# ANN and Handwritten Character Recognition

YAO ZHAO

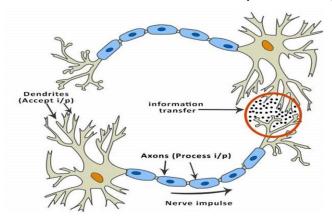
#### ANN

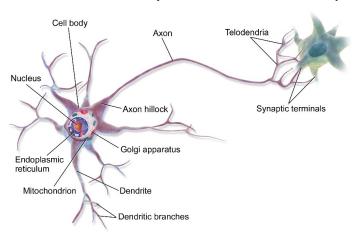
- ▶ The study of artificial neural networks was inspired by attempts to simulate biological neural systems (e.g. human brain).
- ▶ Basic structural and functional unit: nerve cells called neurons
- Work Mechanism
  - ▶ Different neurons are linked together via axons (轴突) and dendrite (树突)
  - ▶ When one neuron is excited after stimulation, it sends chemicals to the connected neurons, thereby changing the potential (电位) within these neurons.
  - ▶ If the potential (电位) of a neuron exceeds a "threshold", then it is activated and send

chemicals to other neurons.

#### ANN

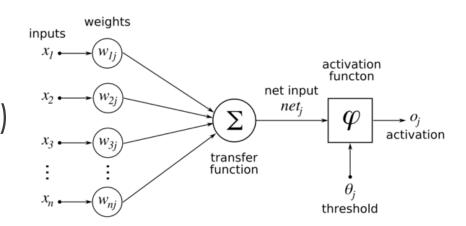
- ▶ A neuron is connected to the axons (轴突) of other neurons via dendrites (树突), which are extensions from the cell body of the neuron.
- ► The contact point between a dendrite (树突) and an axon (轴突) is called a synapse (突触).
- ▶ The human brain learns by changing the strength of the synaptic connection between neurons upon repeated stimulation by the same impulse.





#### Artificial Neuron Mathematical Model

- ▶ Input:  $x_i$  from the i-th neuron
- Weights: connection weights (synapse)
- ightharpoonup Output:  $o_j = \varphi(\sum_{i=1}^n w_{ij}x_i \theta_j)$



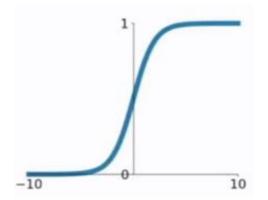
#### Artificial Neuron Model

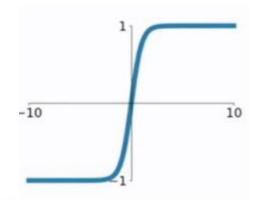
- ▶ Ideal activation function: step function but inapplicable
- Common activation function: sigmoid, tanh, ReLU

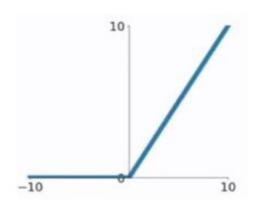
$$g(z)=rac{1}{1+e^{-z}}$$

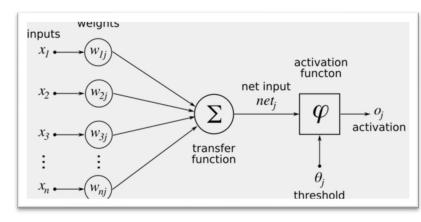
$$g(z) = rac{1}{1 + e^{-z}} \qquad \qquad g(z) = rac{e^z - e^{-z}}{e^z + e^{-z}}$$

$$g(z) = \left\{egin{array}{ll} z, & ext{if } z > 0 \ 0, & ext{if } z < 0 \end{array}
ight.$$



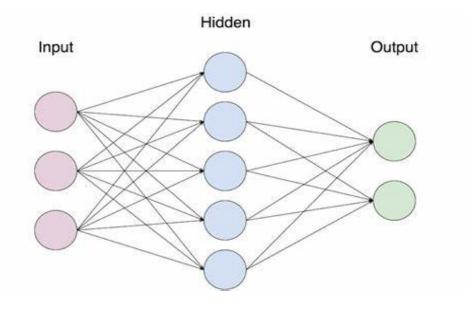






#### Artificial Neural Networks

- Consist of multiple artificial neurons
- Usually have the structure of an input layer, multiple hidden layer, an output layer
- ► The design of an NN or AutoML aims to design appropriate hidden layers and connection weights.



3-layer Feedforward neural networks

#### One Inference Process

$$x_{\rm j}^{(1)} = f(a_{\rm j}^{(1)})$$

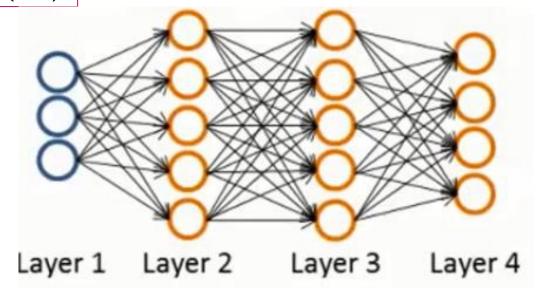
$$x_k^{(2)} = f(a_k^{(2)})$$

$$x_j^{(1)} = f(a_j^{(1)})$$
  $x_k^{(2)} = f(a_k^{(2)})$   $y_l = x_l^{(3)} = f(a_l^{(3)})$ 

$$x = x^{(0)} \rightarrow a^{(1)} \rightarrow x^{(1)} \rightarrow a^{(2)} \rightarrow x^{(2)} \rightarrow a^{(3)} \rightarrow x^{(3)} = y$$

$$a_{j}^{(1)} = \sum_{i=1}^{D} w_{ji}^{(1)} x_{i}^{(0)} + b_{j}^{(1)}$$

$$\mathbf{a}_{k}^{(2)} = \sum_{j=1}^{M} w_{kj}^{(2)} x_{j}^{(1)} + b_{k}^{(2)}$$



Superscript of w: layer index

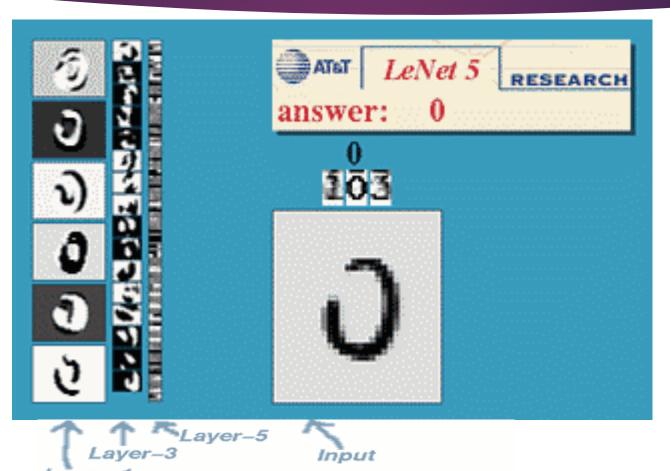
$$a_l^{(3)} = \sum_{k=1}^{N} w_{lk}^{(3)} x_k^{(2)} + b_l^{(3)}$$

## Training of NN

- W and Threshold values decide the output of NN
- ► The training is to find appropriate values for W and Threshold
- ▶ The learning process is to tune weight matrix

<b>x</b> 1	<b>x2</b>	х3	- 11	<b>l</b> 2
1.0	0.1	0.3	1	0
0.1	1.5	1.2	1	0
1.1	1.1	2.0	0	1
0.2	0.2	0.3	0	1

# ANN Application: Handwritten character recognition



http://yann.lecun.com/exd b/lenet/

#### Performance of ANN

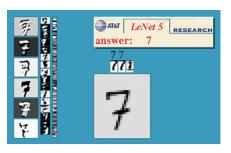
► Anti-interference ability, such as different sizes, digital distortion

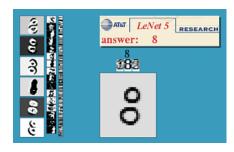












### The practice: Handwritten character recognition

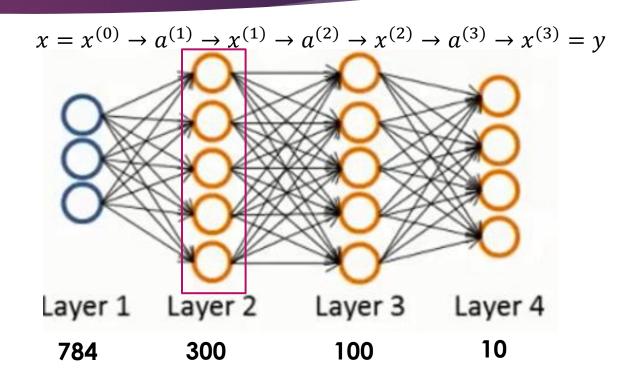
The dataset of this practice is a subset of MNIST

#### A 28\*28 grayscale image:



# Handwritten character recognition ANN network structure

- Suppose 100 training samples, each sample: 28\*28, feature: 784
- ► Layer 1: Input Layer, size D = 784
- ► Layer 2: Hidden Layer 1, size M = 300
- ► Layer 3: Hidden Layer 2, size N = 100
- ► Layer 4: Output Layer, size K = 10

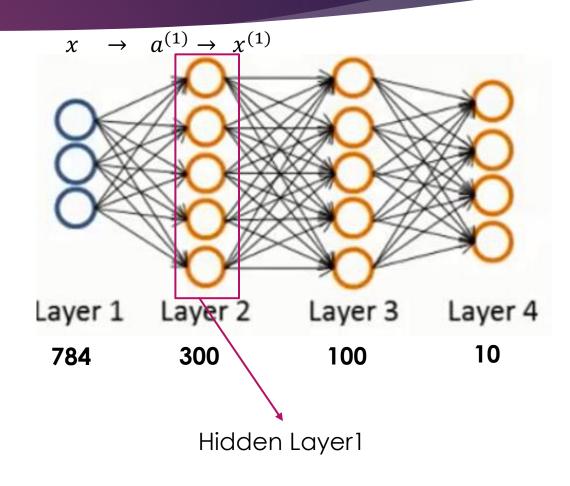


## ANN-Input Layer to Hidden Layer 1

- ▶ Input: 100(samples number) \* 784(feature)
- ▶ Input to Hidden Layer 1: Weight Matrix: 784\*300, b: 1\*300
- Weighted Sum for j th neurons of hidden layer 1:

$$a_{j}^{(1)} = \sum_{i=1}^{D} w_{ji}^{(1)} x_{i}^{(0)} + b_{j}^{(1)}$$

- After activation function, output of j-th neuron:  $x_j^{(1)} = f(a_j^{(1)})$
- Output of Hidden Layer 1,  $x^{(1)}$ : 100(samples number)\* 300 (feature) matrix
- ▶ f: Relu function

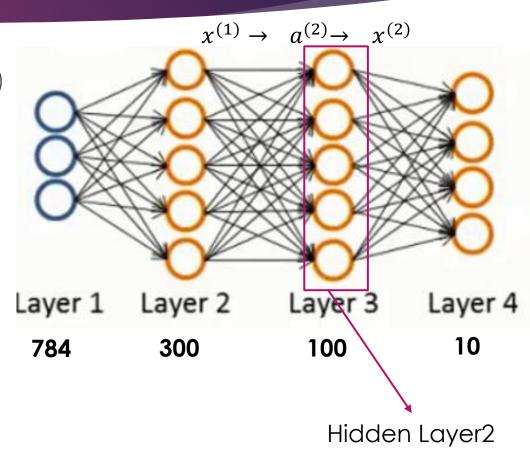


## ANN-Hidden Layer 1 to Hidden Layer 2

- For Hidden Layer 2: Input data  $x^{(1)}$ : 100(samples number)\* 300 (feature)
- ▶ Hidden Layer 1 to Hidden Layer 2: Weight Matrix: 300\*100, b: 1\*100
- Weighted Sum for k th neurons of hidden layer 2:

$$a_k^{(2)} = \sum_{j=1}^M w_{kj}^{(2)} x_j^{(1)} + b_k^{(2)}$$

- After activation function, output of k-th neuron:  $x_k^{(2)} = f(a_k^{(2)})$
- Output of Hidden Layer 2,  $x^{(2)}$ : 100(samples number) \*100 (feature) matrix
- ▶ f: Relu function

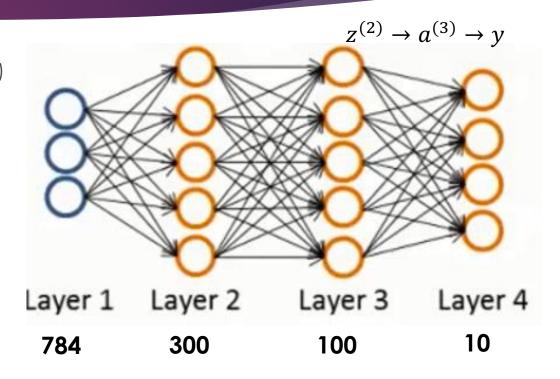


## ANN-Hidden Layer 2 to Output Layer

- For output layer: Input data  $x^{(2)}$ : 100 (samples number) \* 100 (feature)
- ▶ Hidden Layer 2 to Output Layer: Weight Matrix: 10\*100, b: 10\*1
- $\blacktriangleright$  Weighted Sum for l-th neurons of output layer:

$$a_l^{(3)} = \sum_{k=1}^{N} w_{lk}^{(3)} x_k^{(2)} + b_l^{(3)}$$

- After activation function, output of I-th neuron:  $y_l = x_l^{(3)} = \sigma\left(a_l^{(3)}\right)$
- Output of Output Layer, y: 100(samples number) \* 10 (feature)
   matrix
- $\sigma$ : softmax function



## Training of NN

- W and Threshold values decide the output of NN
- ► The training is to find appropriate values for W and Threshold so that the output is close to the true value
- ▶ Given the structure of NN, the learning process is to tune weight matrix in order to in order to minimize the difference between true value and prediction value.

### Loss Function and Gradient Descent

- ▶ How to evaluate the difference? Loss Function
- ▶ How to tune weight matrix? optimization method (e.g. Gradient Descent)

## As an Example

- W and b initialization:
  - Navier: is an initialization scheme for neural networks, make w uniform distributed over  $\left(-\sqrt{\frac{6}{m+n}},\sqrt{\frac{6}{m+n}}\right)$

(m: number of rows of the matrix, n: number of columns of the matrix)

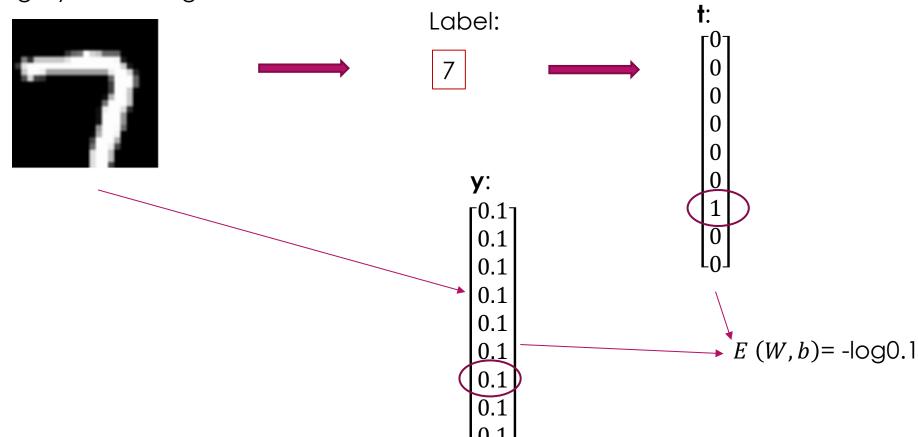
- Loss Function:  $E(y) = \frac{1}{N} \sum_{n=1}^{N} \sum_{k=1}^{10} -t_k^n ln y_k(x_n, w, b)$ N is the samples number,
- ▶ To avoid overfitting, add Regularization term:

$$E_{total}(y) = E(y) + \frac{\lambda}{2} ||W||_2^2$$

Gradient Descent: min  $f(x) \rightarrow x(t+1)=x(t)-\eta^*f'(x(t))$  ( $\eta$ : learning rate)

## Loss

A 28\*28 grayscale image:



### Gradient Descent

$$\frac{\partial E_{total}(W^{(t)}, b^{(t)})}{\partial W^{(t)}}$$

$$= \frac{\partial (\frac{1}{N} \sum_{n=1}^{N} E_n(W^{(t)}, b^{(t)}) + \frac{\lambda}{2} ||W^{(t)}||^2)}{\partial W^{(t)}}$$

$$= \frac{1}{N} \sum_{n=1}^{N} \frac{\partial E_n(W^{(t)}, b^{(t)})}{\partial W^{(t)}} + \lambda W^{(t)}$$

$$\frac{\partial E_{total}(W^{(t)}, b^{(t)})}{\partial b^{(t)}} = \frac{1}{N} \sum_{n=1}^{N} \frac{\partial E_n(W^{(t)}, b^{(t)})}{\partial b^{(t)}}$$

#### Chain Rule Review

- ► Chain rule: to find the derivative of a composite function
- If h(x)=f(g(x)), then h'(x)=f'(g(x))g'(x)
- ► E.g.: f(x)=2x+2, g(x)=3x+3, g(f(x)) is a composite function, g'(f(x))=6

#### One Inference Process

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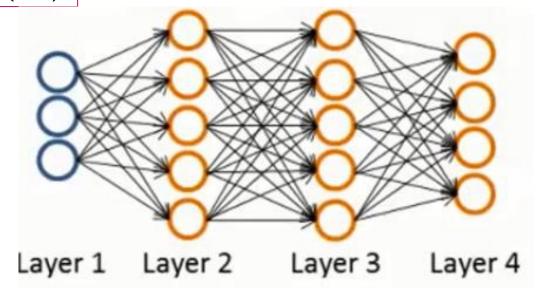
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$$x = x^{(0)} \rightarrow a^{(1)} \rightarrow x^{(1)} \rightarrow a^{(2)} \rightarrow x^{(2)} \rightarrow a^{(3)} \rightarrow x^{(3)} = y$$

$$a_{j}^{(1)} = \sum_{i=1}^{D} w_{ji}^{(1)} x_{i}^{(0)} + b_{j}^{(1)}$$

$$\mathbf{a}_{k}^{(2)} = \sum_{j=1}^{M} w_{kj}^{(2)} x_{j}^{(1)} + b_{k}^{(2)}$$

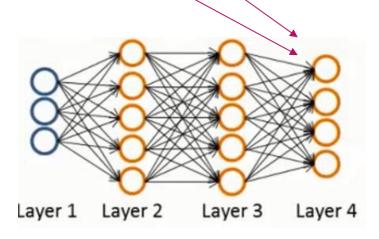


Superscript of w: layer index

$$a_l^{(3)} = \sum_{k=1}^{N} w_{lk}^{(3)} x_k^{(2)} + b_l^{(3)}$$

## Derivative of E on $w^{(3)}$ , $b^{(3)}$

$$\frac{\partial E}{\partial b^{(3)}} = \frac{\partial E(y)}{\partial y} \frac{\partial y(a^{(3)})}{\partial a^{(3)}} \frac{\partial a^{(3)}}{\partial b^{(3)}}$$



$$x_{j}^{(1)} = f(a_{j}^{(1)}) \qquad x_{k}^{(2)} = f(a_{k}^{(2)}) \qquad y_{l} = x_{l}^{(3)} = f(a_{l}^{(3)})$$

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## Derivative of E on $w^{(3)}$ , $b^{(3)}$

$$\frac{\partial E}{\partial w^{(3)}} = \frac{\partial E(y)}{\partial y} \frac{\partial y(a^{(3)})}{\partial a^{(3)}} \frac{\partial a^{(3)}}{\partial w^{(3)}}$$

$$\frac{\partial E}{\partial b^{(3)}} = \frac{\partial E(y)}{\partial y} \frac{\partial y(a^{(3)})}{\partial a^{(3)}} \frac{\partial a^{(3)}}{\partial b^{(3)}}$$

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 $a_l^{(3)} = \sum w_{lk}^{(3)} x_k^{(2)} + b_l^{(3)}$ 

# $\delta^{(3)}$ Step 1

$$\delta^{(3)} = \frac{\partial E(y)}{\partial y} \frac{\partial y(a^{(3)})}{\partial a^{(3)}} - \frac{\partial \sum_{k=1}^{10} -t_k^n lny_k}{\partial y} \frac{\partial \left(\frac{e^{a_j^{(3)}}}{\sum_{k=1}^{10} e^{a_k^{(3)}}}\right)}{\partial a^{(3)}}$$

- Suppose when k=j  $t_i^n$  is 1,
- ► If k=j:

$$\delta_{j}^{(3)} = \frac{\partial (-\ln y_{j})}{\partial y_{j}} \frac{\partial (\frac{e^{a_{j}^{(3)}}}{\sum_{k=1}^{10} e^{a_{k}^{(3)}}})}{\frac{\sum_{k=1}^{10} e^{a_{k}^{(3)}}}{\partial a_{j}^{(3)}}}$$

$$= \left(-\frac{1}{y_{j}}\right) \left(\frac{e^{a_{j}^{(3)}} \sum_{k=1}^{10} e^{a_{k}^{(3)}} - e^{a_{j}^{(3)}} e^{a_{j}^{(3)}}}{(\sum_{k=1}^{10} e^{a_{k}^{(3)}})^{2}}\right)$$

$$= \left(-\frac{1}{y_{j}}\right) \left(\frac{e^{a_{j}^{(3)}}}{\sum_{k=1}^{10} e^{a_{k}^{(3)}}} - \frac{e^{a_{j}^{(3)}} e^{a_{j}^{(3)}}}{(\sum_{k=1}^{10} e^{a_{k}^{(3)}})^{2}}\right)$$

$$= \left(-\frac{1}{y_{j}}\right) \left(y_{j} - y_{j}^{2}\right) = y_{j} - 1$$

Related derivation formula:

$$y = lnx y' = \frac{1}{x}$$

$$y = e^{x} y' = e^{x}$$

$$y = x^{n} y' = nx^{n-1}$$

$$\left(\frac{v(x)}{u(x)}\right)' = \frac{u(x)v'(x) - u'(x)v(x)}{(u(x))^{2}}$$

# $\delta^{(3)}$ Step 2

#### $\blacktriangleright \quad \text{If } k \neq j$ :

$$\delta_{i}^{(3)} = \frac{\partial(-\ln y_{j})}{\partial y_{j}} \frac{\sum_{k=1}^{10} e^{a_{k}^{(3)}}}{\partial a_{i}^{(3)}}$$

$$= \left(-\frac{1}{y_{j}}\right) \left(\frac{0*\sum_{k=1}^{10} e^{a_{k}^{(3)}} - e^{a_{j}^{(3)}} e^{a_{i}^{(3)}}}{(\sum_{k=1}^{10} e^{a_{k}^{(3)}})^{2}}\right)$$

$$= \left(-\frac{1}{y_{j}}\right) \left(-\frac{e^{a_{j}^{(3)}} e^{a_{i}^{(3)}}}{(\sum_{k=1}^{10} e^{a_{k}^{(3)}})^{2}}\right)$$

$$= \left(-\frac{1}{y_{j}}\right) \left(-y_{j}y_{i}\right) = y_{i} - 0$$

 $\delta^{(3)}$ 

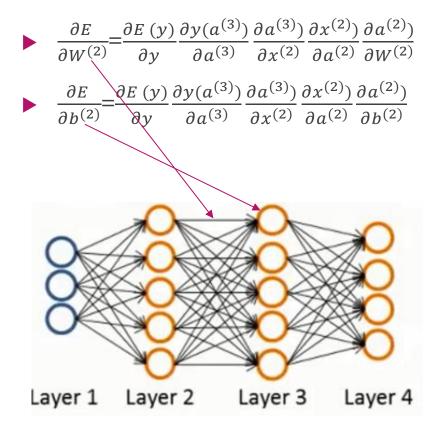
- ► Summary:

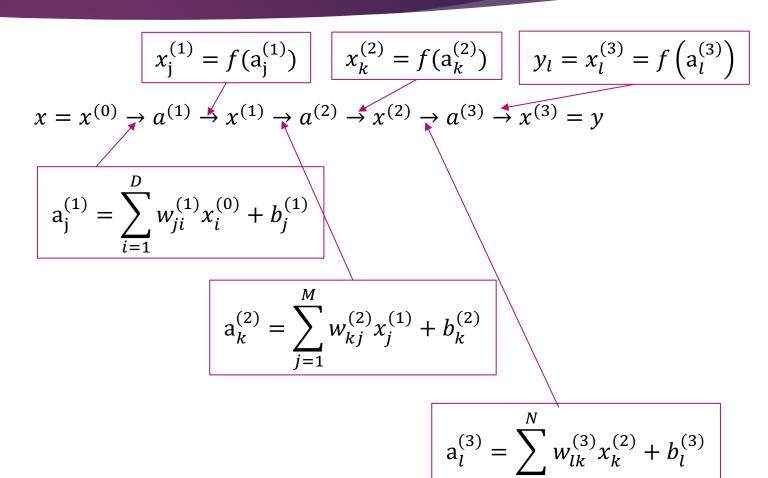
## Derivative of E on $w^{(3)}$ , $b^{(3)}$

$$\frac{\partial E}{\partial w_{ij}^{(3)}} = \frac{\partial E}{\partial a_i^{(3)}} \frac{\partial (a_i^{(3)})}{\partial w_{ij}^{(3)}} = \frac{\partial E}{\partial a_i^{(3)}} \frac{\partial (\sum_{k=1}^N w_{ik}^{(3)} x_k^{(2)} + b_i^{(2)})}{\partial w_{ij}^{(3)}} = \delta_i^{(3)} x_j^{(2)}$$

$$\frac{\partial E}{\partial b_i^{(3)}} = \frac{\partial E}{\partial a_i^{(3)}} \frac{\partial (a_i^{(3)})}{\partial b_i^{(3)}} = \frac{\partial E}{\partial a_i^{(3)}} \frac{\partial (\sum_{k=1}^N w_{ik}^{(3)} x_k^{(2)} + b_i^{(2)})}{\partial b_i^{(3)}} = \delta_i^{(3)} * 1 = \delta_i^{(3)}$$

## Derivative of E on $w^{(2)}$ , $b^{(2)}$





## Derivative of E on $w^{(2)}$ , $b^{(2)}$

$$\frac{\partial E}{\partial W^{(2)}} = \frac{\partial E(y)}{\partial y} \frac{\partial y(a^{(3)})}{\partial a^{(3)}} \frac{\partial a^{(3)}}{\partial x^{(2)}} \frac{\partial x^{(2)}}{\partial a^{(2)}} \frac{\partial a^{(2)}}{\partial W^{(2)}}$$

$$\frac{\partial E}{\partial b^{(2)}} = \frac{\partial E(y)}{\partial y} \frac{\partial y(a^{(3)})}{\partial a^{(3)}} \frac{\partial a^{(3)}}{\partial x^{(2)}} \frac{\partial x^{(2)}}{\partial a^{(2)}} \frac{\partial a^{(2)}}{\partial b^{(2)}}$$

Let 
$$\delta^{(2)} = \frac{\partial E(y)}{\partial y} \frac{\partial y(a^{(3)})}{\partial a^{(3)}} \frac{\partial a^{(3)}}{\partial x^{(2)}} \frac{\partial x^{(2)}}{\partial a^{(2)}} = \frac{\partial E}{\partial a^{(2)}}$$

$$x_{j}^{(1)} = f(a_{j}^{(1)}) \qquad x_{k}^{(2)} = f(a_{k}^{(2)}) \qquad y_{l} = x_{l}^{(3)} = f(a_{l}^{(3)})$$

$$x = x^{(0)} \rightarrow a^{(1)} \rightarrow x^{(1)} \rightarrow a^{(2)} \rightarrow x^{(2)} \rightarrow a^{(3)} \rightarrow x^{(3)} = y$$

$$a_{j}^{(1)} = \sum_{i=1}^{D} w_{ji}^{(1)} x_{i}^{(0)} + b_{j}^{(1)}$$

$$a_{k}^{(2)} = \sum_{i=1}^{M} w_{kj}^{(2)} x_{j}^{(1)} + b_{k}^{(2)}$$

$$a_l^{(3)} = \sum_{k=1}^{N} w_{lk}^{(3)} x_k^{(2)} + b_l^{(3)}$$

 $\delta^{(2)}$ 

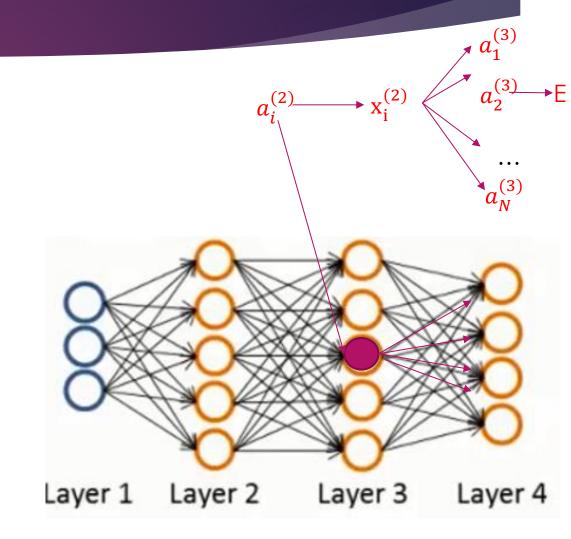
$$\delta_{i}^{(2)} = \sum_{j=1}^{L} \delta_{j}^{(3)} \frac{\partial a_{j}^{(3)}}{\partial x_{i}^{(2)}} \frac{\partial x_{i}^{(2)}}{\partial a_{i}^{(2)}}$$

$$= \sum_{j=1}^{L} \delta_{j}^{(3)} \frac{\partial (\sum_{k=1}^{N} w_{jk}^{(3)} x_{k} + b_{k}^{(3)})}{\partial x_{i}^{(2)}} \frac{\partial x_{i}^{(2)}}{\partial a_{i}^{(2)}}$$

$$= \sum_{j=1}^{L} \delta_{j}^{(3)} w_{ji}^{(3)} f'(a_{i}^{(2)})$$

The matrix is expressed as:

$$\delta^{(2)} = \delta^{(3)}(w^{(3)})^T \odot f'(z^{(2)})$$
f is relu

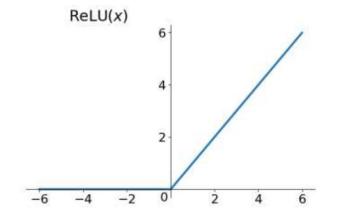


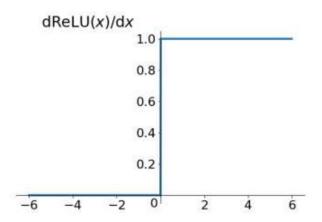
#### Relu and the derivative of relu

Relu:  $f(x) = \max(0, x)$ 

▶ The derivative of relu:

$$f'^{(x)} = \begin{cases} if \ x > 0, f'(x) = 1 \\ else \ f'(x) = 0 \end{cases}$$



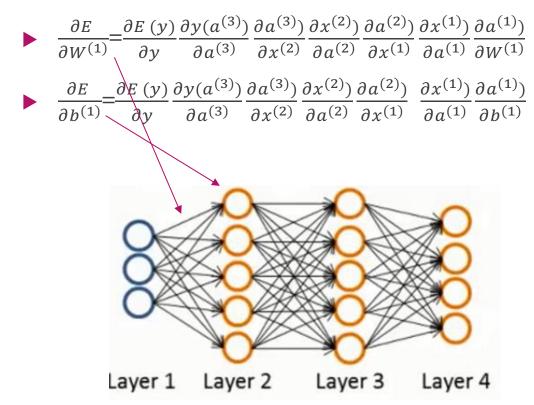


## Derivative of E on $w^{(2)}$ , $b^{(2)}$

$$\frac{\partial E}{\partial w_{ij}^{(2)}} = \frac{\partial E}{\partial a_i^{(2)}} \frac{\partial (a_i^{(2)})}{\partial w_{ij}^{(2)}} = \delta_i^{(2)} \frac{\partial (\sum_{j=1}^M w_{kj}^{(2)} x_j^{(1)} + b_k^{(2)})}{\partial w_{ij}^{(2)}} = \delta_i^{(2)} Z_j^{(1)}$$

$$\frac{\partial E}{\partial b_i^{(2)}} = \frac{\partial E}{\partial a_i^{(2)}} \frac{\partial (a_i^{(2)})}{\partial b_i^{(2)}} = \frac{\partial E}{\partial a_i^{(2)}} \frac{\partial (\sum_{j=1}^M w_{kj}^{(2)} x_j^{(1)} + b_k^{(2)})}{\partial b_i^{(3)}} = \delta_i^{(2)} * 1 = \delta_i^{(2)}$$

## Derivative of E on $w^{(1)}$ , $b^{(1)}$



$$x_{j}^{(1)} = f(a_{j}^{(1)}) \qquad x_{k}^{(2)} = f(a_{k}^{(2)}) \qquad y_{l} = x_{l}^{(3)} = f(a_{l}^{(3)})$$

$$x = x^{(0)} \Rightarrow a^{(1)} \Rightarrow x^{(1)} \Rightarrow a^{(2)} \Rightarrow x^{(2)} \Rightarrow a^{(3)} \Rightarrow x^{(3)} = y$$

$$a_{j}^{(1)} = \sum_{i=1}^{D} w_{ji}^{(1)} x_{i}^{(0)} + b_{j}^{(1)}$$

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$$a_l^{(3)} = \sum_{k=1}^{N} w_{lk}^{(3)} x_k^{(2)} + b_l^{(3)}$$

## Derivative of E on $w^{(1)}$ , $b^{(1)}$

- ▶ Like  $\delta^{(2)}$ :  $\delta^{(1)} = \delta^{(2)}(w^{(2)})^T \odot f'(a^{(1)})$

## Gradient Descent Process (BP Algorithm)

- 1. Set values to max\_iterations and  $\eta$
- 2. Randomly generate  $W^{(0)}$  and  $b^{(0)}$
- 3. For t = 1 to max\_iterations
- 4. Calculate the derivatives:  $\frac{\partial E_{\text{total}}(W^{(t)}, b^{(t)})}{\partial W^{(t)}}$  and  $\frac{\partial E_{\text{total}}(W^{(t)}, b^{(t)})}{\partial b^{(t)}}$
- 5. Update  $W^{(t+1)} = W^{(t)} \eta \frac{\partial E_{\text{total}}(W^{(t)}, b^{(t)})}{\partial W^{(t)}}$ ,  $B^{(t+1)} = b^{(t)} \eta \frac{\partial E_{\text{total}}(W^{(t)}, b^{(t)})}{\partial b^{(t)}}$
- 6. EndFor

#### Note:

E can be loss for a single sample, a batch of randomly selected sample, or all training samples.