# Inner product on a vector space

• The inner product on  $\mathbb{R}^n$  generalizes to an arbitrary vector space.

An **inner product** on a vector space V is a function that, to each pair of vectors  $\mathbf{u}$  and  $\mathbf{v}$  in V, associates a real number  $\langle \mathbf{u}, \mathbf{v} \rangle$  and satisfies the following axioms, for all  $\mathbf{u}, \mathbf{v}$ , and  $\mathbf{w}$  in V and all scalars c:

- 1.  $\langle \mathbf{u}, \mathbf{v} \rangle = \langle \mathbf{v}, \mathbf{u} \rangle$
- 2.  $\langle \mathbf{u} + \mathbf{v}, \mathbf{w} \rangle = \langle \mathbf{u}, \mathbf{w} \rangle + \langle \mathbf{v}, \mathbf{w} \rangle$
- 3.  $\langle c\mathbf{u}, \mathbf{v} \rangle = c \langle \mathbf{u}, \mathbf{v} \rangle$
- **4.**  $\langle \mathbf{u}, \mathbf{u} \rangle \ge 0$  and  $\langle \mathbf{u}, \mathbf{u} \rangle = 0$  if and only if  $\mathbf{u} = \mathbf{0}$

A vector space with an inner product is called an **inner product space**.

- Example: Let  $a_1, \dots, a_n$  be positive real numbers, we can define a "weighted" inner product on  $\mathbb{R}^n$  as  $\langle \mathbf{u}, \mathbf{v} \rangle = a_1 u_1 v_1 + \cdots a_n u_n v_n$ .
- Example

**EXAMPLE 7** For f, g in C[a, b], set

$$\langle f, g \rangle = \int_{a}^{b} f(t)g(t) dt$$

Show that (5) defines an inner product on C[a, b].

Preof: The properties 1). 2), 3) of the inner product is clear. For the last property, notice that  $(f,f) = \int_a^b f(t)^2 dt >> 0$ , and it is Zero iff f = 0.  $\square$ 

## Lengths, distances and orthogonality

- Let V be an inner product space. For  $\mathbf{v} \in V$ , we define its length to be  $\|\mathbf{v}\| = \sqrt{\langle \mathbf{v}, \mathbf{v} \rangle}$ , and the distance between  $\mathbf{u}, \mathbf{v} \in V$  to be  $\|\mathbf{u} \mathbf{v}\|$ .
- Two vectors  $\mathbf{u}, \mathbf{v} \in V$  are said to be orthogonal if  $\langle \mathbf{u}, \mathbf{v} \rangle = 0$ .
- Pythagoras theorem: Two vectors  $\mathbf{u}, \mathbf{v} \in V$  are orthogonal if and only if  $\|\mathbf{u}\|^2 + \|\mathbf{v}\|^2 = \|\mathbf{u} + \mathbf{v}\|^2$ .
- Let W be a sub vector space of V, we can define its orthogonal complement  $W^{\perp}$  as  $\{\mathbf{v} \in V \mid \langle \mathbf{v}, \mathbf{w} \rangle = 0, \forall \mathbf{w} \in W\}$ .
- Theorem: Let W be a sub vector space of V, then  $W^{\perp}$  remains a sub vector space of V, and we have  $W \cap W^{\perp} = \{0\}, W + W^{\perp} = V$ .

- So any vector  $\mathbf{v} \in V$  can be written uniquely as  $\mathbf{v} = \operatorname{Proj}_W(\mathbf{v}) + \operatorname{Proj}_{W^{\perp}}(\mathbf{v})$ , with  $\operatorname{Proj}_W(\mathbf{v}) \in W$ ,  $\operatorname{Proj}_{W^{\perp}}(\mathbf{v}) \in W^{\perp}$ .
- The projection formula holds also in the new more general setting. In particular, for a line  $L = \operatorname{Span}\{\mathbf{u}\}$ , we have  $\operatorname{Proj}_L(\mathbf{v}) = \frac{\langle \mathbf{v}, \mathbf{u} \rangle}{\langle \mathbf{u}, \mathbf{u} \rangle} \mathbf{u}$ .
- Theorem

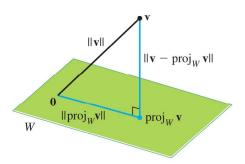
The Cauchy-Schwarz Inequality
For all 
$$\mathbf{u}$$
,  $\mathbf{v}$  in  $V$ ,

$$|\langle \mathbf{u}, \mathbf{v} \rangle| \le \|\mathbf{u}\| \|\mathbf{v}\| \tag{4}$$

$$\Rightarrow \|v\| > \|\text{Pej}_{W}(v)\|$$
In particular, let  $W = \text{Span}\{u\}$ ,
then
$$\|v\| > \|\frac{\langle v, u \rangle}{\langle u, u \rangle} \|u\|$$

$$= \frac{|\langle v, u \rangle|}{\|u\|^{2}} \|u\|$$





**FIGURE 2** The hypotenuse is the longest side.

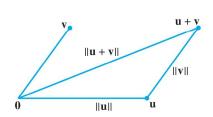
### Theorem

## The Triangle Inequality

For all  $\mathbf{u}$ ,  $\mathbf{v}$  in V,

$$\|\mathbf{u} + \mathbf{v}\| \le \|\mathbf{u}\| + \|\mathbf{v}\|$$

Prof: 
$$\| u + v \|^2 = \langle u + v, u + v \rangle$$
  
 $= \langle u, u \rangle + \langle v, v \rangle + 2 \langle u, v \rangle$   
 $= \| u \|^2 + \| v \|^2 + 2 \langle u, v \rangle$   
cauchy  $\leq \| u \|^2 + \| v \|^2 + 2 \| u \| \cdot \| v \|$   
 $= (\| u \| + \| v \|)^2$   
 $\Rightarrow \| u + v \| \leq \| u \| + \| v \|$ 



# **Quadratic forms and symmetric matrices**

- The Euclidean norm square  $\|\mathbf{v}\|^2 = v_1^2 + \dots + v_n^2$  is a particular quadratic form (二次型) on  $\mathbb{R}^n$ .
- In general, a quadratic form on  $\mathbb{R}^n$  is a function

$$Q(\mathbf{x}) = c_1 x_1^2 + \dots + c_n x_n^2 + \sum_{i \neq j=1}^n c_{ij} x_i x_j.$$

• The terms  $c_{ii}x_ix_i$  are called cross-product terms (交叉项).

- Notice that it can be written in matrix form: Let  $A=(a_{ij})$  be the  $n\times n$  symmetric matrix such that  $a_{ii}=c_i$  and  $a_{ij}=a_{ji}=c_{ij}/2$ , then  $Q(\mathbf{x})=\mathbf{x}^tA\mathbf{x}$ . The matrix A is called the matrix of the quadratic form.
- Similar to the relationship between Euclidean norm and the inner product, we can associate the function  $B(\mathbf{x}, \mathbf{y}) = \mathbf{x}^t A \mathbf{y}$ . It is clear that  $Q(\mathbf{x}) = B(\mathbf{x}, \mathbf{x})$ .
- As A is symmetric, the function  $B(\mathbf{x}, \mathbf{y}) = \mathbf{x}^t A \mathbf{y}$  satisfies the properties:
- 1.  $B(\mathbf{x}, \mathbf{y}) = B(\mathbf{y}, \mathbf{x})$ ,
- 2.  $B(\mathbf{x}_1 + \mathbf{x}_2, \mathbf{y}) = B(\mathbf{x}_1, \mathbf{y}) + B(\mathbf{x}_2, \mathbf{y}),$
- 3.  $B(c\mathbf{x}, \mathbf{y}) = cB(\mathbf{x}, \mathbf{y})$ .
- For this reason,  $\emph{B}$  is called a symmetric bilinear form (对称双线性形式).

- Consider the change of variable  $\mathbf{x} = P\mathbf{y}$ , the quadratic form will be changed to  $Q(\mathbf{y}) = \mathbf{y}^t(P^tAP)\mathbf{y}$ .
- Question: Is it possible to find a change of variable such that the matrix of the quadratic form is nice? For example, diagonal?
- In case that P is orthogonal, i.e.  $P^{-1} = P^t$ , the transformation becomes  $P^{-1}AP$  and is related to the diagonalization of the matrix A.
- Definition: The symmetric matrix A is said to be orthogonally diagonalizable if there exists an orthogonal matrix P such that  $P^{-1}AP$  is diagonal.
- It is clear that A is orthogonally diagonalizabel if and only the eigenvectors of A forms an orthonormal basis of  $\mathbb{R}^n$ .

# Diagonalization of symmetric matrices

Theorem

#### The Spectral Theorem for Symmetric Matrices

An  $n \times n$  symmetric matrix A has the following properties:

- a. A has n real eigenvalues, counting multiplicities.
- b. The dimension of the eigenspace for each eigenvalue  $\lambda$  equals the multiplicity of  $\lambda$  as a root of the characteristic equation.
- c. The eigenspaces are mutually orthogonal, in the sense that eigenvectors corresponding to different eigenvalues are orthogonal.
- d. A is orthogonally diagonalizable.
- Geometrically, this means that we can find an orthonormal basis of  $\mathbb{R}^n$  such that A acts as dilation with respect to this coordinate system.

• Lemma: Let A be an  $n \times n$  symmetric matrix, then all the complex roots of the characteristic equation  $\det(A - \lambda I) = 0$  are in fact real.

Preof: Let  $\det(A - \lambda I) = \prod_{i=1}^{m} (\lambda_i - \lambda)^{m_i}$  with  $\lambda_i \in \mathbb{C}$ . Consider A as a linear transformation  $A: \mathbb{C}^m \to \mathbb{C}^m$ , then for each  $\lambda_i$ , we have an eigenvector

$$A v_i = \lambda_i v_i$$

Over  $\mathbb{C}^n$ , we can define an inner product similar to the Euclidean inner product: For  $z = \begin{pmatrix} z_1 \\ \vdots \\ z_n \end{pmatrix} \in \mathbb{C}^n$ ,  $w = \begin{pmatrix} w_1 \\ \vdots \\ w_n \end{pmatrix} \in \mathbb{C}^n$ , let  $\langle z, w \rangle = \overline{z}_1 w_1 + \cdots + \overline{z}_n w_n = \overline{z}_n \cdot w$ .

It is clear that the inner product has the properties

- $(3, \omega) = \langle \omega, \xi \rangle$
- 2)  $\langle z, c_1 w_1 + c_2 w_2 \rangle = c_1 \langle z, w_1 \rangle + c_2 \langle z, w_2 \rangle$ ,  $\forall c_1, c_2 \in \mathbb{C}$ ,
- 3)  $\langle \xi, \xi \rangle$  is real >0 and  $\langle \xi, \xi \rangle = 0$  iff  $\xi = 0$ .

Now consider the inner product  $\langle v_i, A v_i \rangle = \overline{v}_i^t A v_i$ . On the one hand,  $A \text{ real symmetric} = (A v_i)^t v_i$ 

(\*)  $\langle v_i, A v_i \rangle = \langle v_i, \lambda_i v_i \rangle = \lambda_i \langle v_i, v_i \rangle$  =  $\langle A v_i, v_i \rangle$ On the other hand,

 $(**) \quad \langle v_{i}, A v_{i} \rangle = \langle A v_{i}, v_{i} \rangle = \langle \lambda_{i} v_{i}, v_{i} \rangle = \overline{\lambda_{i}} \langle v_{i}, v_{i} \rangle$ 

Compare (\*), (\*\*), get  $\lambda_i = \overline{\lambda}_i$ , so  $\lambda_i \in \mathbb{R}$  as claim.

• Lemma: Let A be an  $n \times n$  symmetric matrix, let  $\mathbf{v}$  be an eigenvector of A, then A preserves the orthogonal complement of  $\mathrm{Span}\{\mathbf{v}\}$ .

Proof Suppose that 
$$Av = \lambda v$$
 for some  $\lambda \in \mathbb{R}$ .

For  $w \in \text{Span}\{v\}^{\perp}$ , we have
$$\langle v, Aw \rangle = v^{t} A w = (Av)^{t} w = \langle Av, w \rangle$$

$$= \langle \lambda v, w \rangle = 0$$

So AWE Spando), and hence A preserves spandojt.

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• Proof of the theorem:

For the remaining assertions, we'll prove that A is orthogonally diagonalizable, i.e. there exists an orthogonal matrix p such that  $A = p \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix} p^t$   $\begin{pmatrix} p^{-1} = p^t \end{pmatrix}$ 

This implies the assertion b). c), d). Indeed, let  $P = [v_1 \cdots v_n]$ , then  $\{v_1, \cdots, v_n\}$  from an orthonormal basis, and  $A = P \begin{pmatrix} \lambda_1 & \dots & \lambda_n \end{pmatrix} P^t = P \begin{pmatrix} \lambda_1 & \dots & \lambda_n \end{pmatrix} P^{-1}$ 

is equivalent to 
$$AP = P(\lambda_1, \lambda_n)$$
, i.e.  $A(v_1, \dots, v_n) = [v_1, \dots, v_n](\lambda_1, \dots, \lambda_n)$ 

 $\Leftrightarrow$  A  $v_i = \lambda_i \vee i$ ,  $i = 1, \dots, n$ .

We pare the assertion that A is orthogonally diagonalisable by induction. The case n=1 is evident. Suppose that the assertion is proved for n-1. Then for an  $n\times n$  matrix A, it is known from lemma 1 that  $\det (A-\lambda I) = \prod_{i=1}^r (\lambda_i - \lambda_i)^m, \text{ with } \lambda_i \in R.$ 

Let  $v_i$  be an eigenvector with eigenvalue  $\lambda_i$ , (\*)  $A v_i = \lambda v_i$ .

Without less of generality, we can assume that  $\|v_1\| = 1$ . By lemma 2, it is know that A preserves Span  $\{v_1\}^{\perp}$ . Let  $\{v_2, ..., v_n\}$  be an athonormal basis of Span  $\{\vec{v}_i\}$ . Hen  $\{v_1, ..., v_n\}$  is an athonormal basis of  $\mathbb{R}^n$ .

Notice that (\*) and the fact that A preserves Span { v, ] implies:

 $A[v_1 \ v_2 \cdots \ v_n] = [v_1 \ v_2 \cdots \ v_n] \begin{pmatrix} \lambda_1 & 0 \cdots & 0 \\ 0 & & \\ \vdots & & A' \end{pmatrix}$   $P_1 \text{ orthogonal}.$ 

$$\Rightarrow A = P_{1} \begin{bmatrix} \lambda_{1} \\ A' \end{bmatrix} P_{1}^{t}.$$

$$\uparrow \text{ induction hypothesis}$$

$$A' = P_{2} \begin{pmatrix} \lambda_{2} \\ \lambda_{n} \end{pmatrix} P_{2}^{t}.$$

$$\Rightarrow A = P_{1} \begin{pmatrix} \lambda_{1} \\ P_{2} \end{pmatrix} \begin{pmatrix} \lambda_{2} \\ \lambda_{n} \end{pmatrix} P_{2}^{t}$$

$$= P_{1} \begin{pmatrix} 1 \\ P_{2} \end{pmatrix} \begin{pmatrix} \lambda_{1} \\ \lambda_{2} \\ \lambda_{n} \end{pmatrix} \begin{pmatrix} 1 \\ P_{2} \\ \lambda_{n} \end{pmatrix} \begin{pmatrix} P_{1}^{t} \\ P_{2}^{t} \end{pmatrix}$$

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**EXAMPLE 3** Orthogonally diagonalize the matrix 
$$A = \begin{bmatrix} 3 & -2 & 4 \\ -2 & 6 & 2 \\ 4 & 2 & 3 \end{bmatrix}$$
, whose characteristic equation is

$$0 = -\lambda^3 + 12\lambda^2 - 21\lambda - 98 = -(\lambda - 7)^2(\lambda + 2)$$

# Applications to quadratic forms

- Recall that a quadratic form can be written as  $Q(\mathbf{x}) = \mathbf{x}^t A \mathbf{x}$  for a symmetric matrix A, and that a change of variable  $\mathbf{x} = P \mathbf{y}$  by an orthogonal matrix P will change Q to  $Q(\mathbf{y}) = \mathbf{y}^t (P^t A P) \mathbf{y}$ .
- · Combined with the spectral theorem of symmetric matrices, we get the theorem

### The Principal Axes Theorem

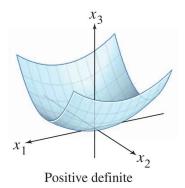
Let A be an  $n \times n$  symmetric matrix. Then there is an orthogonal change of variable,  $\mathbf{x} = P\mathbf{y}$ , that transforms the quadratic form  $\mathbf{x}^T A \mathbf{x}$  into a quadratic form  $\mathbf{y}^T D \mathbf{y}$  with no cross-product term.

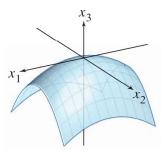
• The column vectors of P are the eigenvectors of A, they are called the principle axes (主轴) of the quadratic form Q.

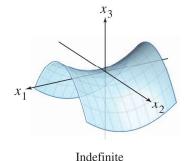
- In other words, with respect to the coordinate system given by the principal axes, the matrix for the quadratic form will be diagonal, i.e. it will be of the form  $Q(\mathbf{y}) = \lambda_1 y_1^2 + \dots + \lambda_n y_n^2$ .
- Definition

A quadratic form Q is:

- a. **positive definite** if  $Q(\mathbf{x}) > 0$  for all  $\mathbf{x} \neq \mathbf{0}$ ,
- b. **negative definite** if  $Q(\mathbf{x}) < 0$  for all  $\mathbf{x} \neq \mathbf{0}$ ,
- c. **indefinite** if  $Q(\mathbf{x})$  assumes both positive and negative values.







Negative definite

### Theorem

## **Quadratic Forms and Eigenvalues**

Let A be an  $n \times n$  symmetric matrix. Then a quadratic form  $\mathbf{x}^T A \mathbf{x}$  is:

- a. positive definite if and only if the eigenvalues of A are all positive,
- b. negative definite if and only if the eigenvalues of A are all negative, or
- c. indefinite if and only if A has both positive and negative eigenvalues.

• A quadratic form is called degenerate, if the associated matrix has 0 as one of its eigenvalues. With respect to the principal axis, it takes the form  $Q(\mathbf{y}) = \lambda_1 y_1^2 + \dots + \lambda_r y_r^2$ , with  $\lambda_1, \dots, \lambda_r \neq 0$  and r < n.

