

# Math Method II

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## Week 2

### - Int. on dif coordinates

x-y:  $dA = dx dy$

polar:  $dA = r dr d\theta$

cylinder:  $\begin{cases} \text{Area: } dA = r d\theta dz \\ \text{Volume: } dV = r d\theta dr dz \end{cases}$

sphere:  $\begin{cases} \text{Area: } r^2 \sin\theta d\theta d\phi \\ \text{Volume: } r^3 \sin\theta dr d\theta d\phi \end{cases}$

### - Method on derive dA

$$dr = \hat{e}_x dx + \hat{e}_y dy + \hat{e}_z dz$$

eg. Sphere:  $d\vec{r} = \frac{dr}{dr} dr + \frac{dr}{d\theta} d\theta + \frac{dr}{d\phi} d\phi$

$$x = r \sin\phi \cos\theta = \hat{e}_r \cdot dr + \hat{e}_\theta \cdot r d\theta + r \sin\phi d\phi$$

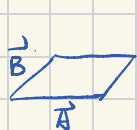
$$\begin{aligned} y &= r \sin\phi \sin\theta \\ z &= r \cos\phi \end{aligned} \quad d\vec{r} = \begin{pmatrix} dx \\ dy \\ dz \end{pmatrix} = \begin{pmatrix} \sin\phi \cos\theta \\ \sin\phi \sin\theta \\ \cos\phi \end{pmatrix} dr + \begin{pmatrix} -\sin\phi \sin\theta \\ \sin\phi \cos\theta \\ 0 \end{pmatrix} r d\theta + \begin{pmatrix} r \cos\phi \cos\theta \\ r \cos\phi \sin\theta \\ -r \sin\phi \end{pmatrix} d\phi$$

### - Int. on scalar field.

eg.  $f(x)$  on polar coordinates find int.

$$f(x, y) \text{ with } x = r \cos\theta, y = r \sin\theta \Rightarrow f(r, \theta) \quad \text{Area} = \int f(r, \theta) dA = \dots$$

### - Unit Area



$$S = \vec{A} \times \vec{B}$$

Arbitrary Surface

$$\frac{\partial \vec{r}}{\partial p} dp \text{ As } \vec{A} \\ \frac{\partial \vec{r}}{\partial \phi} d\phi \text{ As } \vec{B}$$

$$dS = \left| \frac{\partial \vec{r}}{\partial p} \times \frac{\partial \vec{r}}{\partial \phi} \right| dp d\phi$$

eg. Area Unit For sphere

$$\vec{r}_\theta = \frac{\partial \vec{r}}{\partial \theta} = \begin{pmatrix} R \cos\theta \cos\phi \\ R \cos\theta \sin\phi \\ -R \sin\theta \end{pmatrix}$$

$$\vec{r}_\phi = \frac{\partial \vec{r}}{\partial \phi} = \begin{pmatrix} -R \sin\theta \sin\phi \\ R \sin\theta \cos\phi \\ 0 \end{pmatrix}$$

$$\begin{aligned} \vec{N} &= \hat{i} (R^2 \sin^2\theta \cos\theta) + \hat{j} (R^2 \sin^2\theta \sin\phi) + \hat{k} (R^2 \cos^2\phi \sin\theta \cos\theta + R^2 \sin^2\phi \cos\theta \sin\theta) \\ &\quad + \hat{k} (R^2 \sin\theta \cos\theta) \end{aligned}$$

$$A = |N| = R^2 |\sin \theta| \rightarrow dA = R^2 \sin \theta d\theta d\phi$$

-  $\nabla, \nabla^2$  in polar coordinates

$$\nabla = \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial z} = \frac{\partial}{\partial r} \left( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial z} \right) = \frac{\partial}{\partial r} \left( \frac{1}{\sin \phi} \left( \frac{1}{\sin \theta} + \frac{1}{\cos \theta} \right) + \frac{1}{\cos \phi} \right) + \frac{\partial}{\partial \theta} \left( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right) + \frac{\partial}{\partial \phi} \left( \dots \right)$$

$$\begin{cases} x = r \sin \phi \sin \theta \\ y = r \sin \phi \cos \theta \\ z = r \cos \phi \end{cases}$$

X Obsolete Method

★ General Laplacien

+ Scale factor method

$$dr \text{ in sph. coord.} = r \cdot d\theta \Rightarrow (\nabla \psi)_i = \frac{1}{h_i} \cdot \frac{\partial \psi}{\partial q_i} \text{ as } h_i \text{ is scale factor.}$$

$$\downarrow \\ dr = h dq$$

$$\text{For } \psi(x,y,z) \quad \nabla \psi = \sum_{ijk} \frac{1}{h_i} \frac{\partial \psi}{\partial q_i}$$

$$\nabla \cdot A = \lim_{V \rightarrow 0} \oint A ds / V \quad \text{with } V = (h_1 dq_1)(h_2 dq_2)(h_3 dq_3) = h_1 h_2 h_3 dq_1 dq_2 dq_3$$

$$\oint A ds = \text{Flux} \quad 1. \text{ Left Side Flux} = A_1(q_1) h_2 dq_2 h_3 dq_3$$

$$\text{Right Side } (q_1 + dq_1) \text{ Flux} = (A_1 h_2 h_3)(q_1 + dq_1) dq_2 dq_3$$

★ Taylor

$$= [A_1 h_2 h_3]_{q_1} + \frac{\partial}{\partial q_1} (A_1 h_2 h_3) dq_1 \cdot dq_2 dq_3$$

$$\text{Net Flux} = \frac{\partial}{\partial q_1} (A_1 h_2 h_3) dq_1 dq_2 dq_3$$

$$\text{Add on Three sides: } = \left[ \frac{\partial}{\partial q_1} (A_1 h_2 h_3) + \frac{\partial}{\partial q_2} (A_2 h_1 h_3) + \frac{\partial}{\partial q_3} (A_3 h_1 h_2) \right] dq_1 dq_2 dq_3$$

$$\nabla^2 \psi = \nabla \cdot A = \frac{1}{h_1 h_2 h_3} \left[ \dots \right] \quad \text{with } A = \frac{1}{h_i} \frac{\partial \psi}{\partial q_i}$$

$$= \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial q_1} \left( h_2 h_3 \frac{1}{h_1} \frac{\partial \psi}{\partial q_1} \right) + \frac{\partial}{\partial q_2} \left( h_1 h_3 \frac{1}{h_2} \frac{\partial \psi}{\partial q_2} \right) + \frac{\partial}{\partial q_3} \left( h_1 h_2 \frac{1}{h_3} \frac{\partial \psi}{\partial q_3} \right) \right]$$

eg. sphere coord.

$$q_1, q_2, q_3 = r, \theta, \phi$$

$$\Rightarrow \nabla^2 \psi = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \frac{\partial \psi}{\partial r}) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial \psi}{\partial \theta}) + \frac{1}{r^2 \sin \theta} \frac{\partial^2 \psi}{\partial \phi^2}$$

$$\text{with } h_1 = 1 \quad h_2 = r \quad h_3 = r \sin \theta$$

$$\begin{matrix} \uparrow & \uparrow & \uparrow \\ dr = dr & dr = r d\theta & dr = r \sin \theta d\phi \end{matrix}$$