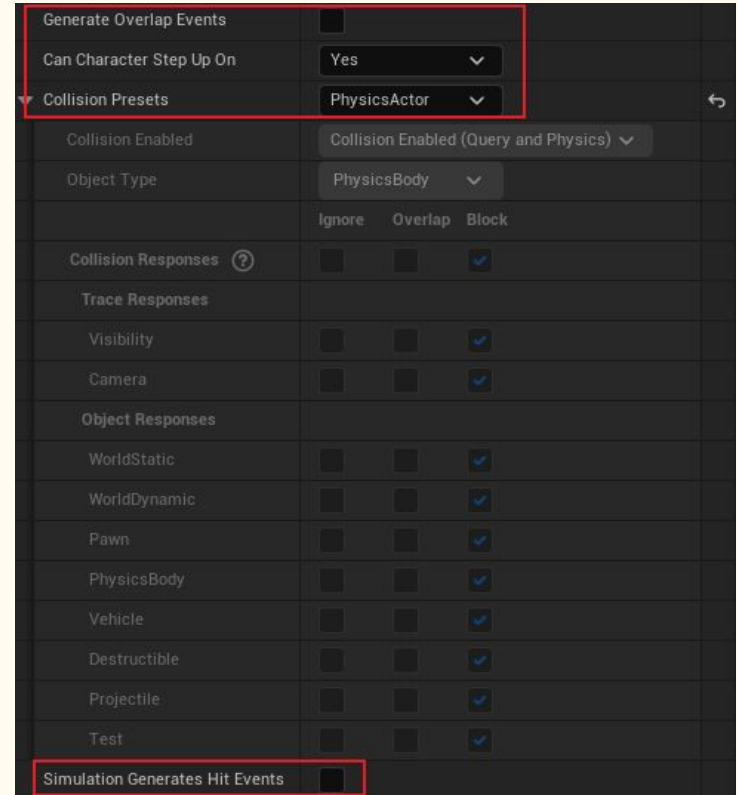
Collision responses

- Coming directly from **Object Type**, collision **responses** is the way to **precise** how the collision should be **handled**
 - **Ignore** : **No collision** or **overlap** event can be **trigger** between this object and the object type
 - **Overlap** : **No collision** can be trigger but **overlap** may be if an **overlap** or **block** is present in the other object type
 - **Block** : **Blocking** can be trigger if a block is **present** in the other object type



Other parameters & rules to keep in mind

- As you can see, there is a bunch of other parameters that are needed to configure as you would like
 - **Simulation Generated Hit Events** : It needs to be **enabled** in order to execute **Event Hit** which is used in **Blueprint**, **Destructible Actors**, **Triggers**, etc...
 - **Generate Overlap Events** : It is needed if you want actors to be in **overlap mode**. If you select a **response** as **overlap** but **don't enabled** this option, it will be **essentially** the same as **Ignore**
 - **CanCharacterStepUpOn** : It is **reflecting** how the **physics** should behave when a **mesh is falling / walking** on the **component**. If set to **false**, it will **reject** it with a **bump**
- There is some **rules** to keep in mind when dealing with collision
 - For 2 or more simulating object to block each other, they **both** needs to be set to **block** their **respective object types**
 - For 2 or more simulating object, if **one is block** and the **second one is overlap**, **overlap** will occurs but **not the block**
 - **Overlap events** can be generated even if an object **Blocks** another, especially at **high speeds**
 - It is **not recommended** for an object to have **both collision** and **overlap events**
 - If an **object** is set to **ignore** and the **second one** to **overlap**, no **overlap** will be fired



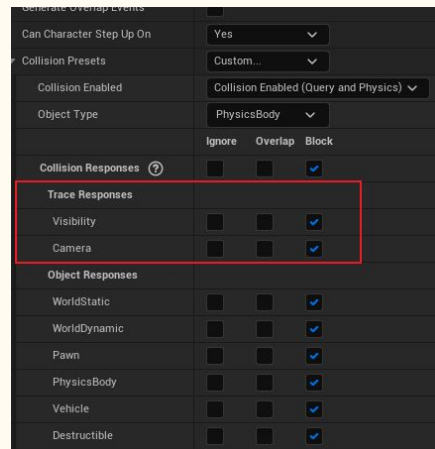
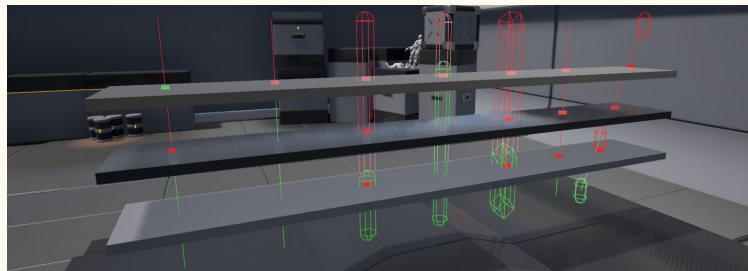
Overlap Events

- Unlike collisions that can **fire every frame**, overlap are based on **event** with
 - **ReceiveBeginOverlap** : It will be called when the **component** which is compatible in the collision matrix will have it's **collider entering** into the object one
 - **ReceiveEndOverlap** : It will be called the same way of **receive**, but when the **collider exit** the object one.
- Warning about this **type of event**, it will fire for **every overlap** object. It mean that you need to **properly setup collision matrix** or you may fall into **pawn armor pieces** for example that will trigger **overlap** event when you'll not want
- **REMINDER** : For an overlap to occurs, **both Actors** needs to enable **Generate Overlap Events**.

Generate Overlap Events	<input type="checkbox"/>
Can Character Step Up On	Yes ▾
Collision Presets	PhysicsActor ▾
Collision Enabled	Collision Enabled (Query and Physics) ▾
Object Type	PhysicsBody ▾
	Ignore Overlap Block
Collision Responses ?	<input type="checkbox"/> <input type="checkbox"/> <input checked="" type="checkbox"/>
Trace Responses	
Visibility	<input type="checkbox"/> <input type="checkbox"/> <input checked="" type="checkbox"/>
Camera	<input type="checkbox"/> <input type="checkbox"/> <input checked="" type="checkbox"/>
Object Responses	
WorldStatic	<input type="checkbox"/> <input type="checkbox"/> <input checked="" type="checkbox"/>
WorldDynamic	<input type="checkbox"/> <input type="checkbox"/> <input checked="" type="checkbox"/>
Pawn	<input type="checkbox"/> <input type="checkbox"/> <input checked="" type="checkbox"/>
PhysicsBody	<input type="checkbox"/> <input type="checkbox"/> <input checked="" type="checkbox"/>
Vehicle	<input type="checkbox"/> <input type="checkbox"/> <input checked="" type="checkbox"/>
Destructible	<input type="checkbox"/> <input type="checkbox"/> <input checked="" type="checkbox"/>
Projectile	<input type="checkbox"/> <input type="checkbox"/> <input checked="" type="checkbox"/>
Test	<input type="checkbox"/> <input type="checkbox"/> <input checked="" type="checkbox"/>
Simulation Generates Hit Events	<input type="checkbox"/>

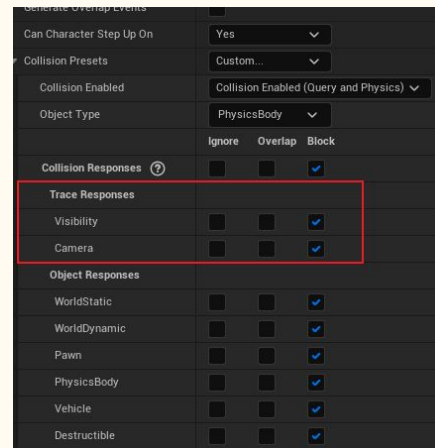
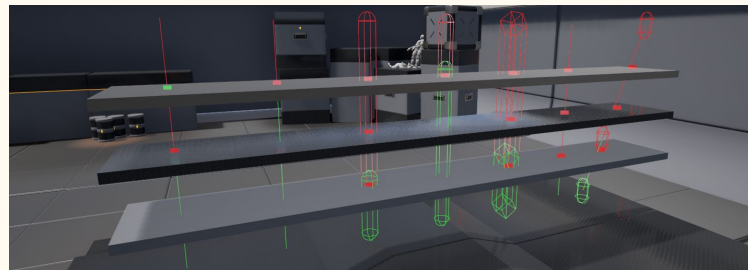
Trace overview

- Another important subject when it comes to physic is **Raycasting**
- Raycasting is **essentially** the **same** as **Trace** in some other engine or software packages. In order to stay inline with **Unreal naming convention**, we'll only use **traces** now
- Trace offer a method for **reaching out in your levels** and **getting** feedback on what is **present** along a **line segment**.
- You use them by providing **two end points** (**start** and **end**) and the **physic engine** will **traces** a line segment between those points, **reporting any Actors** (with collision) that it **hits**
- You'll use traces in **many circumstances**
 - Know if an Actor can see another
 - Get the normal of a specific polygon
 - Simulate high velocity weaponry
 - Check if an actor entered a space
- Traces offer a **reliable** and **computationally cheap** solution.
- Trace uses the physics system and therefore responses system.



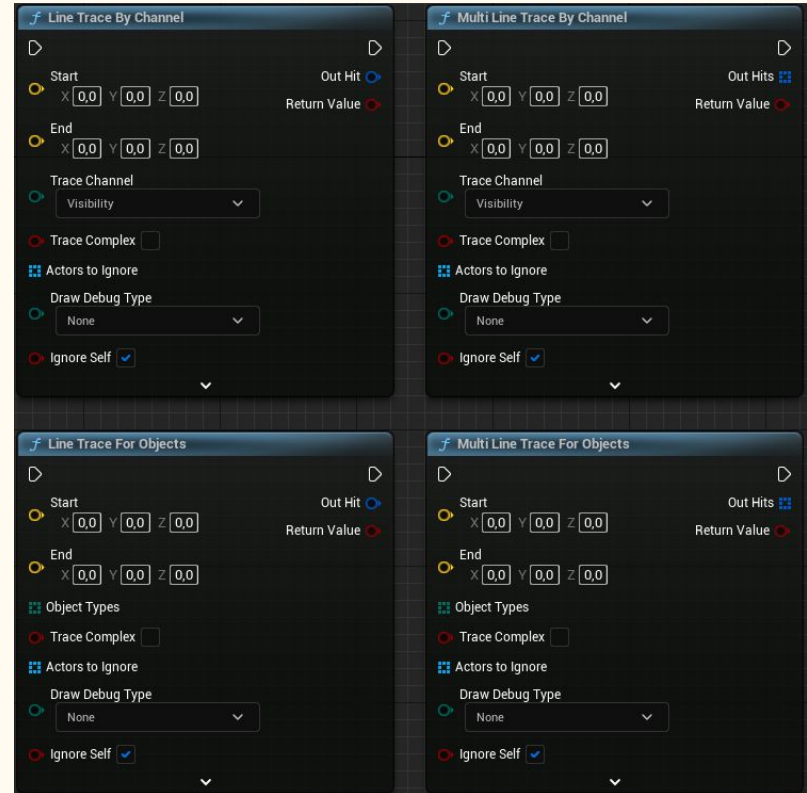
Trace by channel or Object Type

- Even if traces uses **response system** there is **2 options** that you can choose when tracing
 - **Channels** : Channels are used for things like **visibility** or **camera** and almost **exclusively** have to do with **tracing**.
 - This is a good way for example to **ensure** to **trace** against specific **actor** that **response** to that traces
 - Like **Object Type**, you can **create** custom trace response in **Project settings**
 - **Object types** : There are physics types of Actors with collision in your scene like Pawns, Vehicles, etc...
- The choice between tracing **by channel** or **object type** will always be **different** based on the **context** and there is **no global answer** to that question



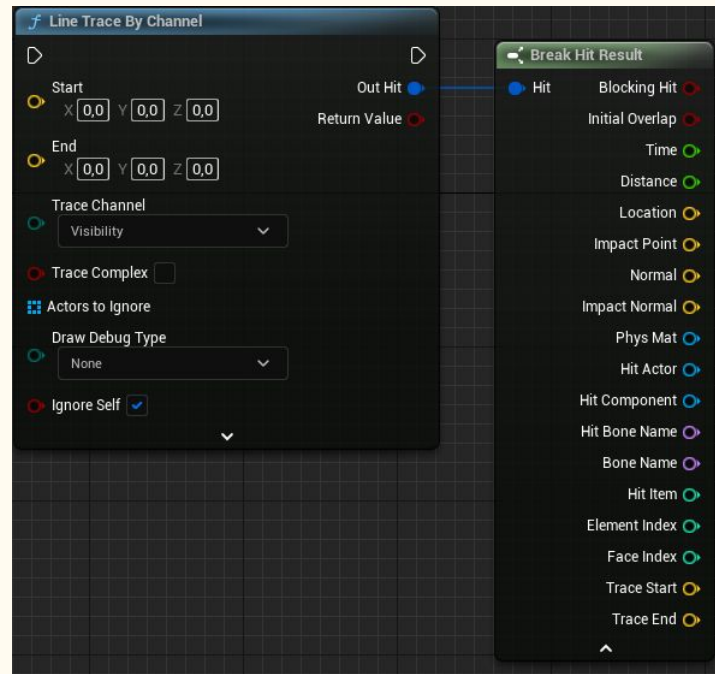
Trace Single or Multiple Hits

- When you are tracing, you can choose to return the **first things** that matches the criteria hit by trace or you can return **everything** hit by the trace that matches the criteria
- **Note** : A special consideration is given to Multi trace by channel versus Multi trace for objects
 - With **MultiTrace by Channel**, the trace will return all **Overlaps** up to and **including** the first **Block**
 - With **Multi trace by object**, it will return **everything** that matches an object type trace trace is looking for.
- Keep in mind that **generally speaking, except** for trace for **objects**, if an object blocks the trace, it will make sure that the multi trace **will not registered** result **after** the **blocking one**



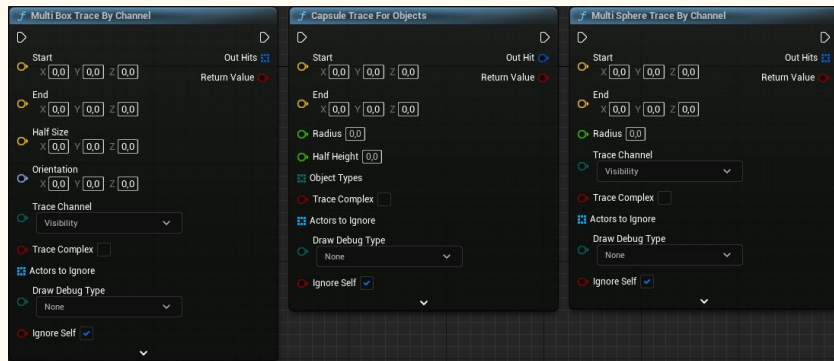
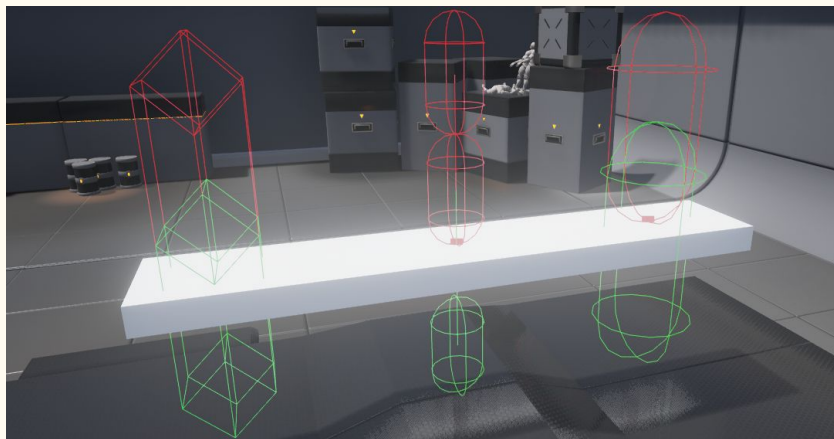
Hit Results

- When a trace hit something, it will return **true** and a **struct** which is available in **blueprint** and **C++**.
- There is a bunch of member in that struct that we can check on
 - **Blocking Hit** : Is the hit a blocking one ?
 - **Initial Overlap** : Is the first overlap ?
 - **Location** : **World space location** of the hit, **modified** based on the shape of the trace
 - **Impact Point** : **Absolute location** of the hit, **does not include** the **shape** of the trace, only the point of the hit
 - **Normal** : Direction of the trace
 - **Impact Normal** : Normal of the hit surface
 - **Phys Mat** : Physical Material of the hit surface
 - **Hit Actor** : The hitten Actor
 - Etc...
- Difference between **Location** and **ImpactPoint** only matter for **shape trace**
- Do not hesitate to **consult documentation** if you are not sure about the member variable



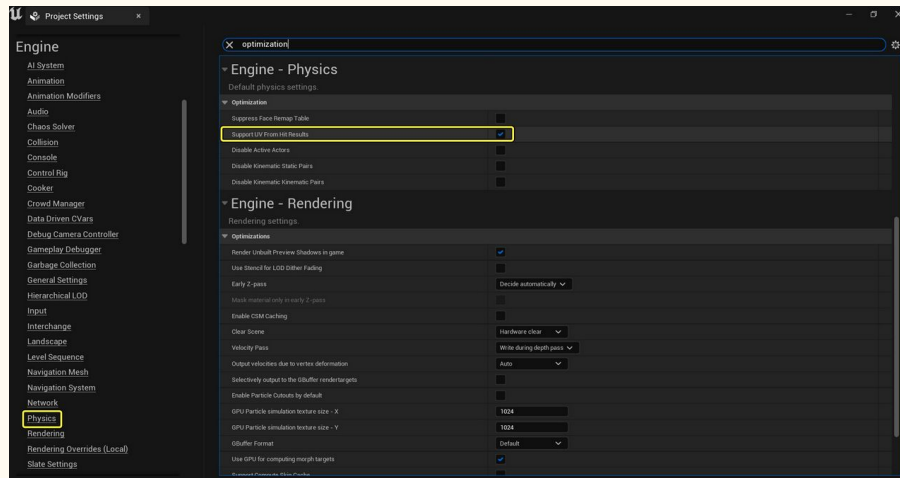
Shape traces

- Sometimes, **Line Trace** are not enough
- Shape trace are **based** on line trace with more **complex computation**
- They function like **Line Traces**, giving an **HitResult** and having **multiple variants** for single or multi trace and **For Objects** or **By Channel**
- They have an **added layer of checking** obviously as they are using a **shape** as a **volume** in the **tracing**



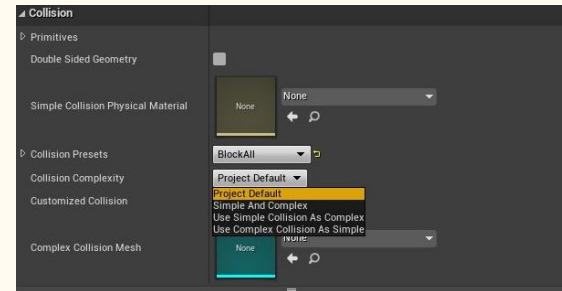
Getting UV Coordinates from Trace

- Let's talk about a last point that may be useful in some cases, getting **UV coordinates** from trace
- It assumes that **trace complex** is **enabled** in the trace settings
- It assumes that **Support UV From HitResult** is **enabled** in **Project Settings**
- It has **some limitation** like only working on **Static Mesh Components** and **Procedural Mesh Component**.
- It increases **CPU memory usage** as the engine needs to **keep an additional copy** of vertex positions and UV coordinates in main memory
- It **allows** in **HitResult** to get **UV coordinate** of the **hit**, which may be useful for example in **creating visual effect** precisely on the impact point directly on the **material texture**



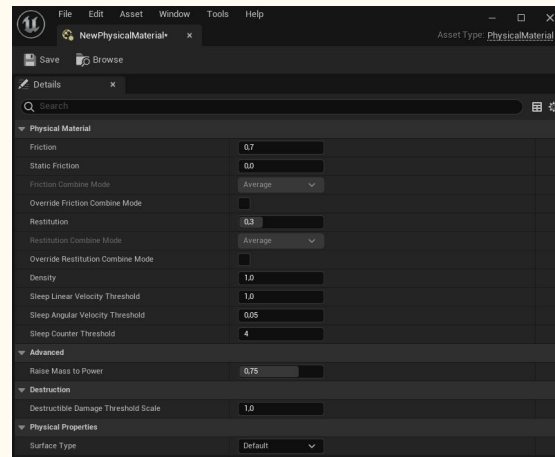
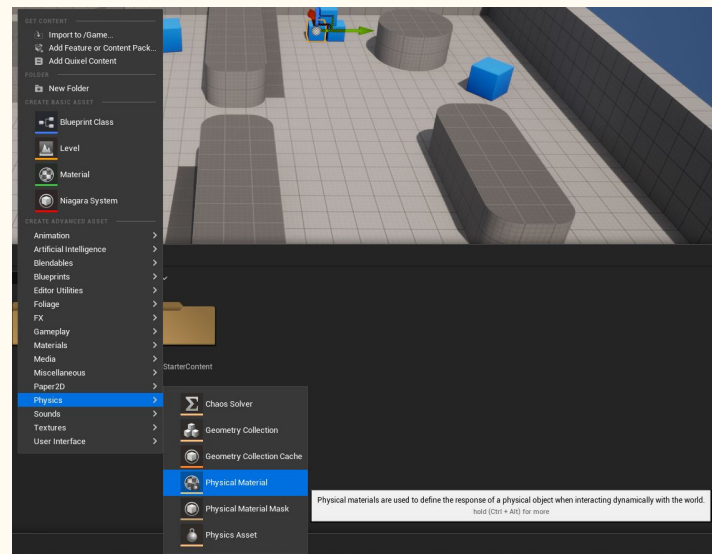
Simple VS Complex Collision

- You have access to **simple** and **complex collision shapes**. **Simple Collision** are **primitives** like **cubes**, **spheres**, **capsules**, and **convex hulls**. **Complex Collision** is the **trimesh** of a given object. By default, Unreal Engine creates **both simple** and **complex** shapes, then, based on what the user **wants** (complex query versus simple query), the **physics solver** will use the **corresponding shape** for scene queries and collision tests.
- There is 4 types of collision complexity
 - **Project Default** : Using the **project's physics settings**, this will cause **simple collision** requests to use **simple collision**, and **complex** requests to use **complex collision**; the "default" behavior.
 - **Simple and Complex** : This flag **enables** the creation of **simple** and **complex** shapes, using **simple shapes for regular scene queries and collision tests**, and using **complex** (per poly) shapes for **complex scene queries**.
 - **Use Simple Collision As Complex** : This means that if a **complex query** is requested, the engine will still **query against simple shapes**; basically ignoring the **trimesh**. This helps **save memory** since we don't need to **bake** the trimesh and can **improve performance**
 - **Use Complex Collision As Simple** : This means that if a **simple query is requested**, the engine will **query against complex shapes**; basically ignoring the simple collision. This allows us to use the **trimesh** for the physics simulation collision. Note that if you are using **UseComplexAsSimple** you **cannot simulate** the object, but you can use it to **collide** with other **simulated** (simple) **objects**.



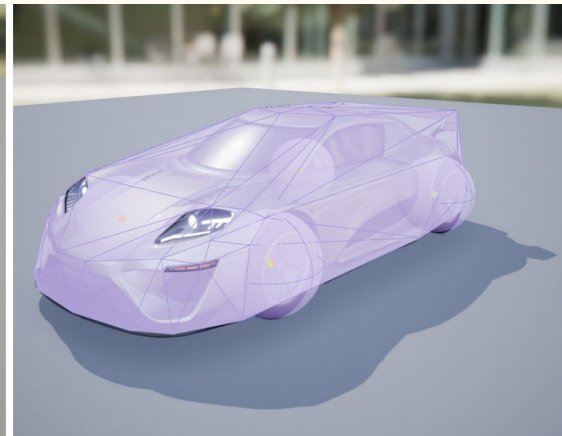
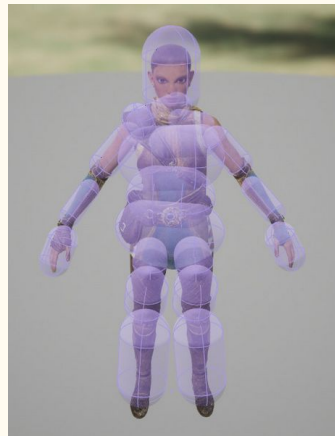
Physical Material

- **Physical Material** are .uasset element
- You can choose from which **class** you want your **Physical Material** to inherit from, the default one being the most common
- You can then **adjust** the settings of your **physical material**.
- You can see that the **last member** of the PM is **Surface Type**. It can be whatever you **want** from all surface type available in your project. You can **create new ones** in **Project Settings > Physics > Physical Surface**.
 - If can be useful to specify for example that your physical material represent grass or sand
- There is multiple ways to assign a PM to a material
 - **To a material** : In detail panel directly in **Material**
 - **To a material instance** : In detail panel of your **Material Instance**
 - **To a Physics Asset** : From a **Physics Asset**, open the **Physical material dropdown** and select your asset
 - **To a Static Mesh** : In the **Simple Collision Physical Dropdown**, you can select the desired PM
- For a breakdown of the properties, check [PM Properties](#)



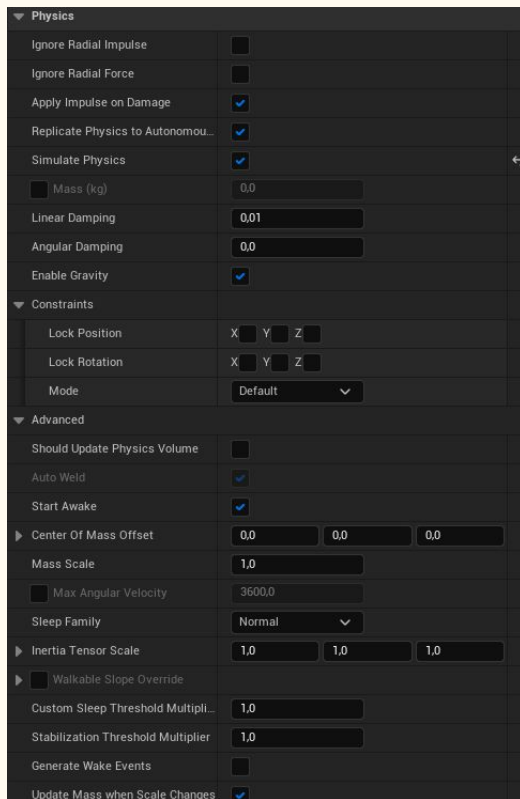
Physical Asset

- **Physic Asset** are .uasset element
- They can be set up for any skeletal mesh for simulation
 - It can be a **Character**
 - It can be a **Vehicle**
- **Physic Asset** are used to defined the **physics** and **collision** used by a **Skeletal Mesh**. These contain a **set** of **rigid bodies** and **constraints** that make up a single **ragdoll**.
- They are basically the **physic representation** in the physical engine.
- You can create a **PA** by enabling the option while **importing**
- You can create a PA from the **content drawer** Physics > PhysicAsset
- It is more likely that this **kind of setup** will not be made by you but from **artist**, so we'll not go any further in this, but keep in mind that this is the thing **dictating** how your **Skeletal Mesh** will behave.



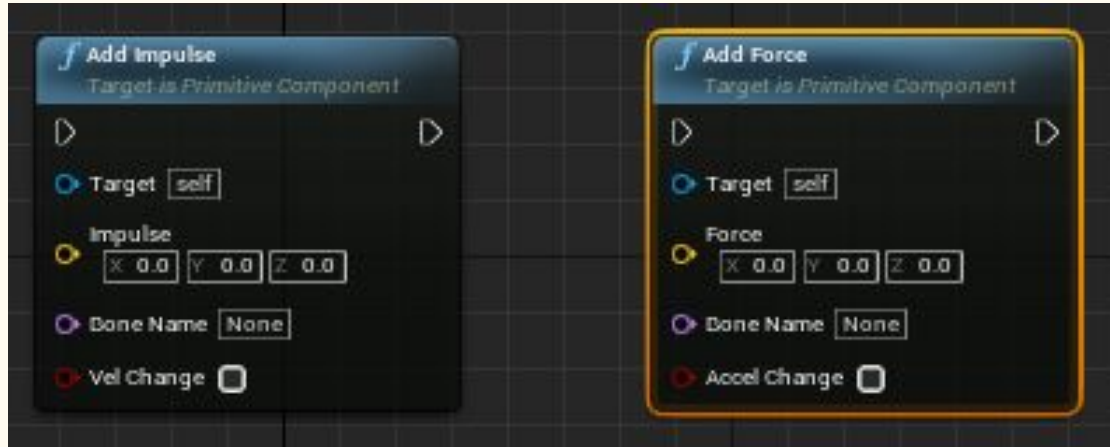
Physics bodies

- **Physics bodies** is the complex system that dictate how an **entity** behave in **physic engine**.
- It obviously cover the **collision responses**, but also all **parameters** that **specify** the **mass**, the **linear damping**, the **mass scale** etc...
- This value are set by **default**, but it is obviously **something** that needs to be **tweak** to match with the game feels looked for
- Again, it is more likely that this values will be setup by **artists** or **designer**, but it important to know where to find this informations if there is an **issue** in the **physics simulation** of the game



Add forces

- When you want to make your character moves, you should use the Character Movement Component way to do so, by calling for example
 - **AddMovementInput**
 - **SimpleMoveToLocation**
 - **Etc...**
- In some cases, you may want to add a physical force to your character, that interact correctly based on the physic system, in order to do so, you have access to two main calls
 - **AddImpulse** is designed to be used **only once** to add a **burst** at a location. E.g hitting a golf ball.
 - **Add force** is designed to be used **multiple times** to gradually **move objects**. E.g Player pushing a heavy cube



Time to.... highlight a concept

Prepare your job interviews

Practice

- **General**

- Place 4 cubes in your level which needs to interact differently with the player
 - 1st : It completely ignore the player just like a non-interactive decor element
 - 2nd : It doesn't trigger any physical change, the object remains in place BUT it display a message on the screen
 - 3rd : It interact physically with the player, making the cube moved upon collision
 - 4th : It interact physically with the player, making the cube moved upon collision + it display a message on the screen
- Create a Physical Material for your 3rd cube in order to make it heavier and much more difficult to move
- Create a method that check if an object is inside a cone in front of your player, like a sword slash, do it mathematically

- **Follow-through project**

- Ensure that your guards are able to detect your player and make it easy to tweak the value like search distance, etc...
 - Feel free to manage that as you want, but try to make a double test like a detection cone, then a trace
- Make your player interact with gold ingot in order to collect it.
 - Upon collision, destroy the gold ingot
 - Upon collision, trigger a Niagara System to inform player that it has collected a gold ingot
 - Upon collision, increase the number of ingot collected
- Create an ability that is triggered when you press a Key, for example E
 - It uses the scan detector which detect every guards around the player, even if they are behind a wall
 - It create 3 pulses separated by 3 seconds, and cannot be used for 1 minutes after that
 - For every guard affected, it change the material of its outfit
- Create an ability that is triggered when you press a Key, for example R
 - It uses an IEM system, starting at mouse location, it cast a cube around it and cancel every electronics of environment
 - Guard / Lamp / etc... are disable